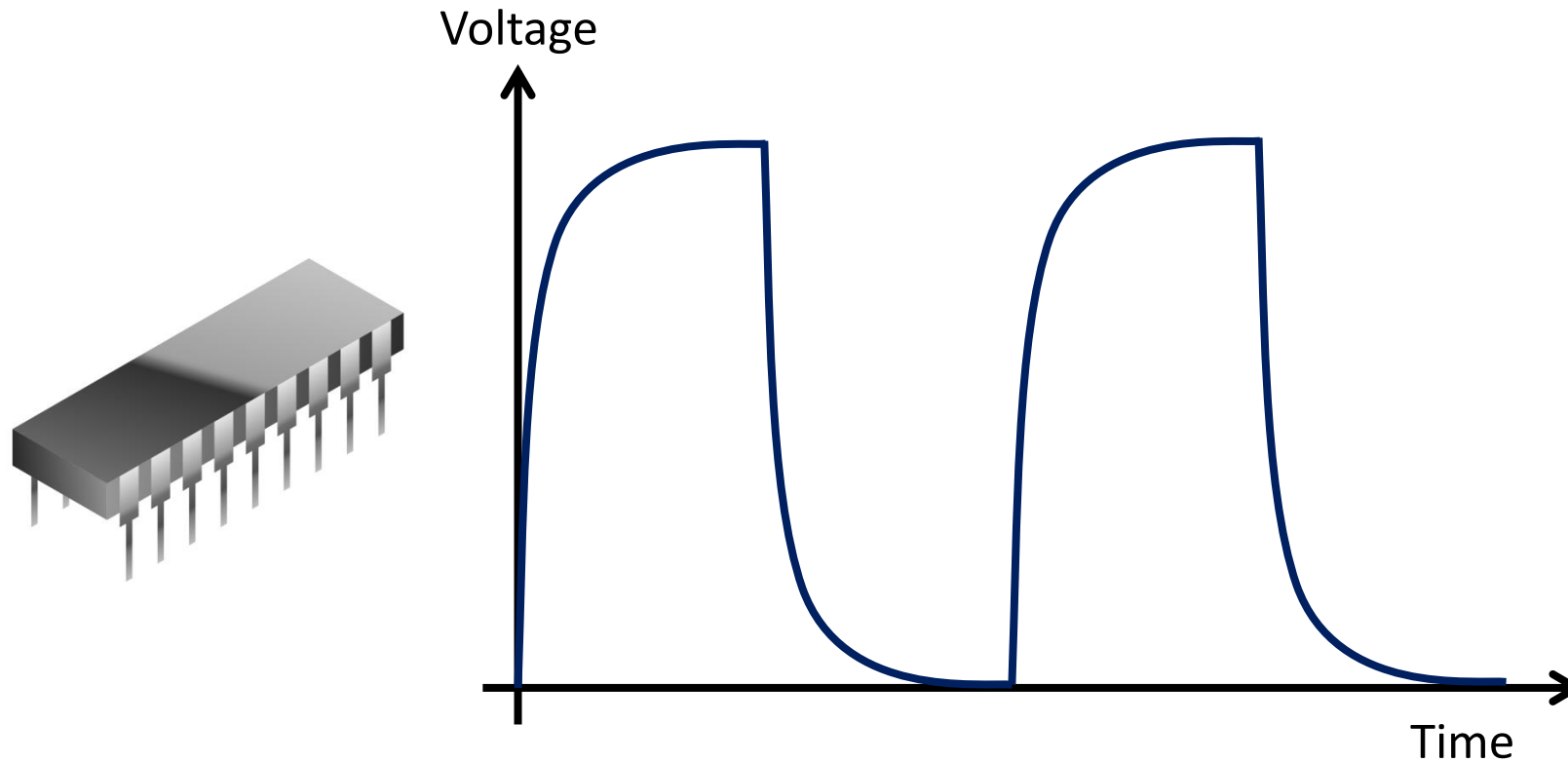


# Thermodynamic binding networks

slides © 2021, David Haley and David Doty

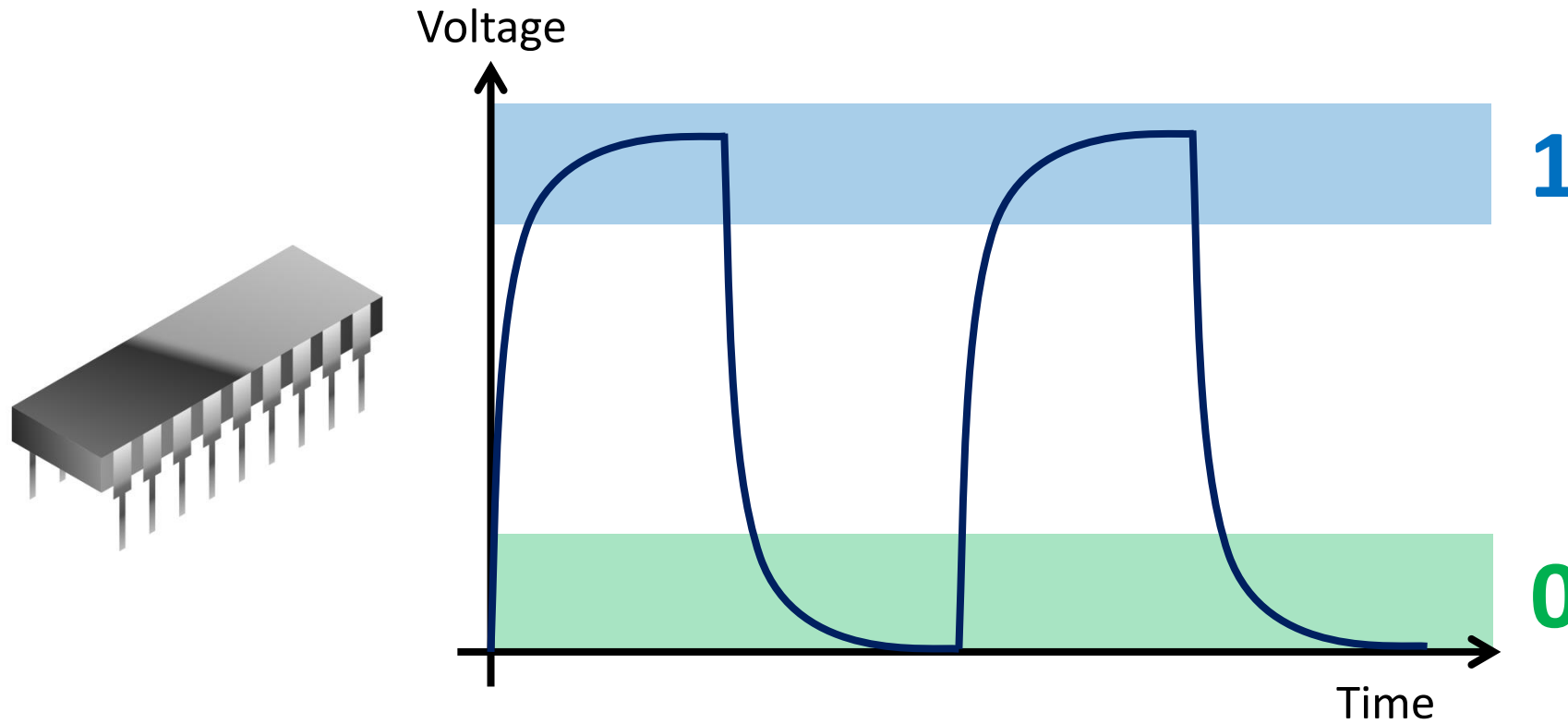
ECS 232: Theory of Molecular Computation, UC Davis

# Representing Information with Molecules



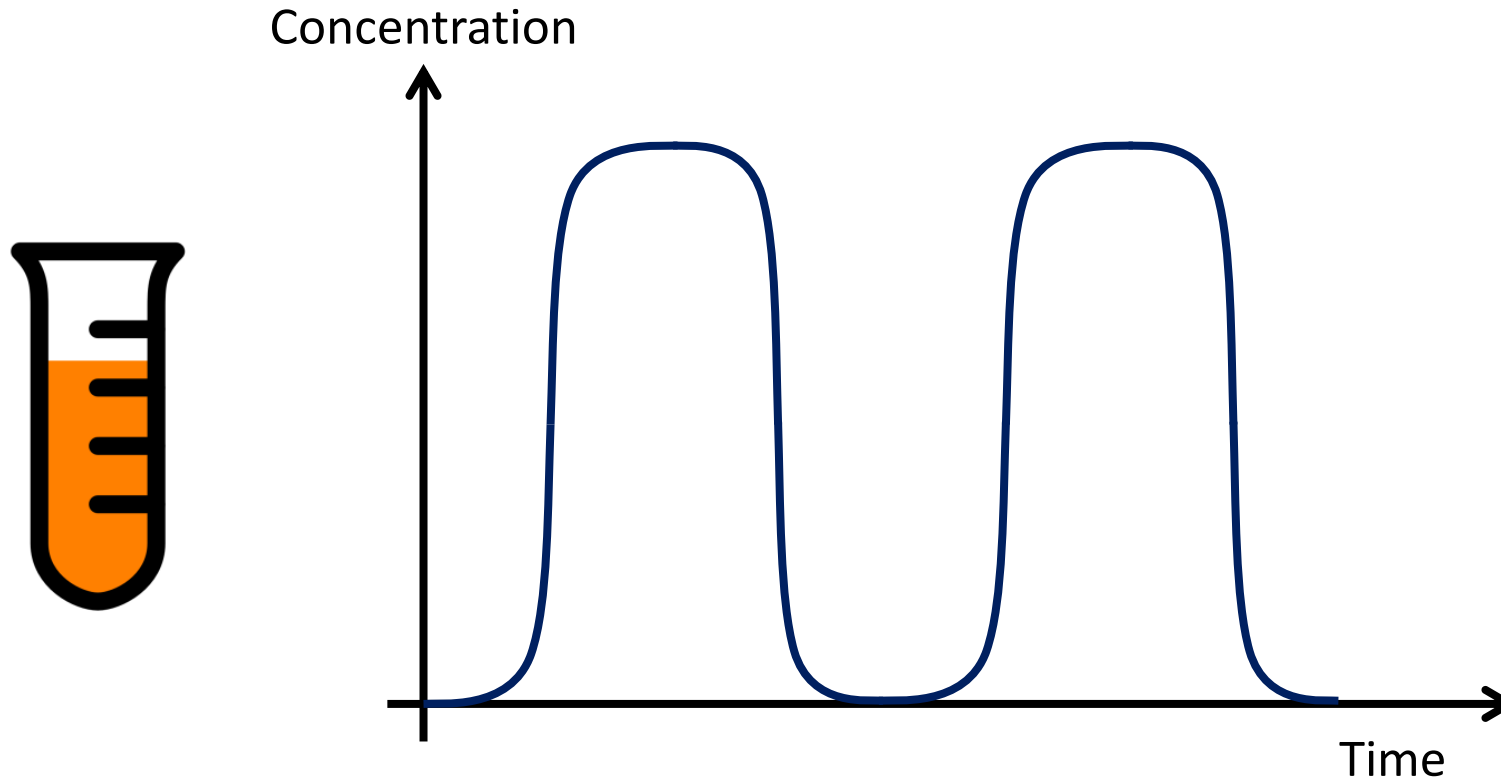
In an electronic circuit,  
**voltage** can represent Boolean input

# Representing Information with Molecules



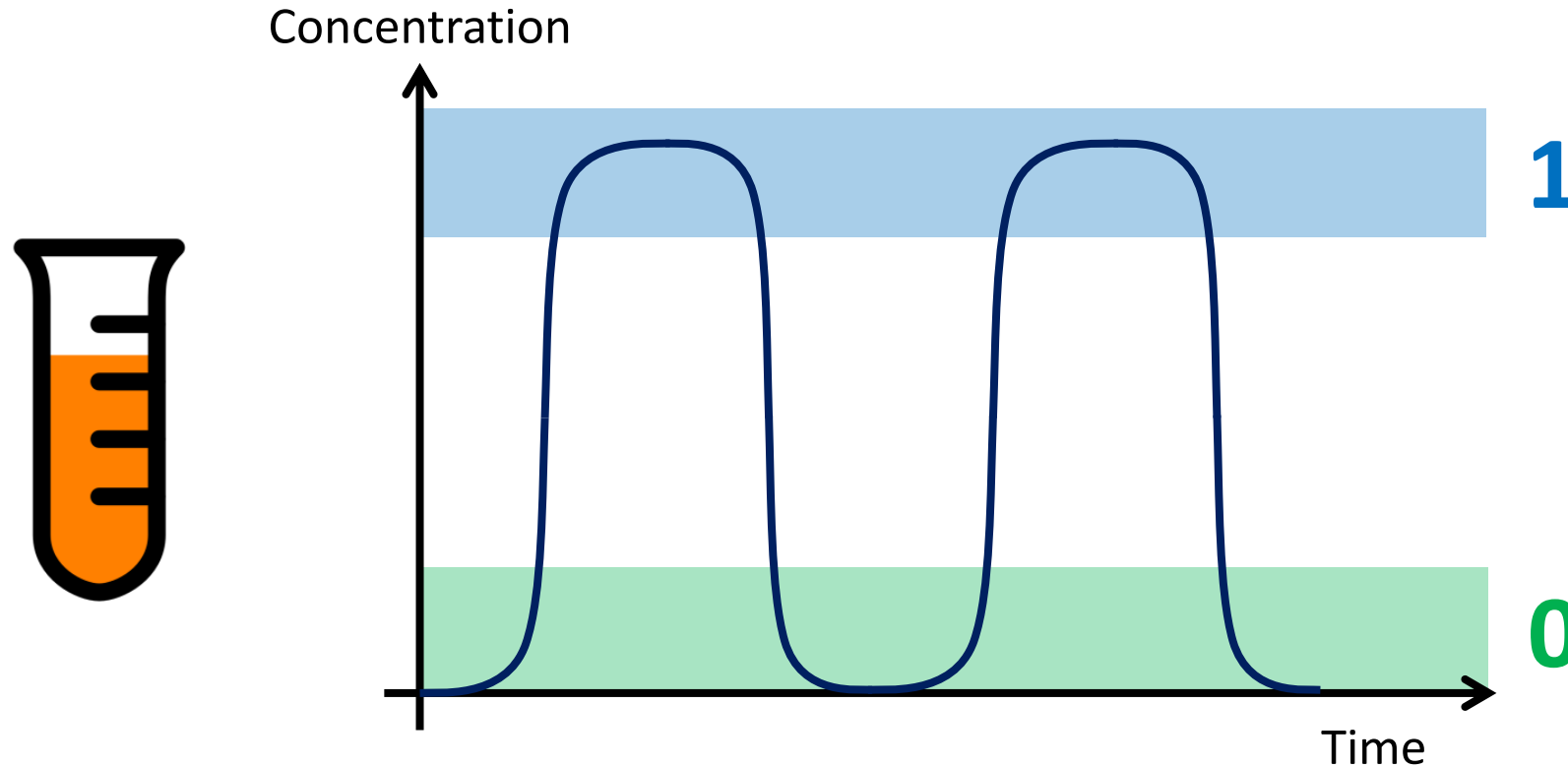
In an electronic circuit,  
**voltage** can represent Boolean input

# Representing Information with Molecules



In a well-mixed solution,  
**concentration** can represent Boolean input

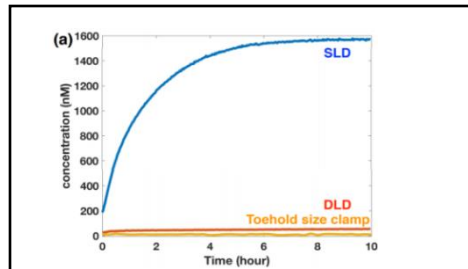
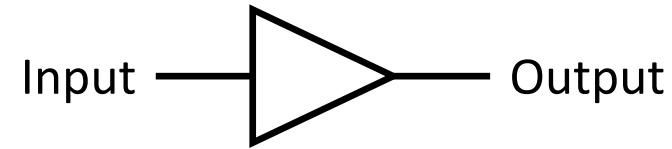
# Representing Information with Molecules



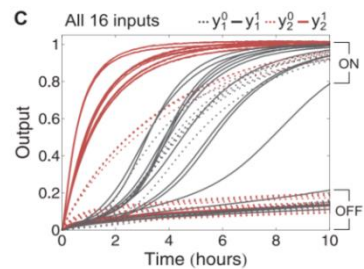
In a well-mixed solution,  
**concentration** can represent Boolean input

# Chemical Identity Gate: Idealized vs. Actual Behavior

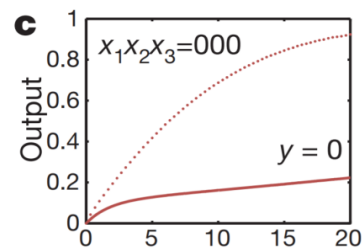
## Experimental Implementation of Chemical Logic



Wang et al. *DNA* 23, 2017



Qian et al. *Science* 332, 2011

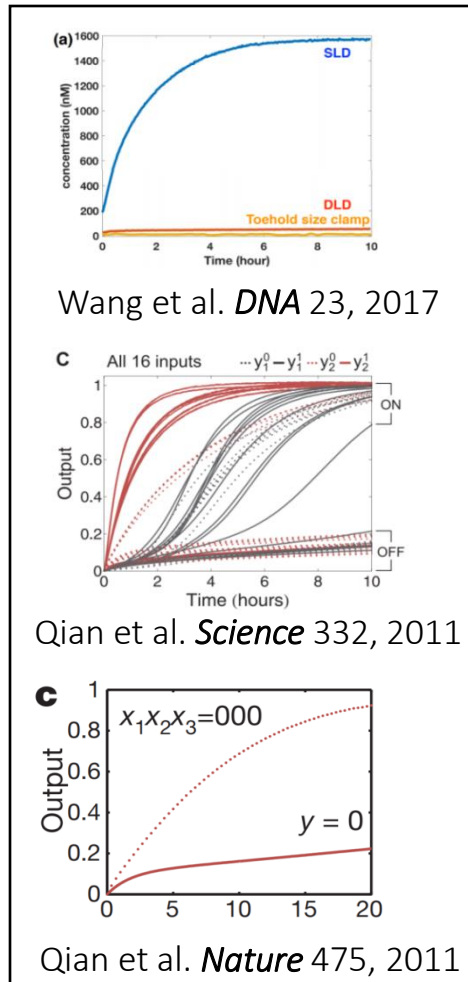


Qian et al. *Nature* 475, 2011

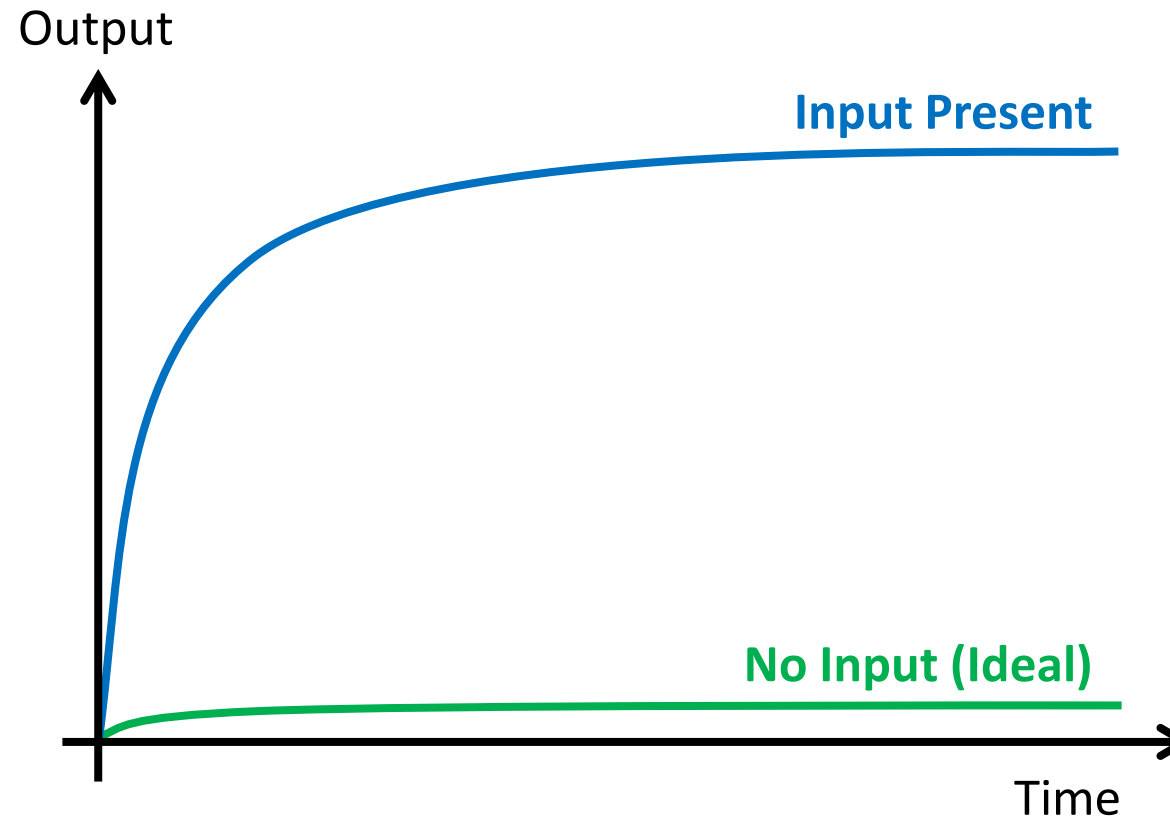
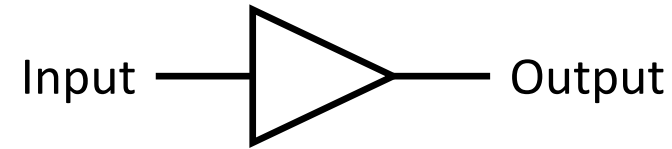
(Don't worry about the details in the pictures above)

# Chemical Identity Gate: Idealized vs. Actual Behavior

## Experimental Implementation of Chemical Logic

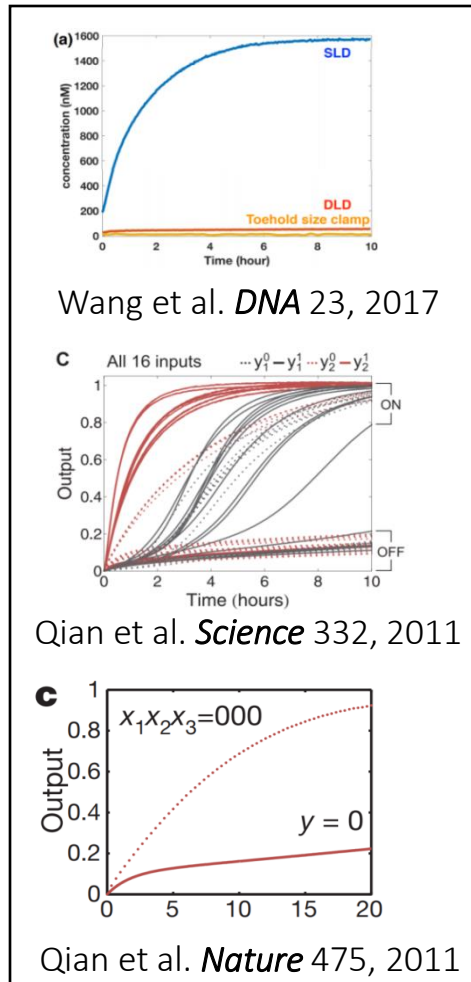


(Don't worry about the details in the pictures above)

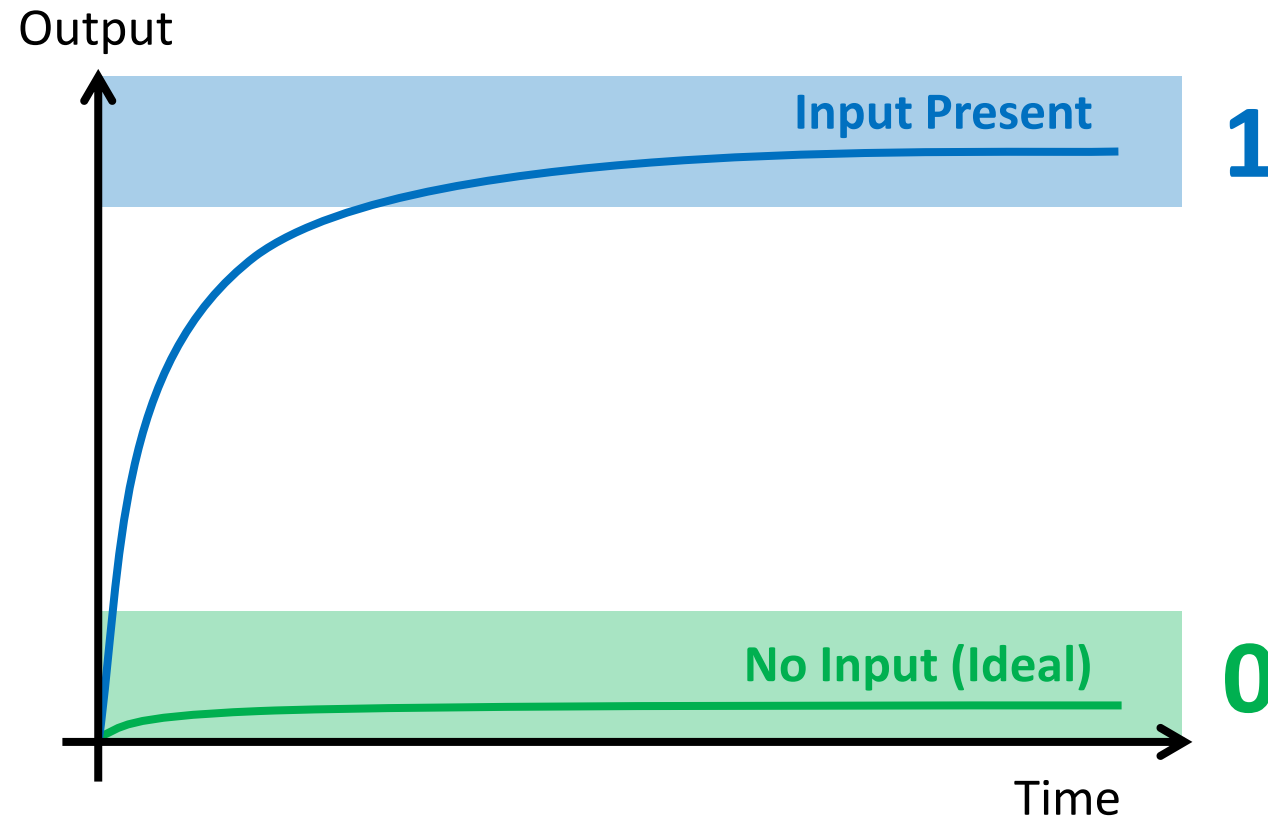
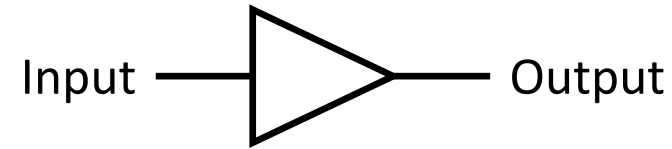


# Chemical Identity Gate: Idealized vs. Actual Behavior

## Experimental Implementation of Chemical Logic



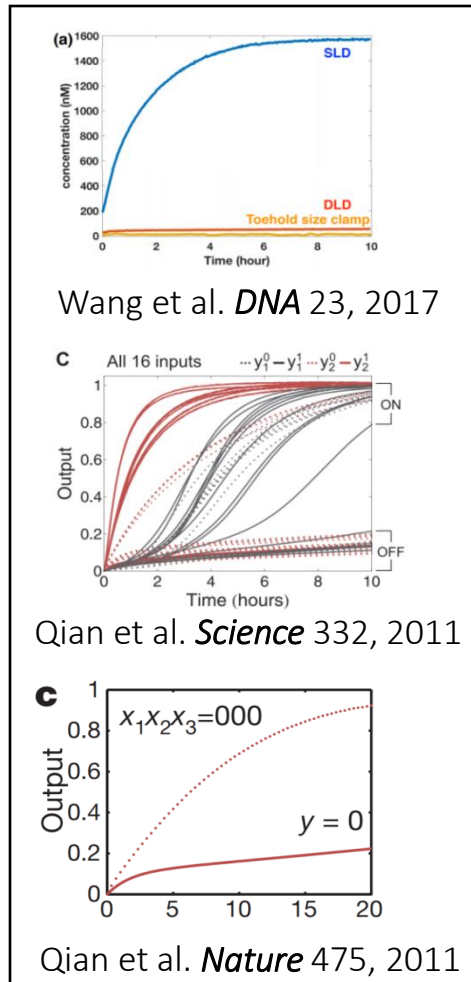
(Don't worry about the details in the pictures above)



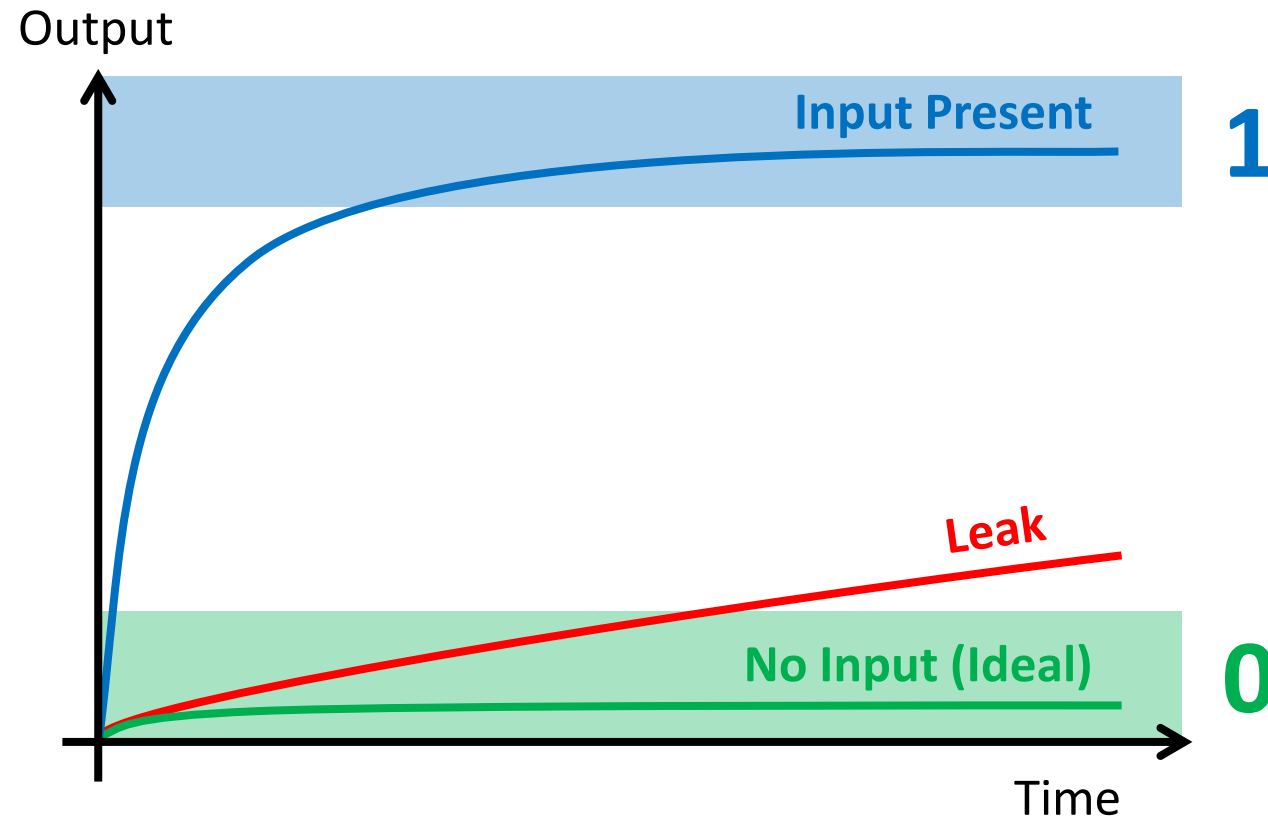
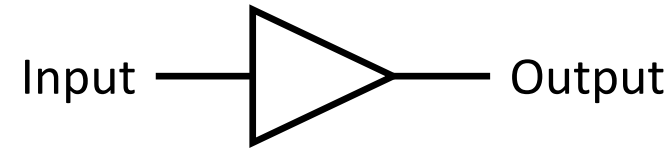


# Chemical Identity Gate: Idealized vs. Actual Behavior

## Experimental Implementation of Chemical Logic



(Don't worry about the details in the pictures above)



# Levels of Abstraction

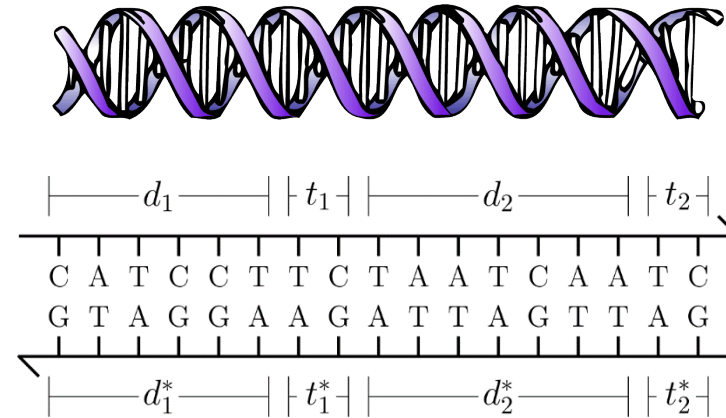
# Levels of Abstraction

DNA

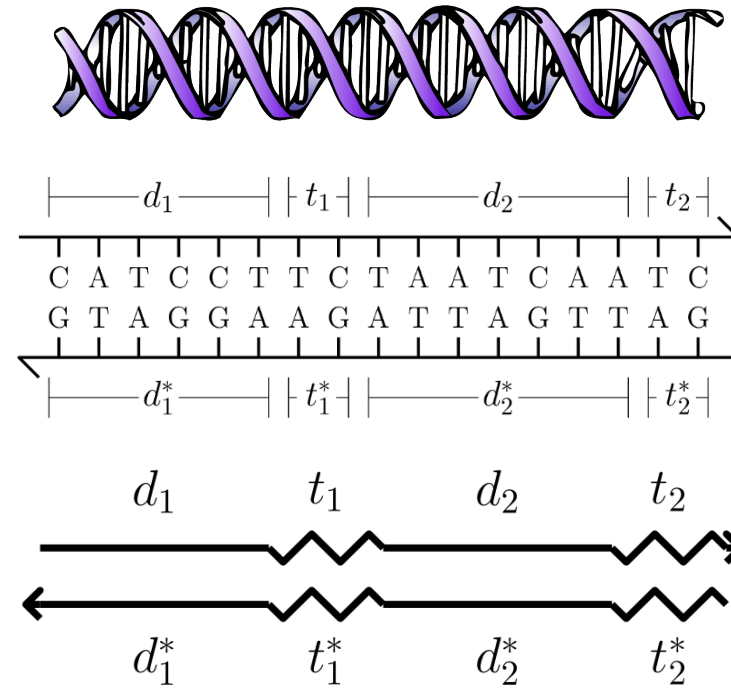
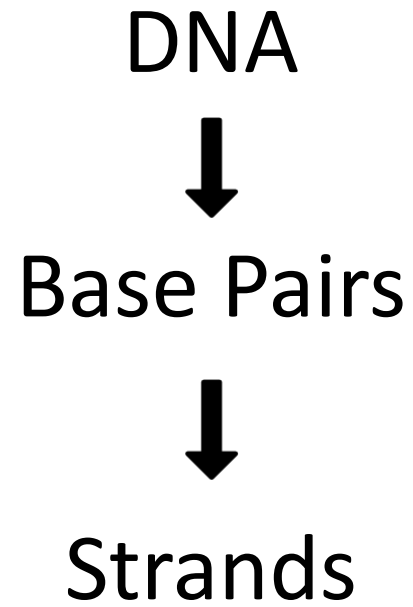


# Levels of Abstraction

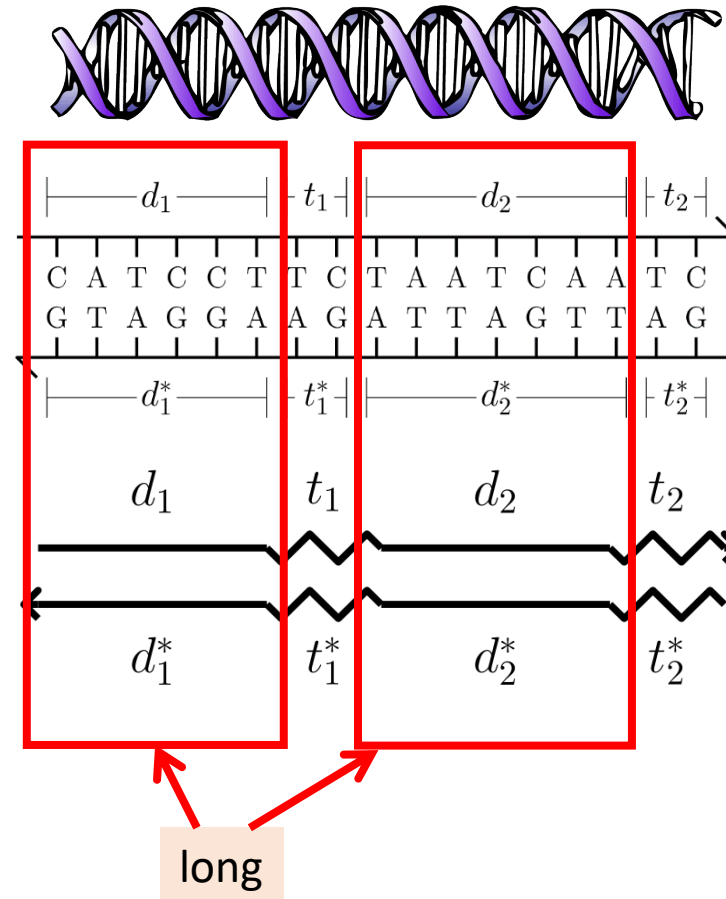
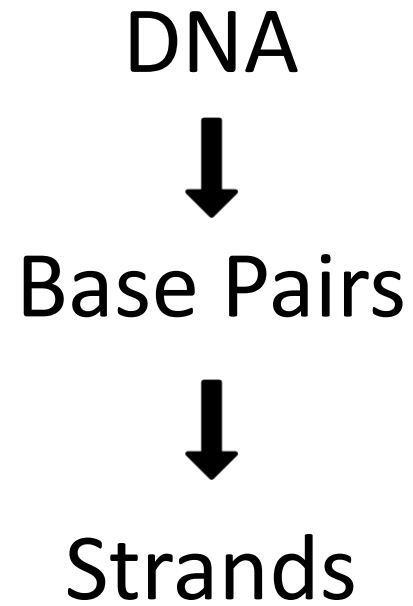
DNA  
↓  
Base Pairs



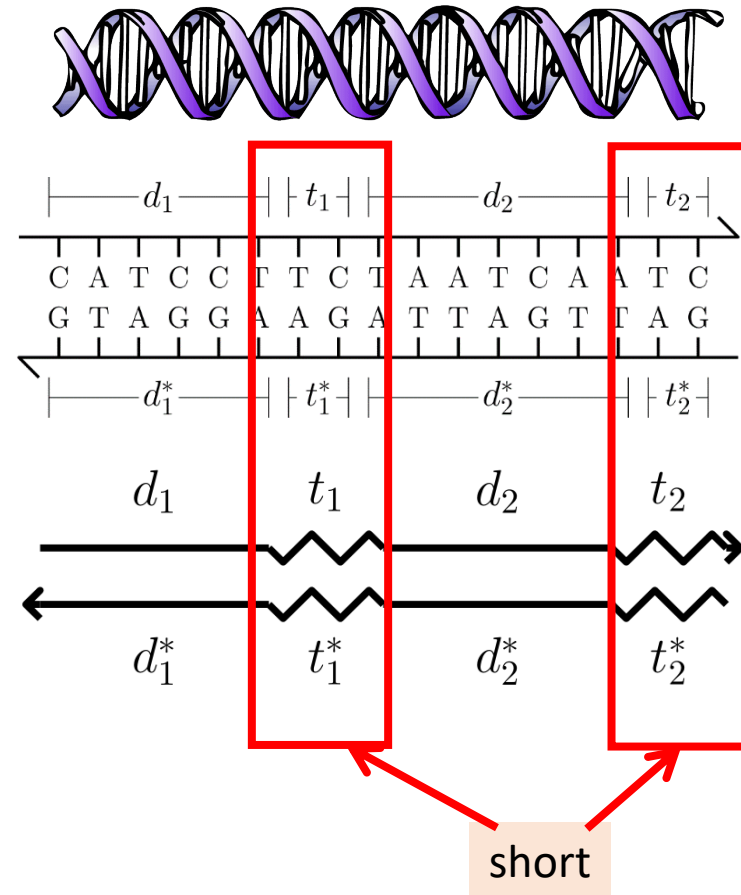
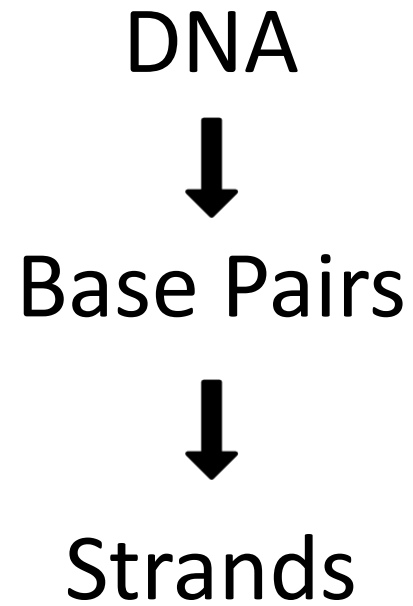
# Levels of Abstraction



