- 1. Numerical integration plays key roles for computing, and some well-known functions are *definied* as integrals.
- 2. Numerical integration, also known as quadrature:

Given a sample of n points for a function f, find an approximation of  $\int_a^b f(x) dx$ .

Interpolatory quadrature, also known as Newton-Cotes rules

let

$$f(x) = \sum_{i=1}^{n} a_i \phi_i(x)$$

where  $\phi_i(x)$  are basis functions (see Chapter 13 on Interpolation). Then the integral of f:

$$\int_{a}^{b} f(x) = \sum_{i=1}^{n} a_i \left( \int_{a}^{b} \phi_i(x) \right)$$

Newton-Cotes rules:

▶ n = 1, midpoint rule

$$\mathsf{error} = O((b-a)^3)$$

▶ n = 1, trapezoidal rule

$$\mathsf{error} = O((b-a)^3)$$

Note: the same order as the midpoint rule

▶ n = 2, Simpson's rule

$$\operatorname{error} = O((b-a)^5)$$

**Composite rules**: Let [a, b] be subdivided into k intervals, say, take  $\Delta x = \frac{b-a}{k}$ , and  $x_i = a + (i-1)\Delta x$ .

the composite trapezoidal rule is given by

$$\int_{a}^{b} f(x) \approx \sum_{i=1}^{k} \left( \frac{f(x_i) + f(x_{i+1})}{2} \right) \Delta x$$
$$= \left( \frac{1}{2} f(a) + f(x_2) + \dots + f(x_k) + \frac{1}{2} f(b) \right) \Delta x$$

 $\mathrm{error} = O((\varDelta x)^3) \times \tfrac{b-a}{\varDelta x} = O((\varDelta x)^2).$ 

▶ By a similar scheme, we can also derive a composite Simpson's rule. error =  $O(\Delta x^5) \times \frac{b-a}{\Delta x} = O(\Delta x^4)$ .

#### Adaptive Simpson's quadrature

▶ **Goal**: approx.  $I = \int_a^b f(x) dx$  to within an error tolerance  $\epsilon > 0$ .

• step 1: Simpson's rule with h = (b - a)/2

$$I = S(a, b) - E_1 := S_1 - E_1$$

▶ step 2: Composite Simpson's rule with  $h_1 = (b - a)/2^2$ 

$$I = S(a, \frac{a+b}{2}) + S(\frac{a+b}{2}, b) - E_2 := S_2 - E_2$$

• It can be shown that  $E_1 \approx 16E_2$ . Then

$$S_1 - S_2 = E_1 - E_2 \approx 15E_2.$$

which implies that

$$|I - S_2| = |E_2| \approx \frac{1}{15}|S_1 - S_2|.$$

Adaptive Simpson's quadrature, cont'd

- ▶ If  $|S_1 S_2|/15 < \epsilon$ , then  $|I S_2| < \epsilon$ .  $S_2$  is sufficiently accuracy.
- Otherwise, apply the same error estimation procedure to the subintervals  $[a, \frac{a+b}{2}]$  and  $[\frac{a+b}{2}, b]$ , respectively to determine if the approximation to the integral on each subinterval is within a tolerance of  $\epsilon/2$

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- Recursive algorithm
- MATLAB code: quadtx.m

 $1. \ \mbox{Quadrature rules in a general form}$ 

$$\int_{a}^{b} f(x)dx \approx Q(f) = \sum_{i=1}^{n} w_{i}f(x_{i})$$

where  $x_i$  are *knots*, and  $w_i$  are *weights*.

- 2. The choices of  $\{x_i\}$  and  $\{w_i\}$  determine a quadrature rule.
- 3. The method of undetermined coefficients fix  $\{x_i\}$ , choose  $\{w_i\}$  so that Q(f) approximate the integral of f for reasonably smooth functions.

Example of the method of undetermined coefficients

▶ Let  $x_1 = 0$ ,  $x_2 = 1/2$  and  $x_3 = 1$ . pick  $f_1(x) = 1$ ,  $f_2(x) = x$  and  $f_3(x) = x^2$  such that

$$\int_0^1 f_1(x)dx = w_1f_1(x_1) + w_2f_1(x_2) + w_3f_1(x_3)$$
$$\int_0^1 f_2(x)dx = w_1f_2(x_1) + w_2f_2(x_2) + w_3f_2(x_3)$$
$$\int_0^1 f_3(x)dx = w_1f_3(x_1) + w_2f_3(x_2) + w_3f_3(x_3)$$

Consequently, we have the Simplson's rule

$$\int_0^1 f(x)dx \approx Q(f) = \frac{1}{6}f(0) + \frac{2}{3}f(\frac{1}{2}) + \frac{1}{6}f(1)$$

▶ By the change of interval  $[a, b] \rightarrow [0, 1]$ , x = a + (b - a)y, we have the Simplson's rule on the interval [a, b]:

$$\int_{a}^{b} f(x)dx \approx Q(f) = (b-a) \left[ \frac{1}{6}f(a) + \frac{2}{3}f(\frac{b+a}{2}) + \frac{1}{6}f(b) \right]$$