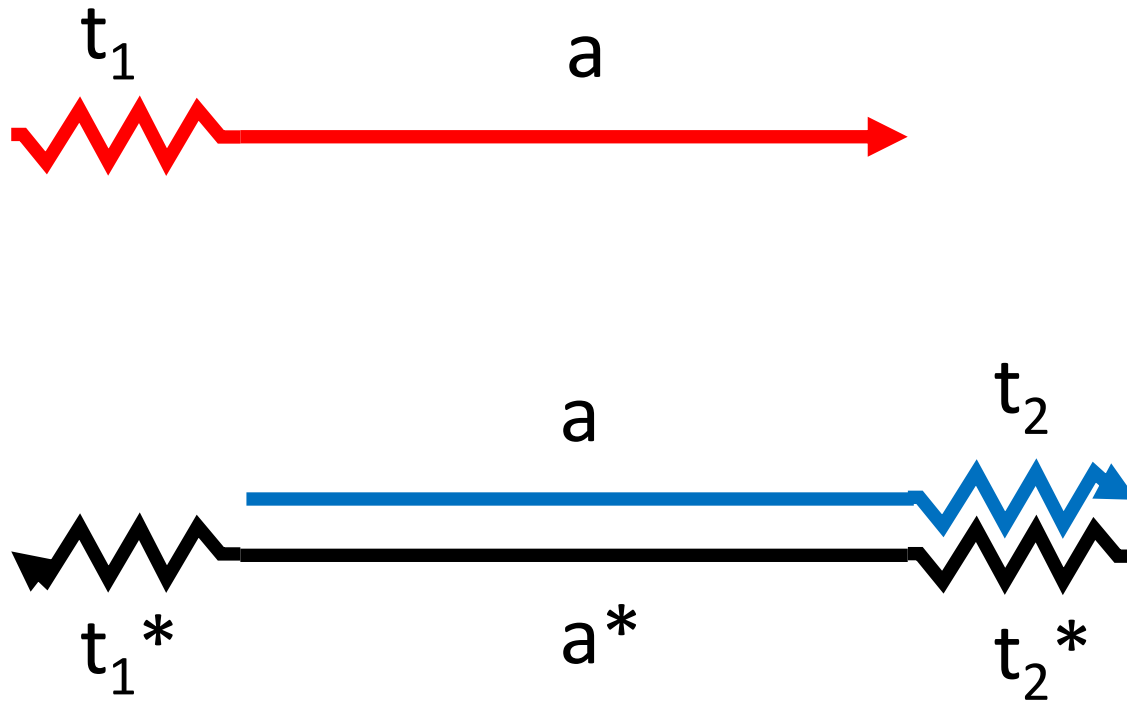
# Levels of Abstraction



# Levels of Abstraction



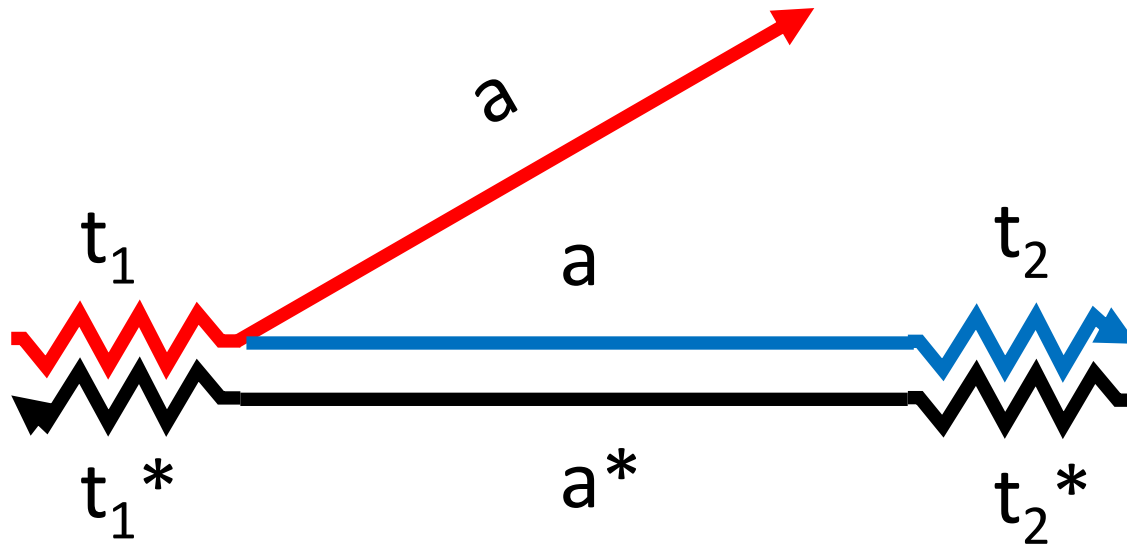
# DNA strand displacement





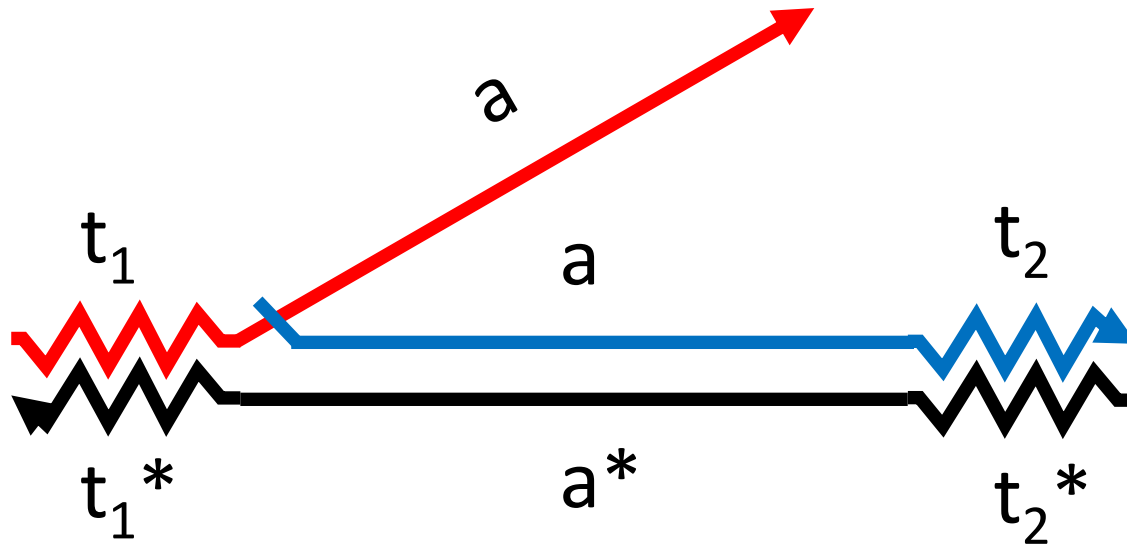
# DNA strand displacement

Bind



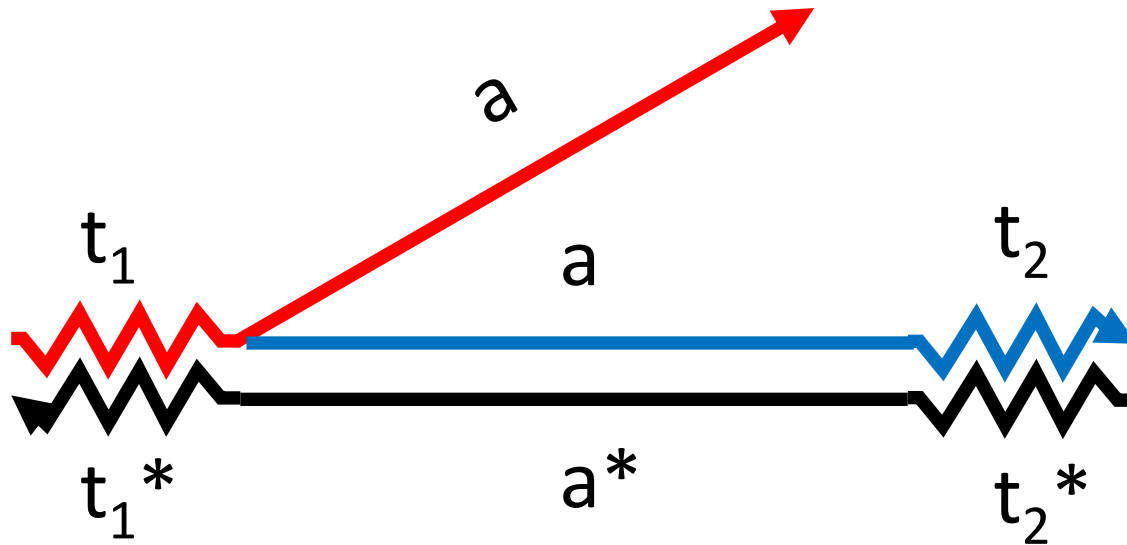
# DNA strand displacement

Bind

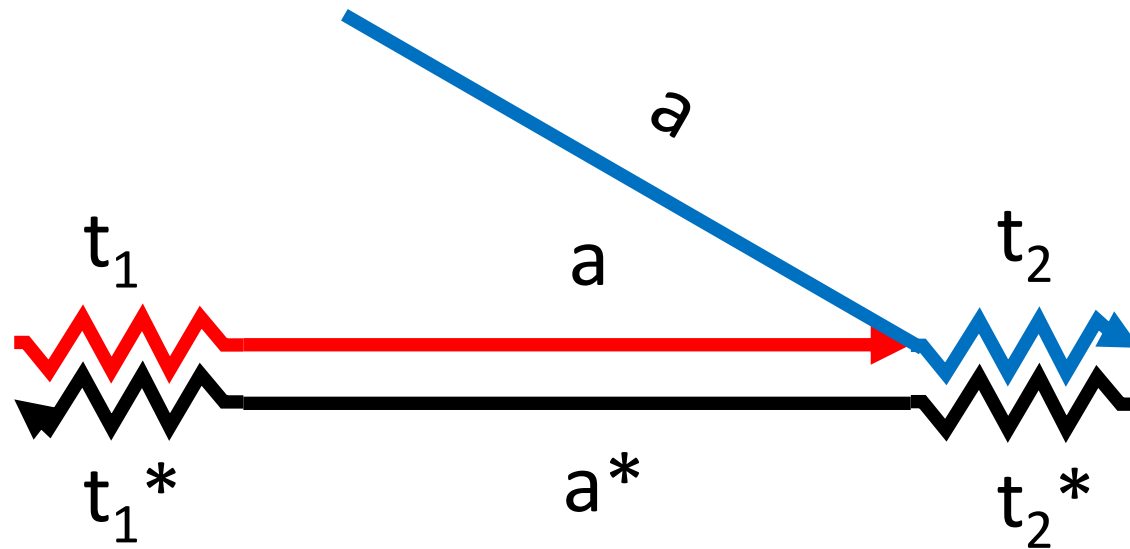


# DNA strand displacement

Bind



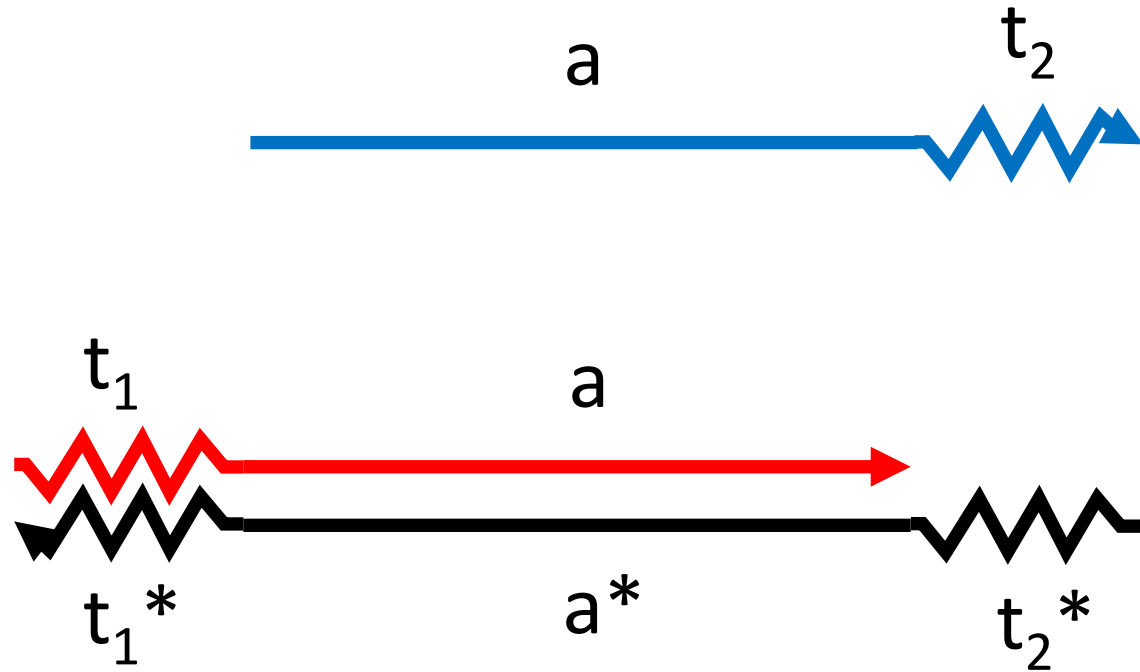
# DNA strand displacement



Bind

Displace

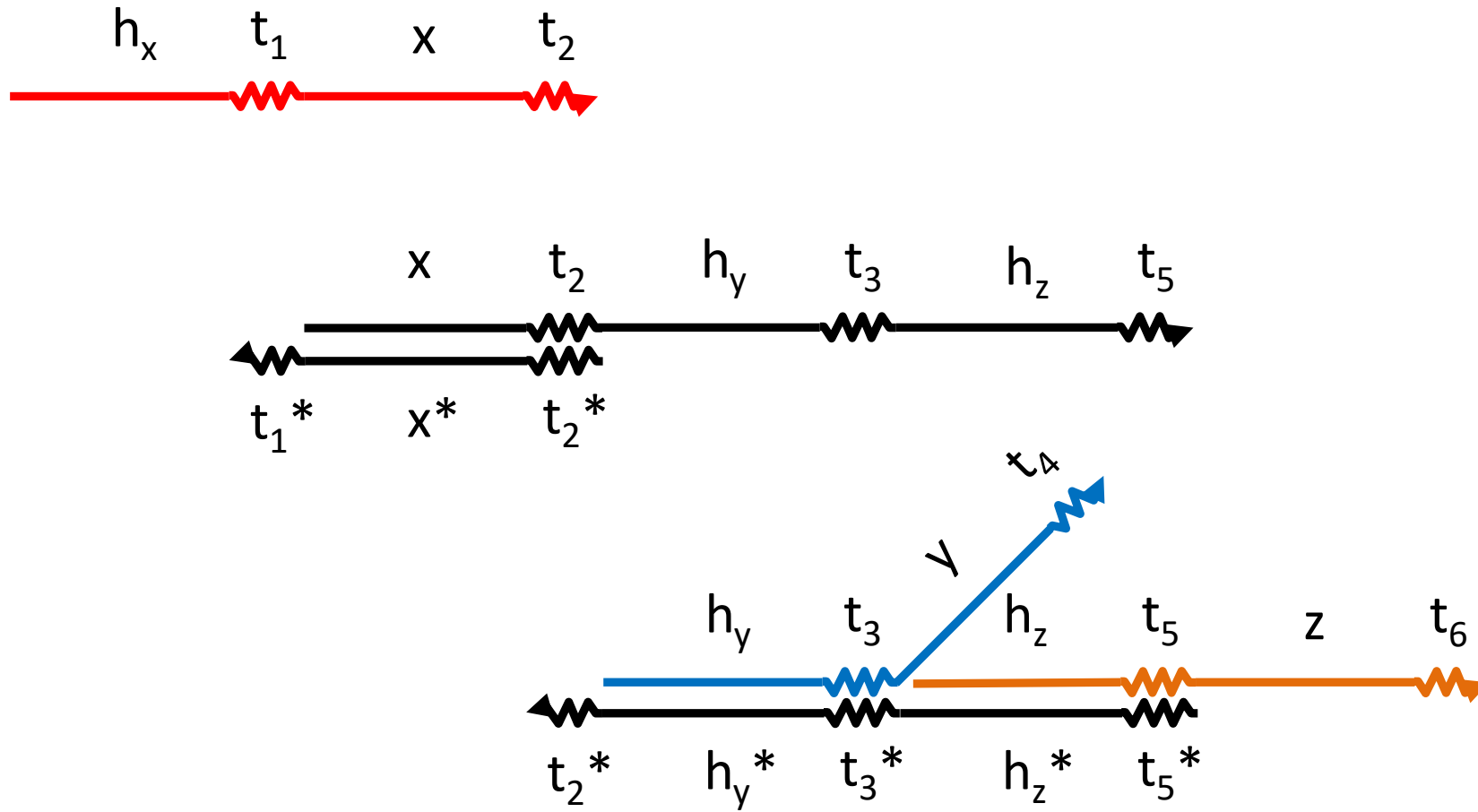
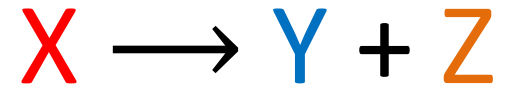
# DNA strand displacement

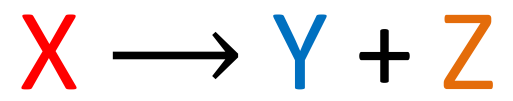


Bind

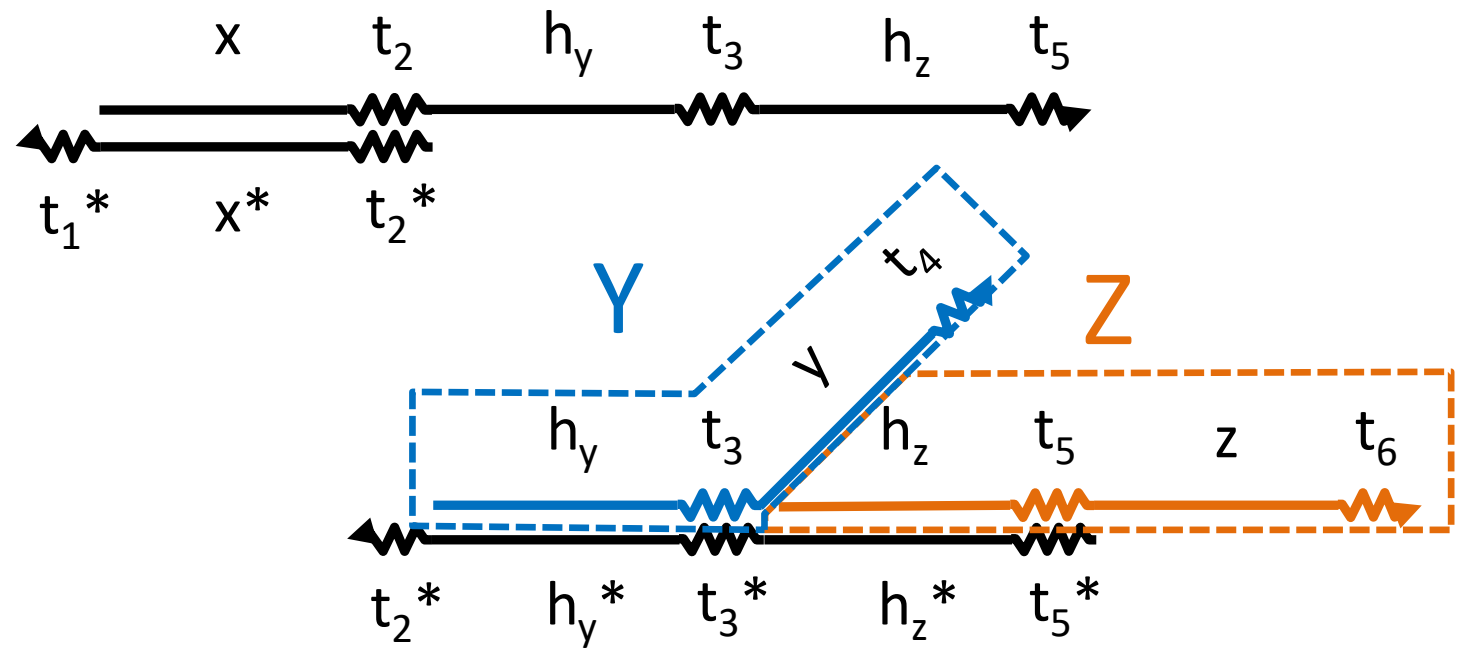
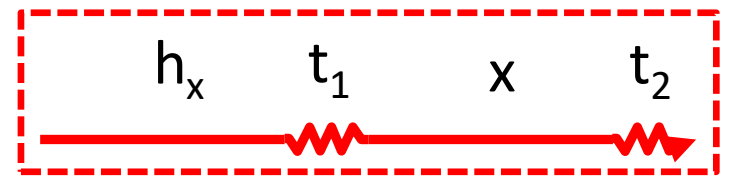
Displace

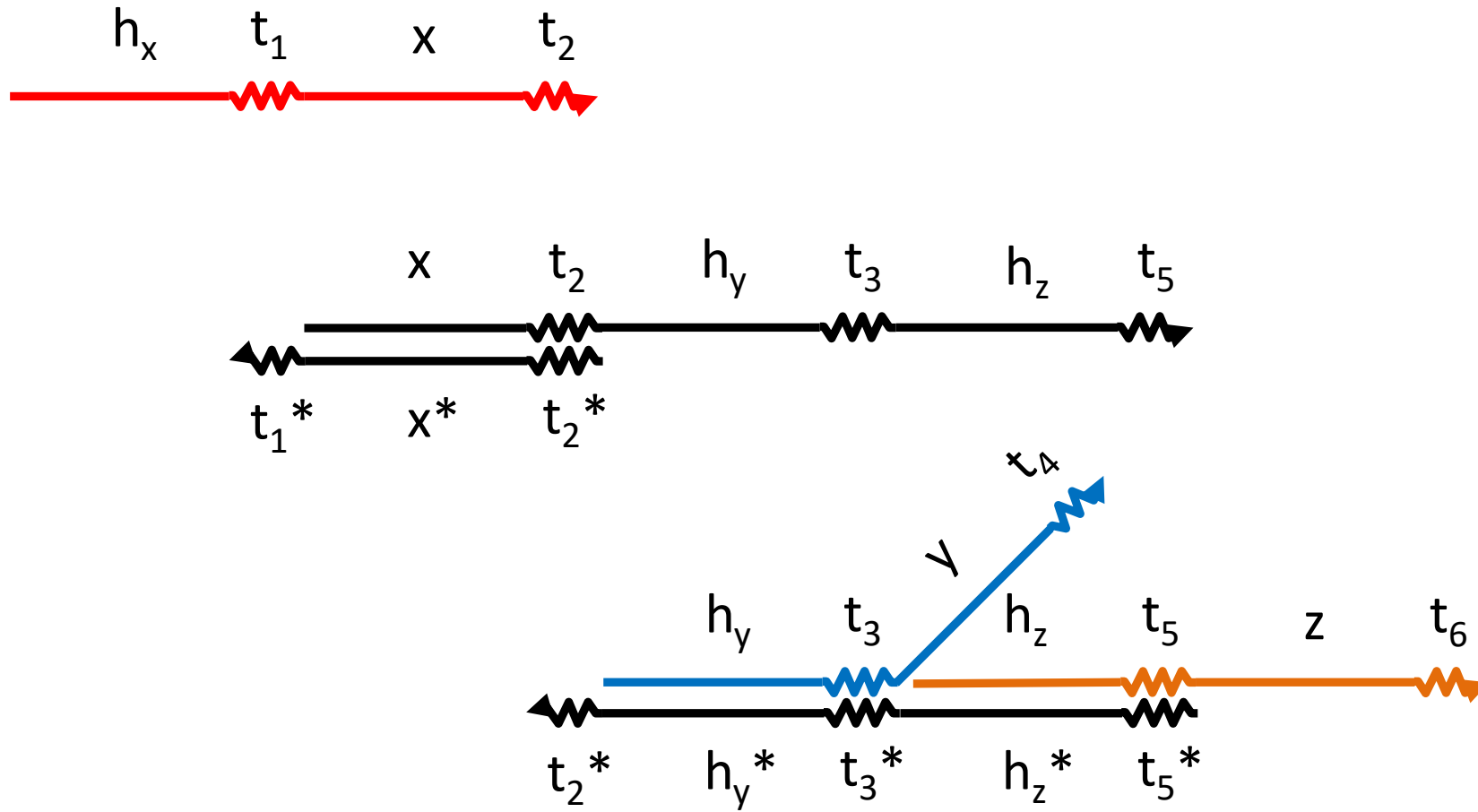
Release



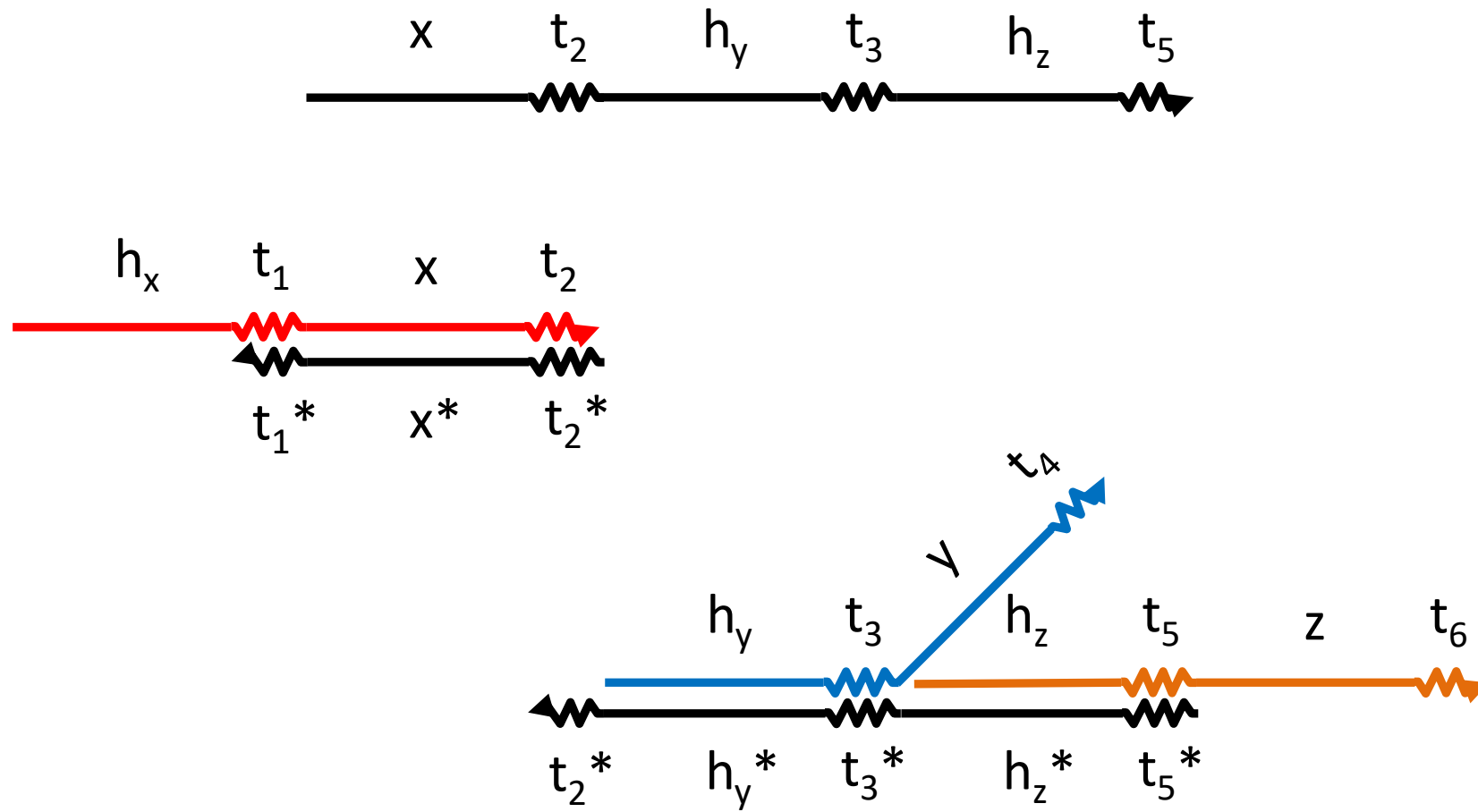
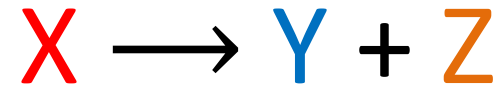


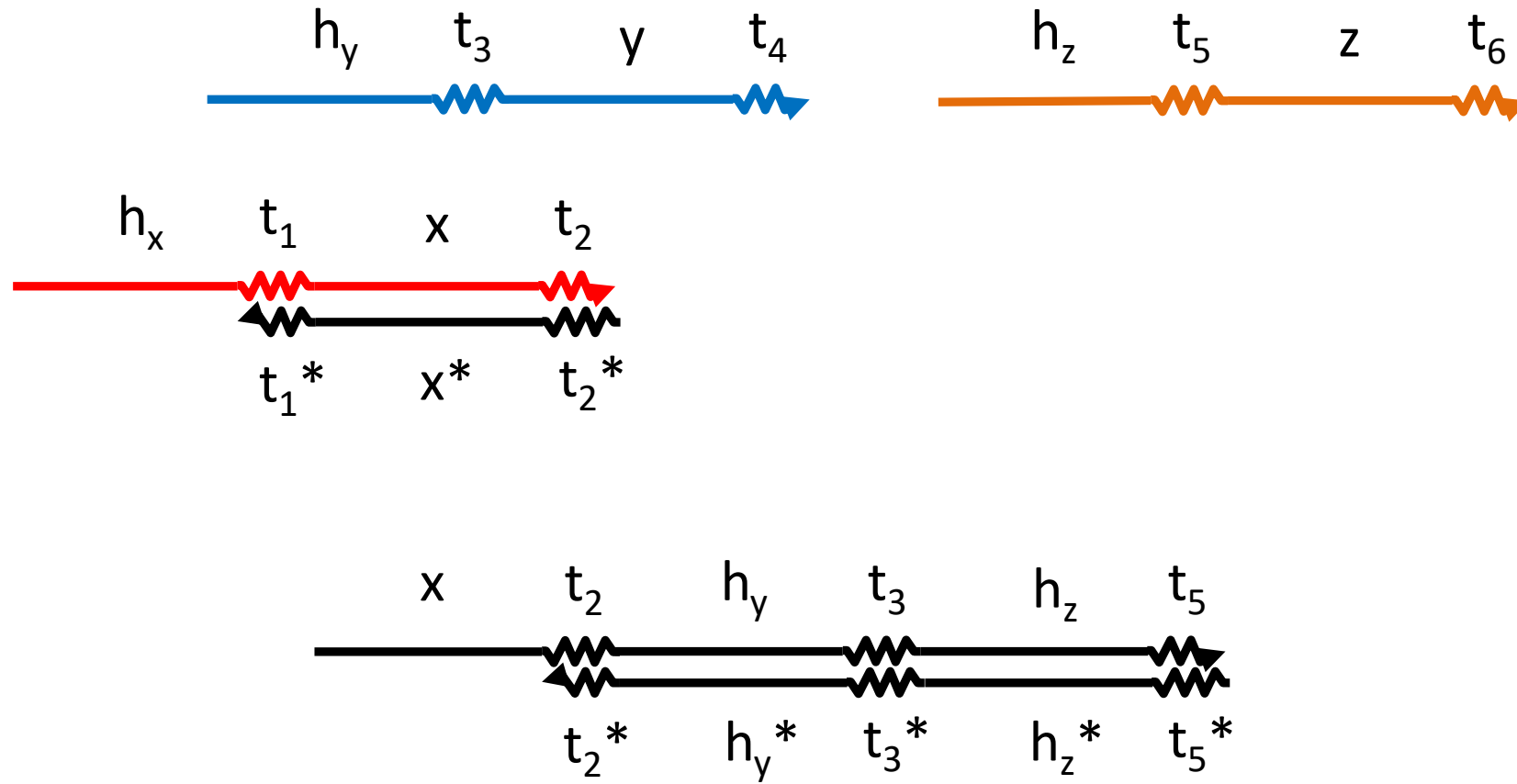
X



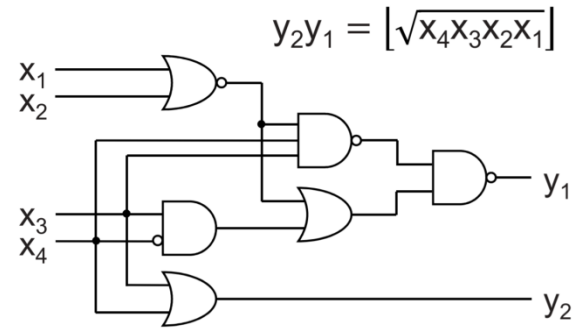






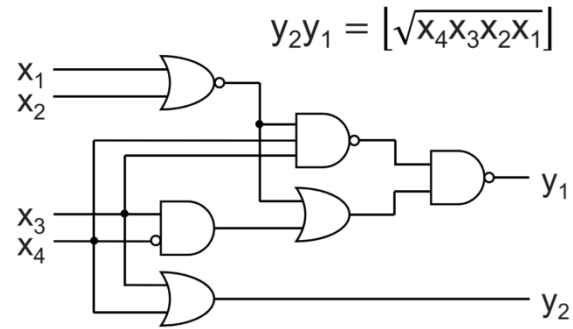


# Leak in strand displacement experiments

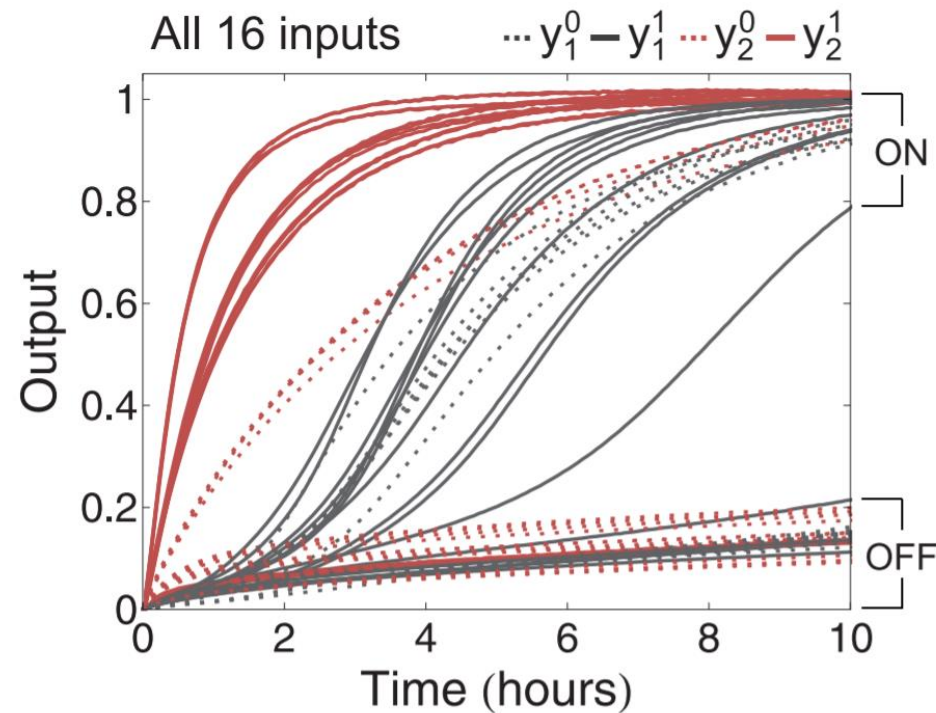


Source:  
Lulu Qian, Erik Winfree.  
Scaling Up Digital Circuit Computation  
*Science* 332, 2011

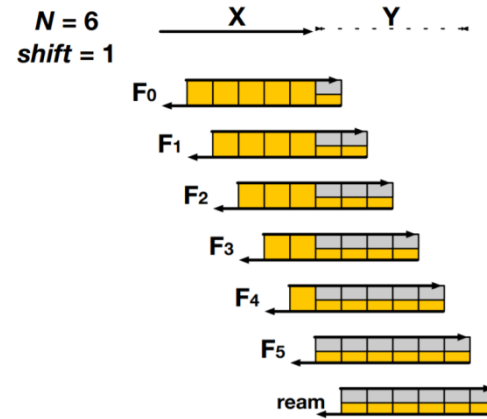
# Leak in strand displacement experiments



Source:  
Lulu Qian, Erik Winfree.  
Scaling Up Digital Circuit Computation  
*Science* 332, 2011



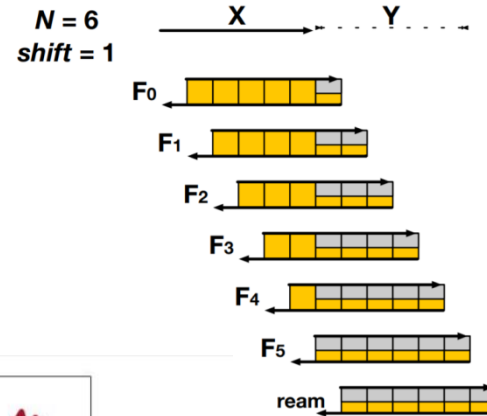
# Reducing Leak



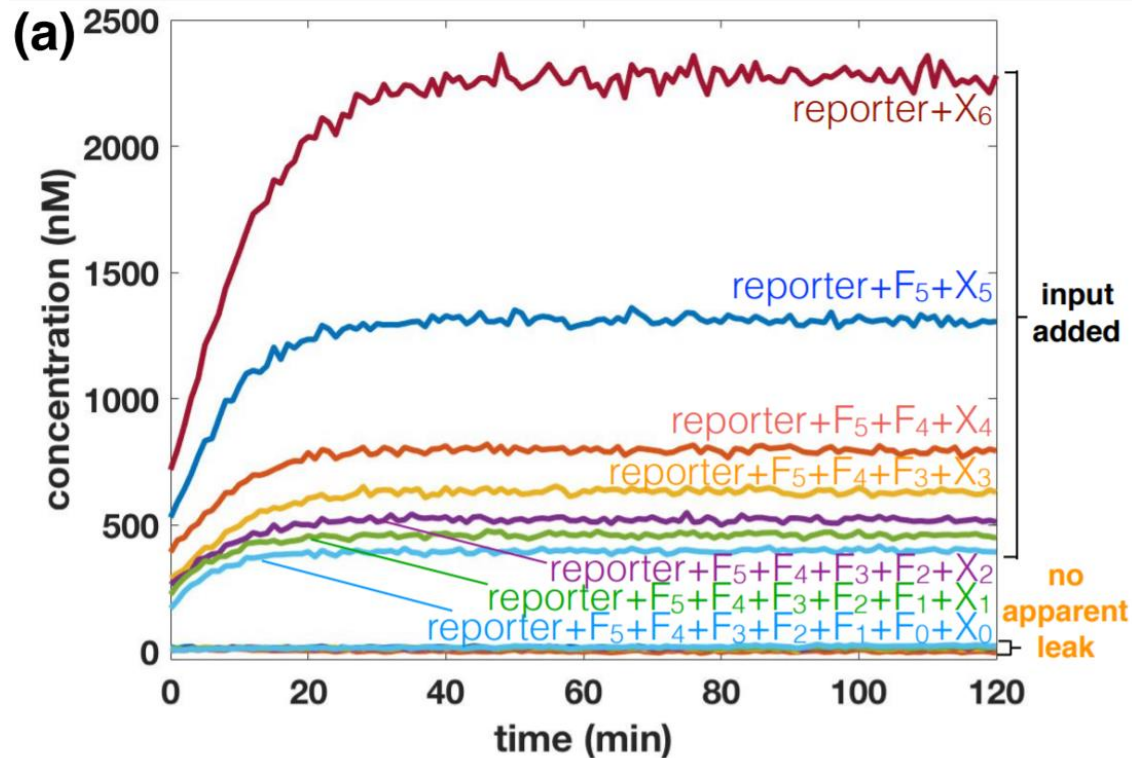
[Boya Wang, Chris Thachuk, Andrew Ellington, David Soloveichik. *The Design Space of Strand Displacement Cascades with Toehold-Size Clamps* DNA Computing Conference, 2017]

# Reducing Leak

Intended:

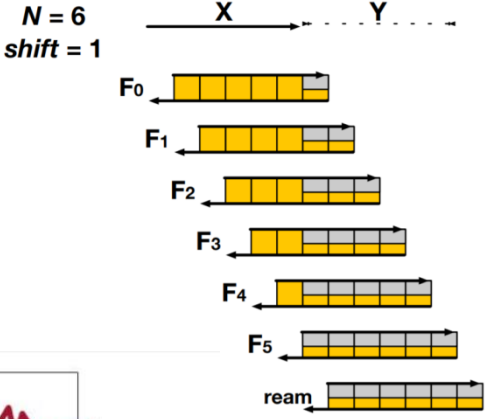


[Boya Wang, Chris Thachuk, Andrew Ellington, David Soloveichik. *The Design Space of Strand Displacement Cascades with Toehold-Size Clamps* DNA Computing Conference, 2017]

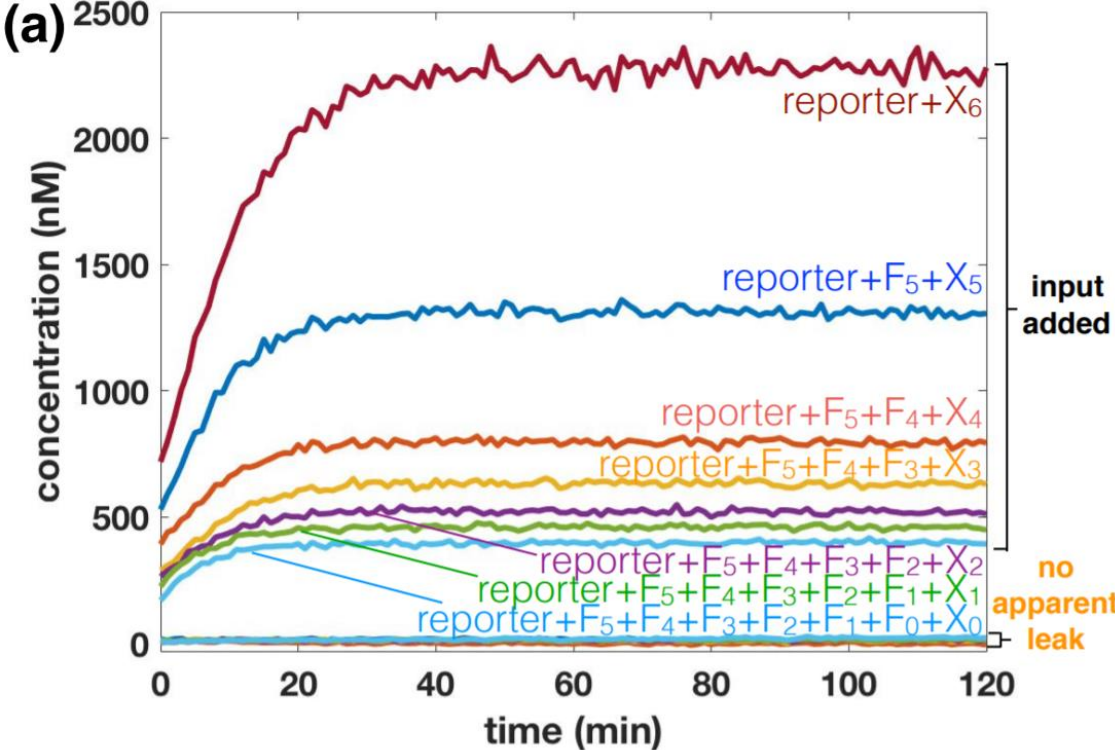


# Reducing Leak

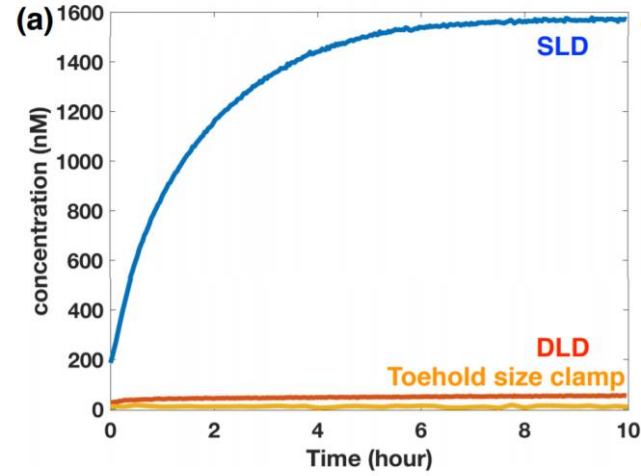
Intended:

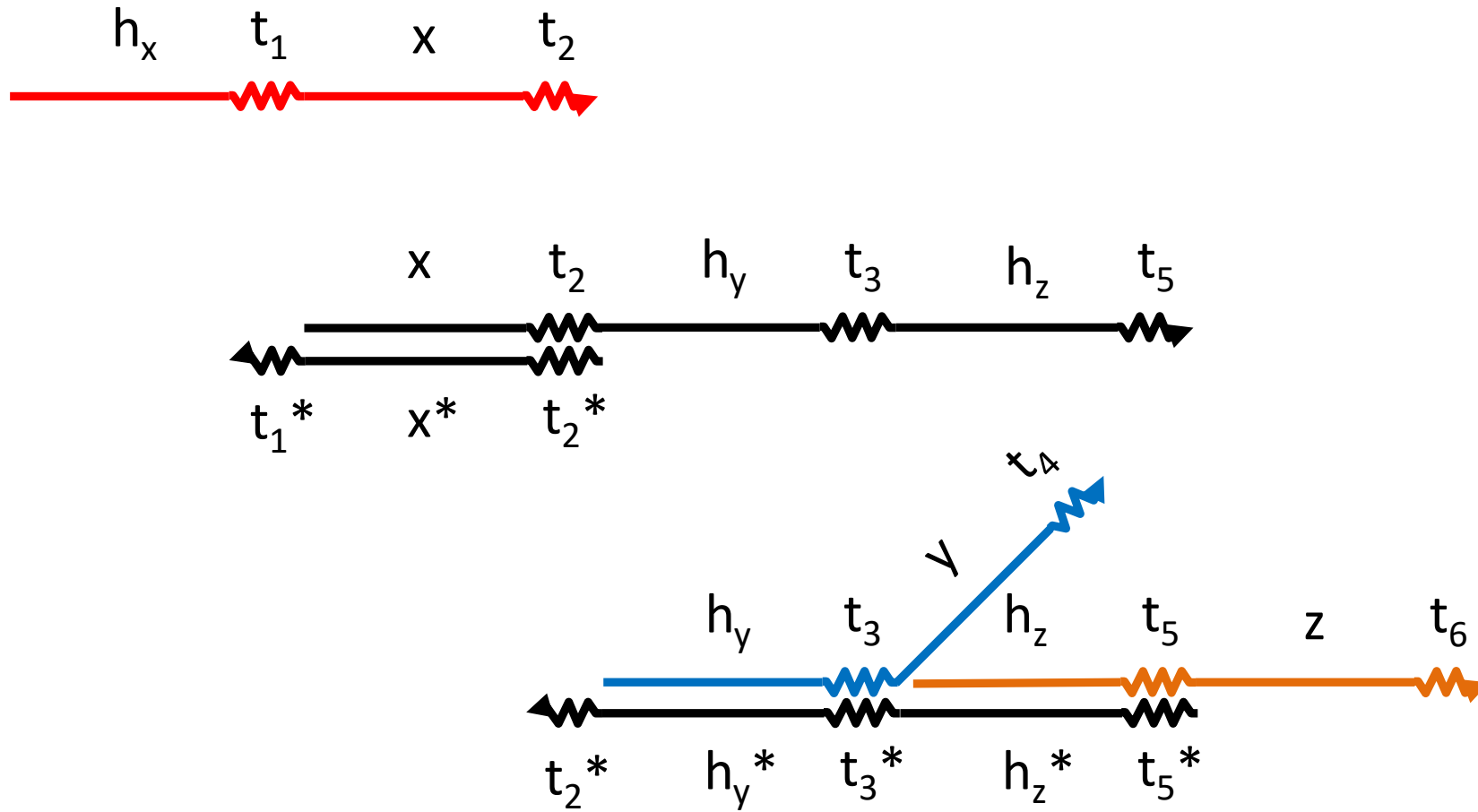
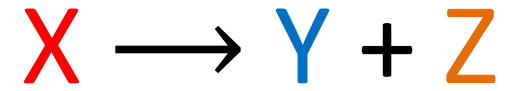


[Boya Wang, Chris Thachuk, Andrew Ellington, David Soloveichik. *The Design Space of Strand Displacement Cascades with Toehold-Size Clamps* DNA Computing Conference, 2017]



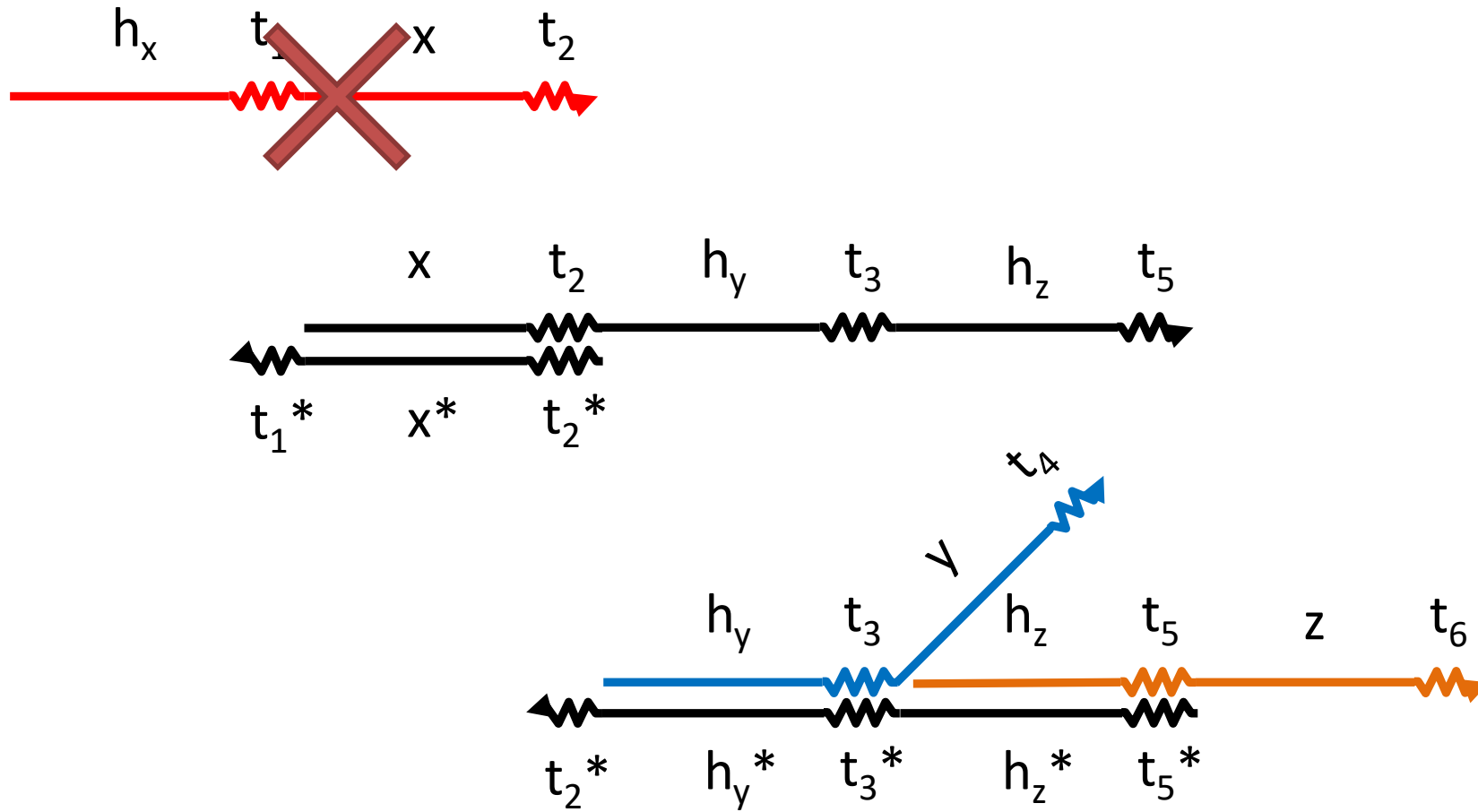
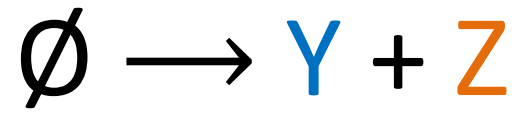
Leak:



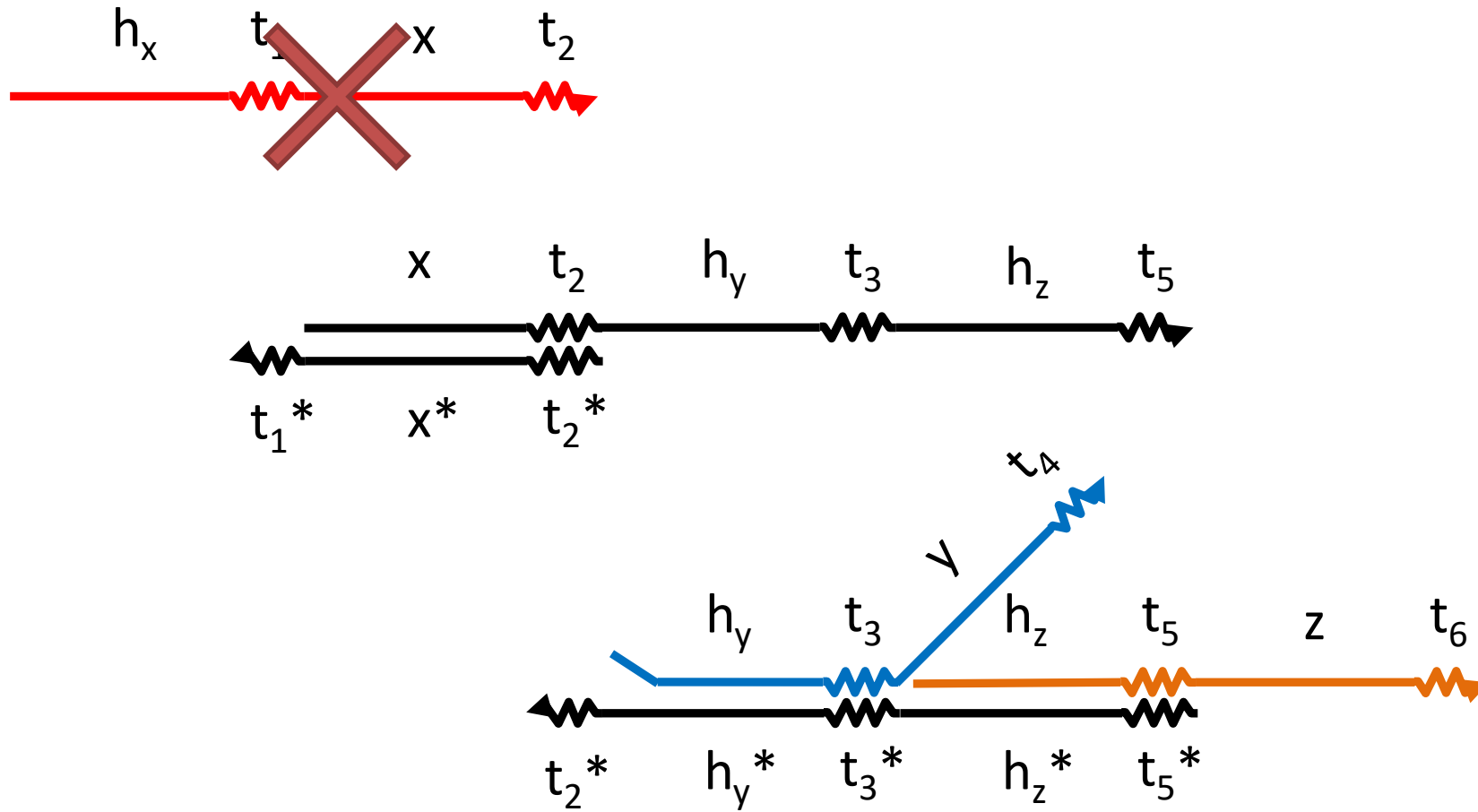
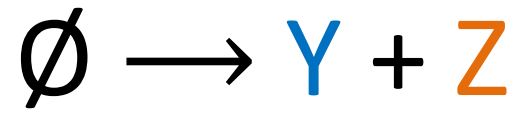




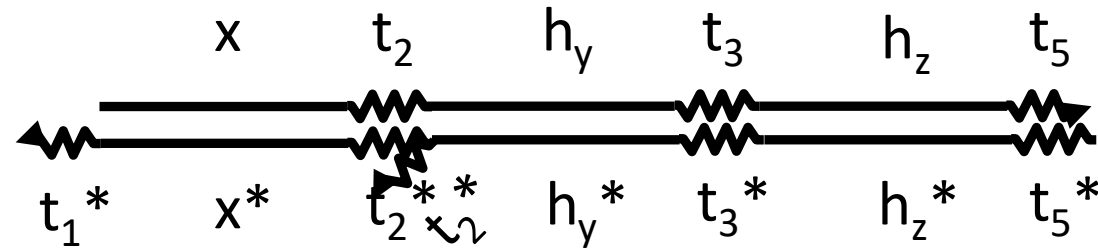
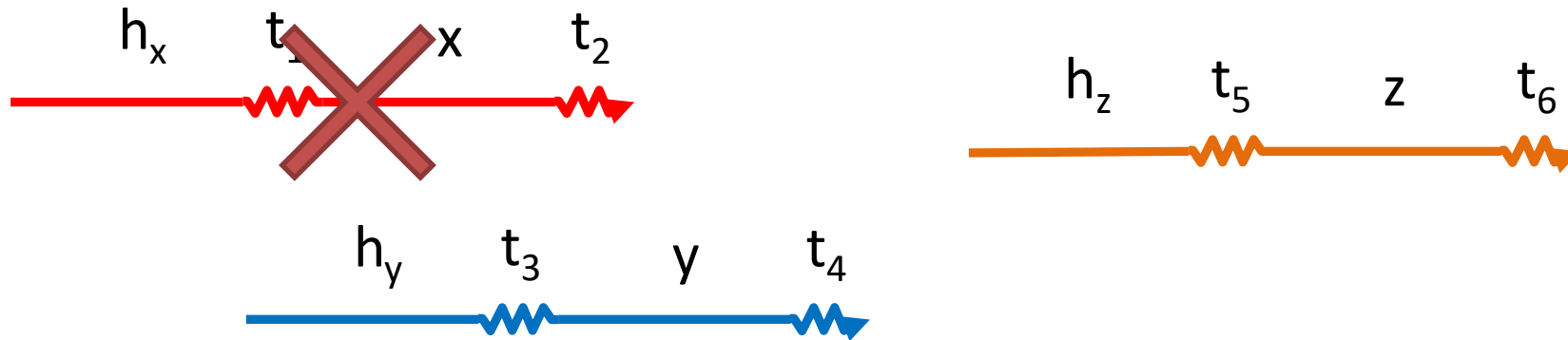
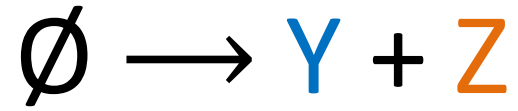
What causes leak  
“kinetically”?



What causes leak  
“kinetically”?

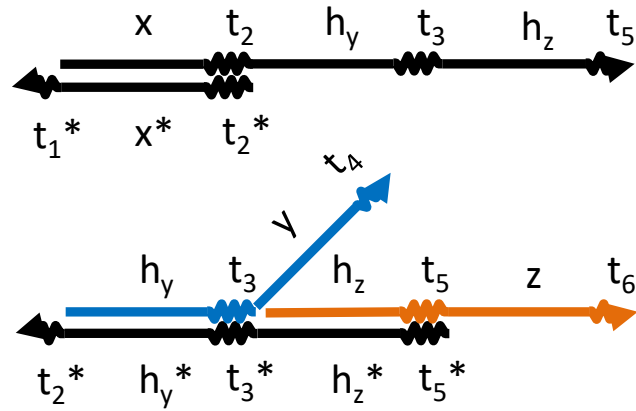


What causes leak  
“kinetically”?

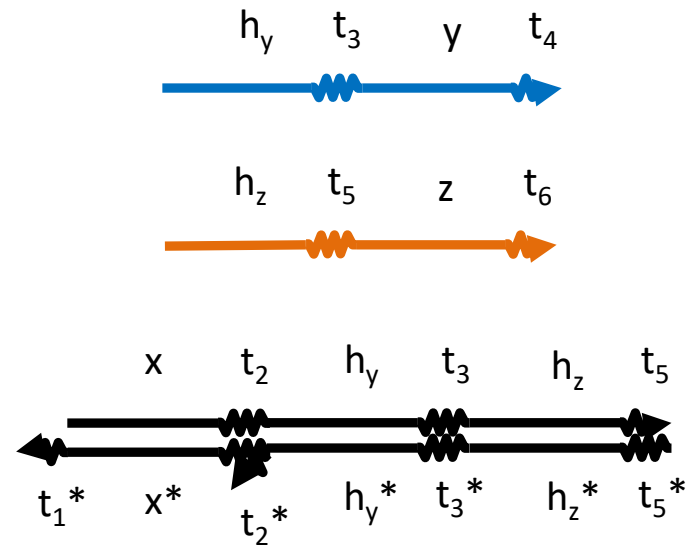


# What causes leak “thermodynamically”?

Before:

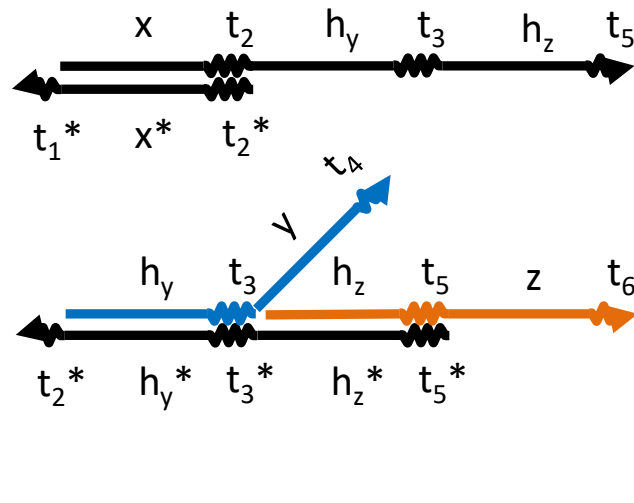


After:



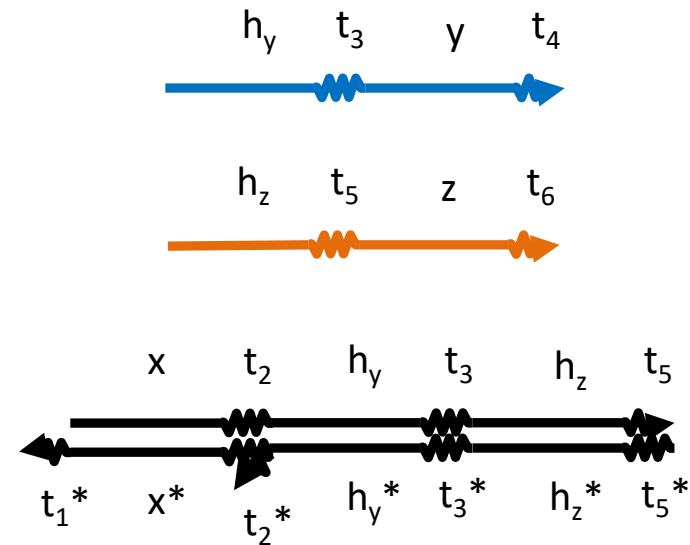
# What causes leak “thermodynamically”?

Before:



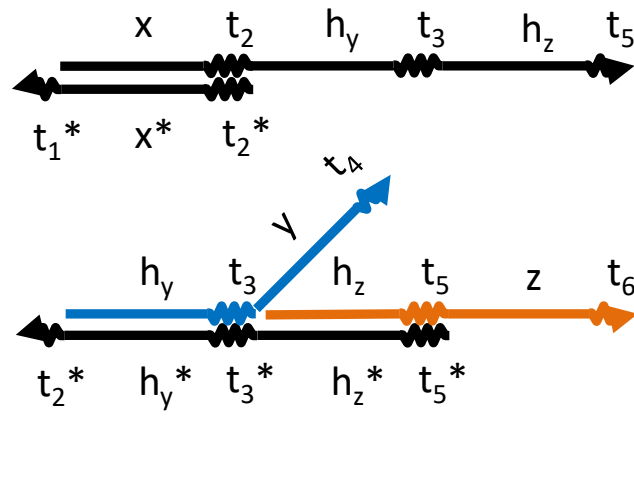
slow

After:



# What causes leak “thermodynamically”?

Before:



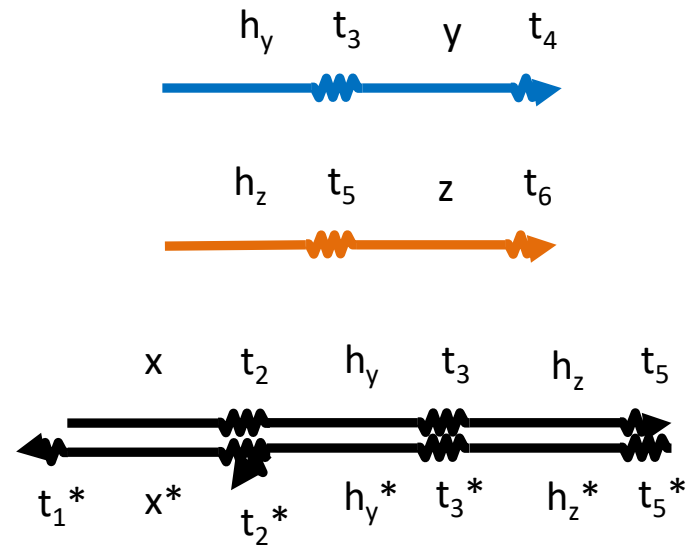
slow



very slow

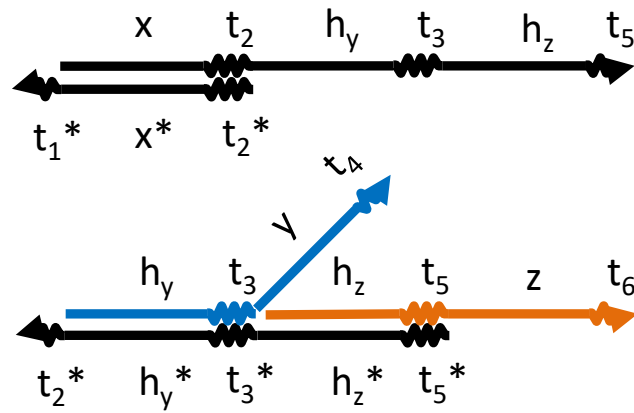


After:



# What causes leak “thermodynamically”?

Before:



less favorable

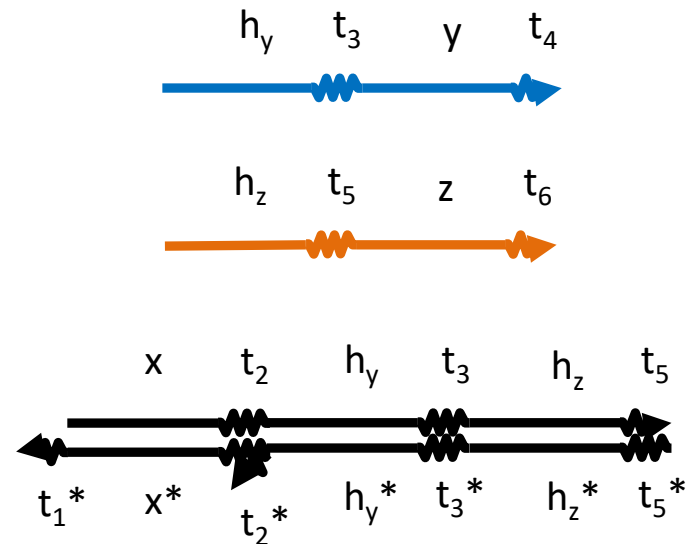
slow



very slow



After:



more favorable

Need a *kinetic* binding network model



# Need a *kinetic* binding network model

- Can we design pathways that maintain local stability?

# Need a *kinetic* binding network model

- Can we design pathways that maintain local stability?



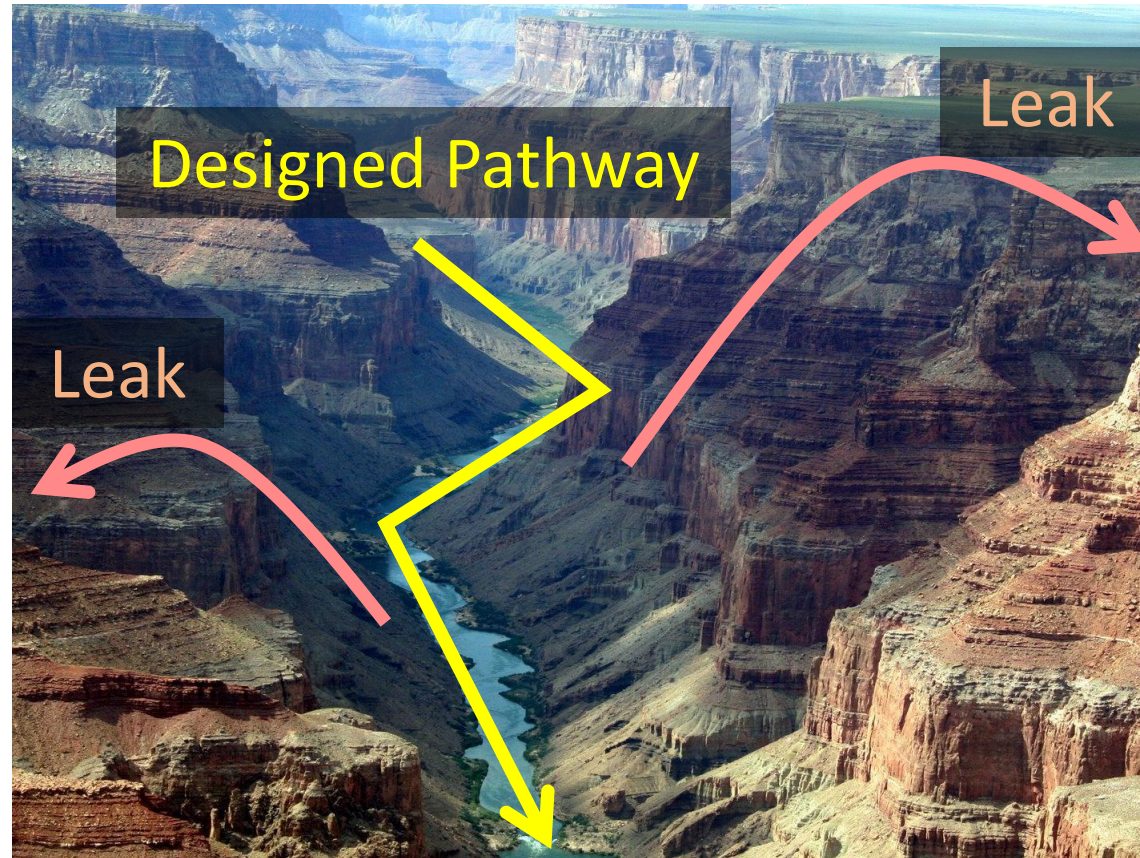
# Need a *kinetic* binding network model

- Can we design pathways that maintain local stability?

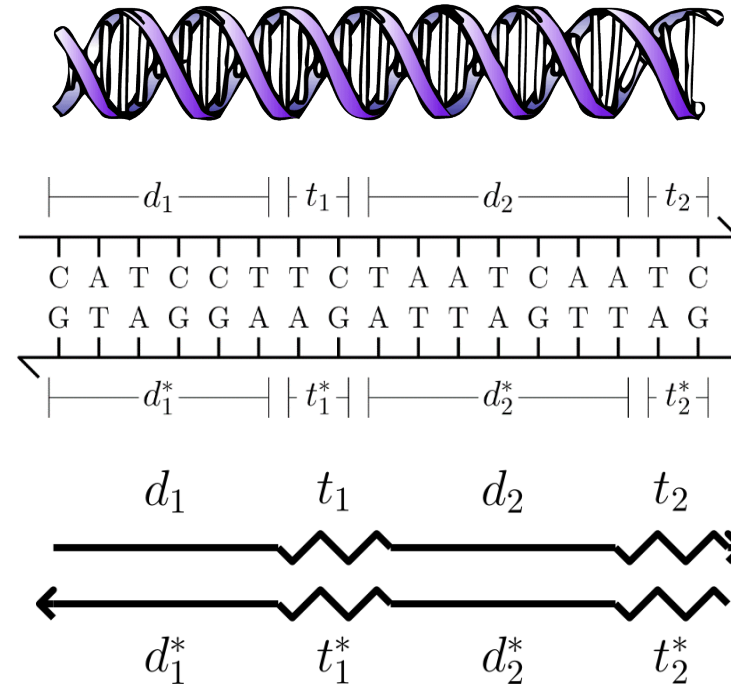
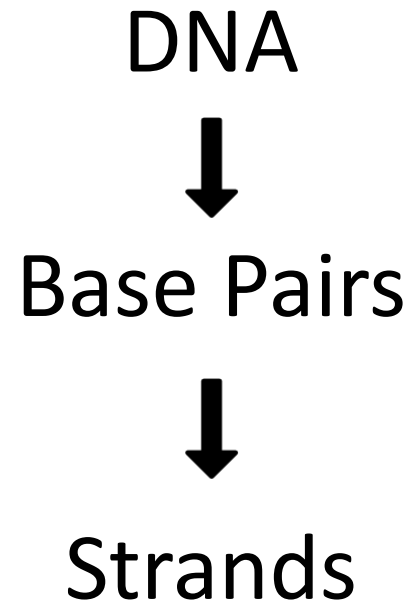


# Need a *kinetic* binding network model

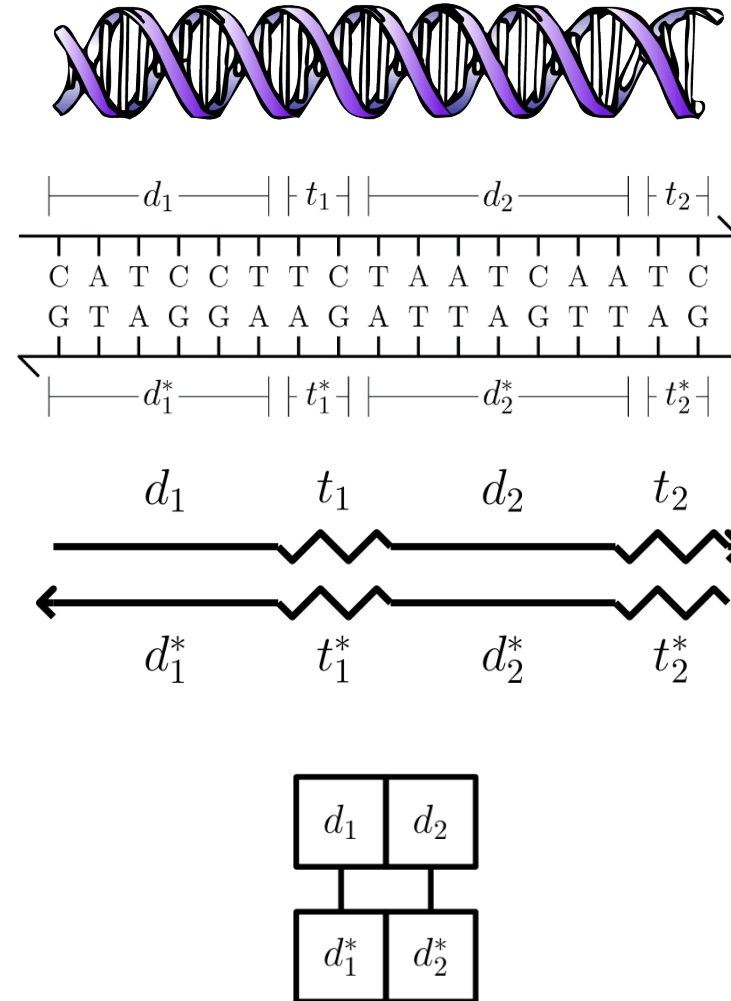
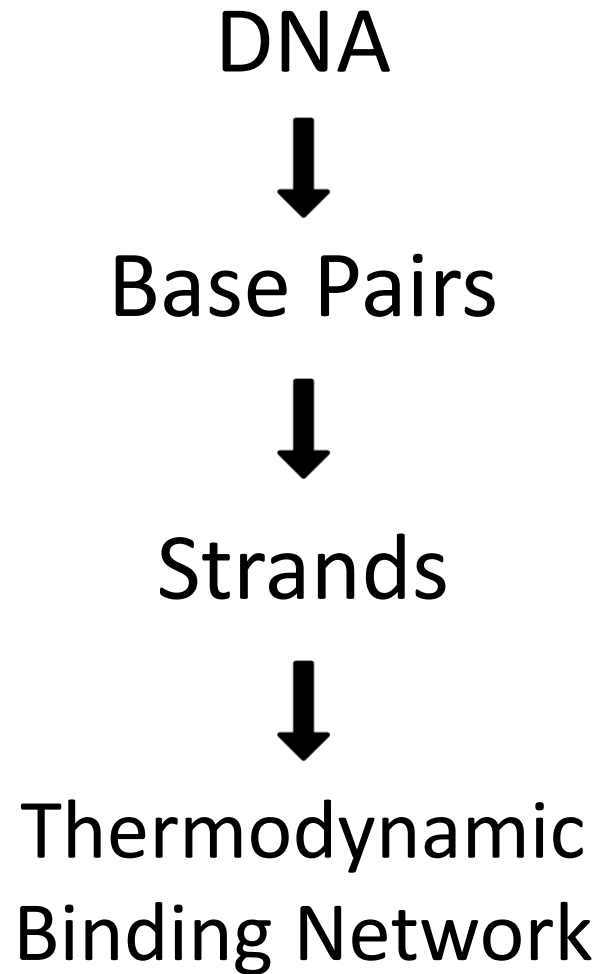
- Can we design pathways that maintain local stability?



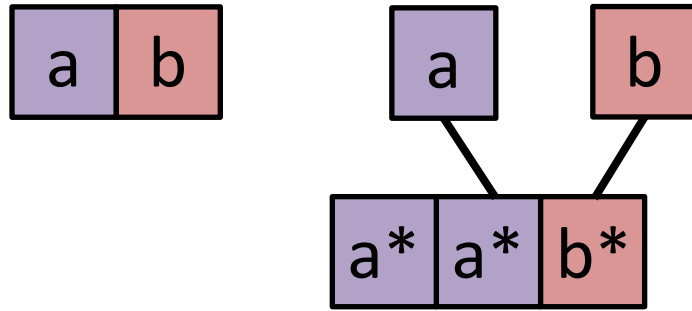
# Levels of Abstraction



# Levels of Abstraction



# Thermodynamic Binding Networks



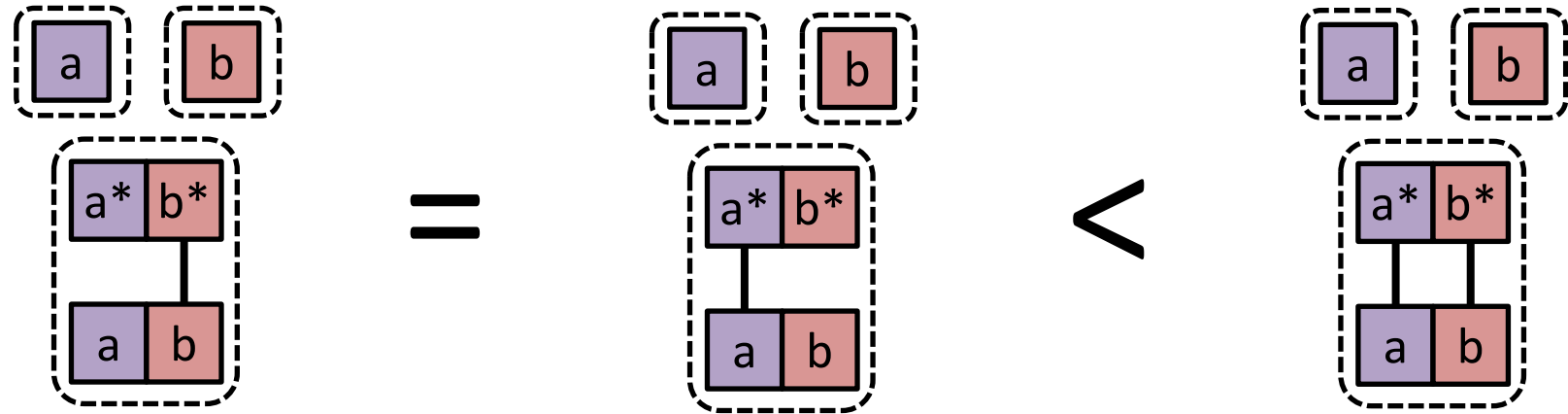
Geometry-Free Model:  
The domains within a monomer are unordered

Monomer = collection of domains

Configuration = how monomers are bound

# Energetic favorability: Bonds and complexes

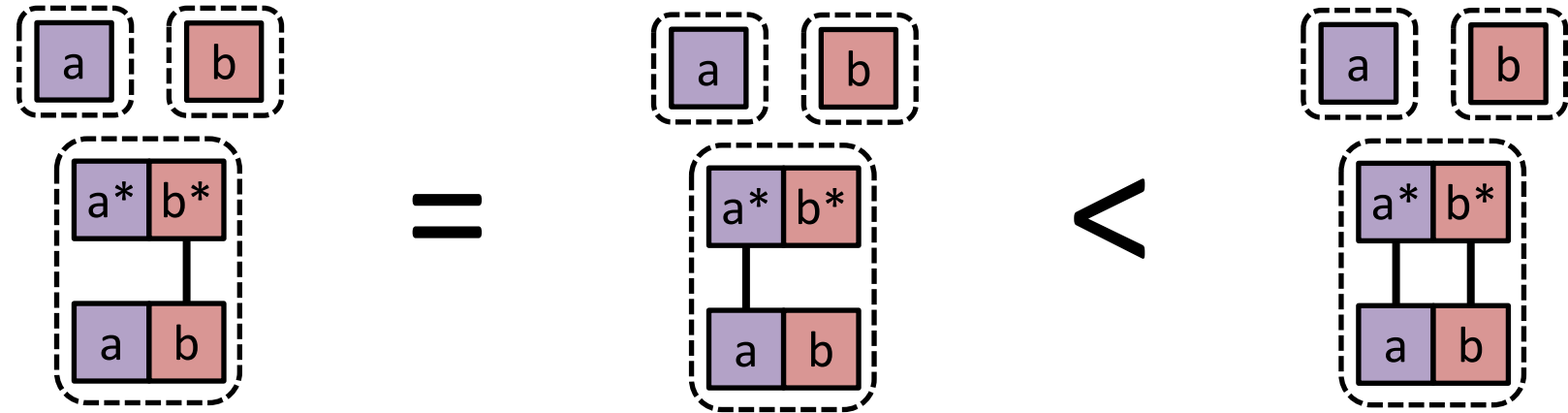
all else equal,  
more bonds  
= more favorable



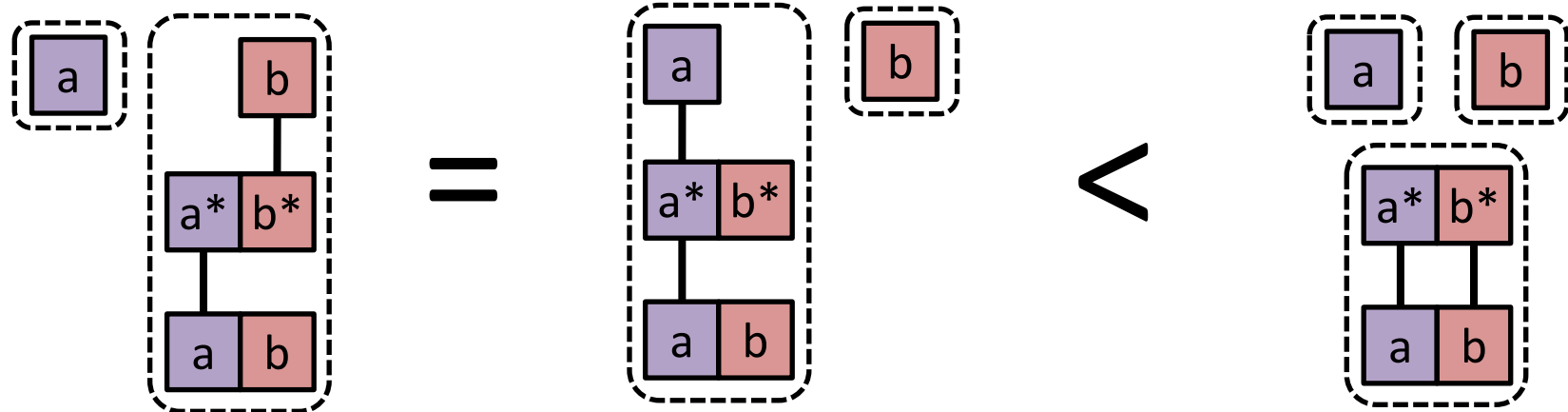


# Energetic favorability: Bonds and complexes

all else equal,  
more bonds  
= more favorable



all else equal,  
more complexes  
= more favorable



# Tradeoff between #bonds and #complexes

# Tradeoff between #bonds and #complexes

- in general, there's some weight parameter  $w$ :  
energy =  $w \cdot \text{\#bonds} + \text{\#complexes}$

# Tradeoff between #bonds and #complexes

- in general, there's some weight parameter  $w$ :  
energy =  $w \cdot \text{\#bonds} + \text{\#complexes}$   
(*physics notation:  $\Delta G = \Delta H - T \cdot \Delta S$* )

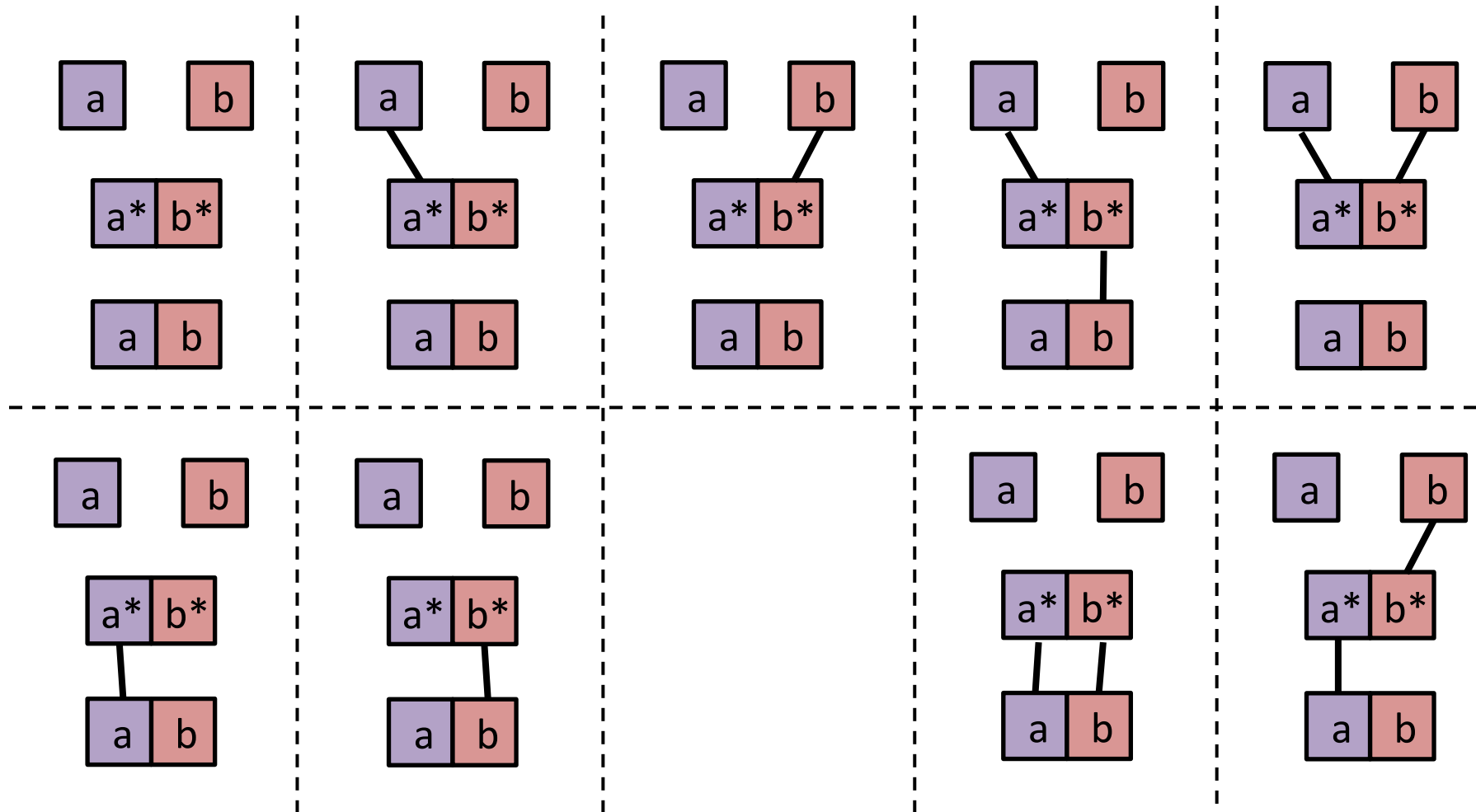
# Tradeoff between #bonds and #complexes

- in general, there's some weight parameter  $w$ :  
energy =  $w \cdot \#bonds + \#complexes$   
(*physics notation:  $\Delta G = \Delta H - T \cdot \Delta S$* )
- We often consider a natural limiting case:
  - favoring # bonds infinitely over #complexes
  - require maximal #bonds formed; use #complexes only as tiebreaker

# Tradeoff between #bonds and #complexes

- in general, there's some weight parameter  $w$ :  
energy =  $w \cdot \#bonds + \#complexes$   
(*physics notation:  $\Delta G = \Delta H - T \cdot \Delta S$* )
- We often consider a natural limiting case:
  - favoring # bonds infinitely over #complexes
  - require maximal #bonds formed; use #complexes only as tiebreaker
  - Corresponds to bonds that are so strong they cannot spontaneously dissociate, but can exchange with each other to find configurations with more complexes

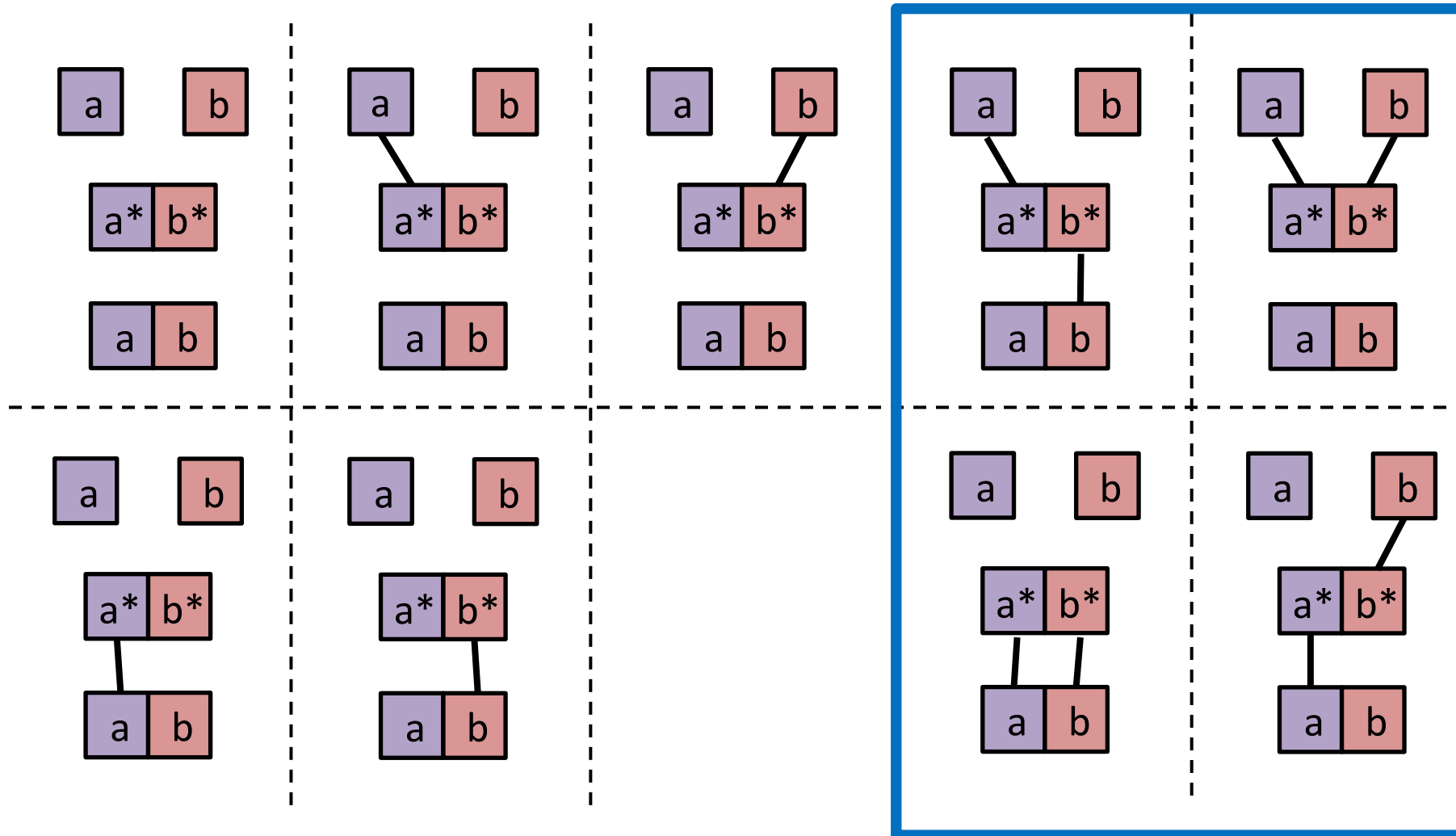
# Thermodynamic Binding Networks



# Thermodynamic Binding Networks

saturated = maximum #bonds formed

Saturated



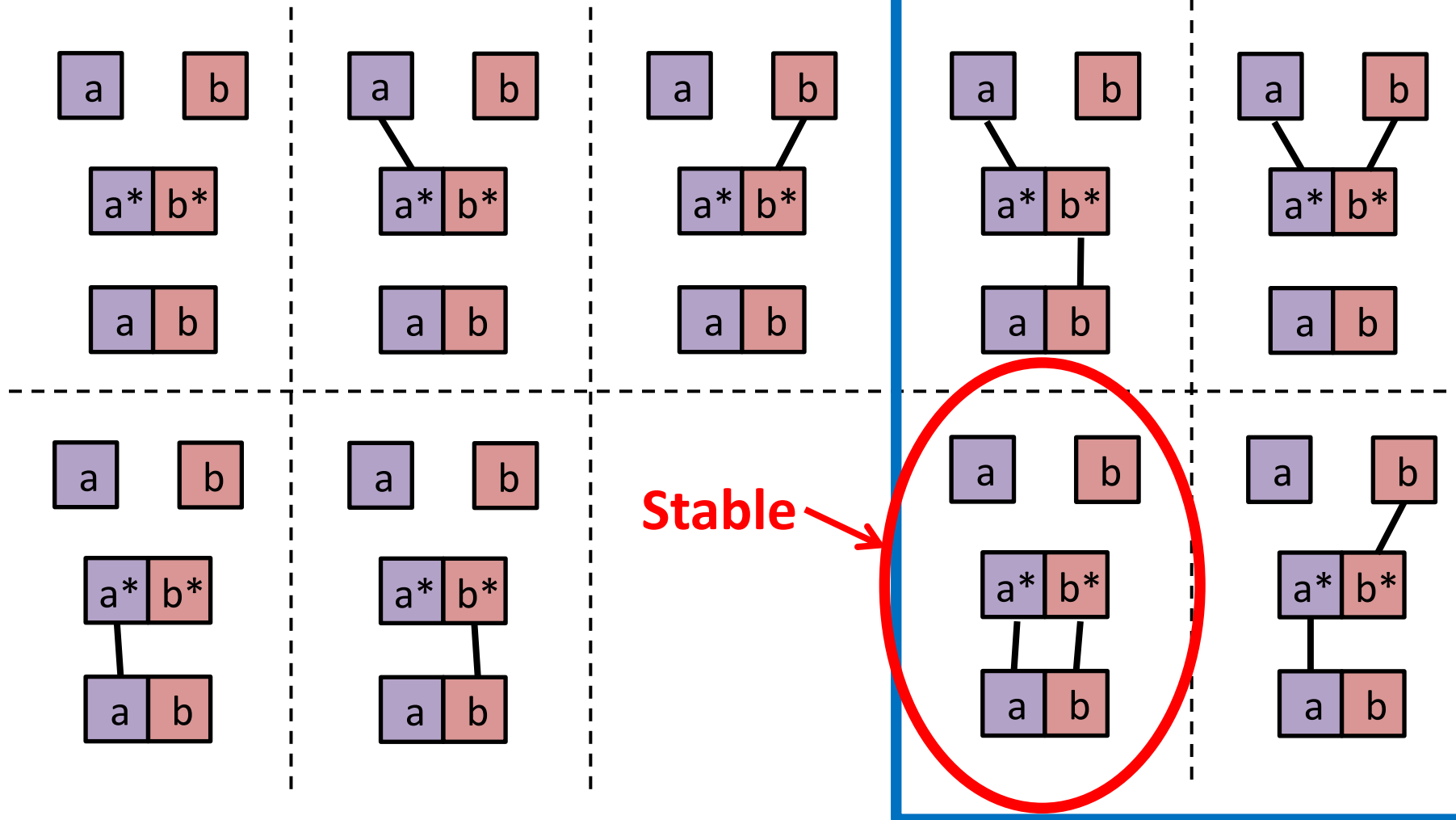


# Thermodynamic Binding Networks

saturated = maximum #bonds formed

stable = saturated, AND maximum #complexes

Saturated

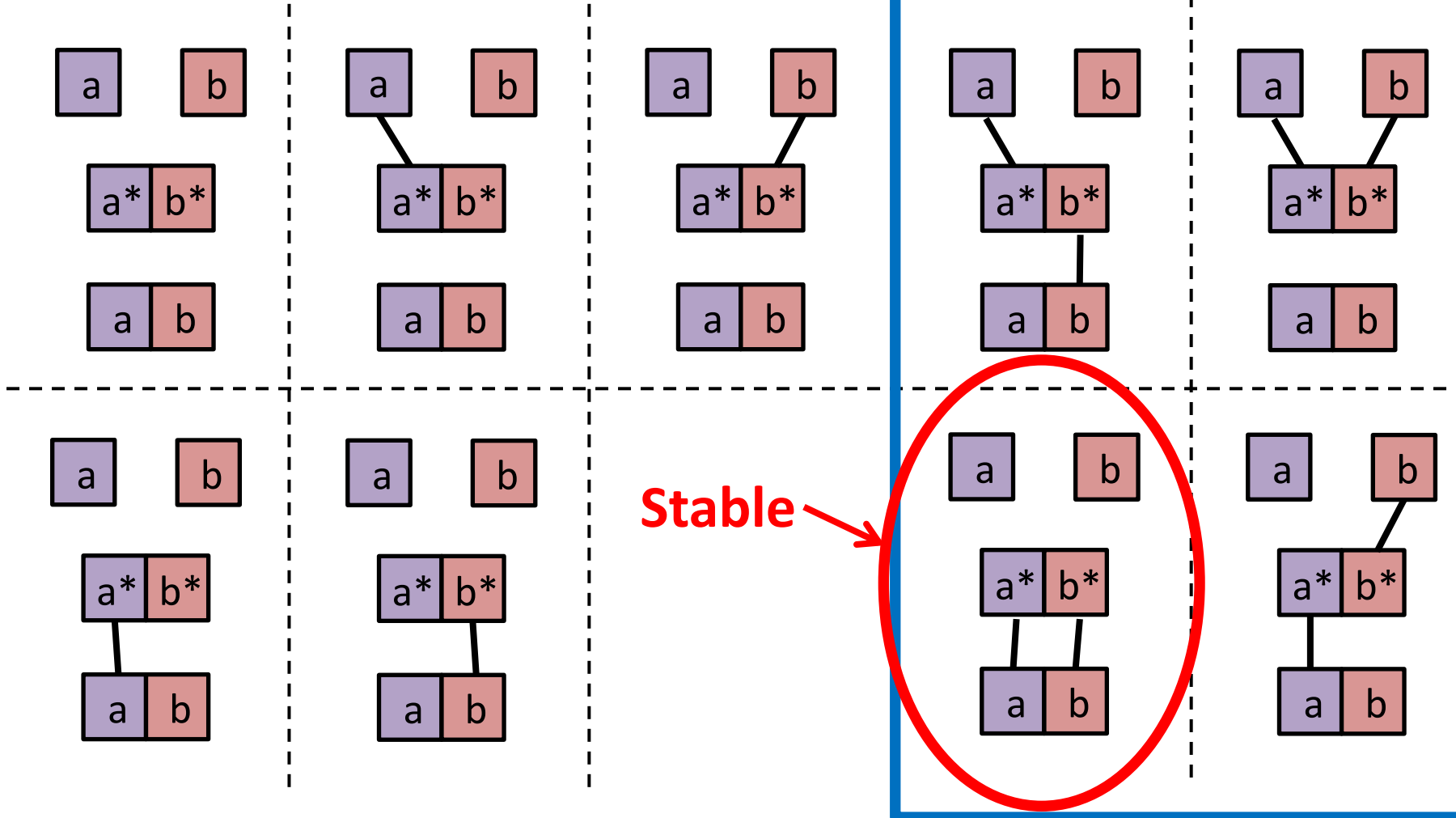


# Thermodynamic Binding Networks

saturated = maximum #bonds formed

stable = saturated, AND maximum #complexes

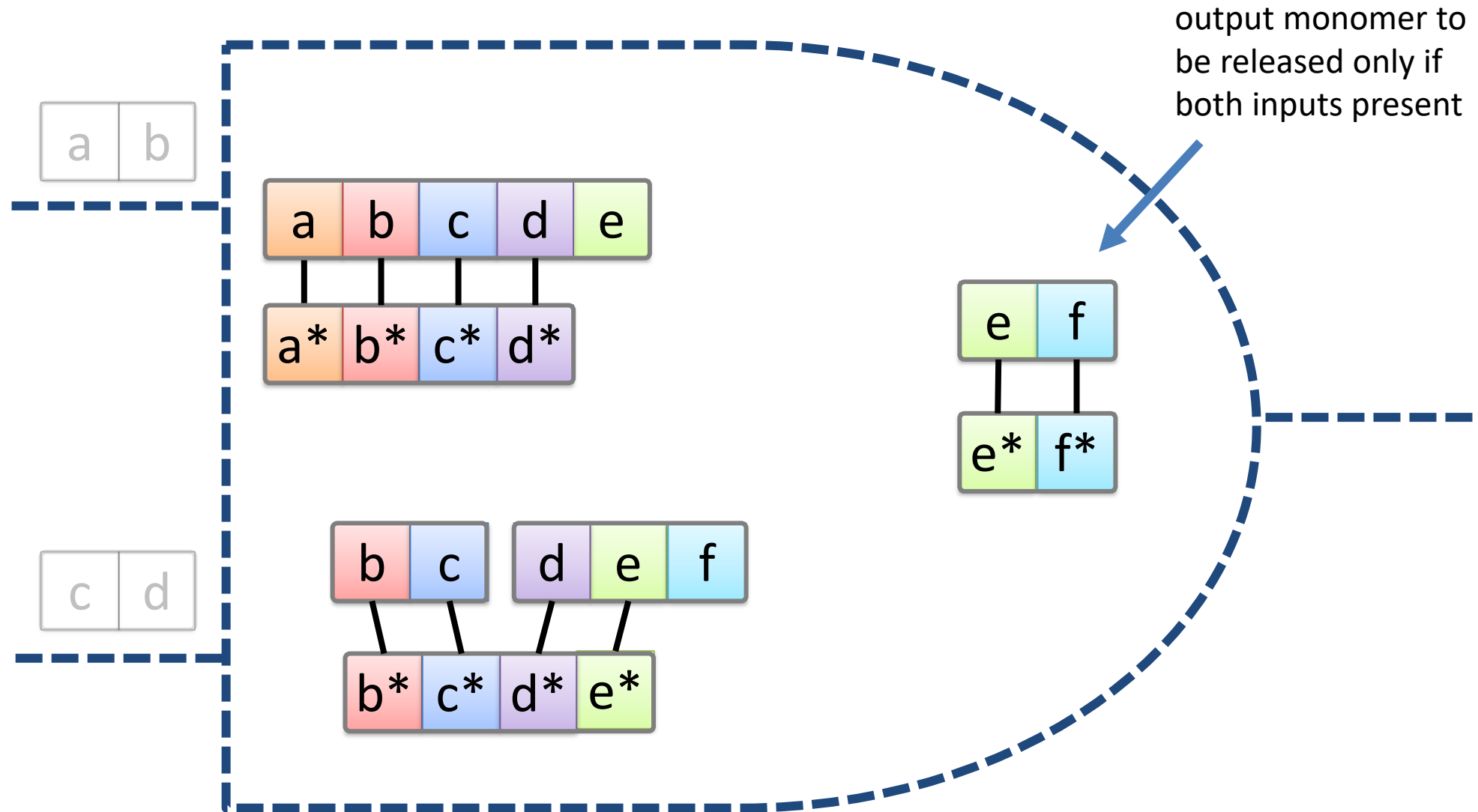
Saturated



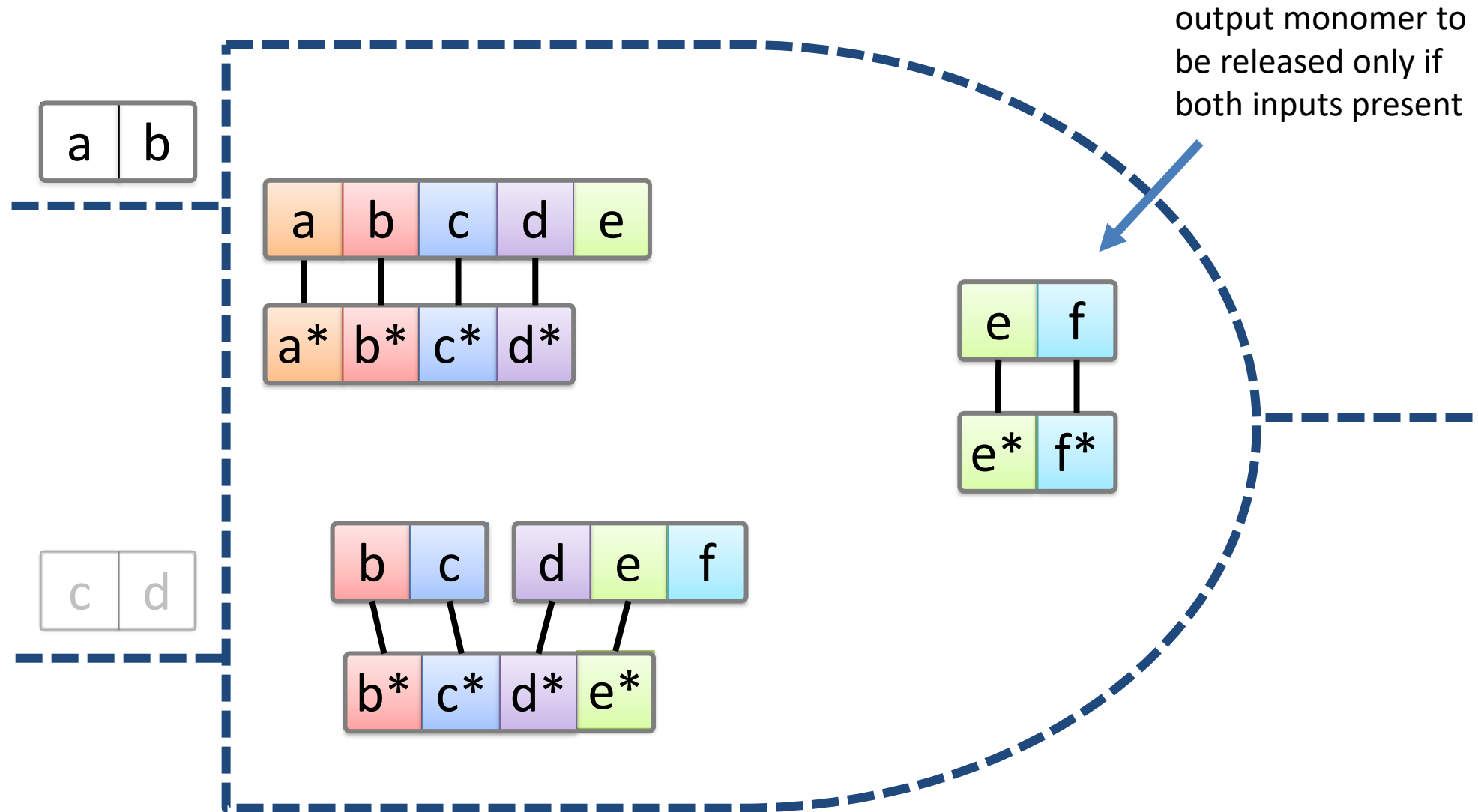
If we're careful to make starred binding sites limiting, then *saturated = all starred sites are bound*

# Computing via Thermodynamic Equilibrium

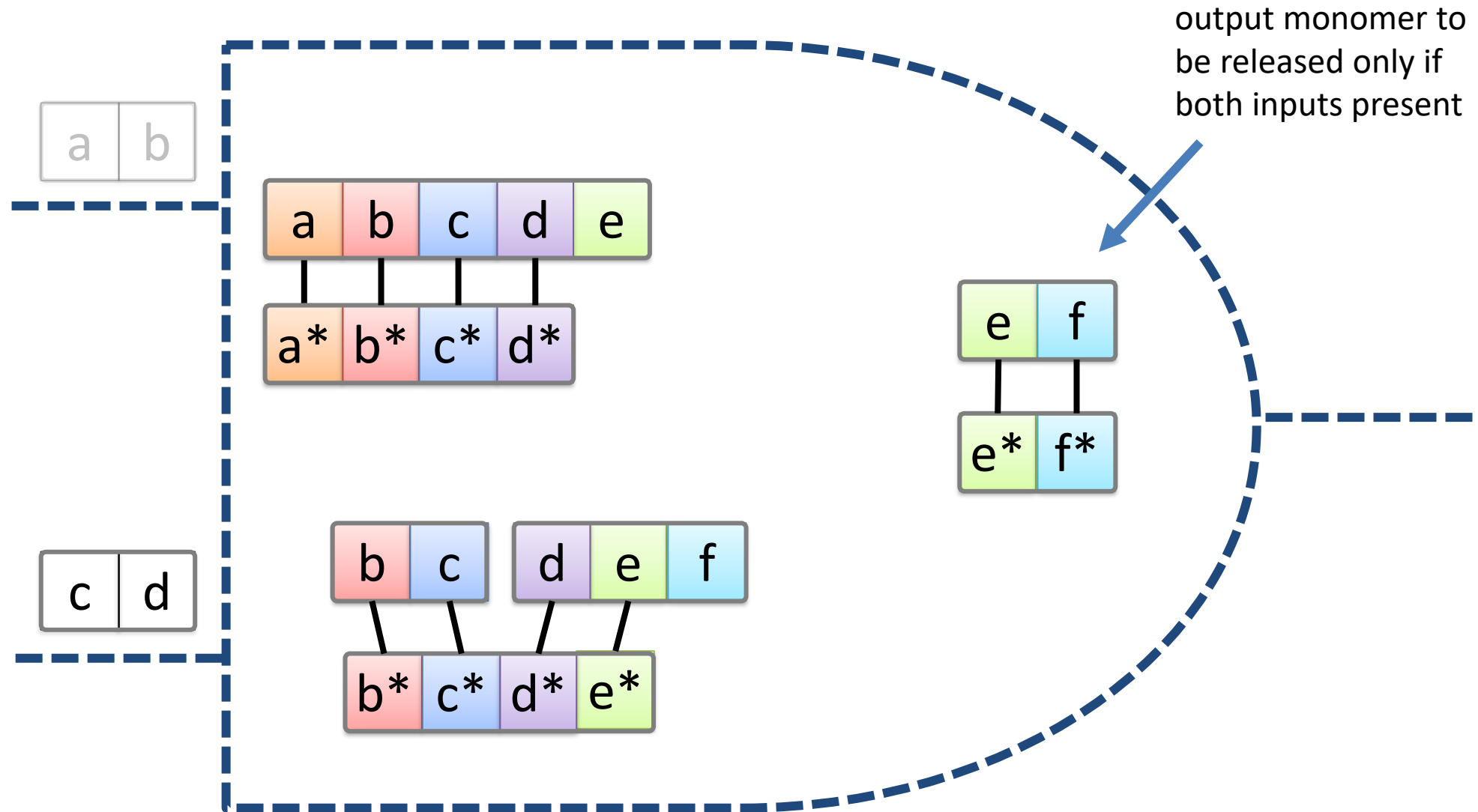
# AND gate



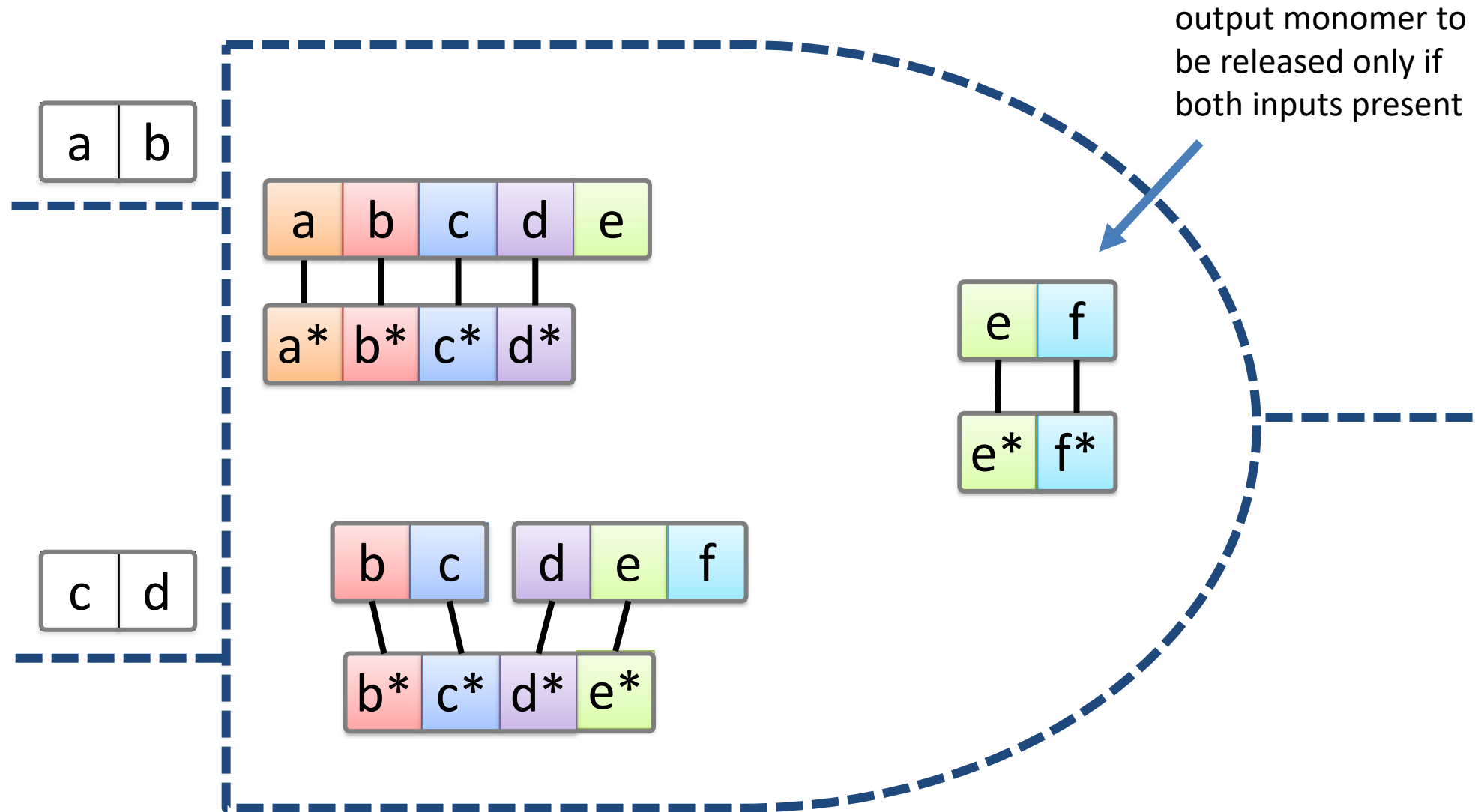
# AND gate



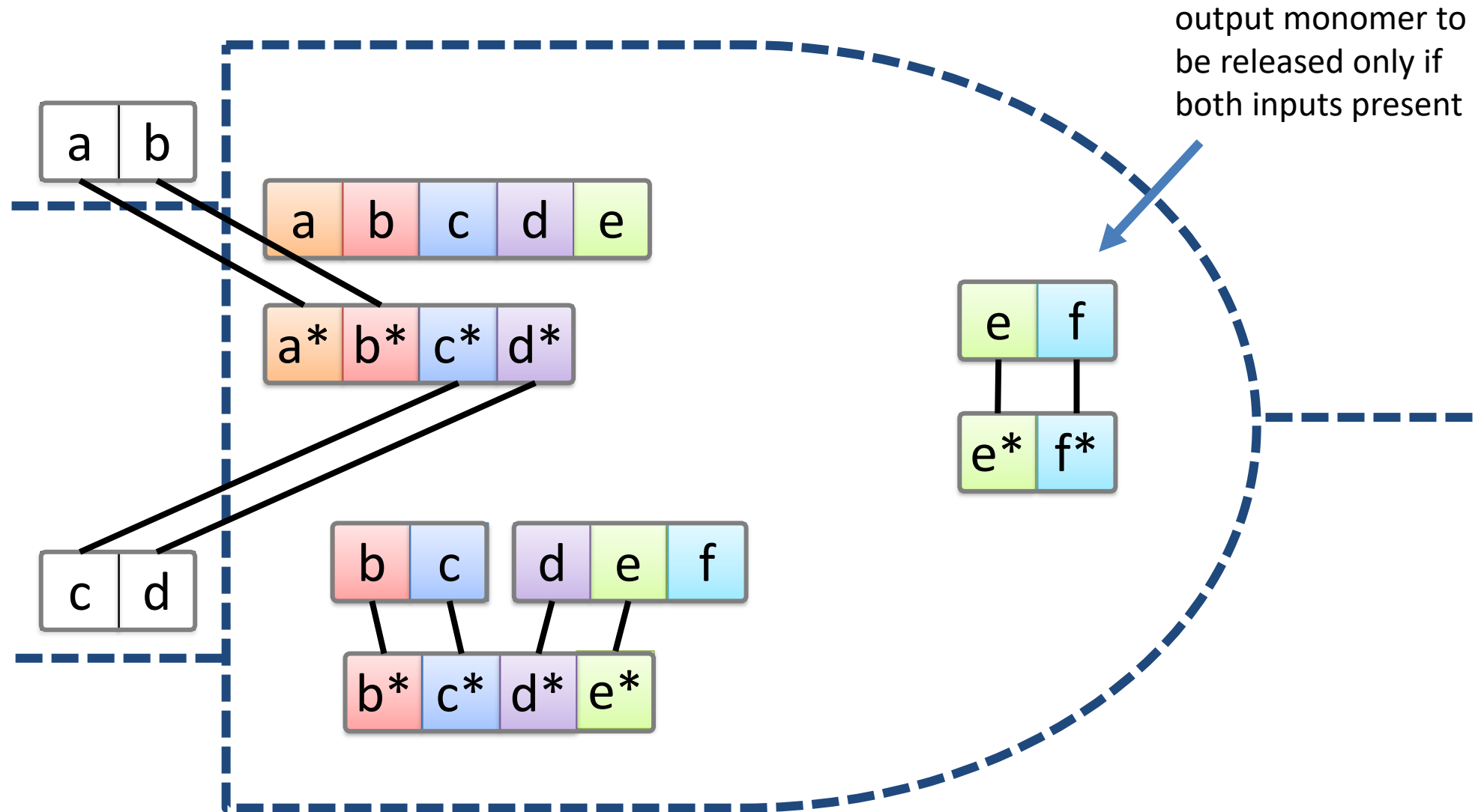
# AND gate



# AND gate

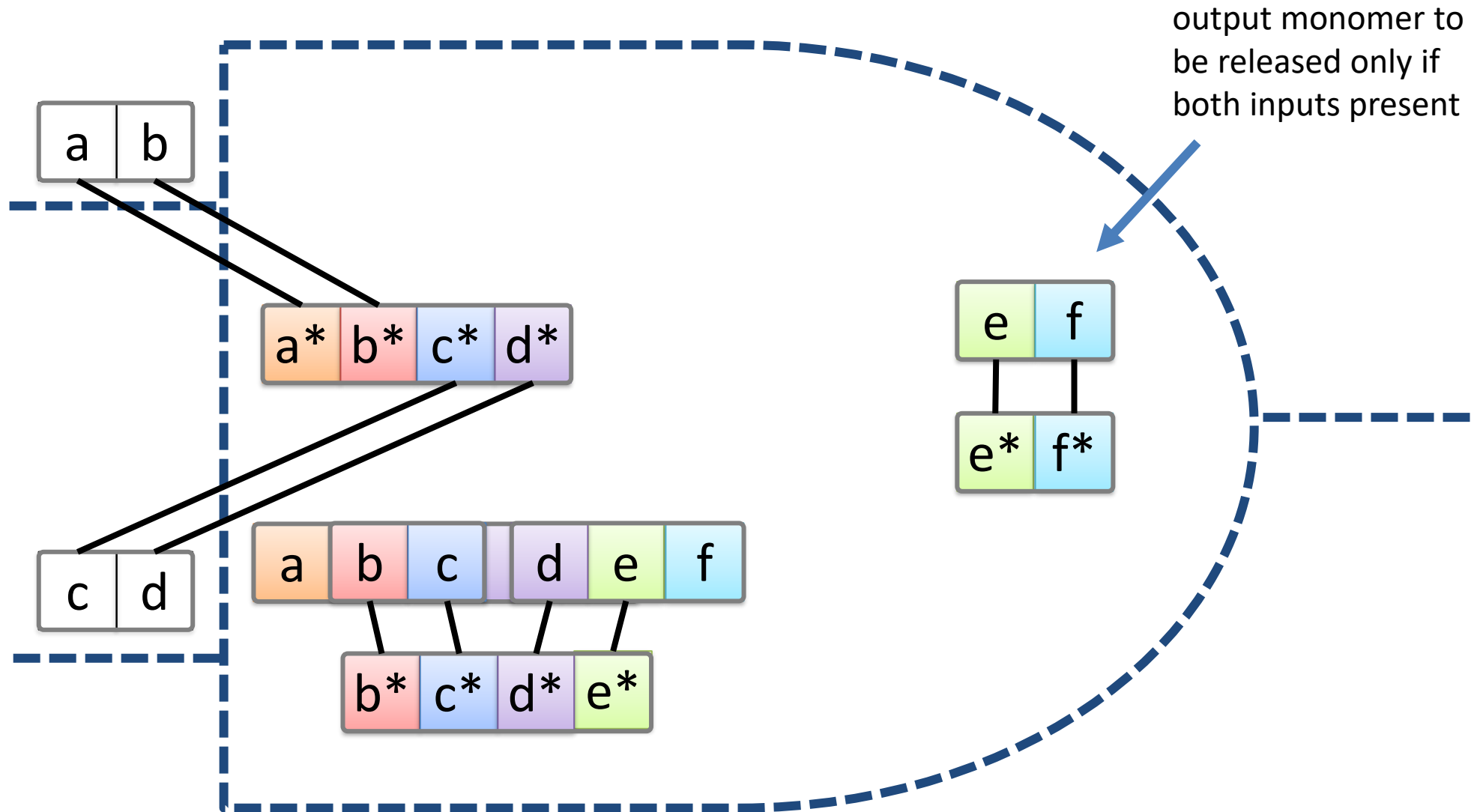


# AND gate

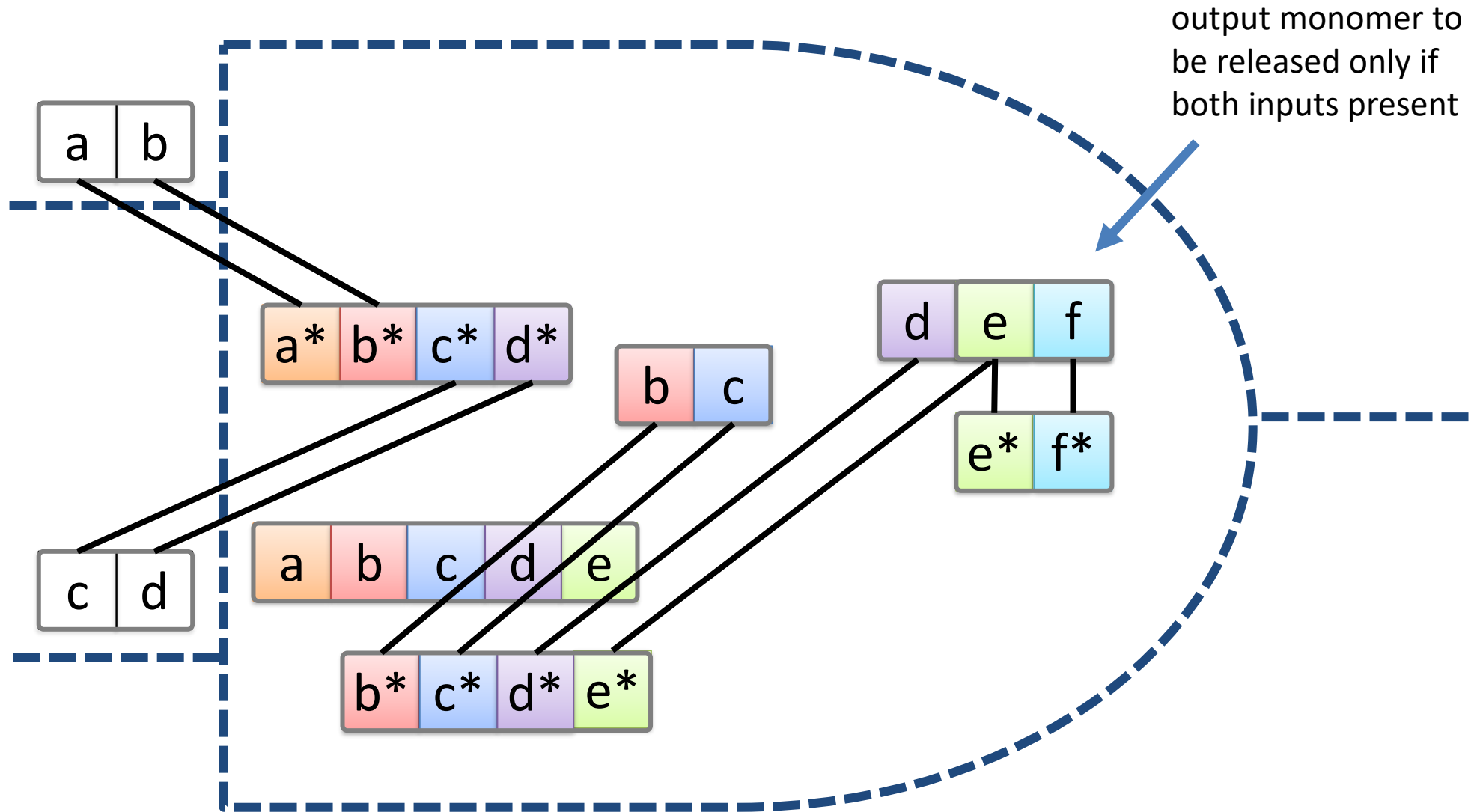




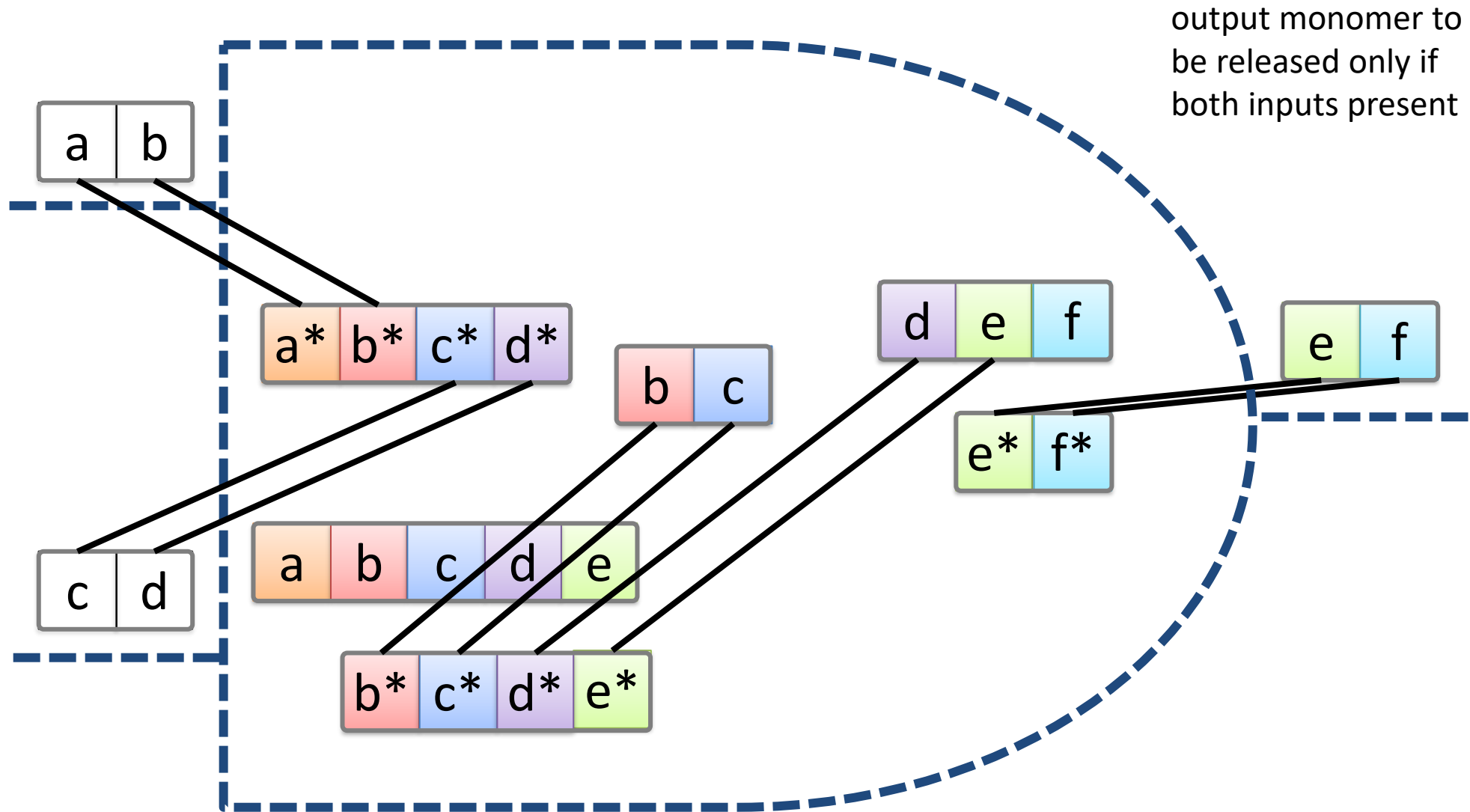
# AND gate



# AND gate



# AND gate



# Issues with Boolean logic

# Issues with Boolean logic

- How to compose?
  - We don't know how to prove the previous gate is composable, and used a more complex design in the paper

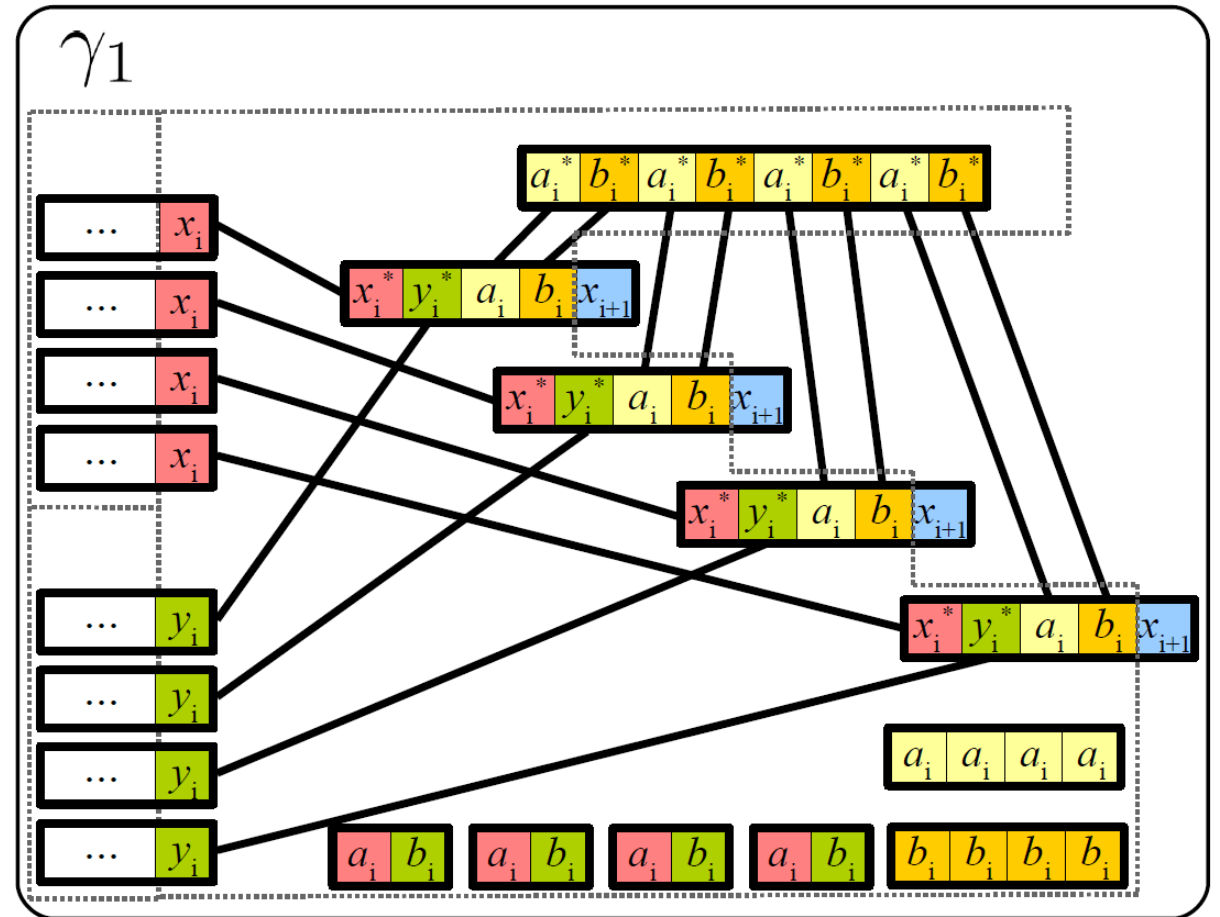
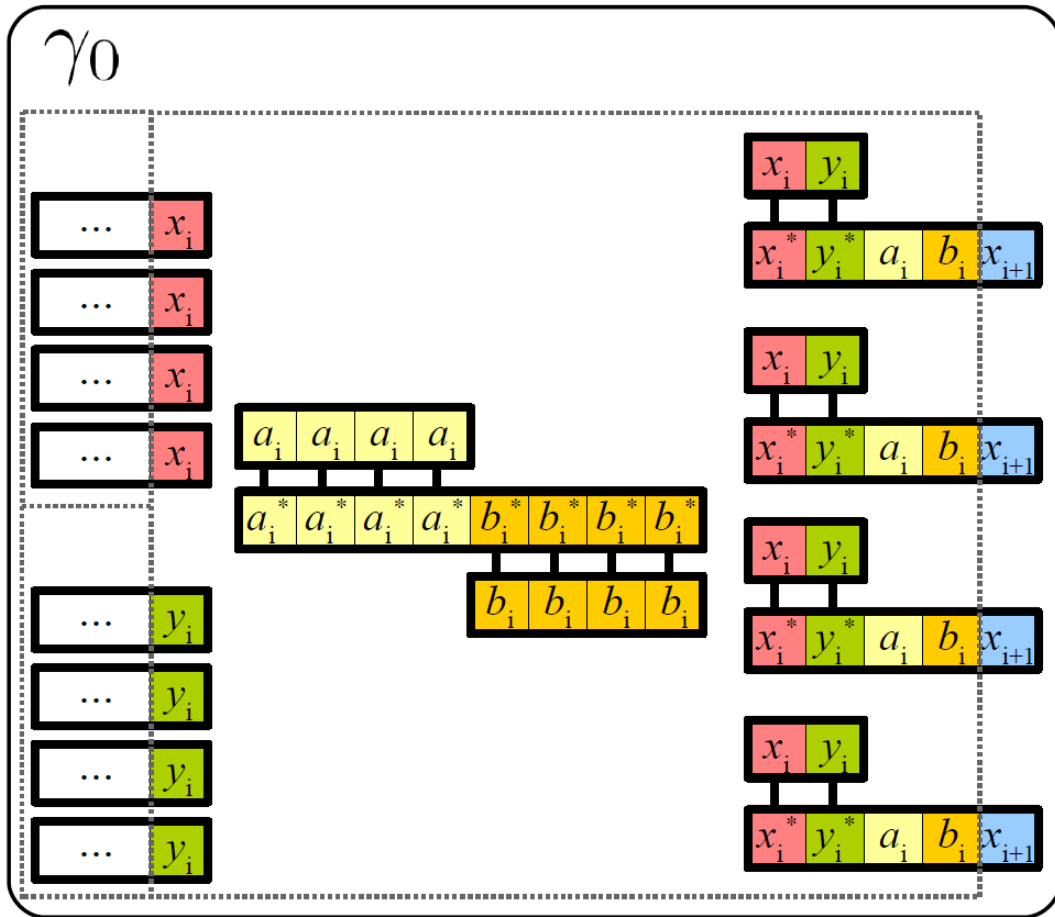
# Issues with Boolean logic

- How to compose?
  - We don't know how to prove the previous gate is composable, and used a more complex design in the paper
- Want “entropy gap”:
  - Need not merely that unwanted configurations are unstable (i.e., if saturated, they have lower entropy), but more strongly that they have much lower entropy.
  - We can use  $O(n)$  domain/monomer types to achieve an entropy gap of  $n$ .

# Issues with Boolean logic

- How to compose?
  - We don't know how to prove the previous gate is composable, and used a more complex design in the paper
- Want “entropy gap”:
  - Need not merely that unwanted configurations are unstable (i.e., if saturated, they have lower entropy), but more strongly that they have much lower entropy.
  - We can use  $O(n)$  domain/monomer types to achieve an entropy gap of  $n$ .
- Output convention?
  - Obvious one: “there's a unique stable configuration with the correct output”
  - It's problematic, so we have a one-sided convention:
    - if correct output is 0, unique stable configuration with correct answer
    - if correct output is 1, then both the “output=1” and “output=0” configurations are stable

# Composable AND gate with entropy gap 3



Rather than release a single output monomer, it suffices to gather all output domains on one complex.

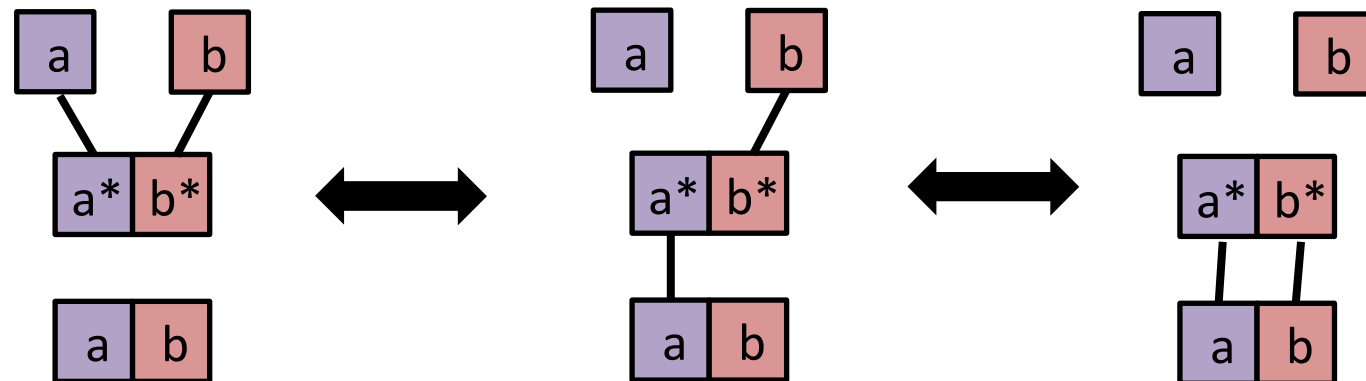


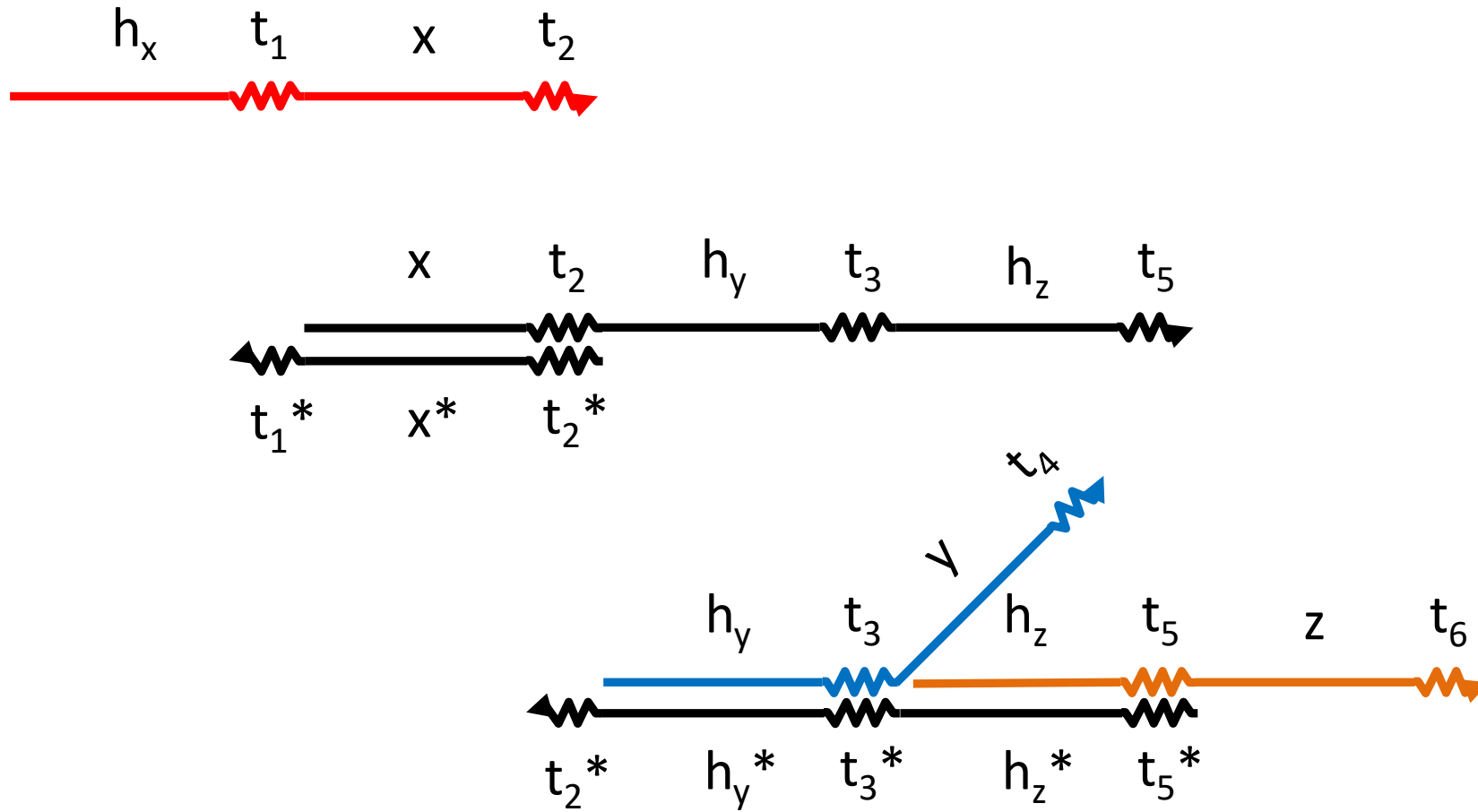
# Kinetic pathways and energy barriers

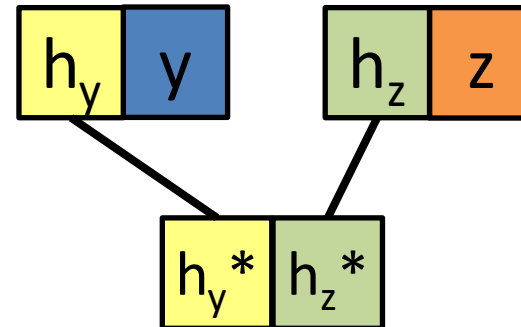
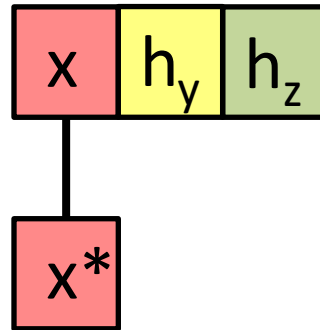
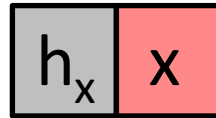
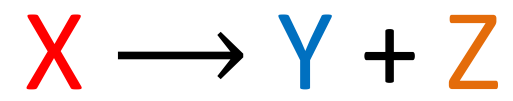
# Pathways

**Thermodynamics:** Which configurations are energetically favorable

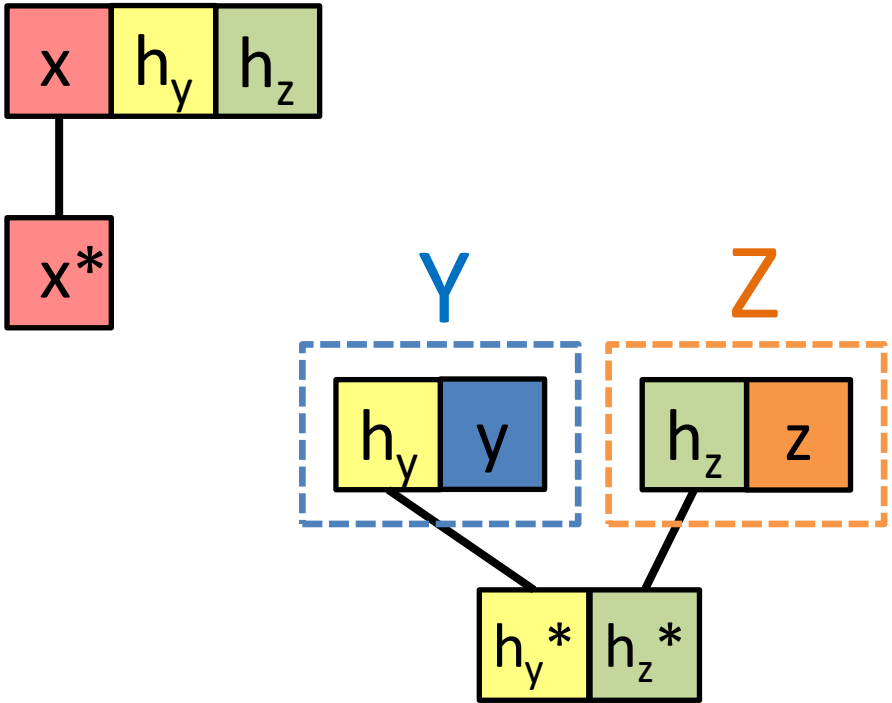
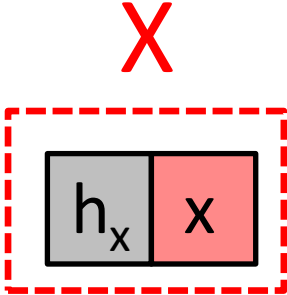
**Kinetics:** How a system moves between configurations over time

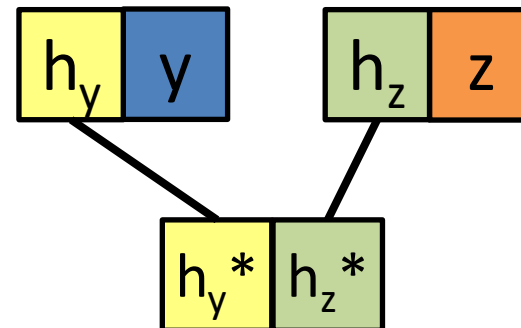
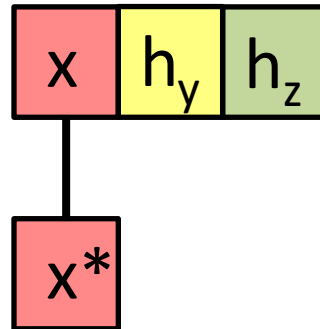
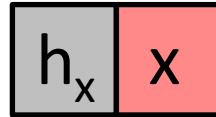
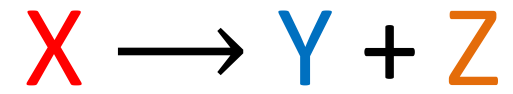


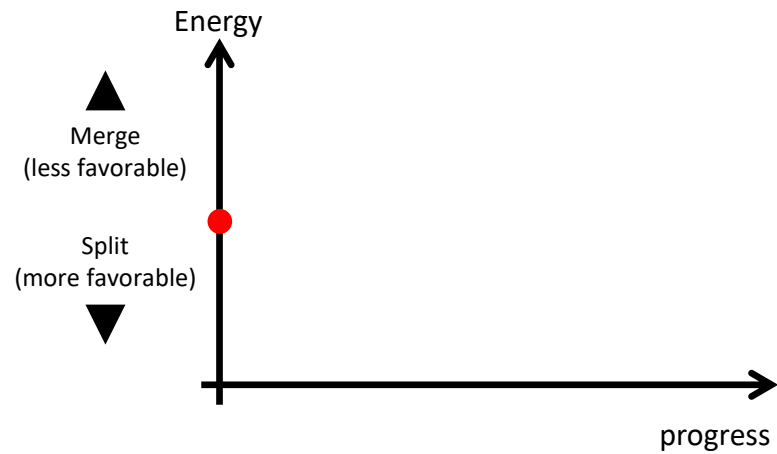
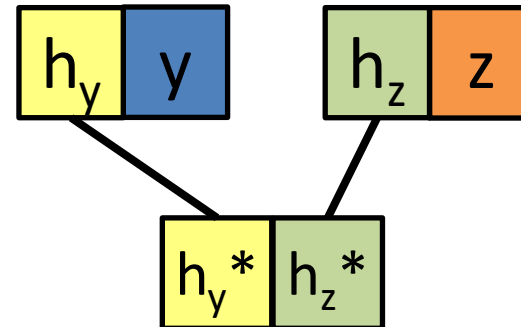
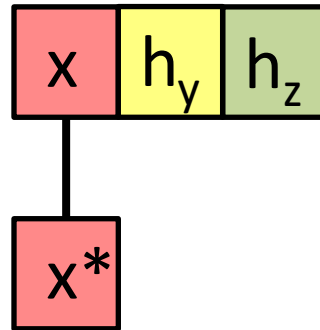
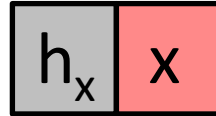


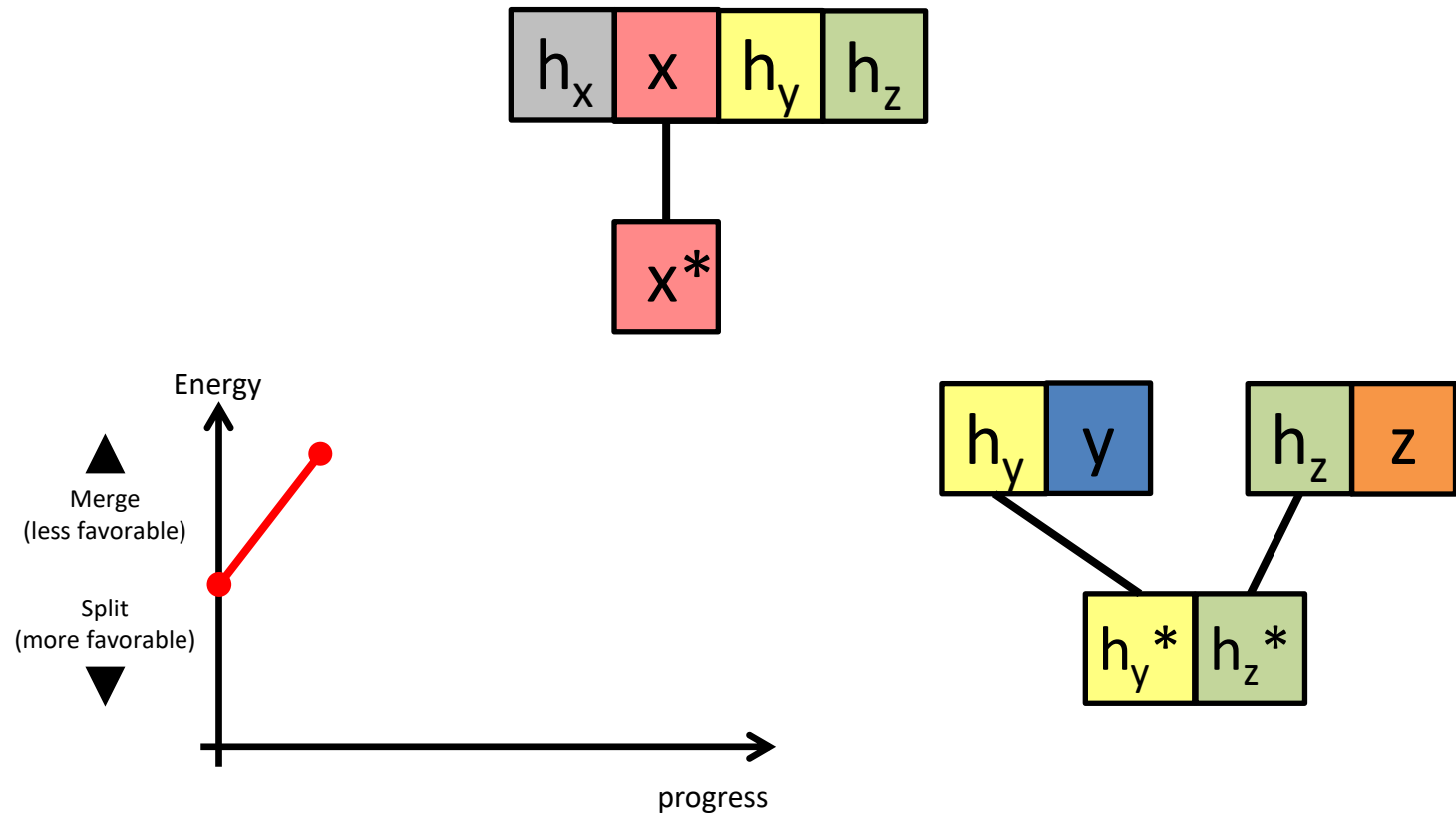


$$X \rightarrow Y + Z$$

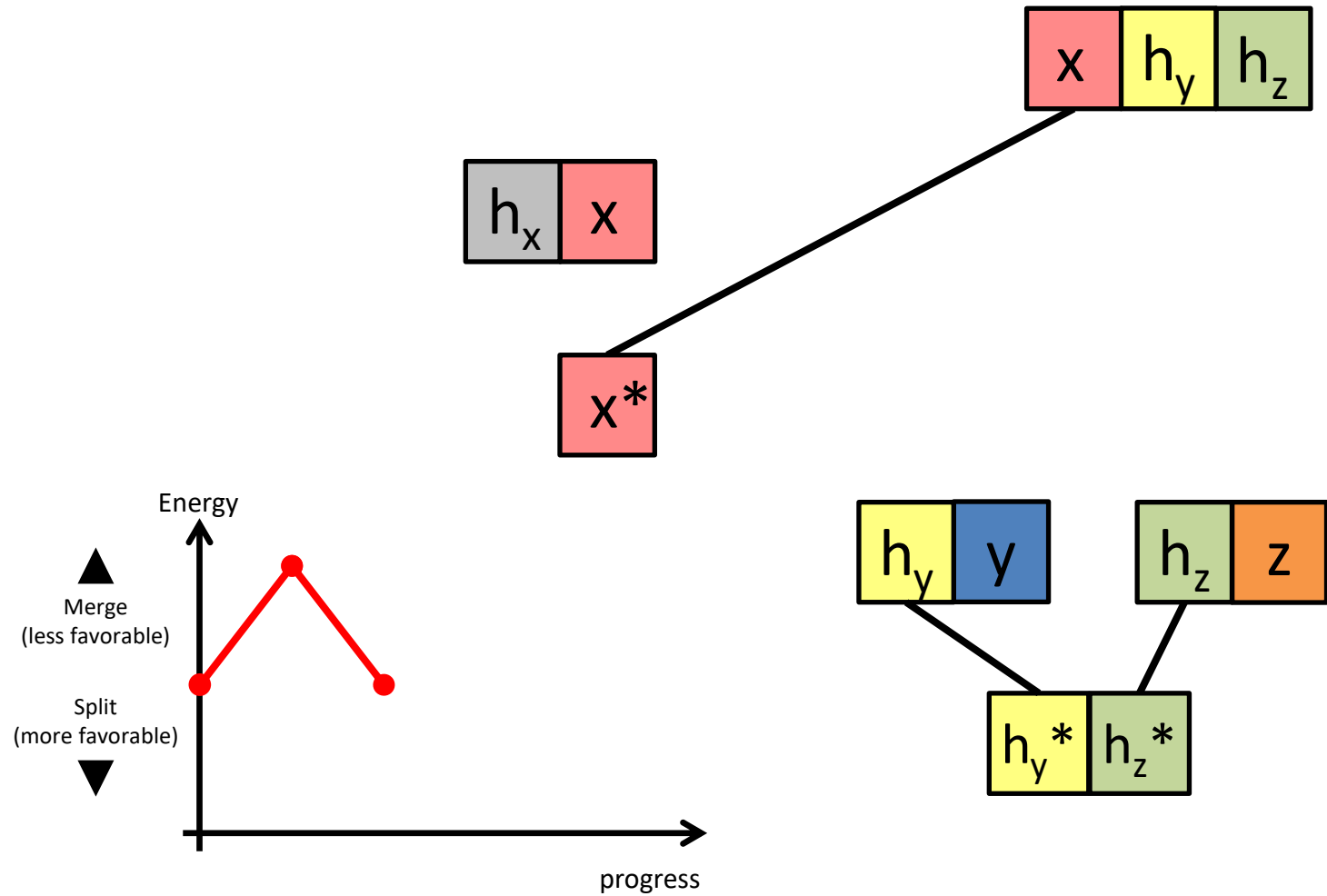


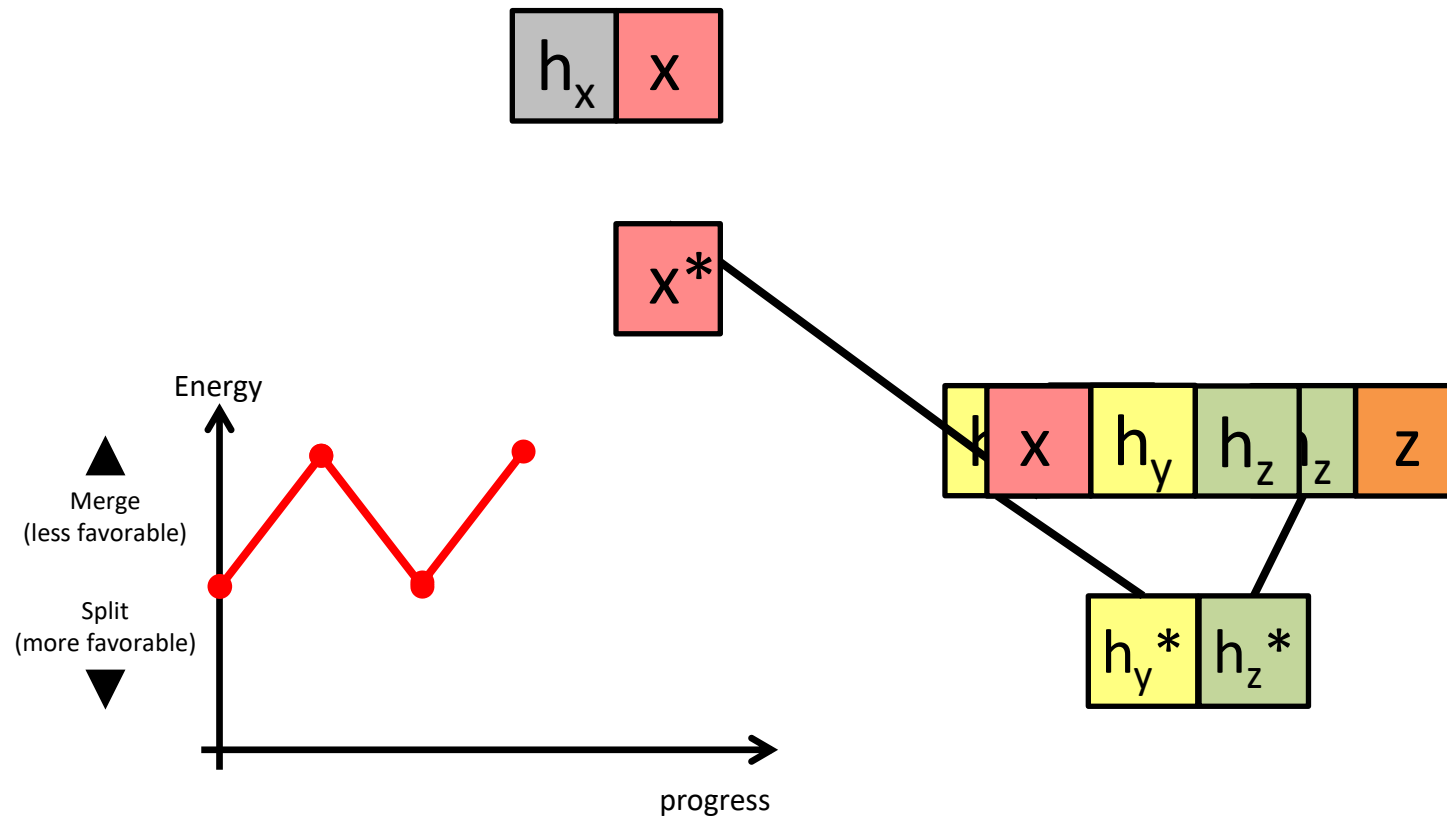
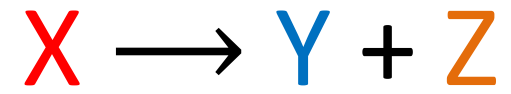


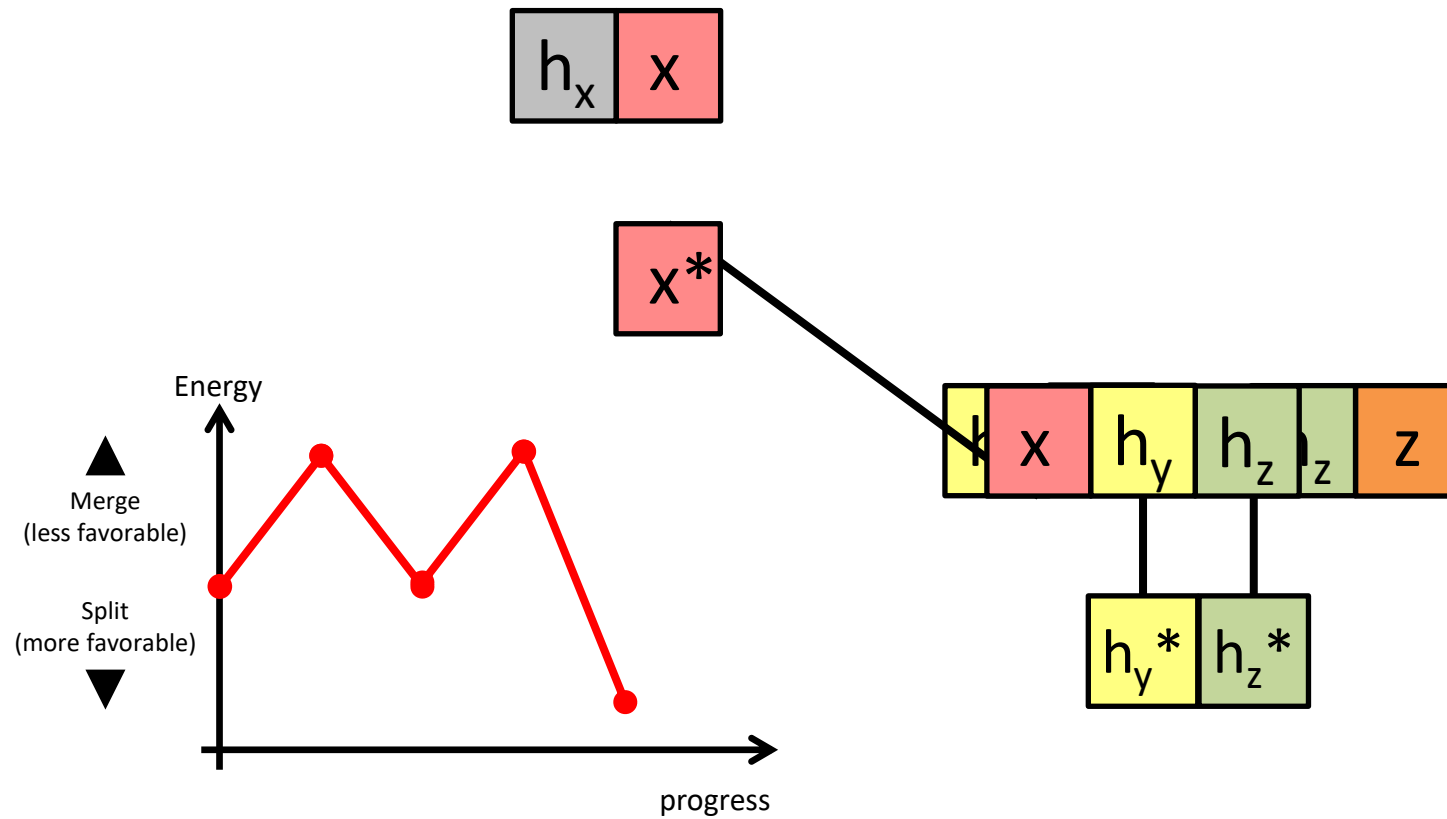
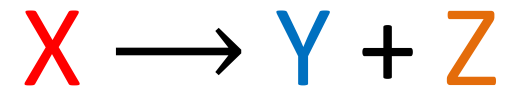


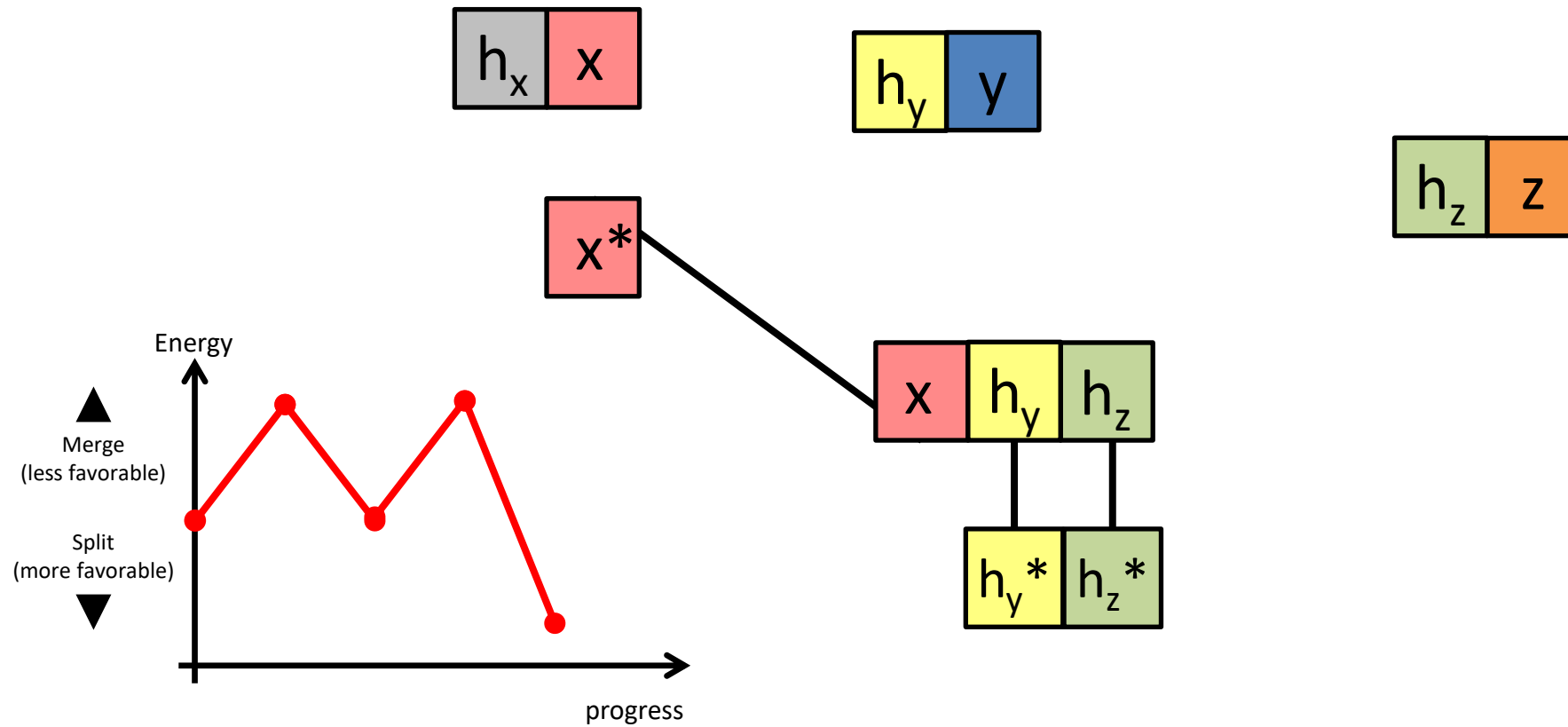
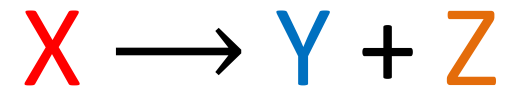


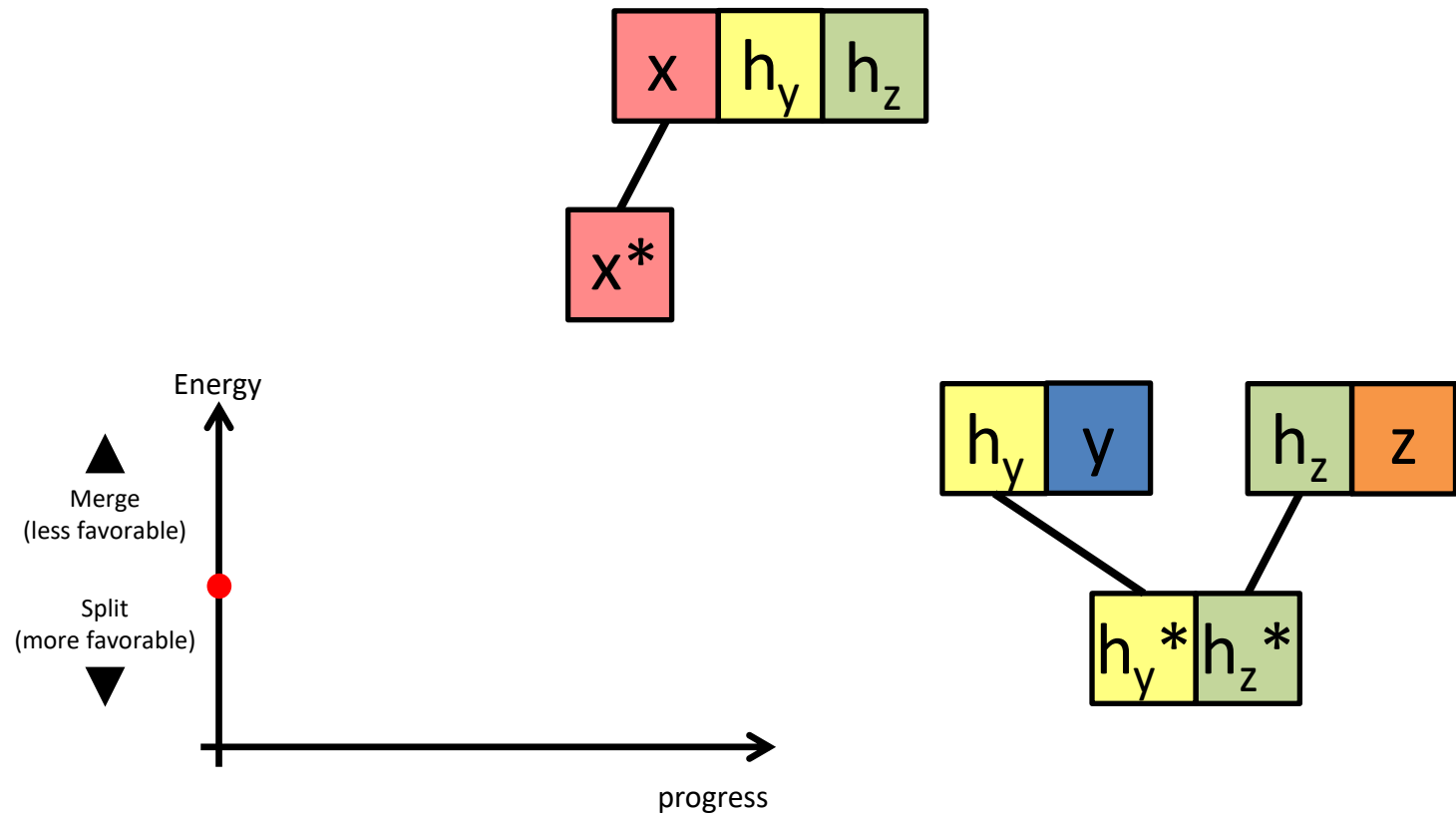
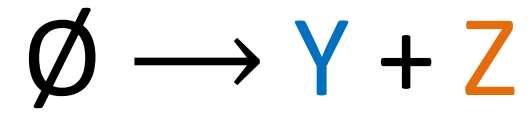


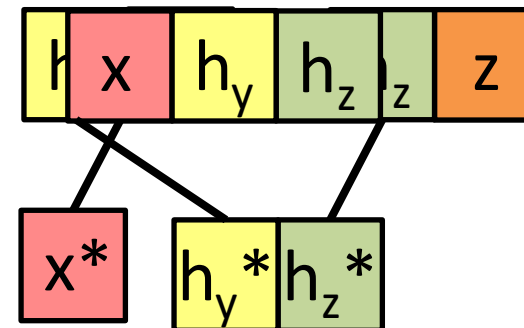
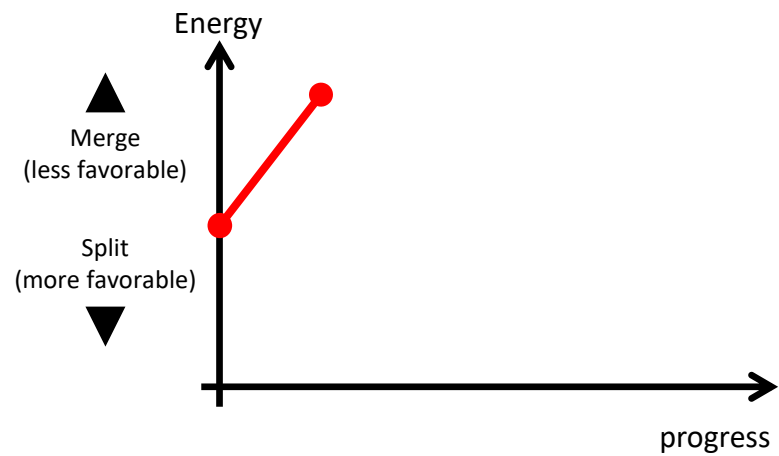
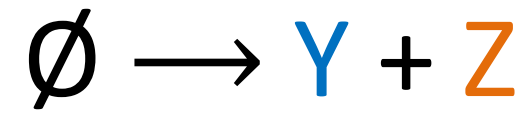


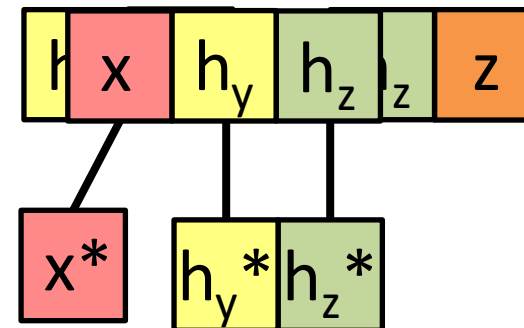
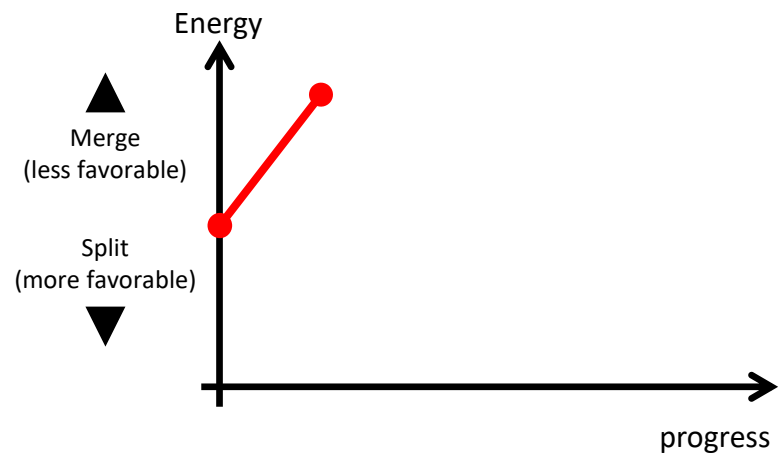
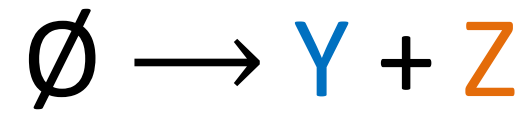




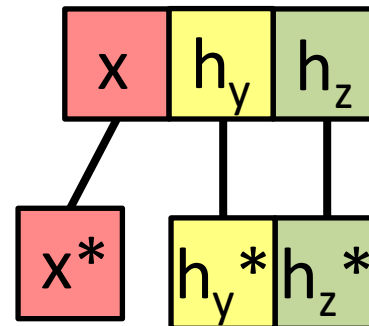
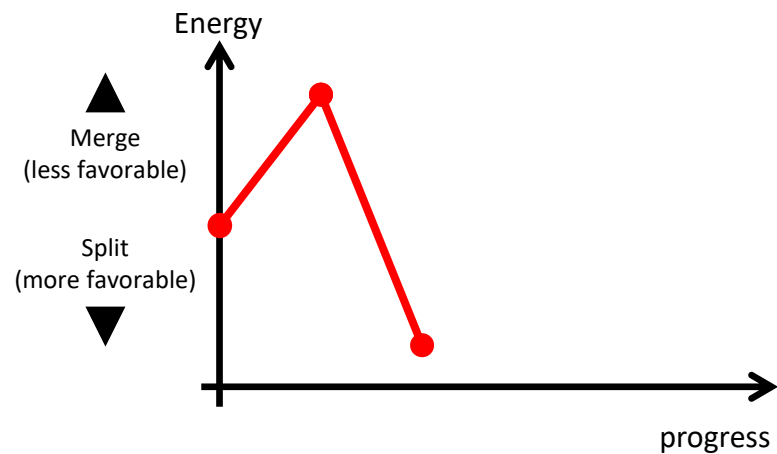
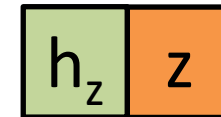
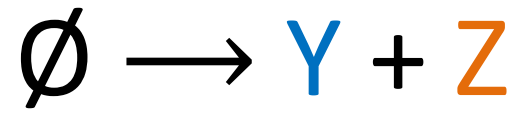








What causes leak  
“kinetically”?





# Kinetic Binding Networks

# Kinetic Binding Networks

- Favorability is a combination of bond count and complex count

# Kinetic Binding Networks

- Favorability is a combination of bond count and complex count

Weighted average:

$$\text{Energy} := -w_H(\# \text{ bonds}) - (\# \text{ complexes})$$

# Kinetic Binding Networks

- Favorability is a combination of bond count and complex count

Weighted average:

$$\text{Energy} := -w_H(\# \text{ bonds}) - (\# \text{ complexes})$$

- Define pathways to consist of merges and splits

# Kinetic Binding Networks

- Favorability is a combination of bond count and complex count

Weighted average:

$$\text{Energy} := -w_H(\# \text{ bonds}) - (\# \text{ complexes})$$

- Define pathways to consist of merges and splits
- But for  $w_H \geq 2$ , only saturated pathways need be considered

[Keenan Breik, Cameron Chalk, David Doty, David Haley, David Soloveichik. *Programming Substrate-Independent Kinetic Barriers with Thermodynamic Binding Networks*. Computational Methods in Systems Biology 2018]

# Kinetic Binding Networks

- Favorability is a combination of bond count and complex count

Weighted average:

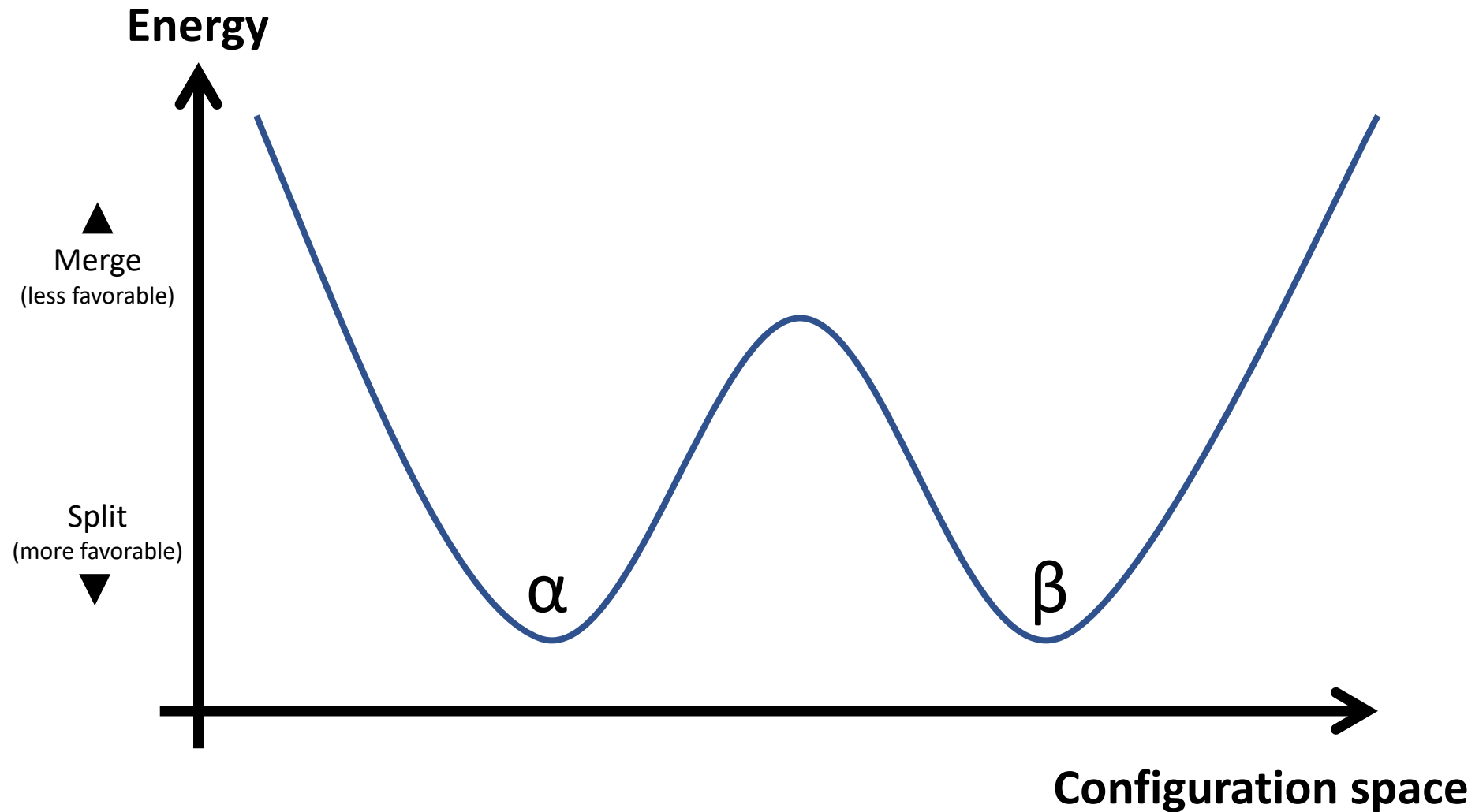
$$\text{Energy} := -w_H(\# \text{ bonds}) - (\# \text{ complexes})$$

- Define pathways to consist of merges and splits
- But for  $w_H \geq 2$ , only saturated pathways need be considered

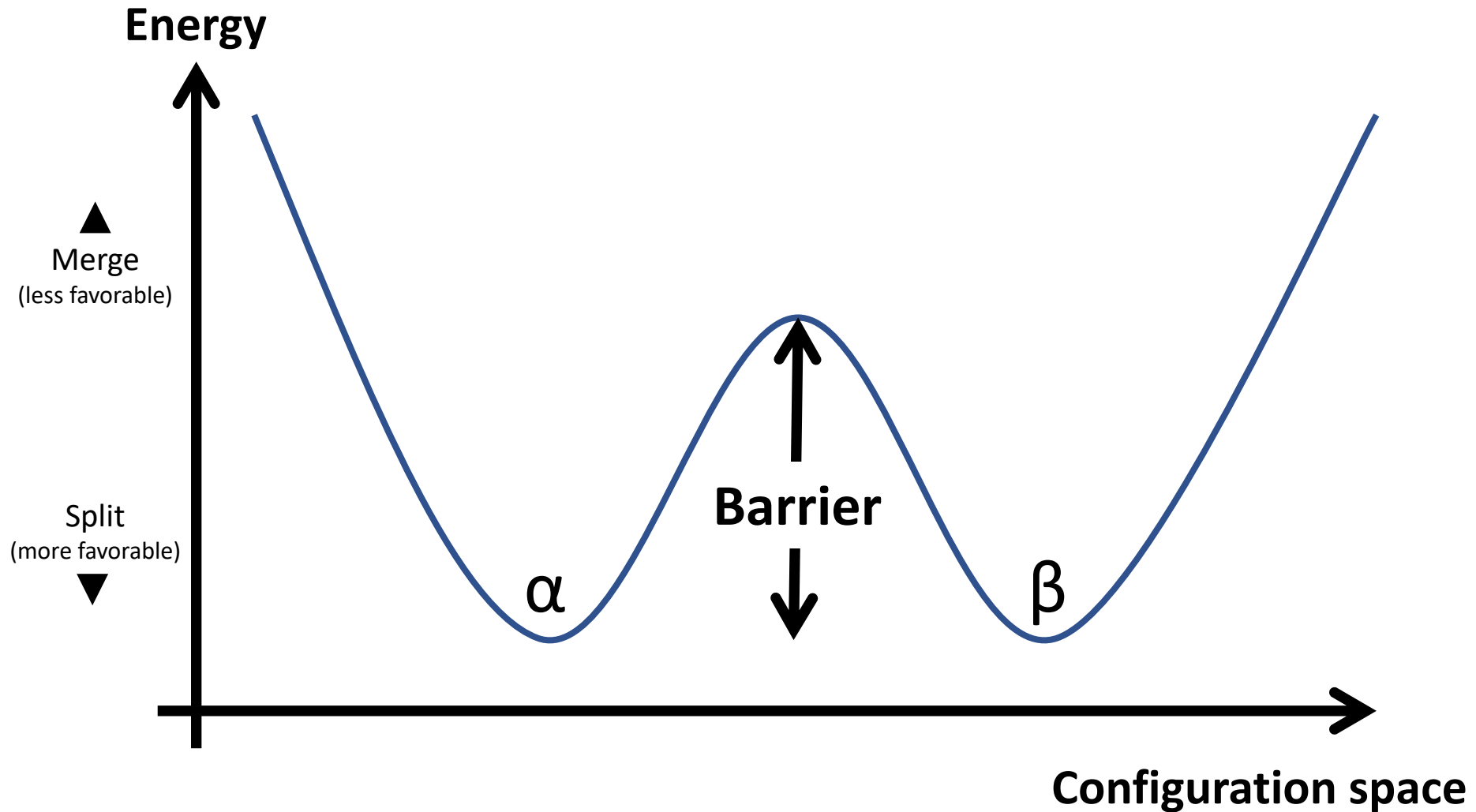
**Since all saturated configurations have an equal number of bonds, we can focus solely on the number of complexes**

[Keenan Breik, Cameron Chalk, David Doty, David Haley, David Soloveichik. *Programming Substrate-Independent Kinetic Barriers with Thermodynamic Binding Networks*. Computational Methods in Systems Biology 2018]

# Large Energy Barriers

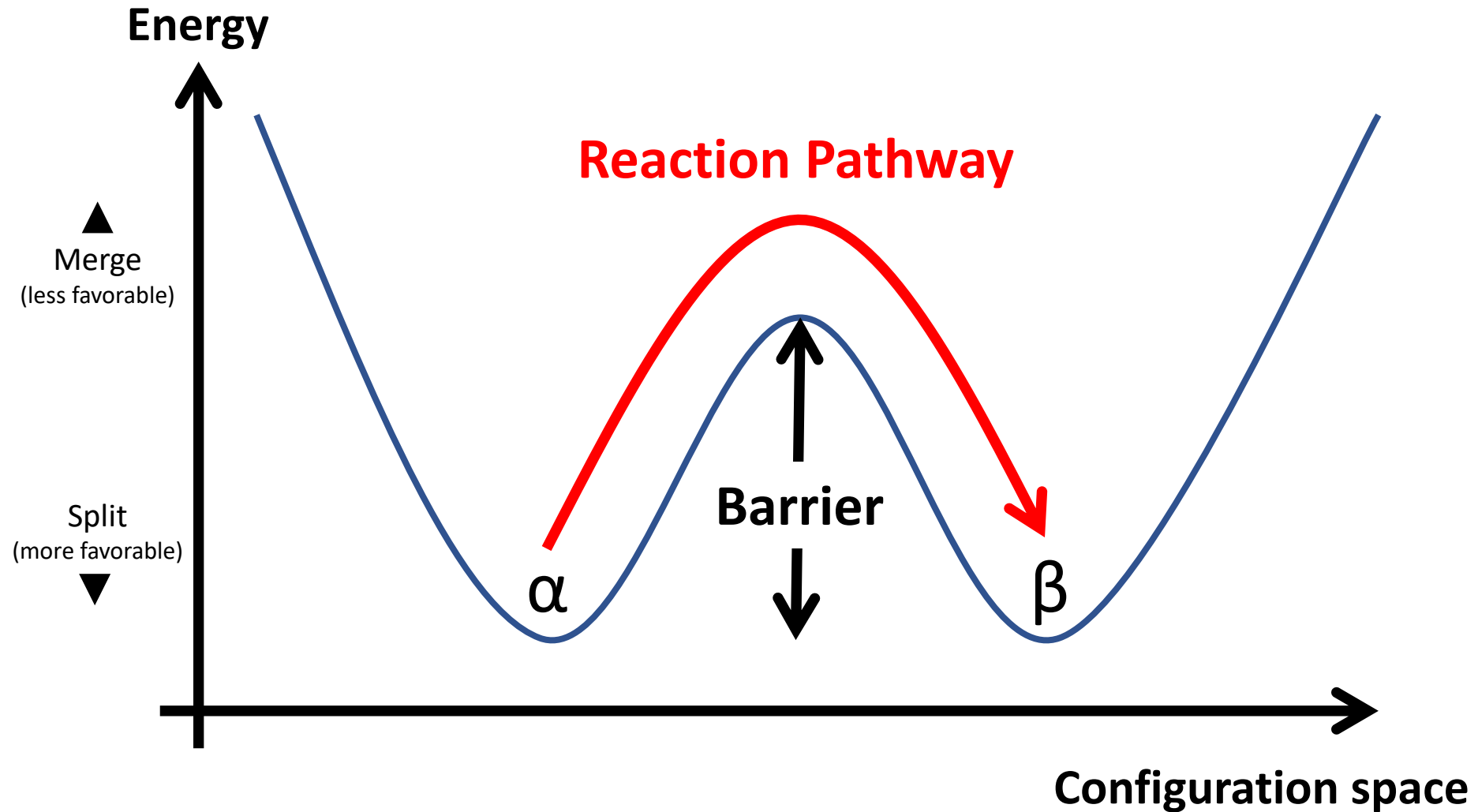


# Large Energy Barriers

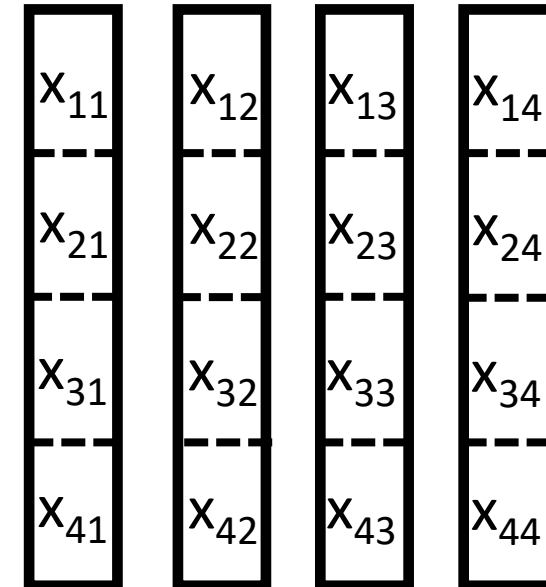
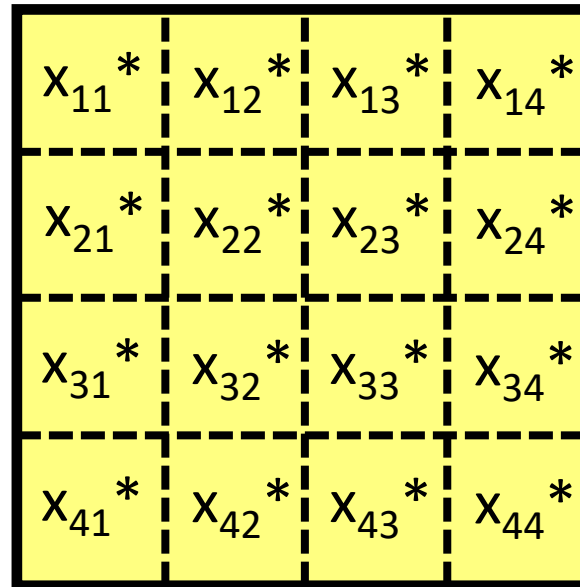
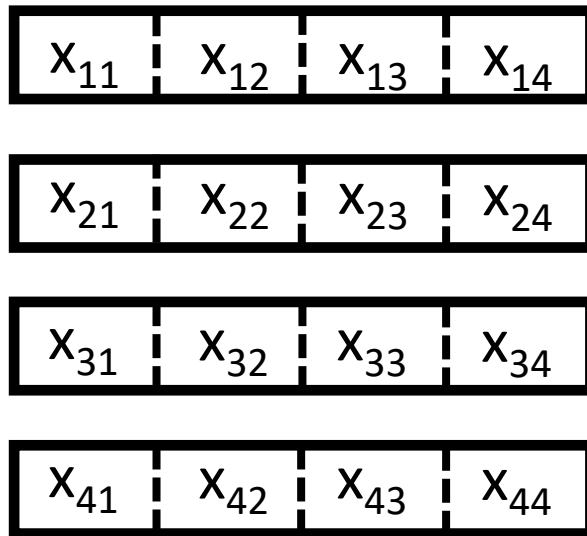
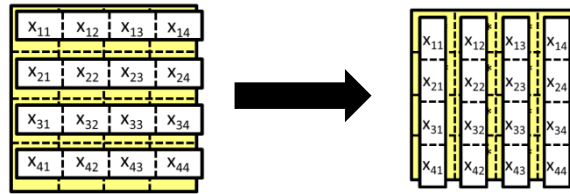




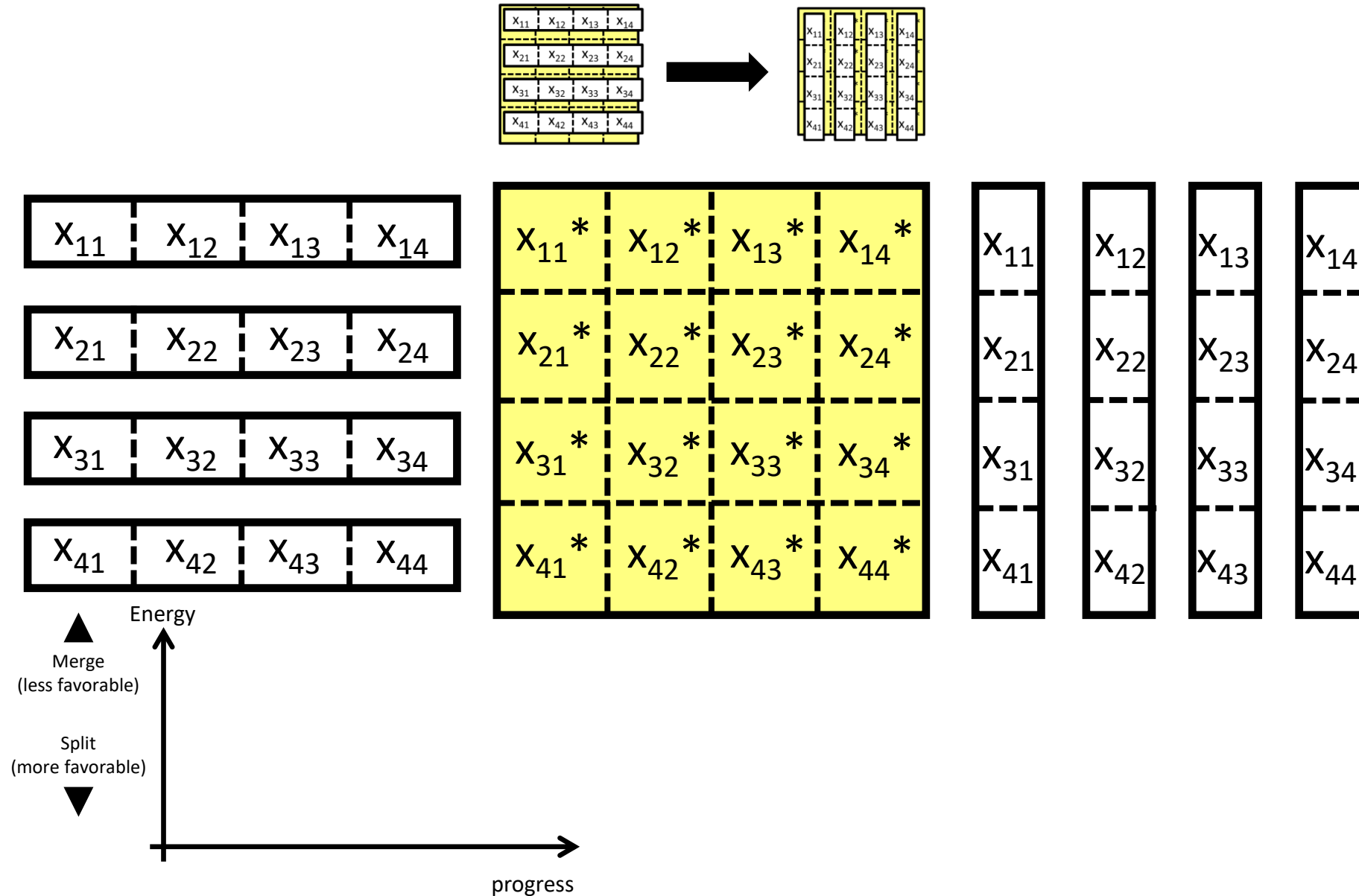
# Large Energy Barriers



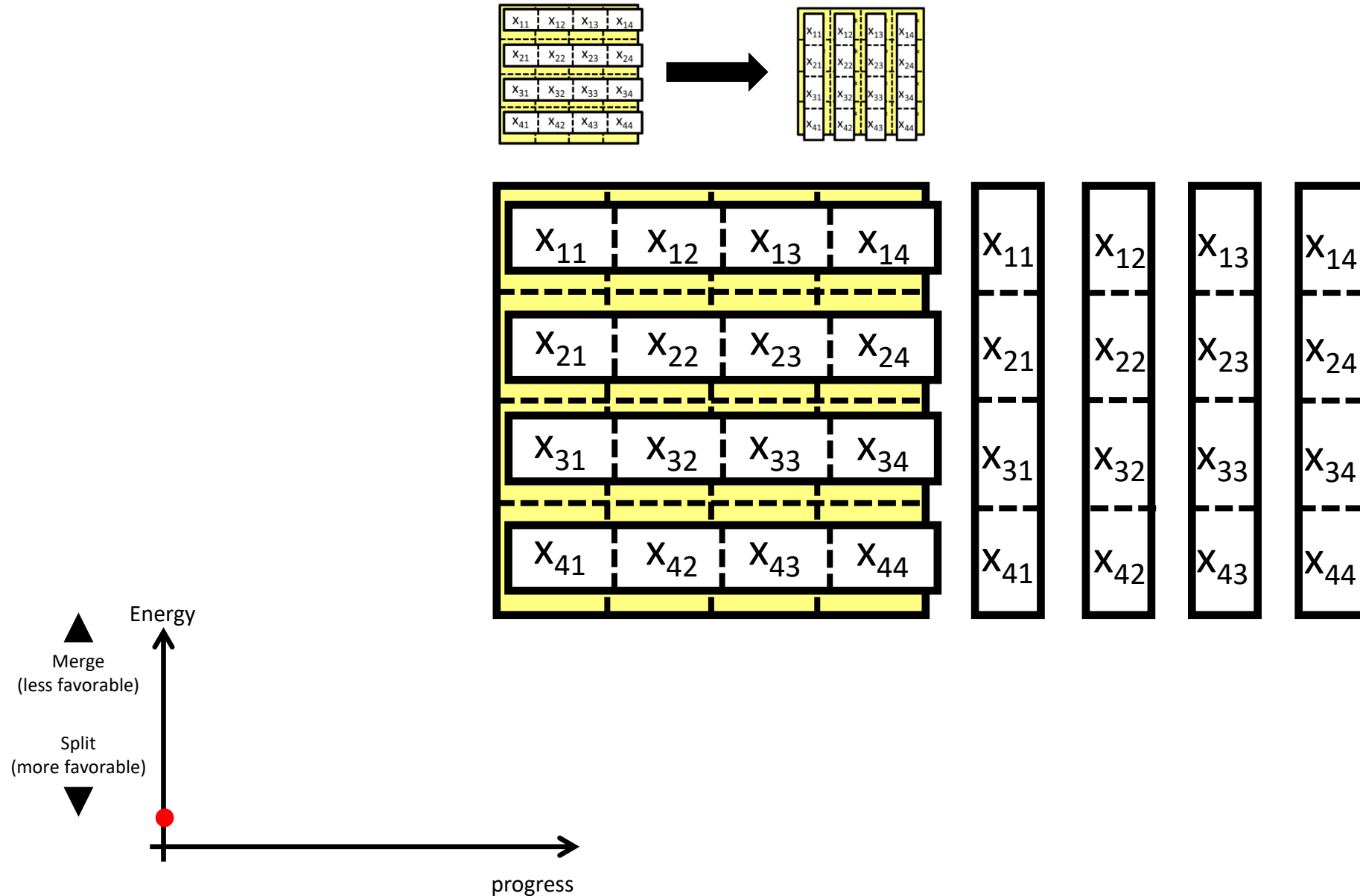
# A Network with a Programmable Energy Barrier



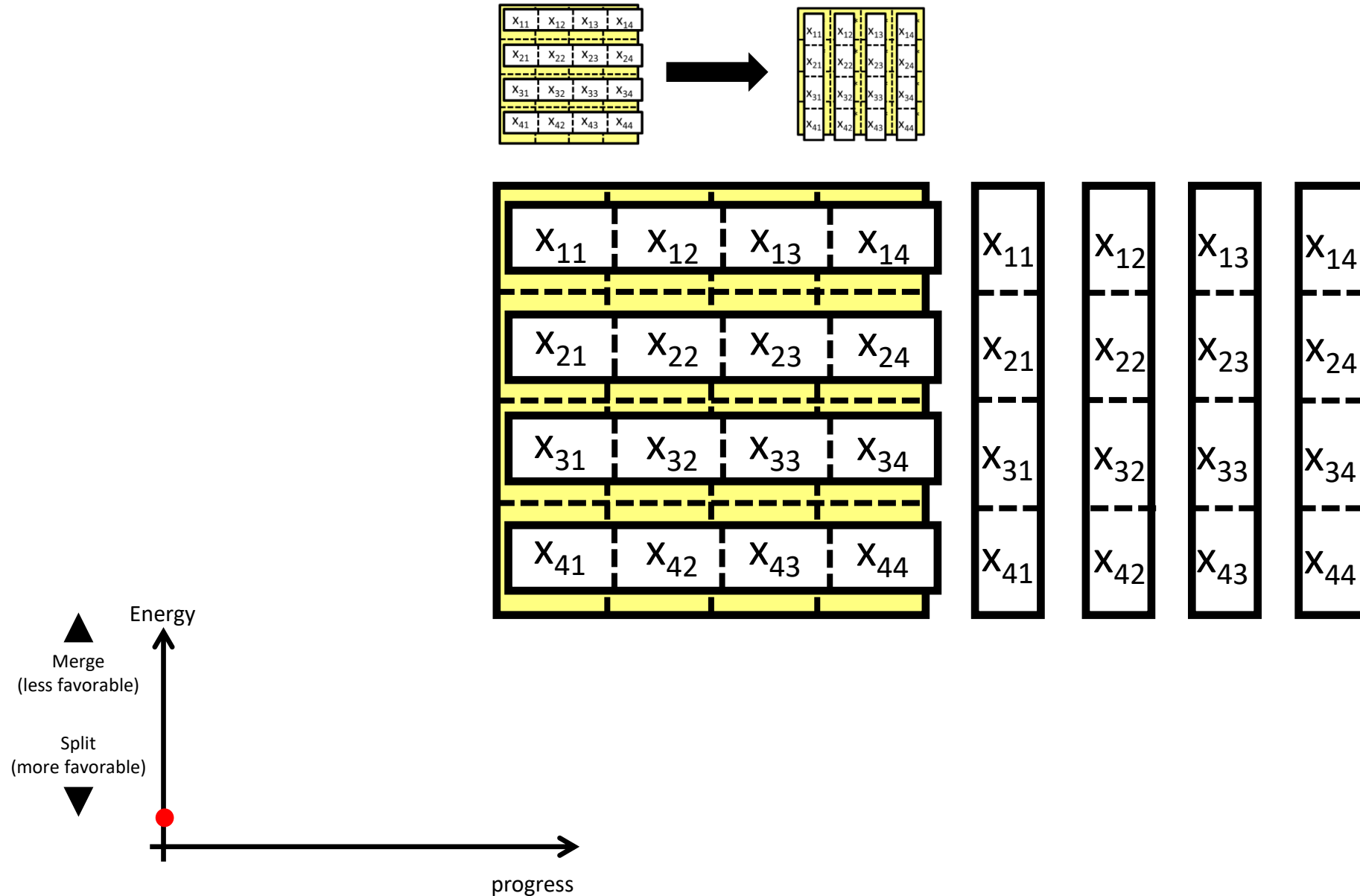
# A Network with a Programmable Energy Barrier



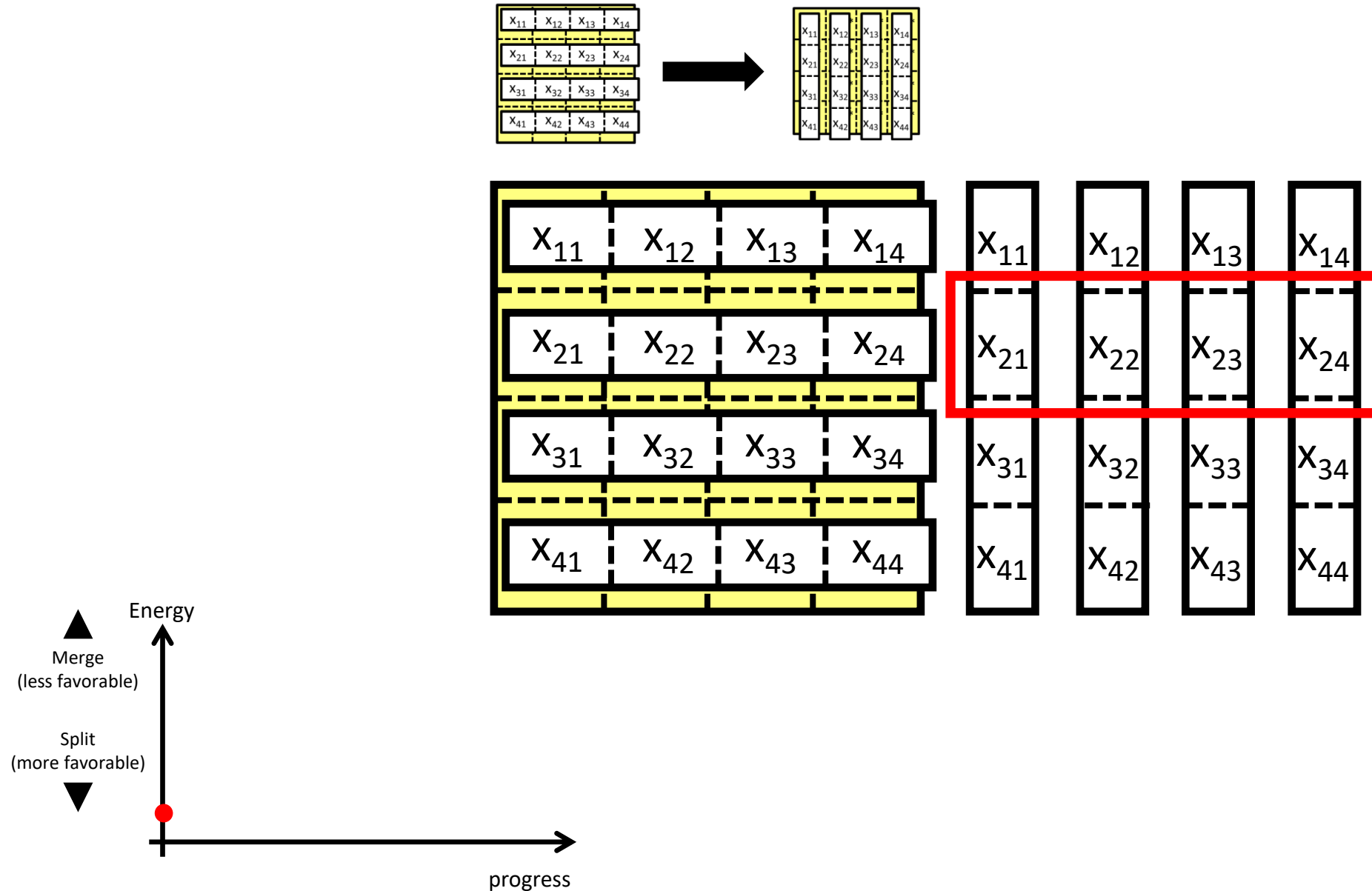
# A Network with a Programmable Energy Barrier



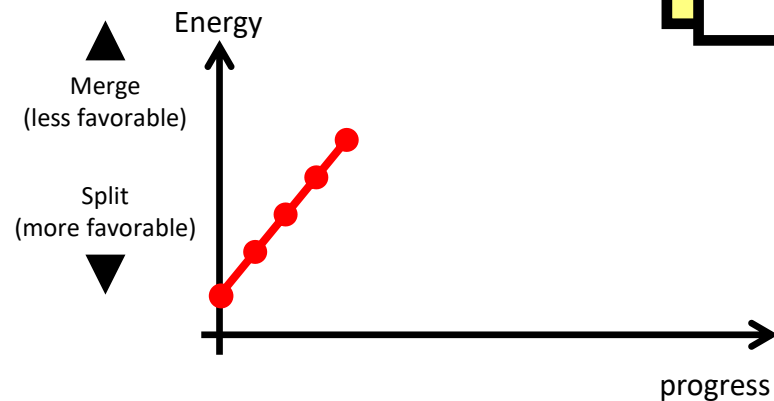
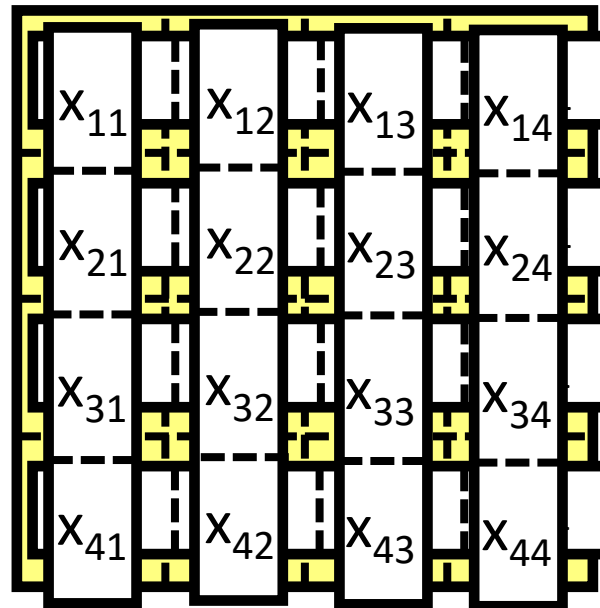
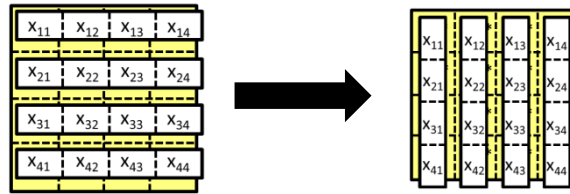
# A Network with a Programmable Energy Barrier



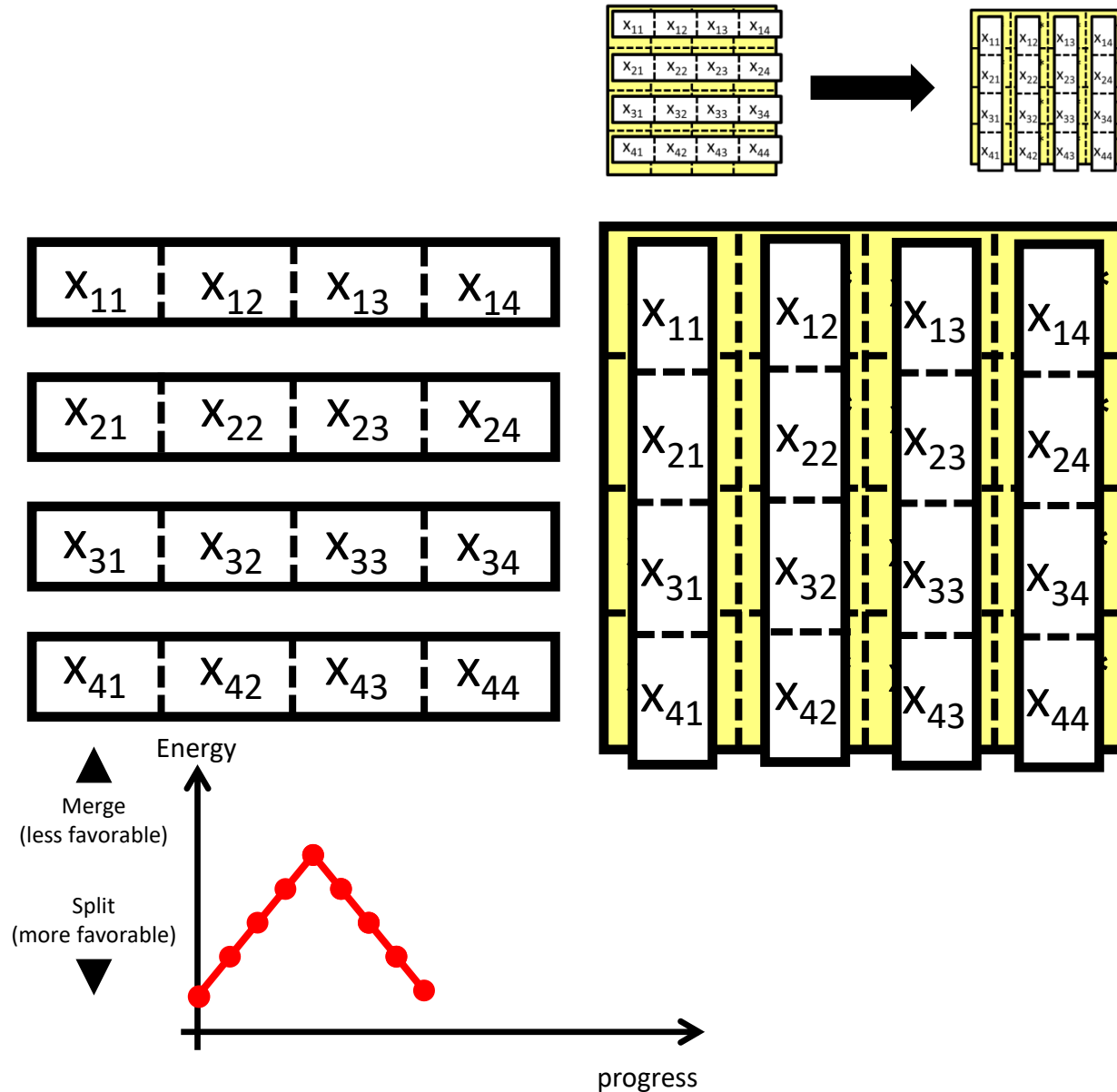
# A Network with a Programmable Energy Barrier



# A Network with a Programmable Energy Barrier

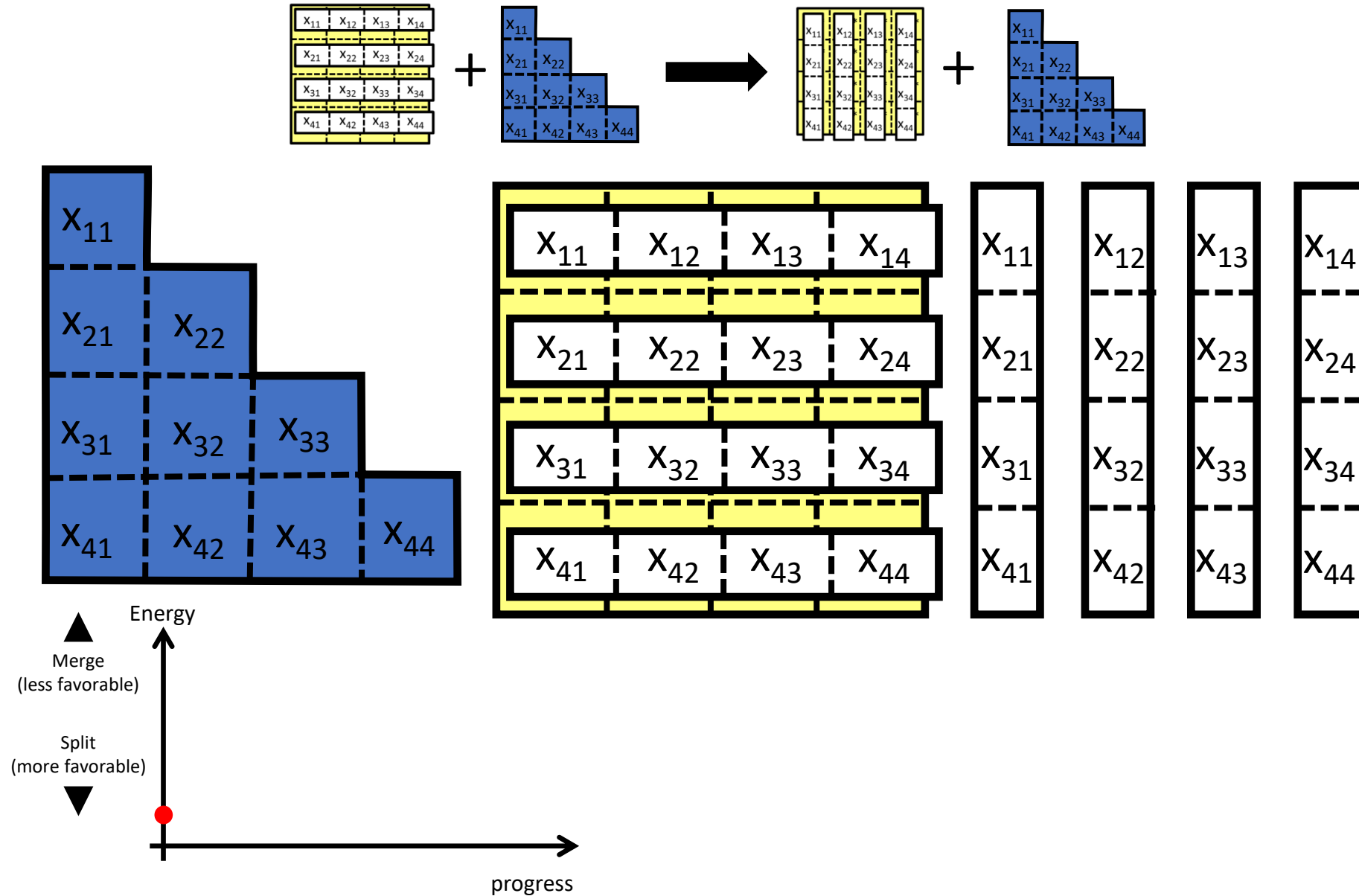


# A Network with a Programmable Energy Barrier

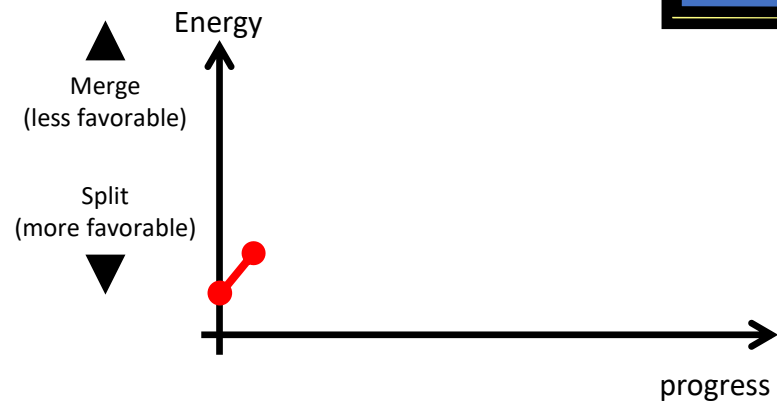
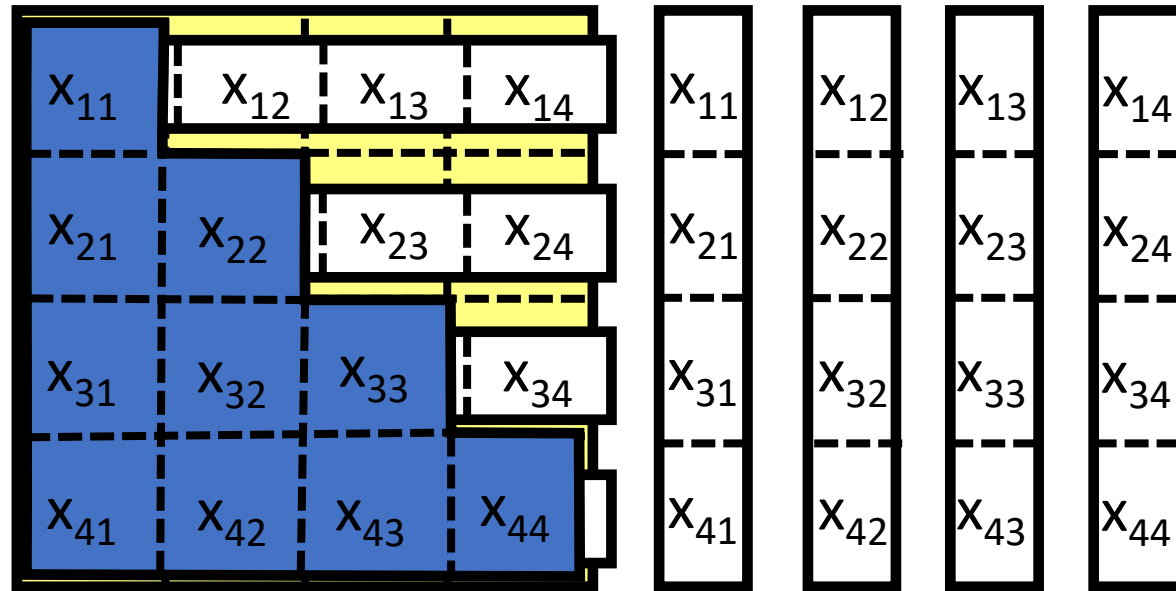
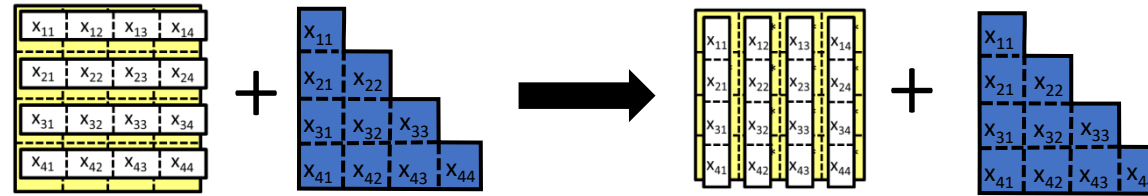




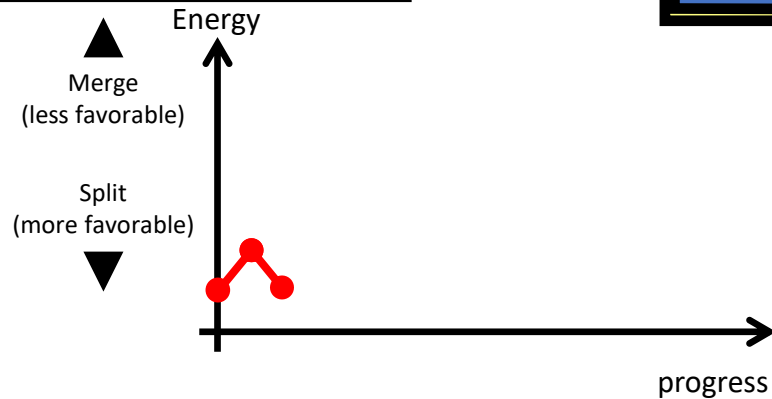
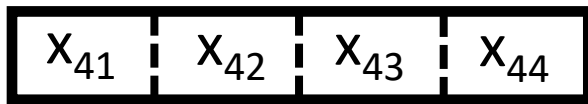
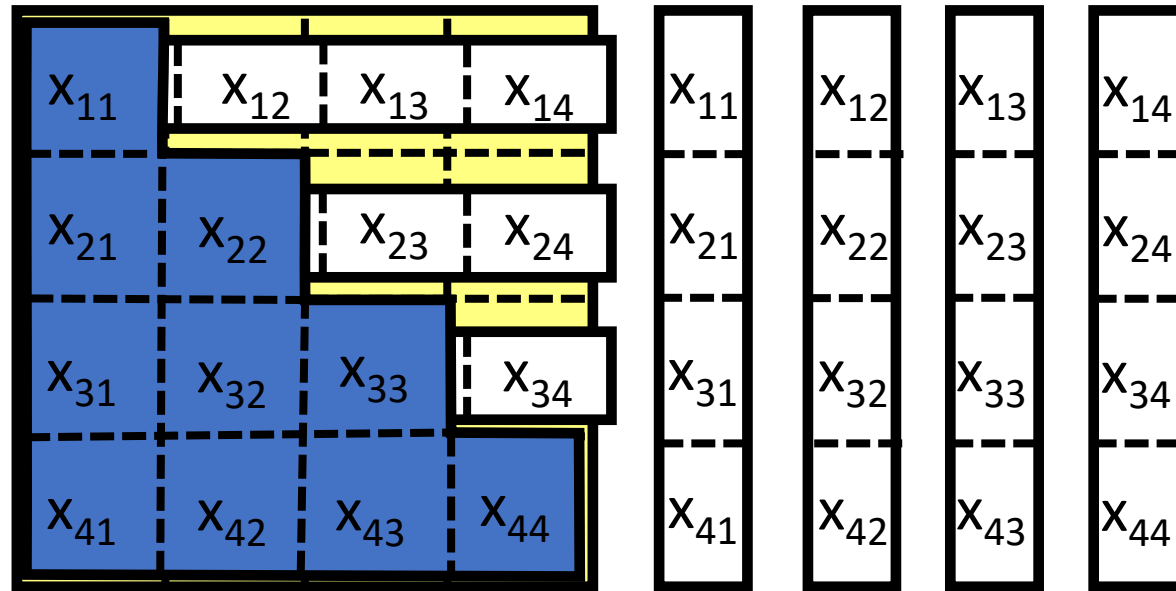
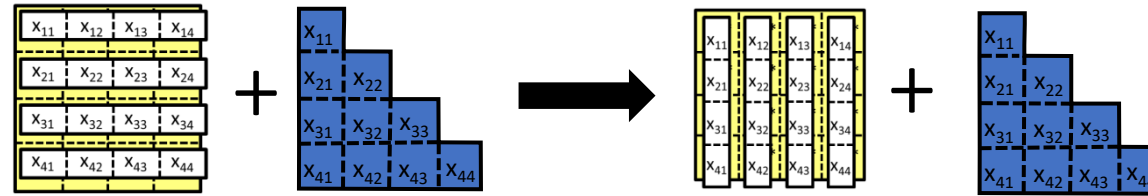
# Catalysis



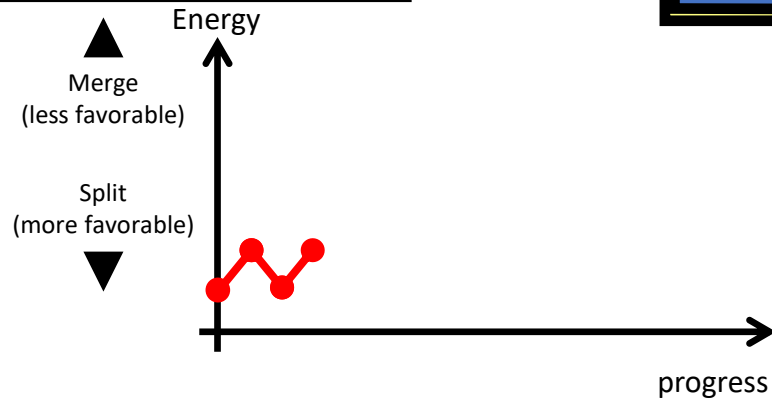
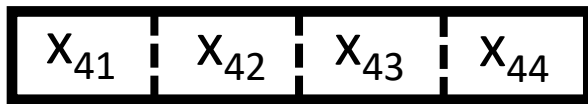
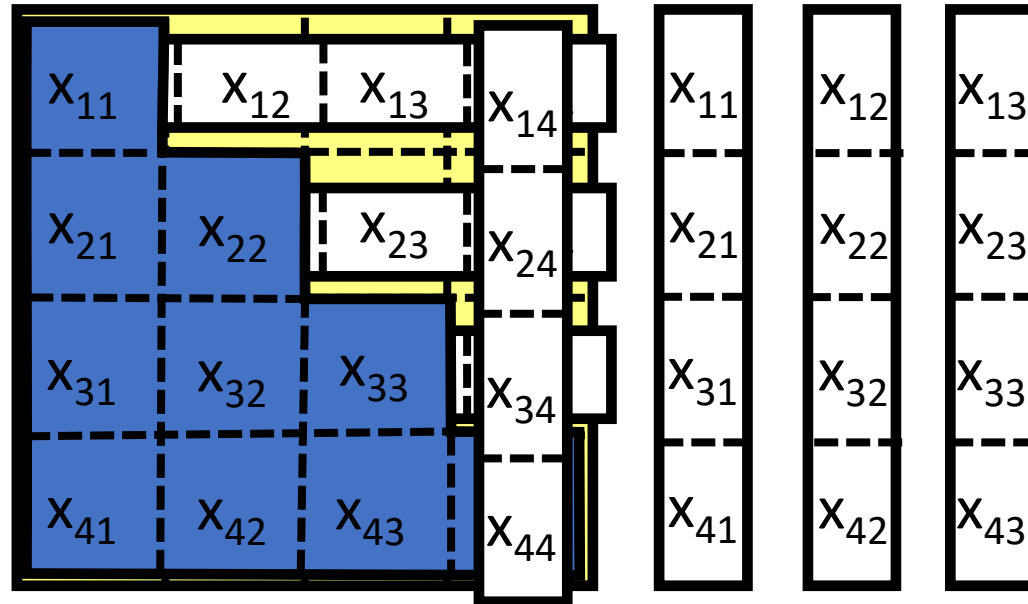
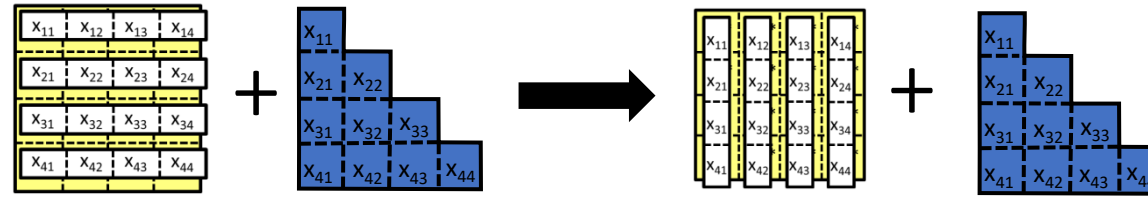
# Catalysis



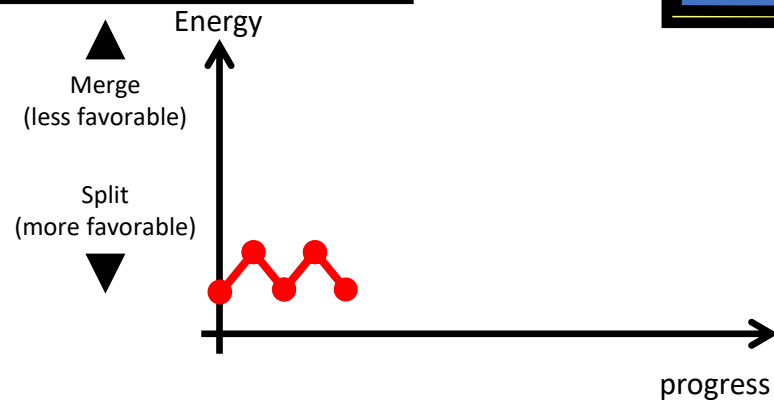
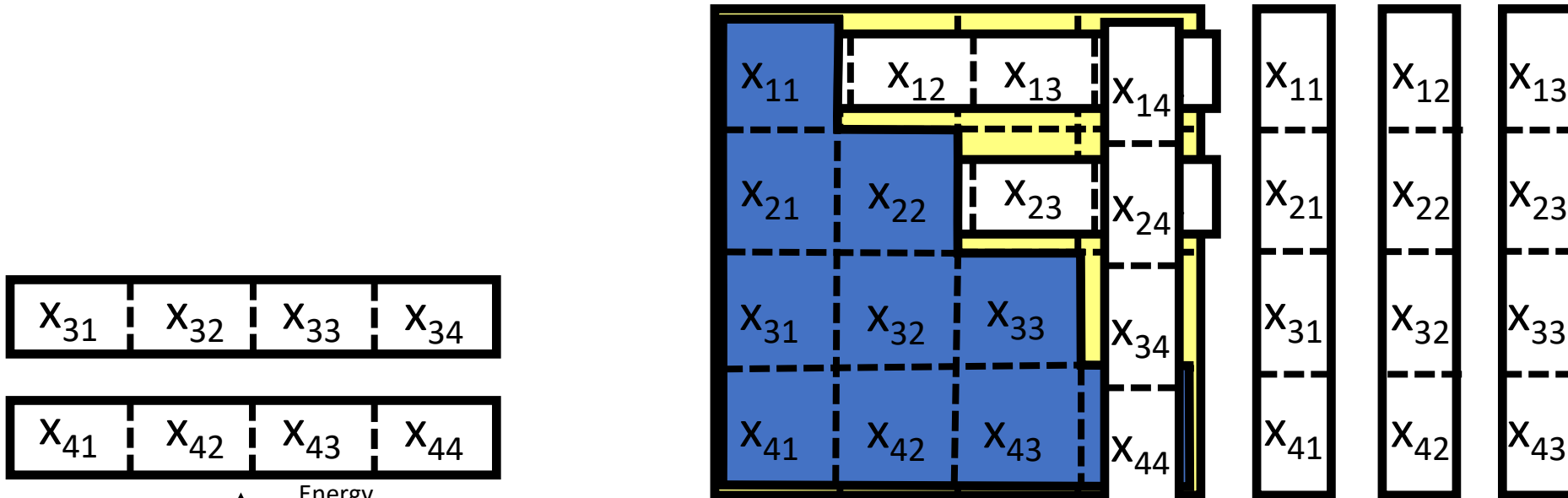
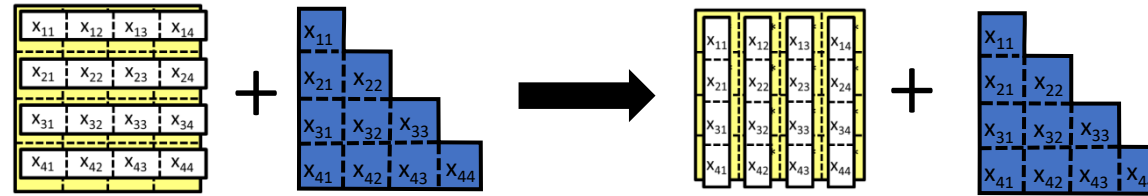
# Catalysis



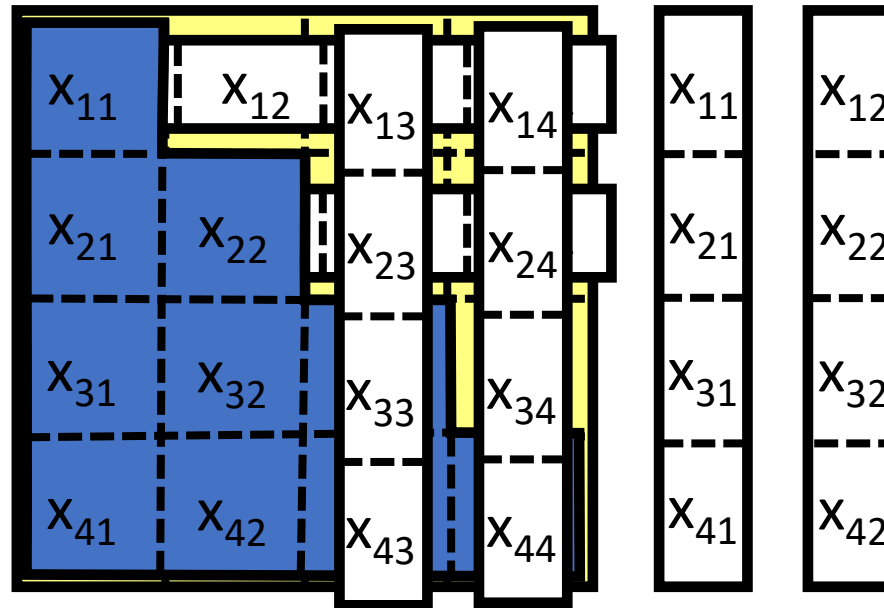
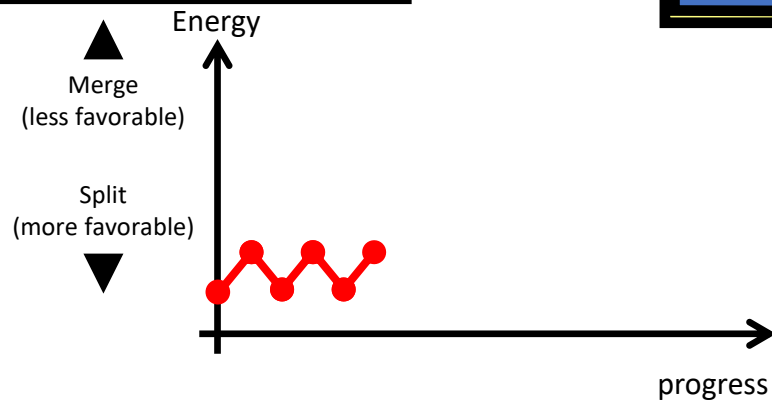
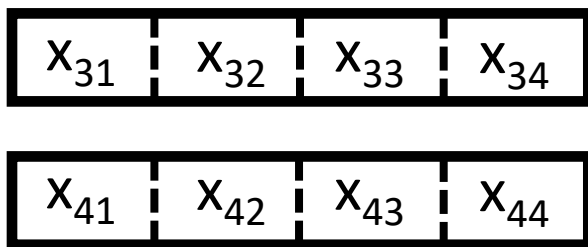
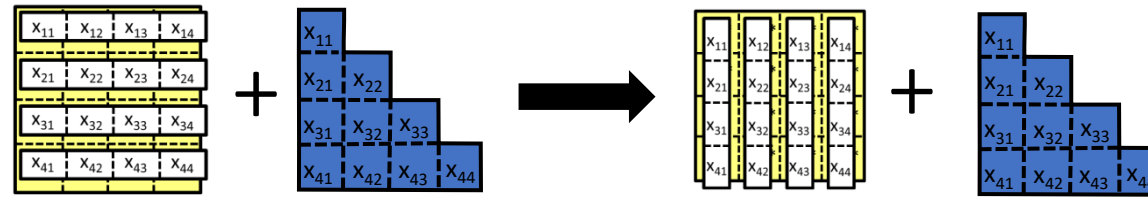
# Catalysis



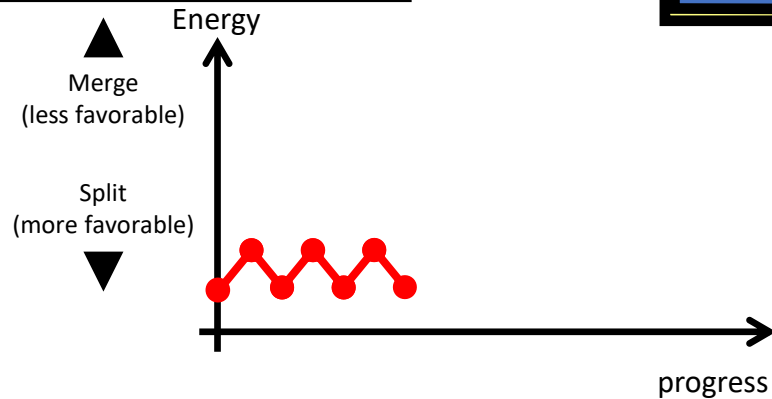
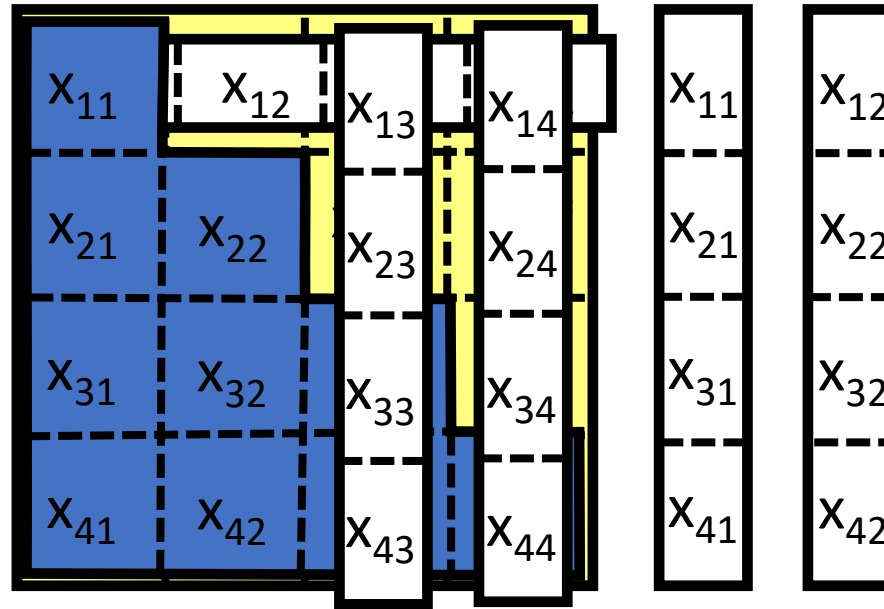
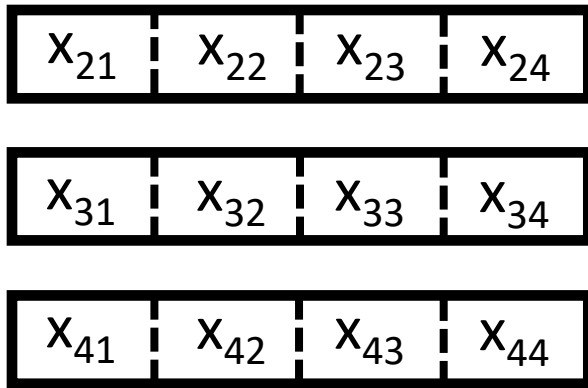
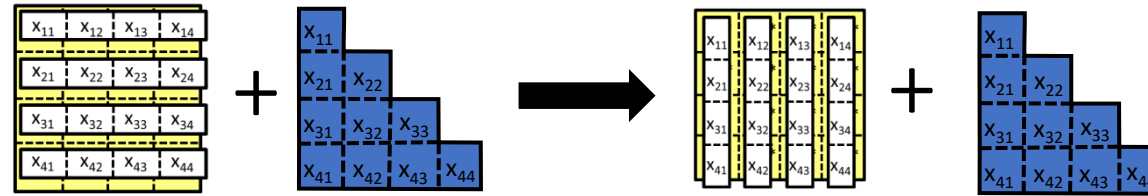
# Catalysis



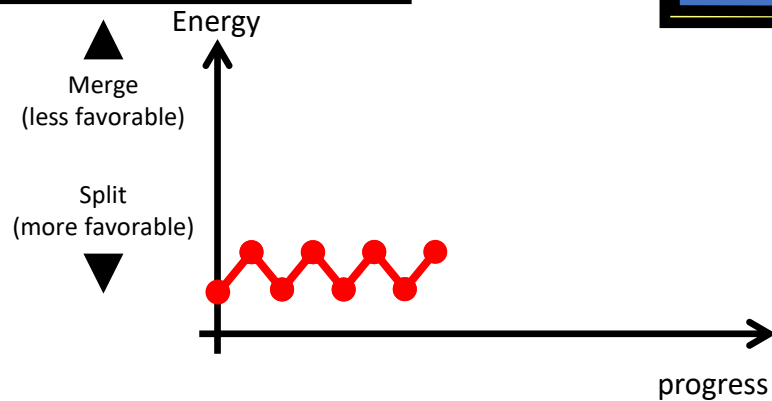
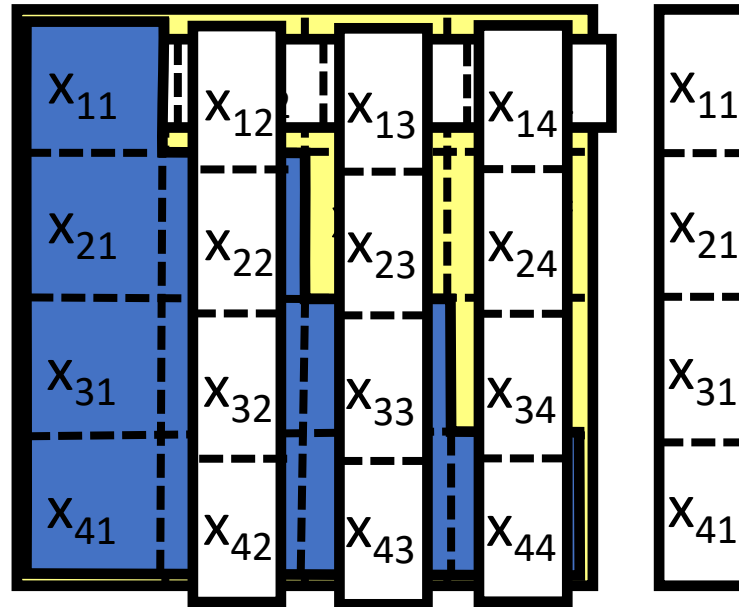
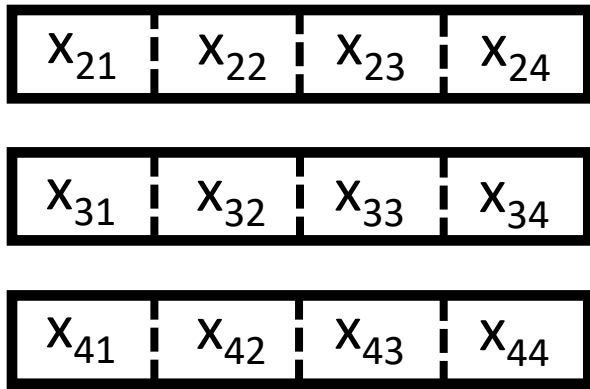
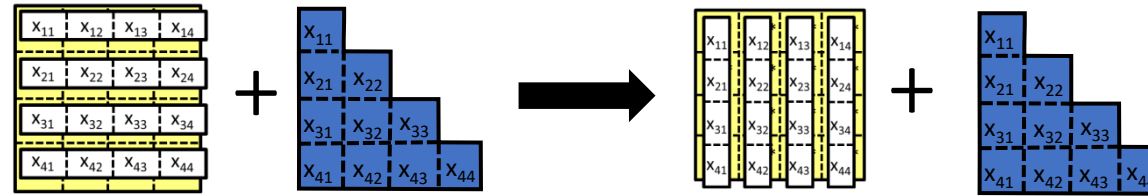
# Catalysis



# Catalysis

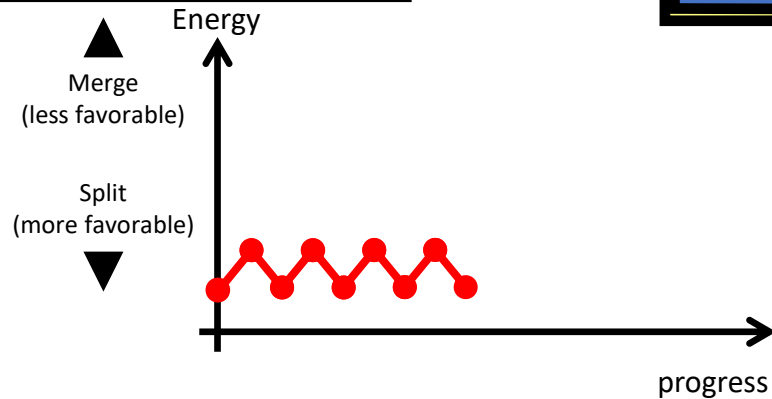
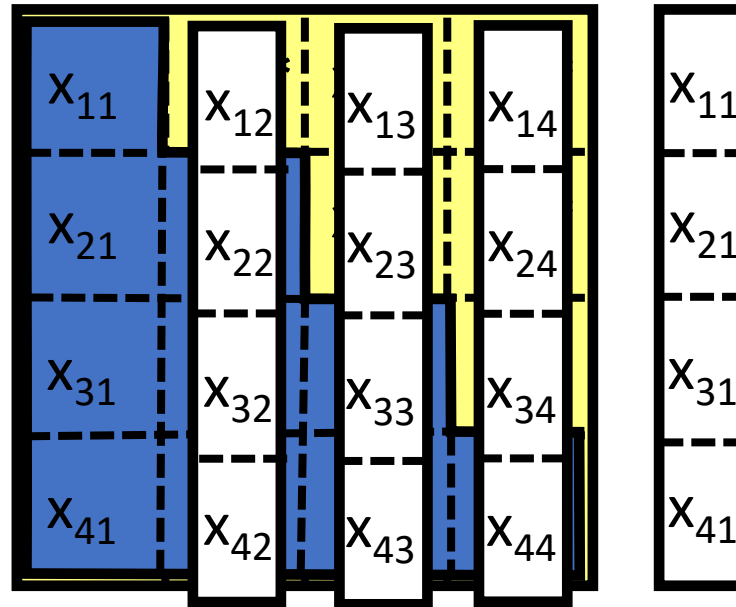
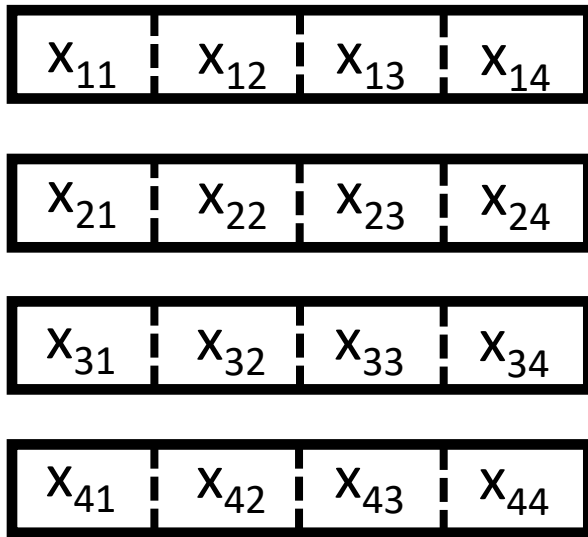
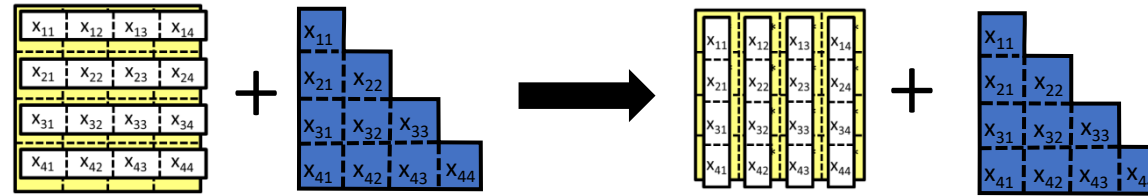


# Catalysis

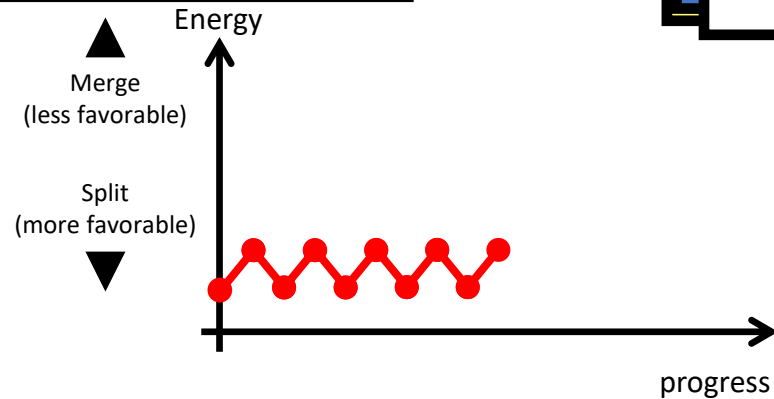
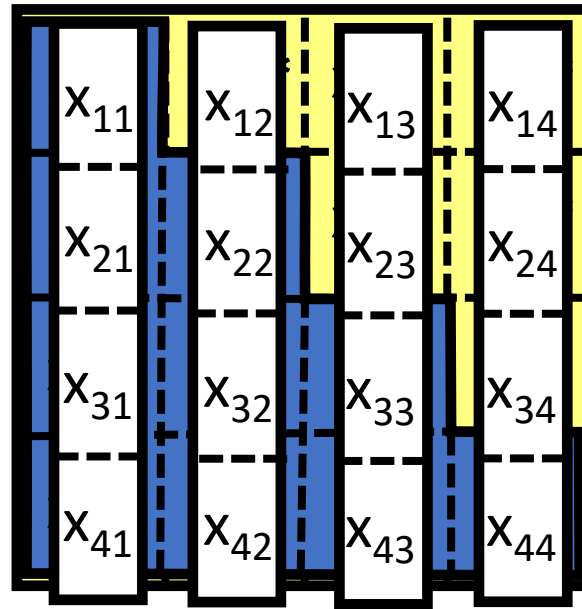
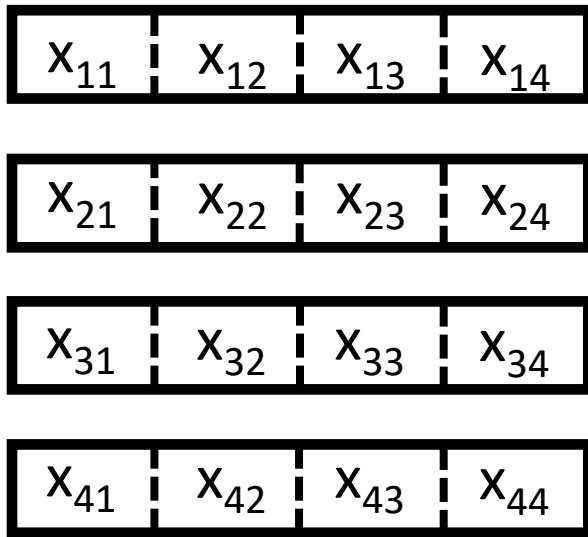
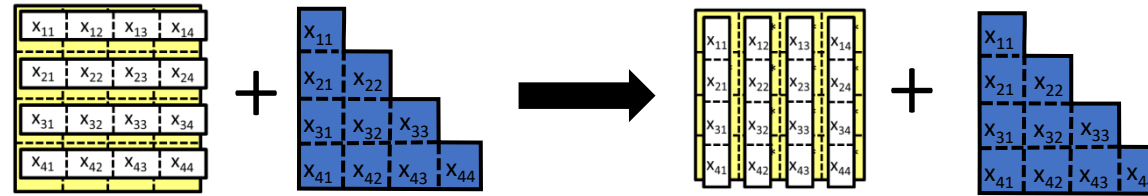




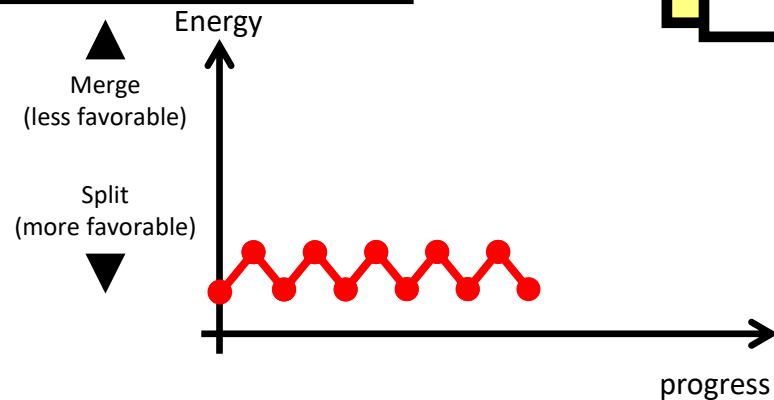
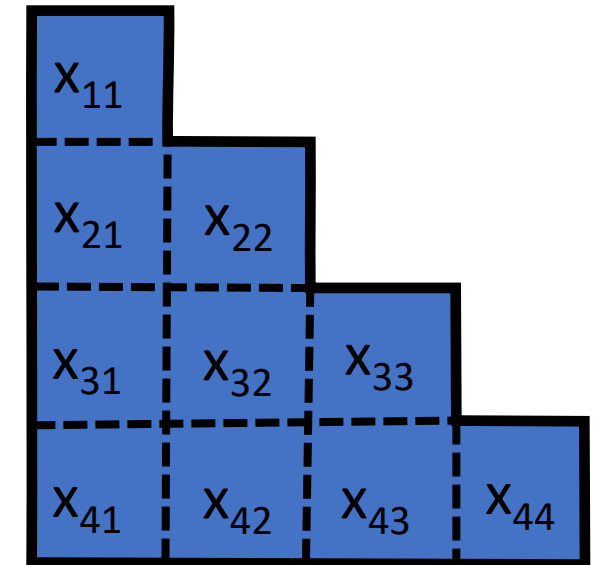
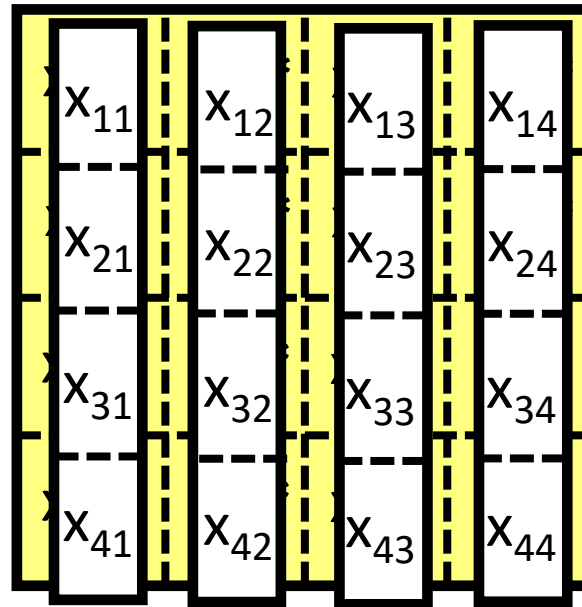
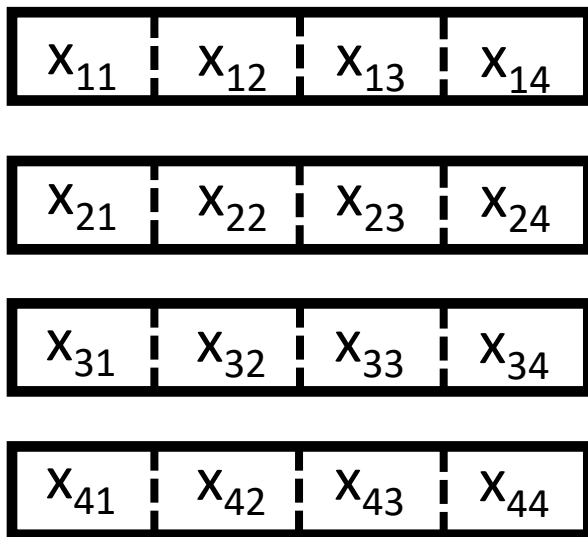
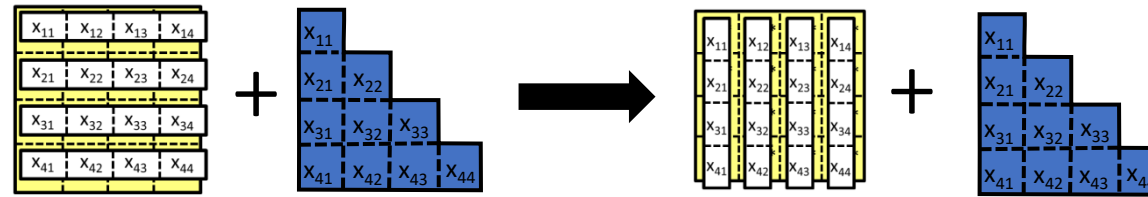
# Catalysis



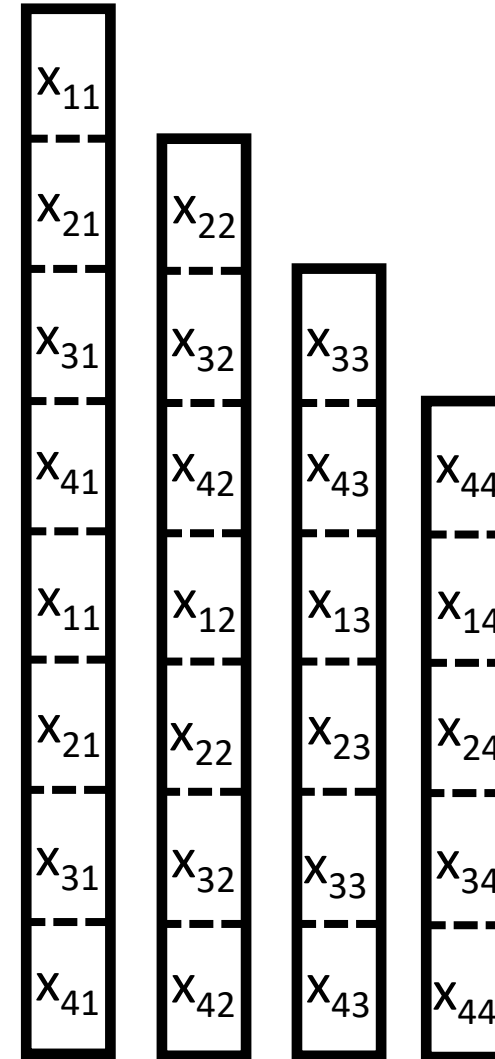
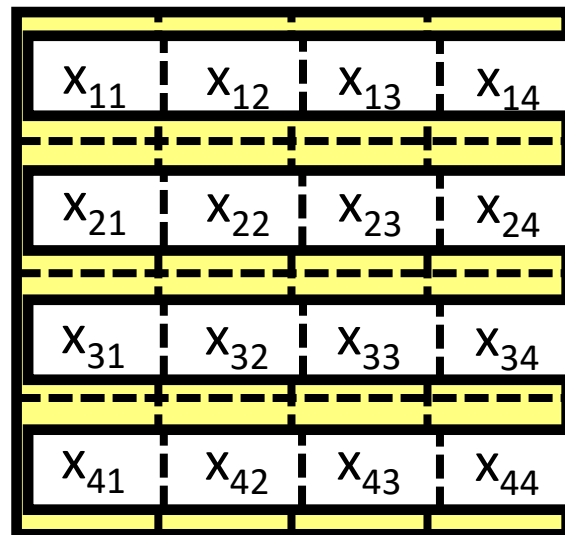
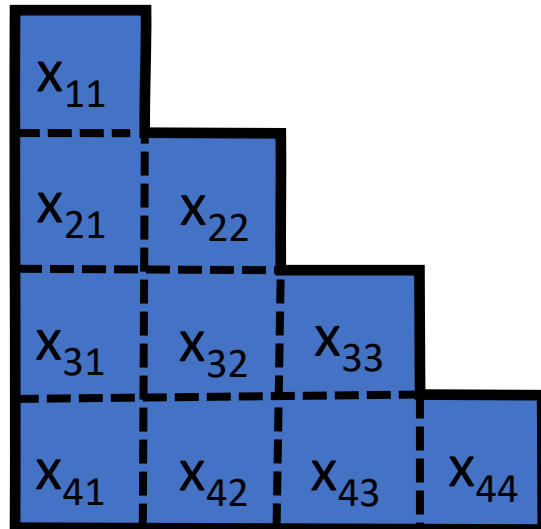
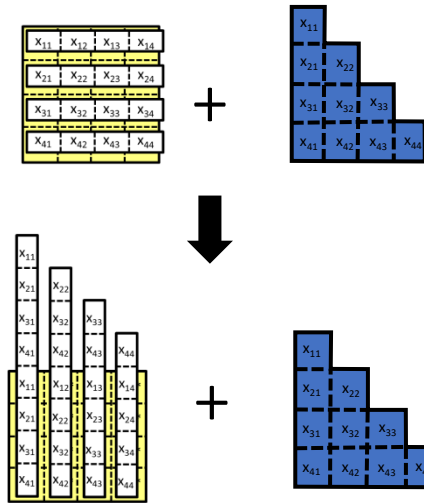
# Catalysis



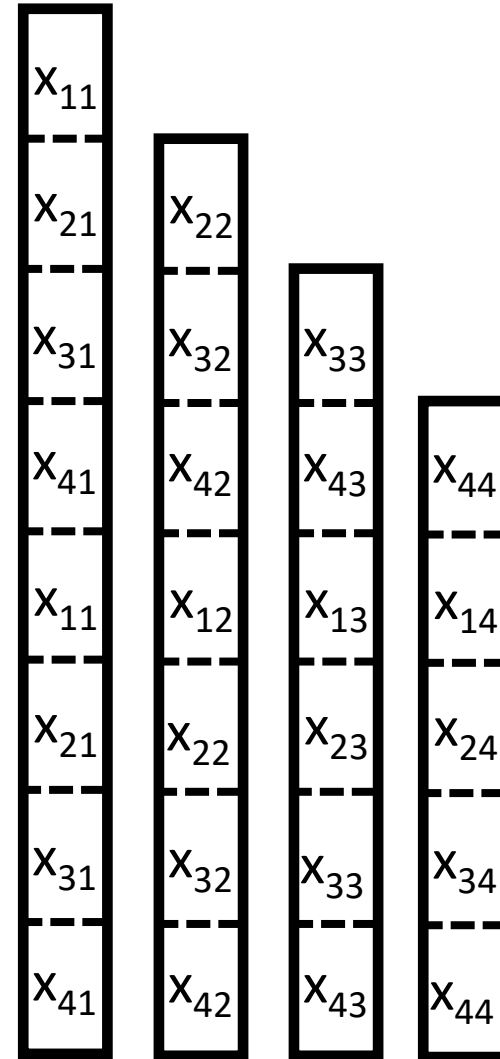
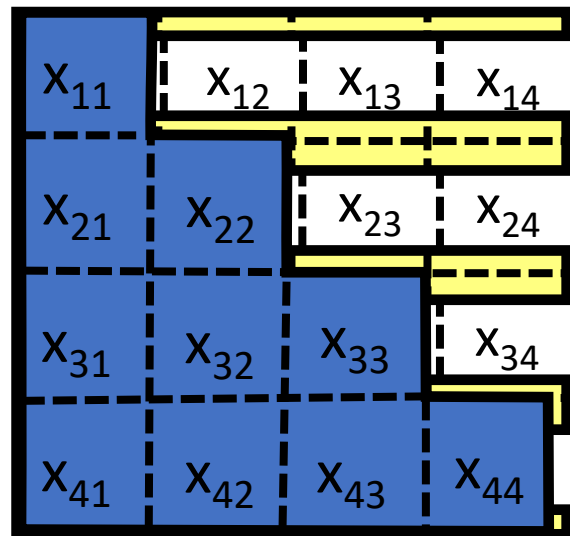
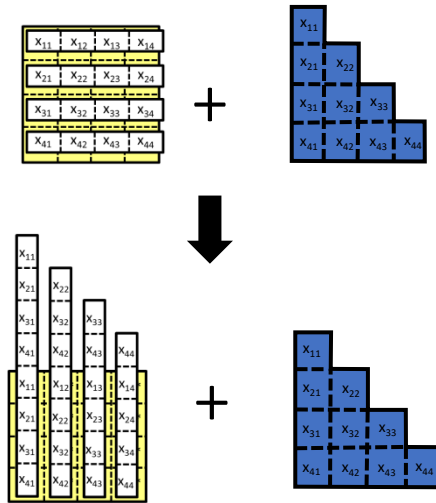
# Catalysis



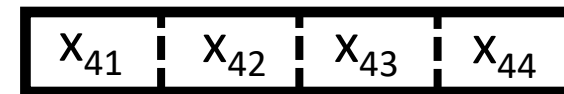
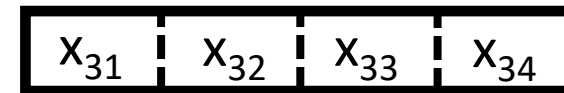
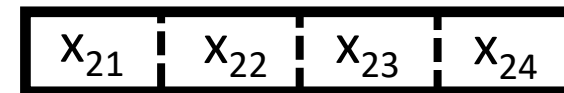
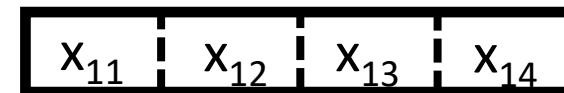
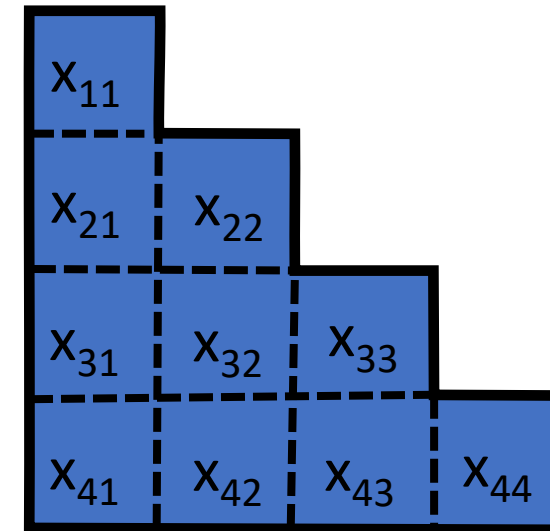
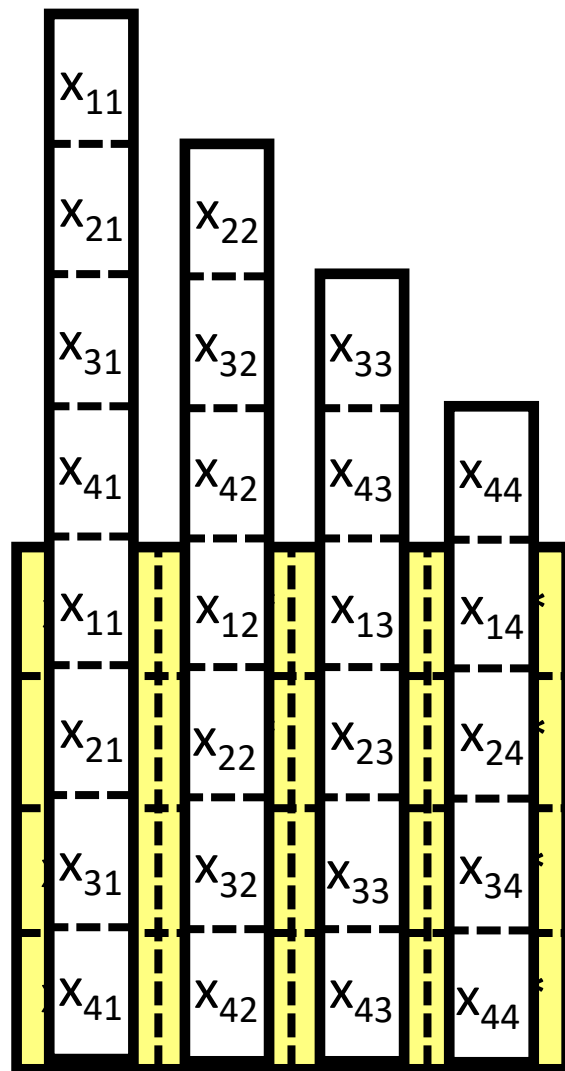
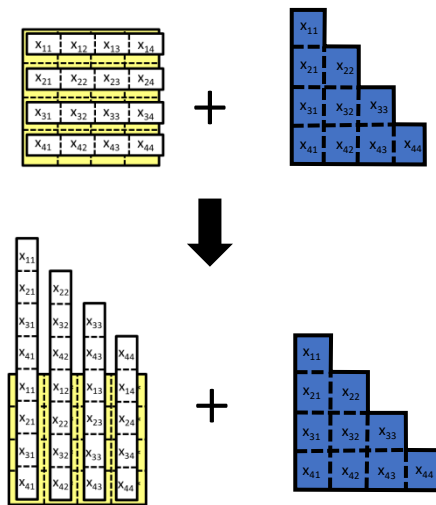
# Autocatalysis



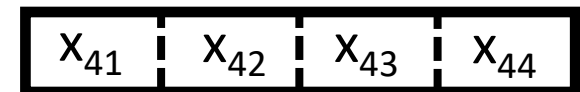
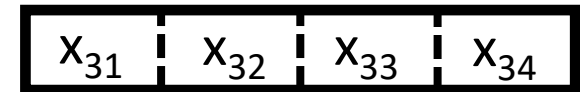
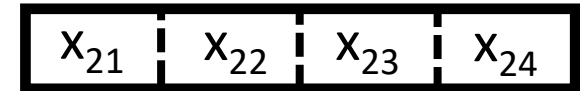
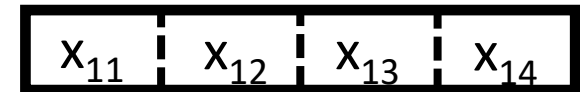
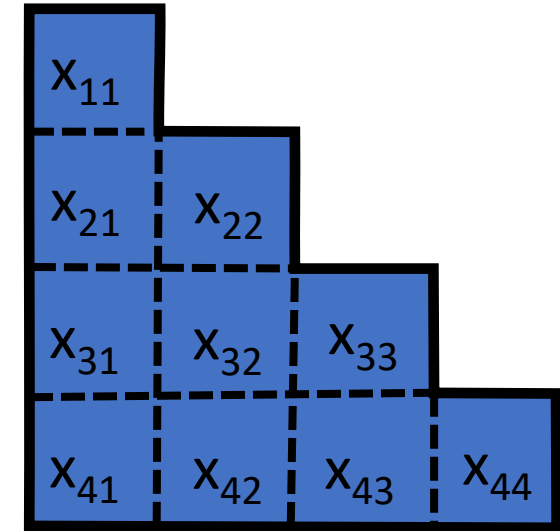
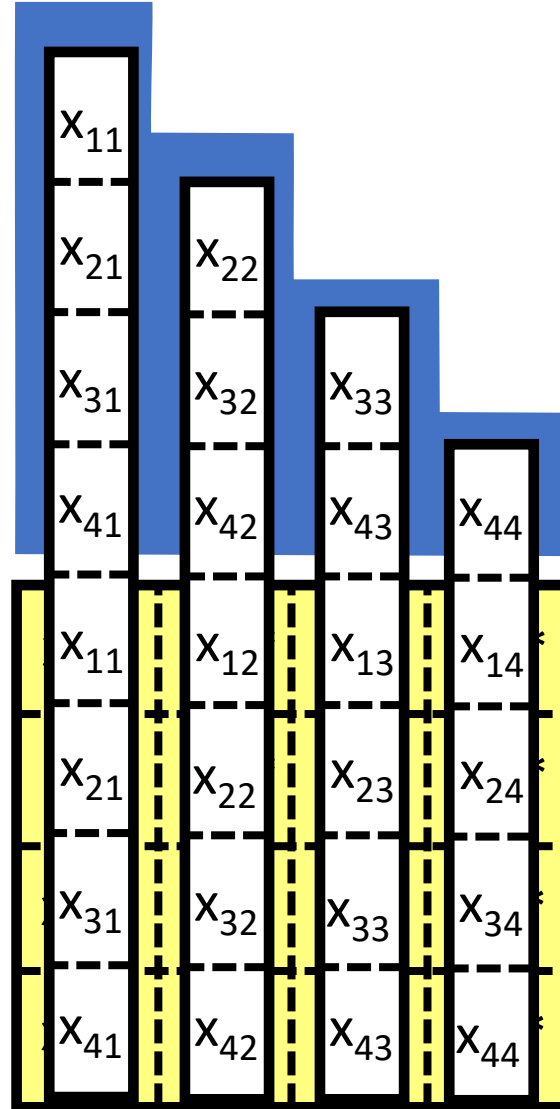
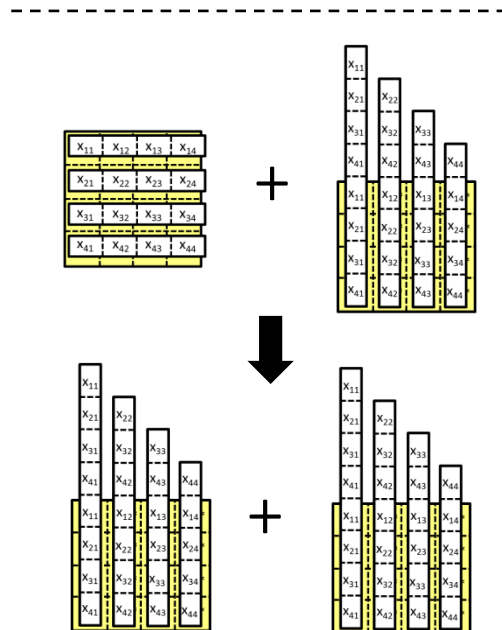
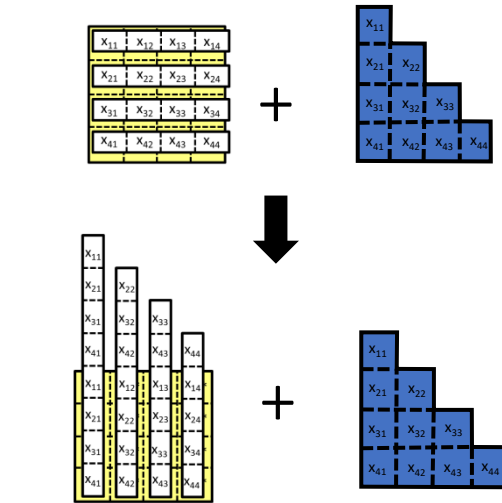
# Autocatalysis



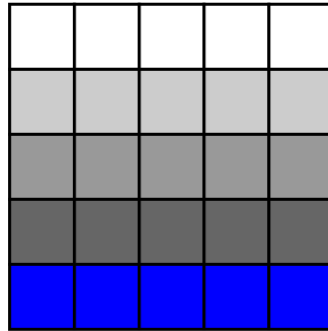
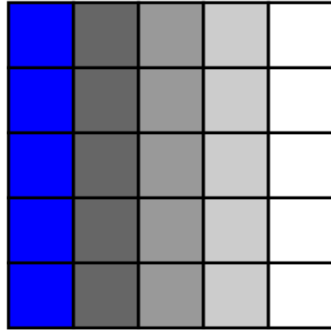
# Autocatalysis



# Autocatalysis

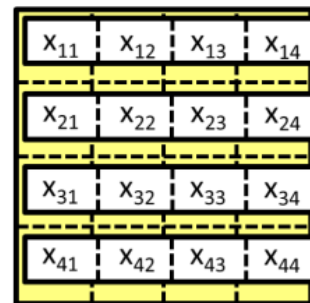
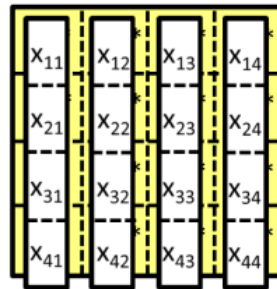
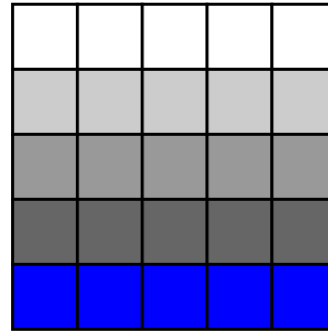
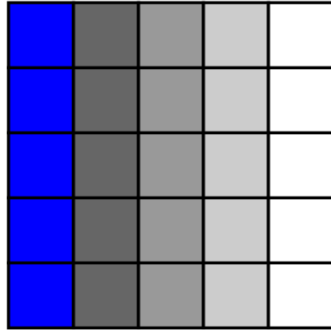


# Multiple Stable Configurations

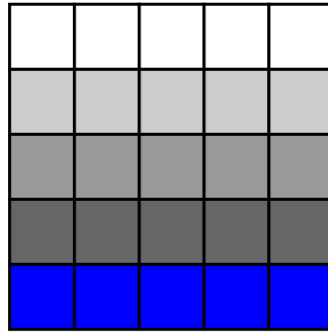
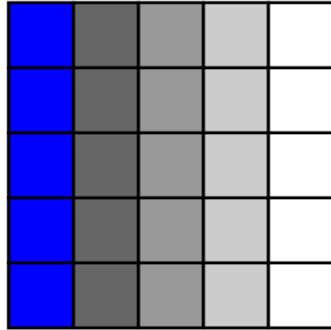




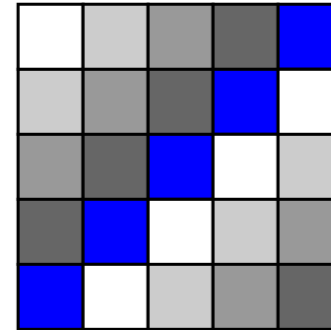
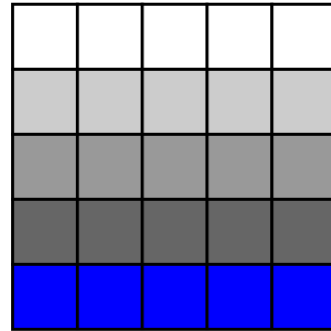
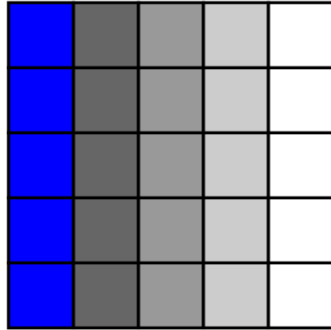
# Multiple Stable Configurations



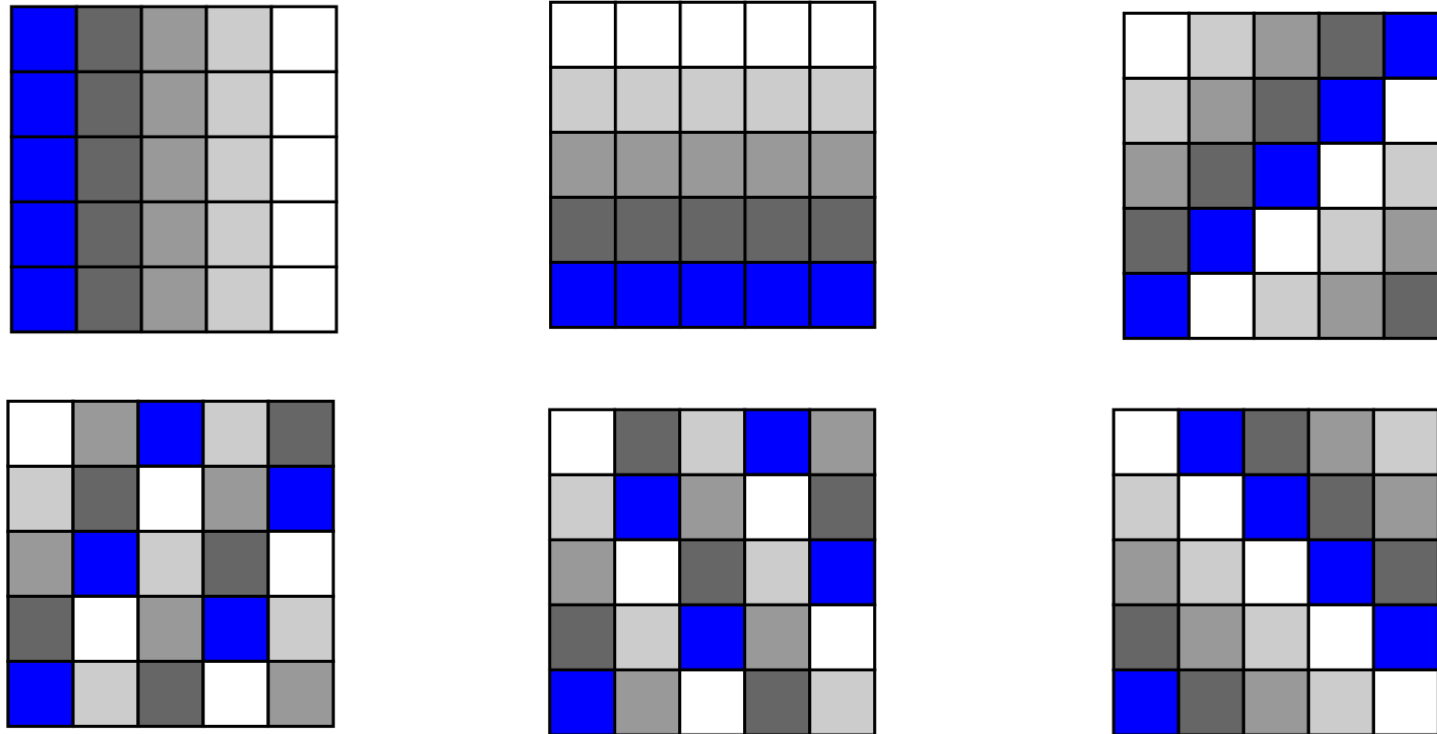
# Multiple Stable Configurations



# Multiple Stable Configurations

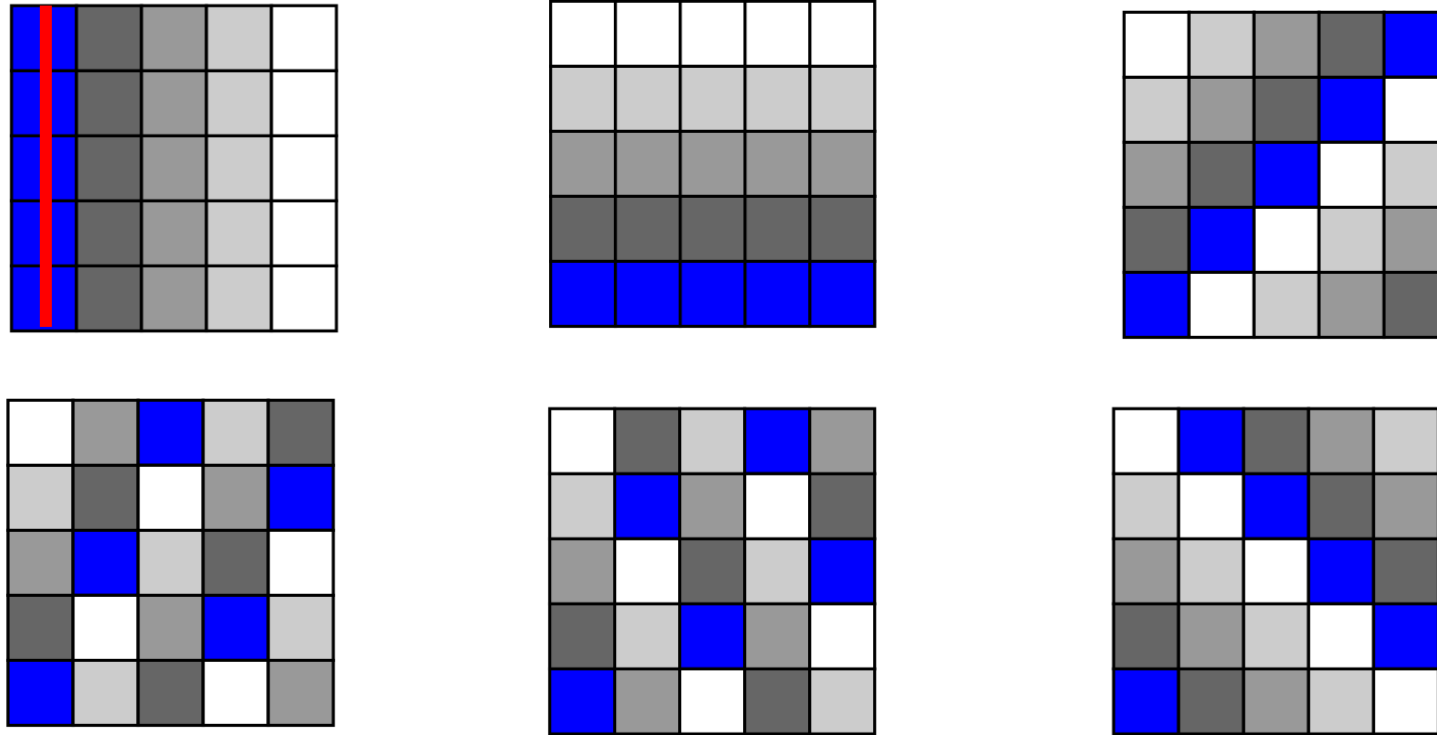


# Multiple Stable Configurations



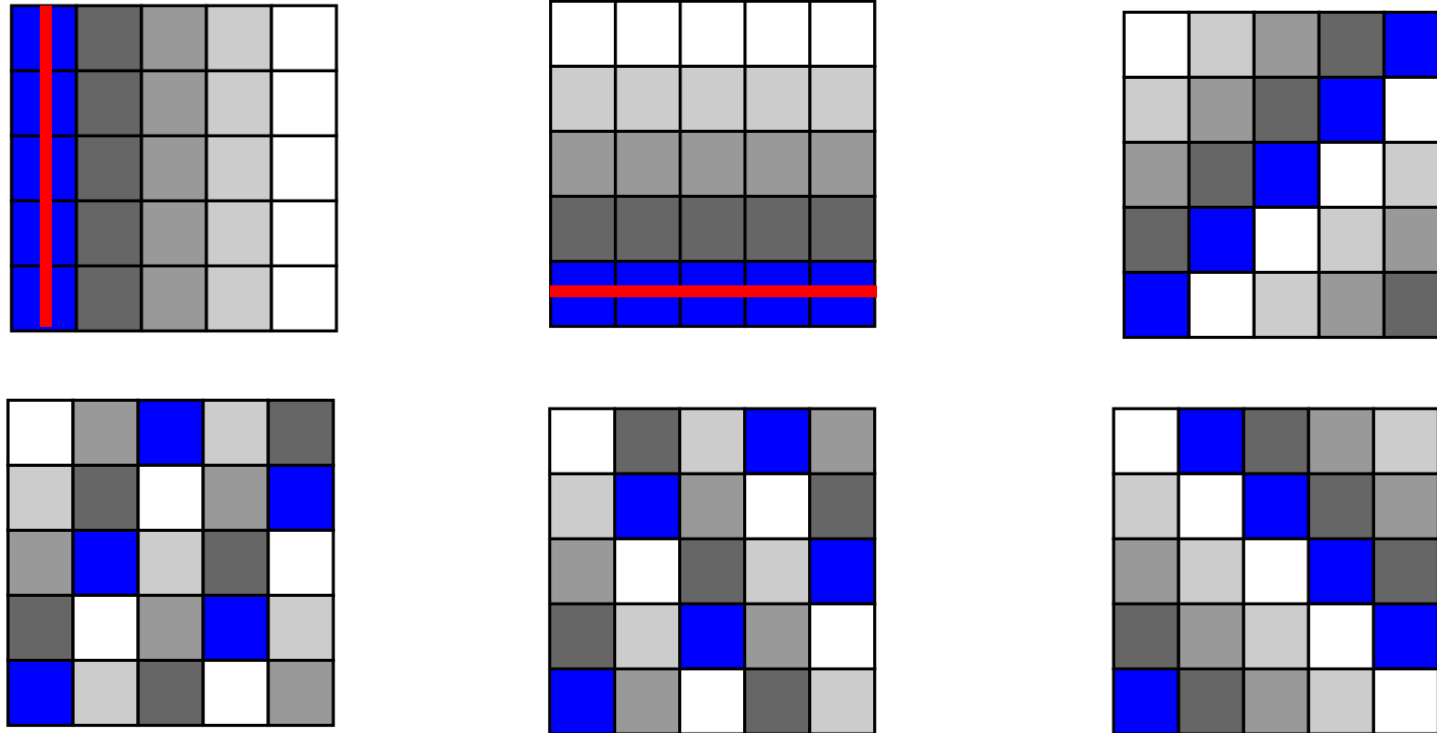
For a grid of prime size  $n \times n$ , there can be at most  $n+1$  different stable configurations with barrier  $n$  to pass between any of them

# Multiple Stable Configurations



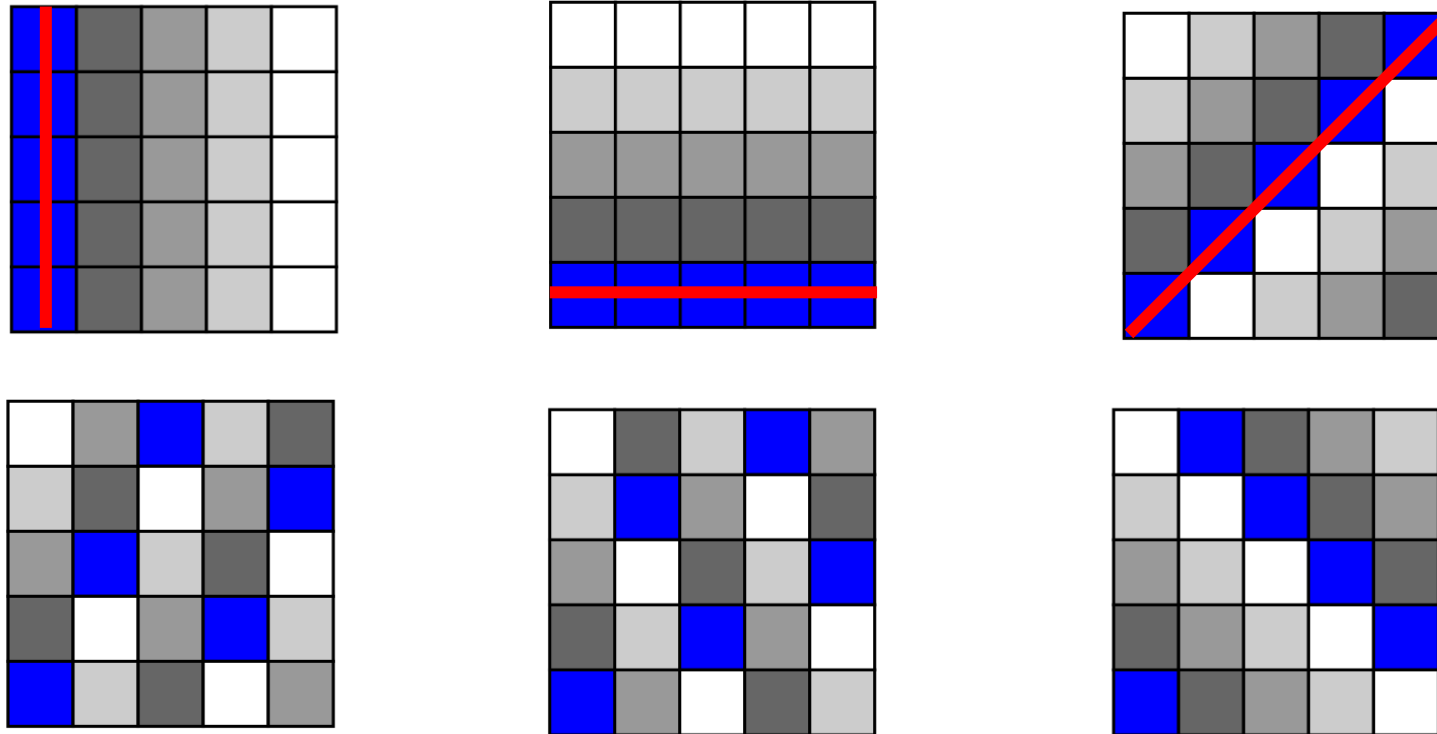
For a grid of prime size  $n \times n$ , there can be at most  $n+1$  different stable configurations with barrier  $n$  to pass between any of them

# Multiple Stable Configurations



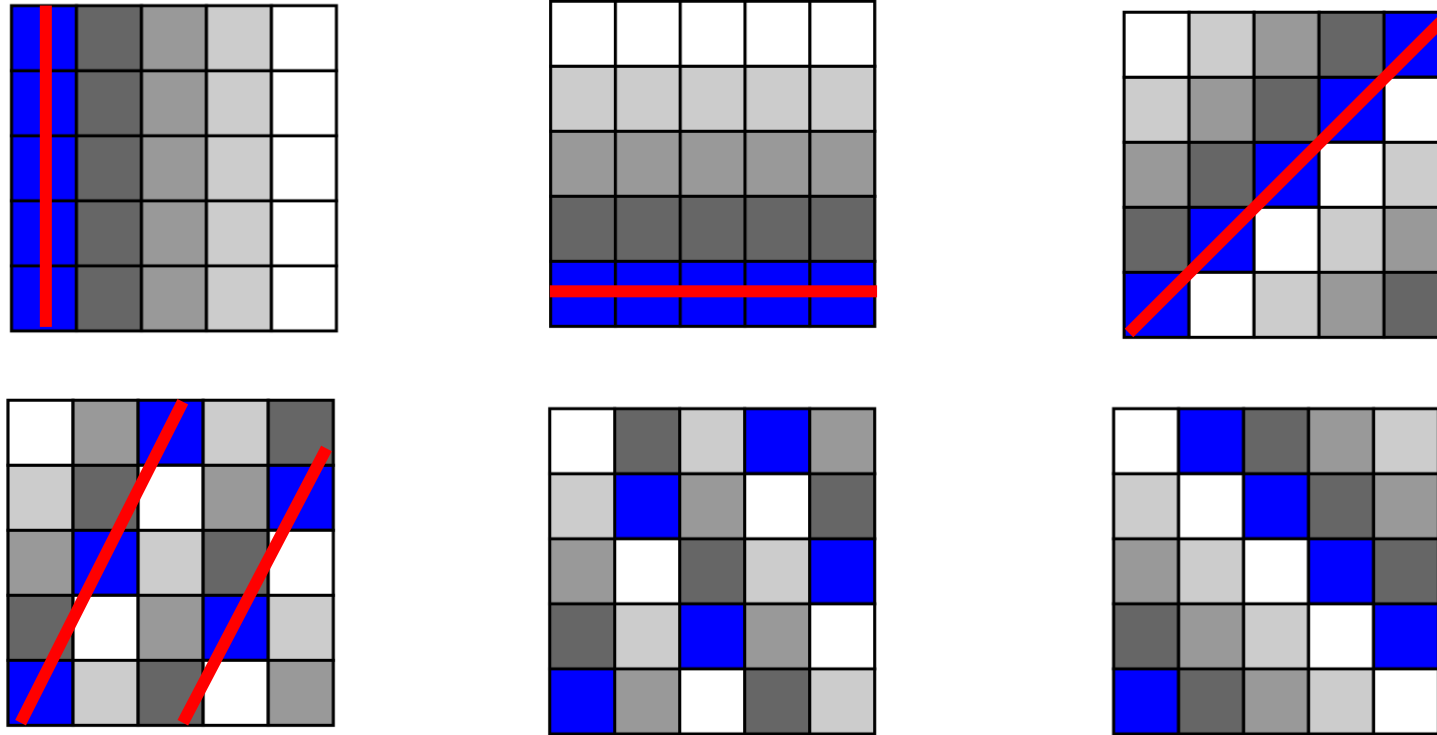
For a grid of prime size  $n \times n$ , there can be at most  $n+1$  different stable configurations with barrier  $n$  to pass between any of them

# Multiple Stable Configurations



For a grid of prime size  $n \times n$ , there can be at most  $n+1$  different stable configurations with barrier  $n$  to pass between any of them

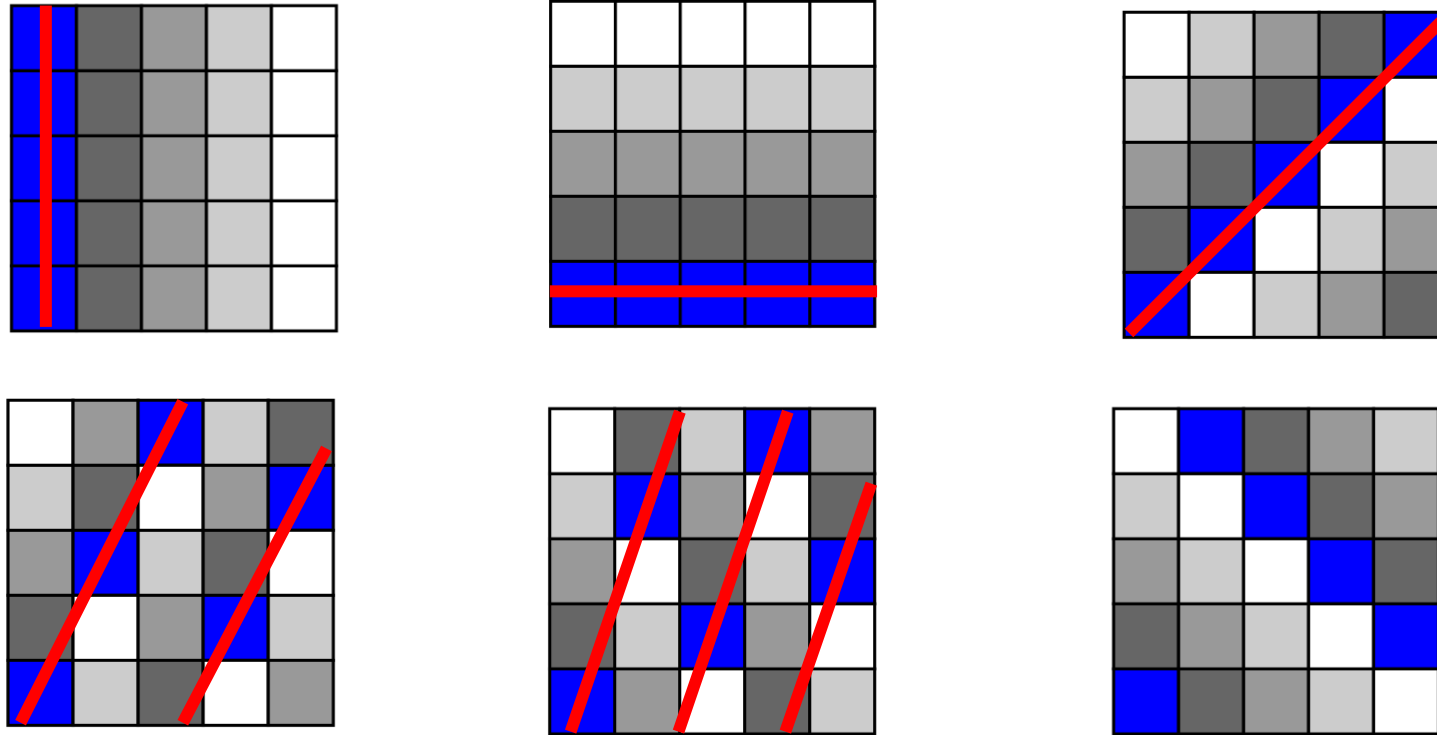
# Multiple Stable Configurations



For a grid of prime size  $n \times n$ , there can be at most  $n+1$  different stable configurations with barrier  $n$  to pass between any of them

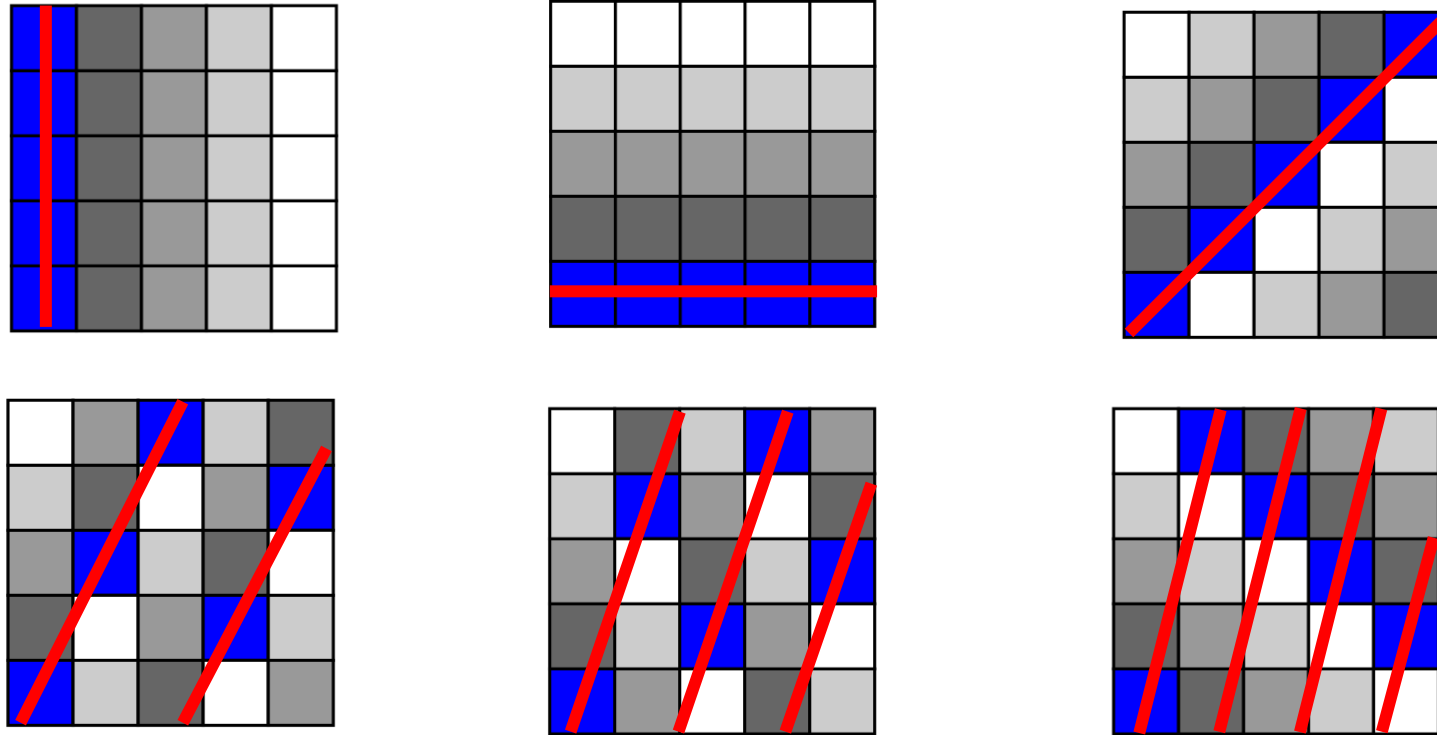


# Multiple Stable Configurations



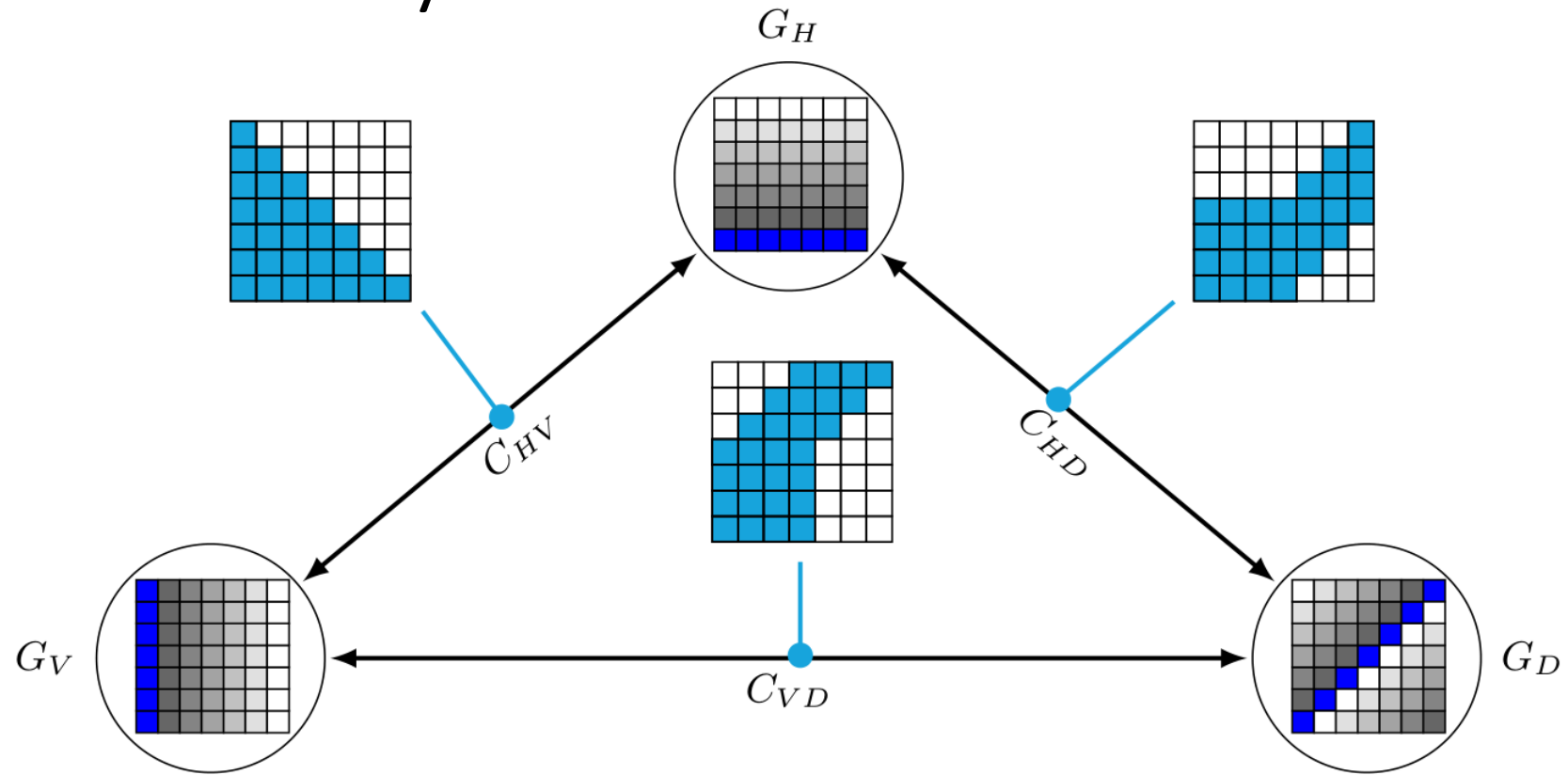
For a grid of prime size  $n \times n$ , there can be at most  $n+1$  different stable configurations with barrier  $n$  to pass between any of them

# Multiple Stable Configurations

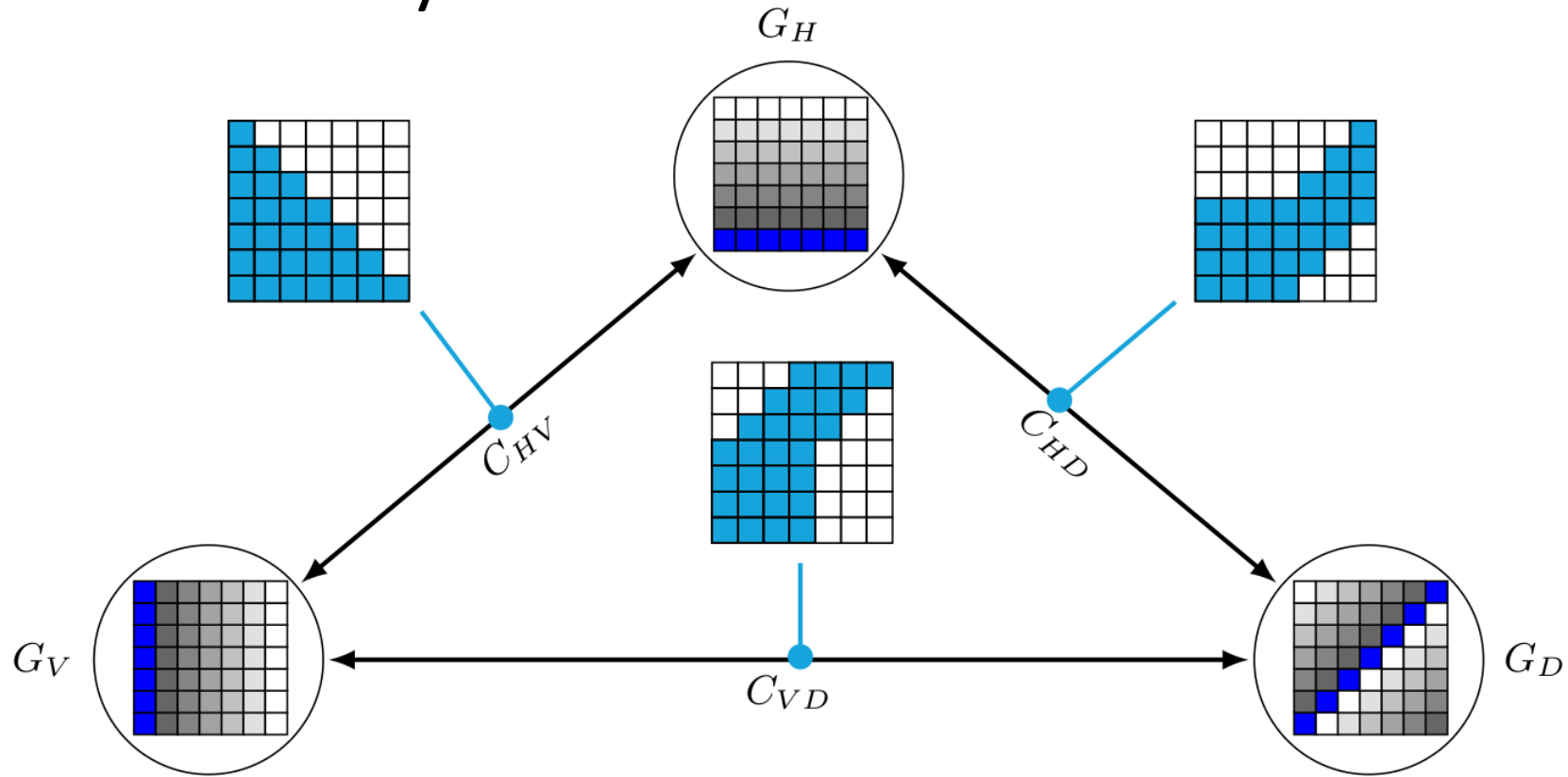


For a grid of prime size  $n \times n$ , there can be at most  $n+1$  different stable configurations with barrier  $n$  to pass between any of them

# Directed Catalysis

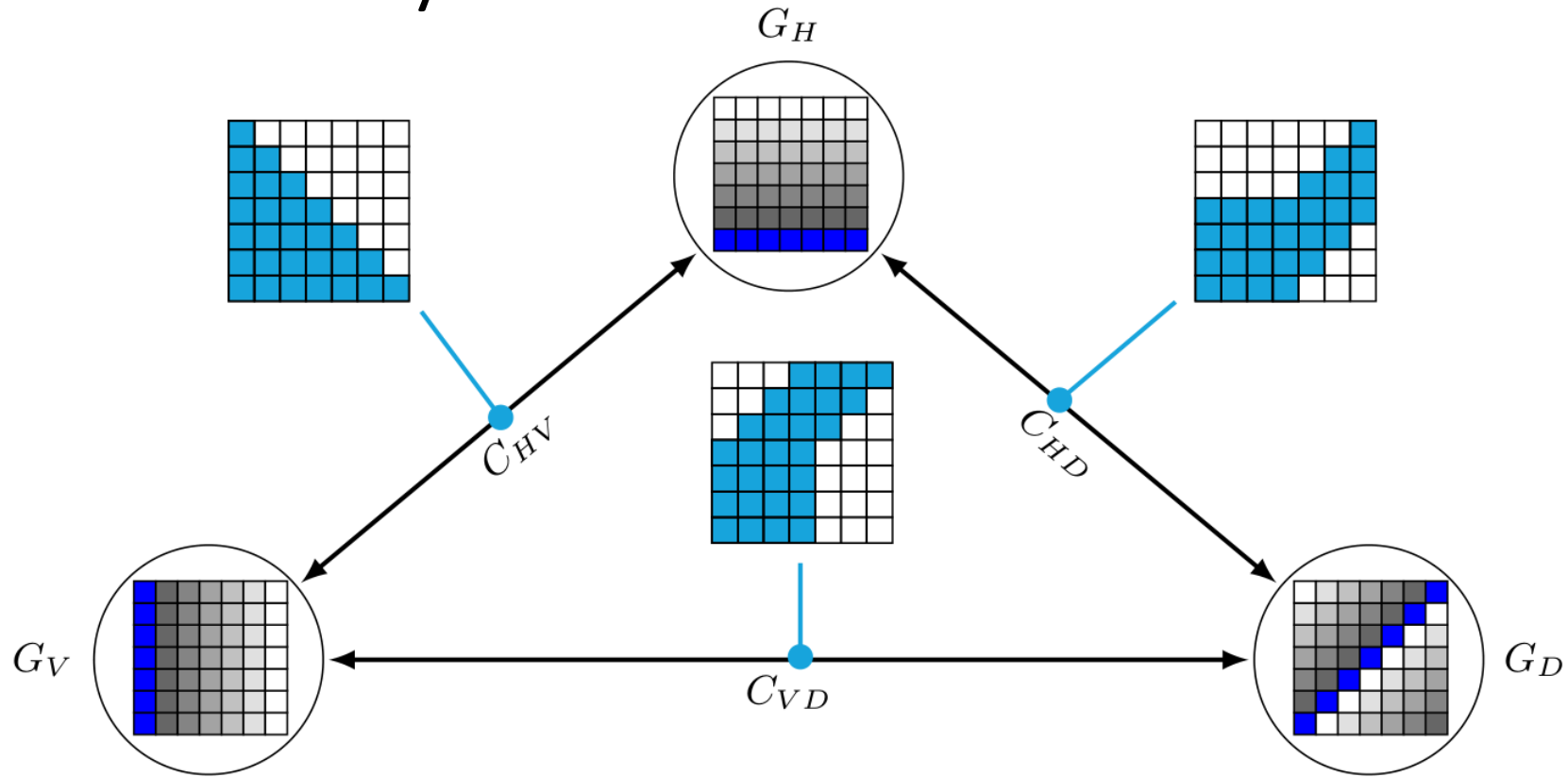


# Directed Catalysis



Along a catalyzed pathway, the barrier is 1

# Directed Catalysis



Along a catalyzed pathway, the barrier is 1

Otherwise the barrier is  $n/2$

# Social Golfer Problem

- Can  $25 (n^2)$  golfers play in 5-somes ( $n$ -somes) for 6 ( $n+1$ ) days, so that no two golfers play together more than once?

# Social Golfer Problem

- Can  $25$  ( $n^2$ ) golfers play in 5-somes ( $n$ -somes) for  $6$  ( $n+1$ ) days, so that no two golfers play together more than once?
- First studied by Euler.

# Social Golfer Problem

- Can  $25 (n^2)$  golfers play in 5-somes ( $n$ -somes) for 6 ( $n+1$ ) days, so that no two golfers play together more than once?
- First studied by Euler.
- True if  $n$  is a prime power (2,3,4,5,7,8,9,11,13,...)



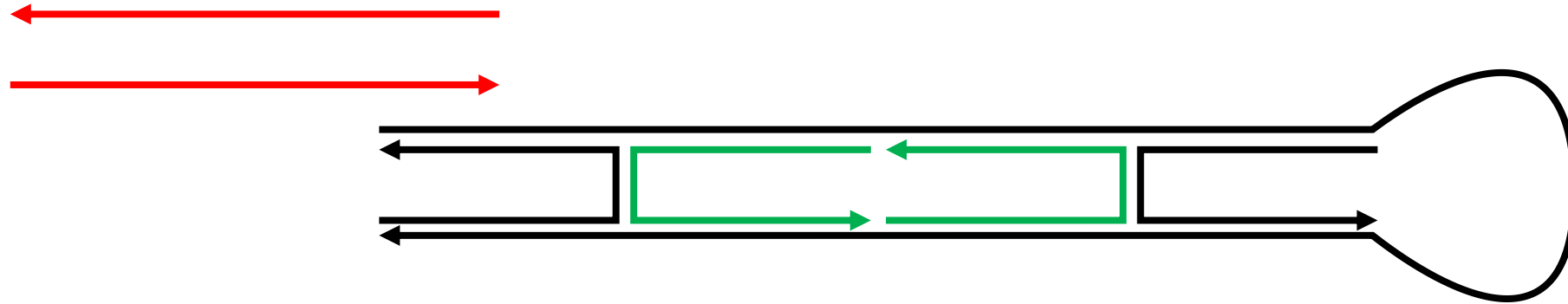
# Social Golfer Problem

- Can  $25 (n^2)$  golfers play in 5-somes ( $n$ -somes) for 6 ( $n+1$ ) days, so that no two golfers play together more than once?
- First studied by Euler.
- True if  $n$  is a prime power (2,3,4,5,7,8,9,11,13,...)
- False for smallest non-prime power  $n=6$ : can only play for 3 days!  
[Gaston Tarry (1901). "Le Problème des 36 Officiers". *Compte Rendu de l'Association Française pour l'Avancement des Sciences*. Secrétariat de l'Association. 2: 170–203.]

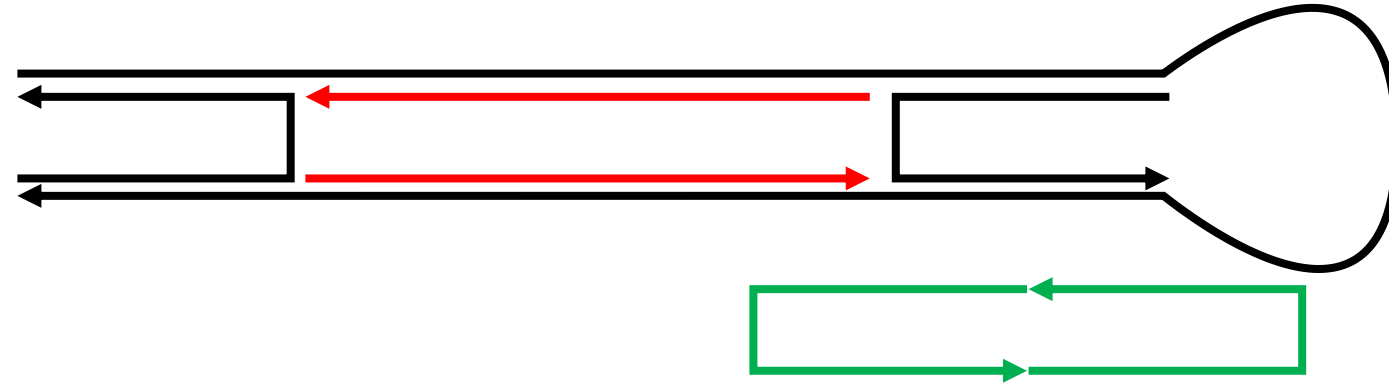
# Social Golfer Problem

- Can  $25 (n^2)$  golfers play in 5-somes ( $n$ -somes) for  $6 (n+1)$  days, so that no two golfers play together more than once?
- First studied by Euler.
- True if  $n$  is a prime power (2,3,4,5,7,8,9,11,13,...)
- False for smallest non-prime power  $n=6$ : can only play for 3 days!  
[Gaston Tarry (1901). "Le Problème des 36 Officiers". *Compte Rendu de l'Association Française pour l'Avancement des Sciences*. Secrétariat de l'Association. 2: 170–203.]
- Unknown for next prime power  $n=10$ :
  - trivial upper bound is 11 days
  - best known lower bound is 3

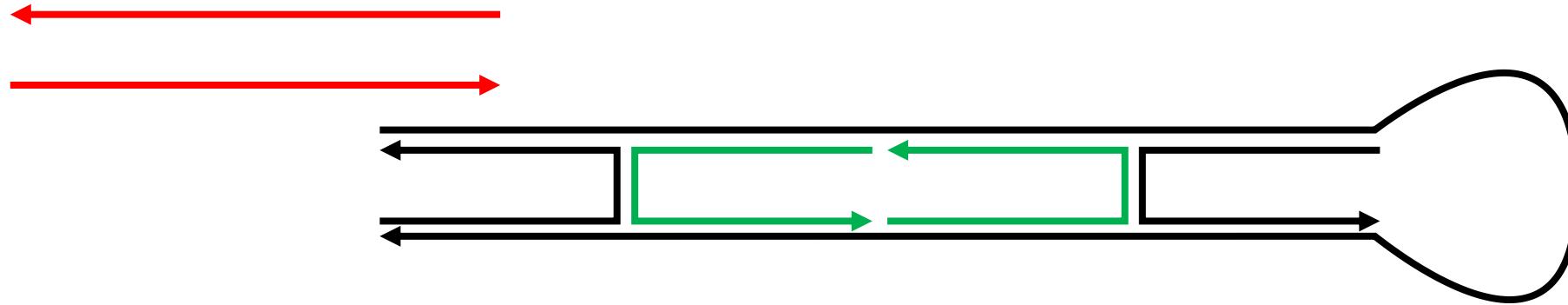
# (Feasible?) DNA implementation



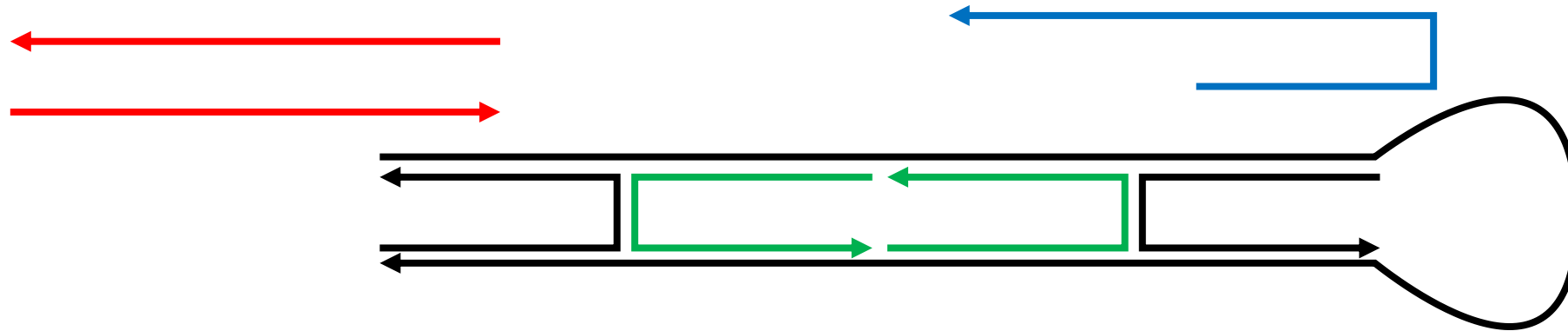
# (Feasible?) DNA implementation



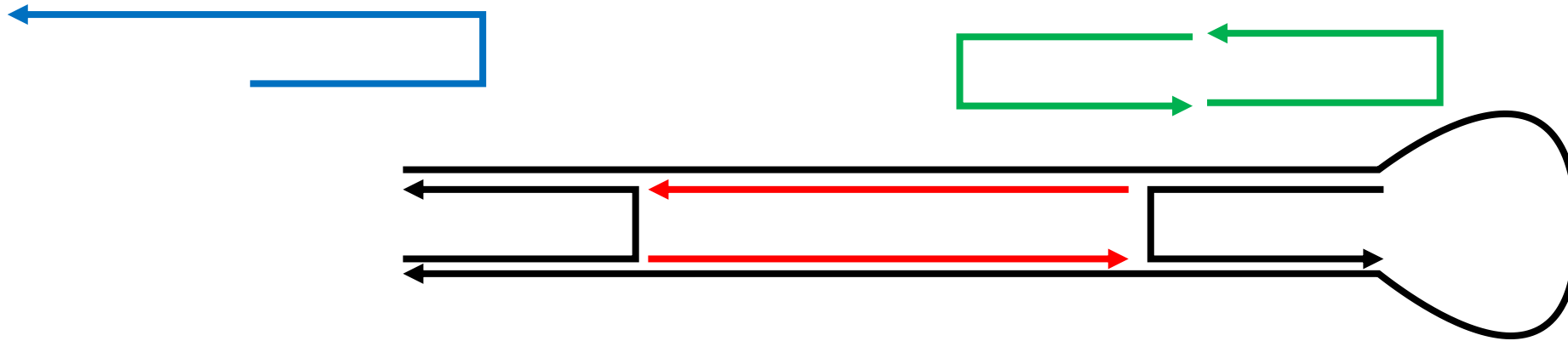
# (Feasible?) DNA implementation



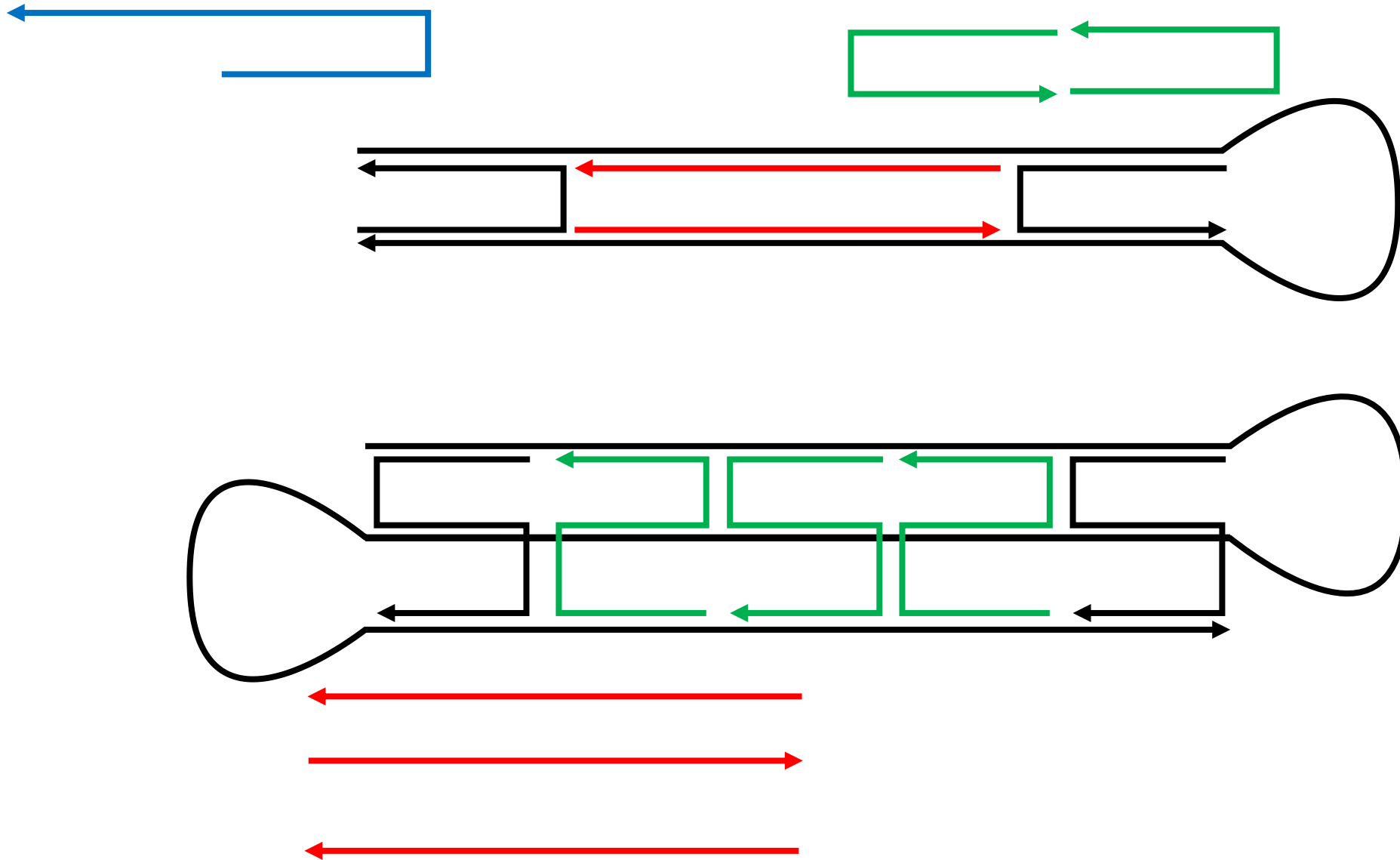
# (Feasible?) DNA implementation



# (Feasible?) DNA implementation

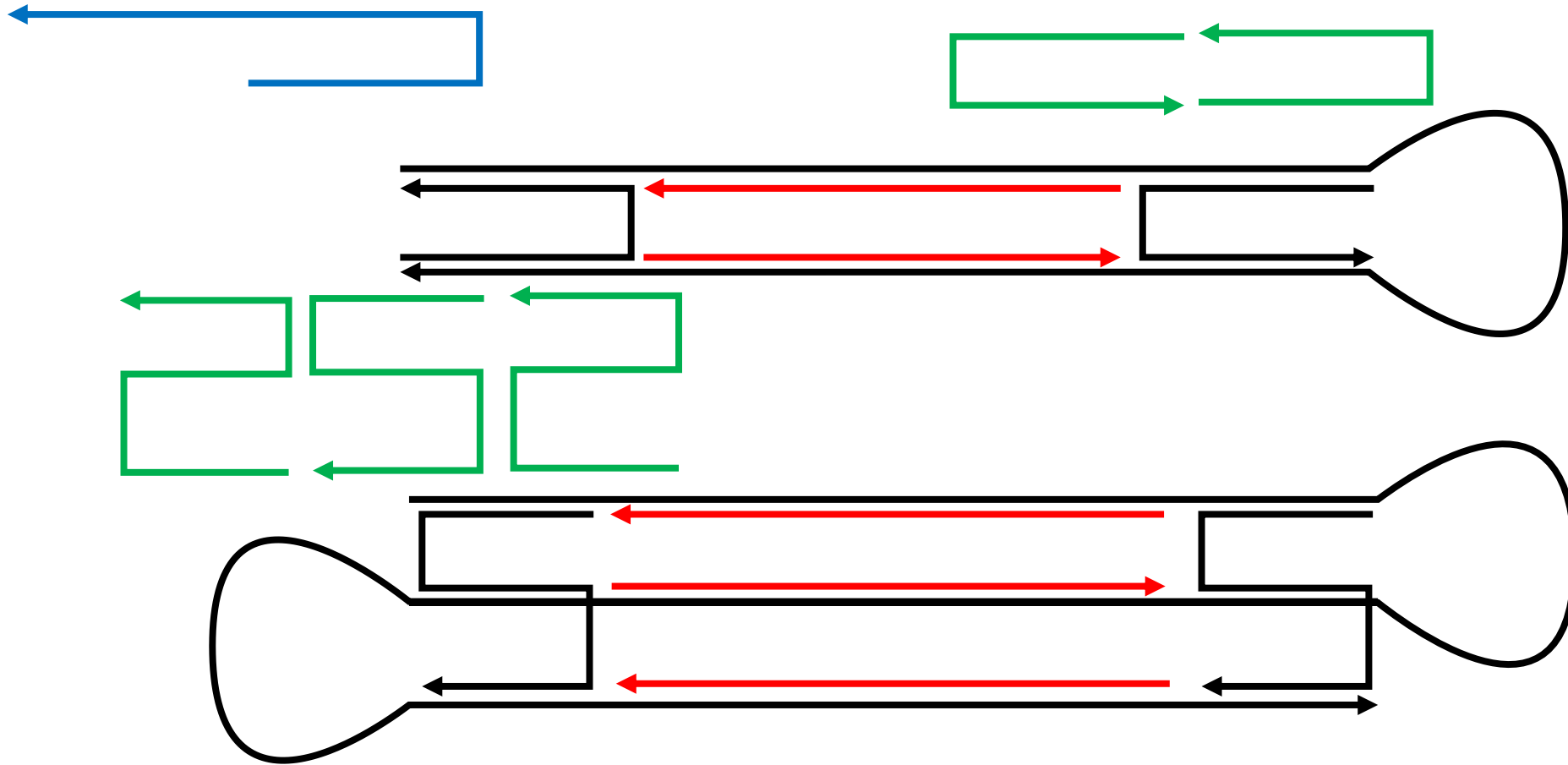


# (Feasible?) DNA implementation

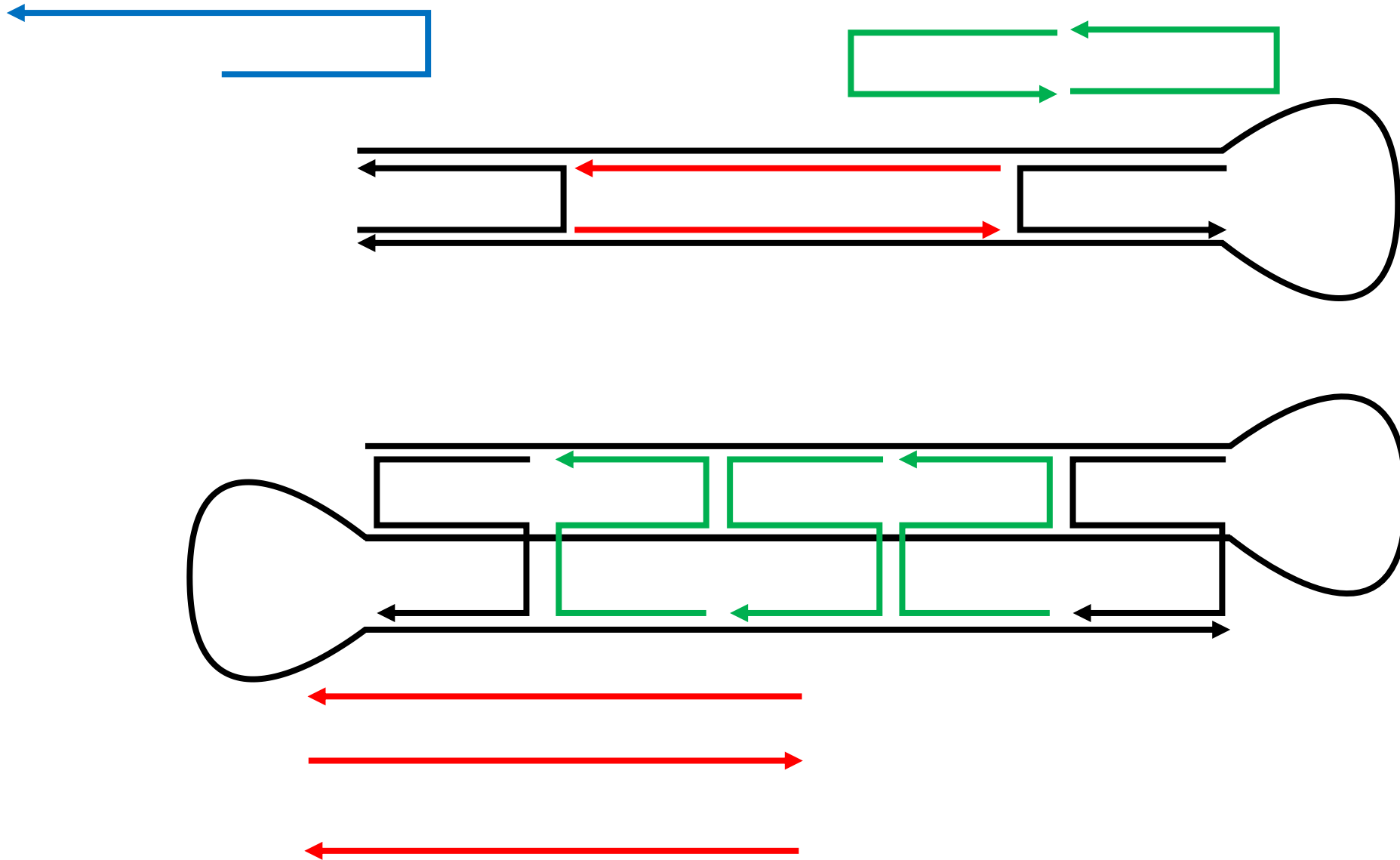




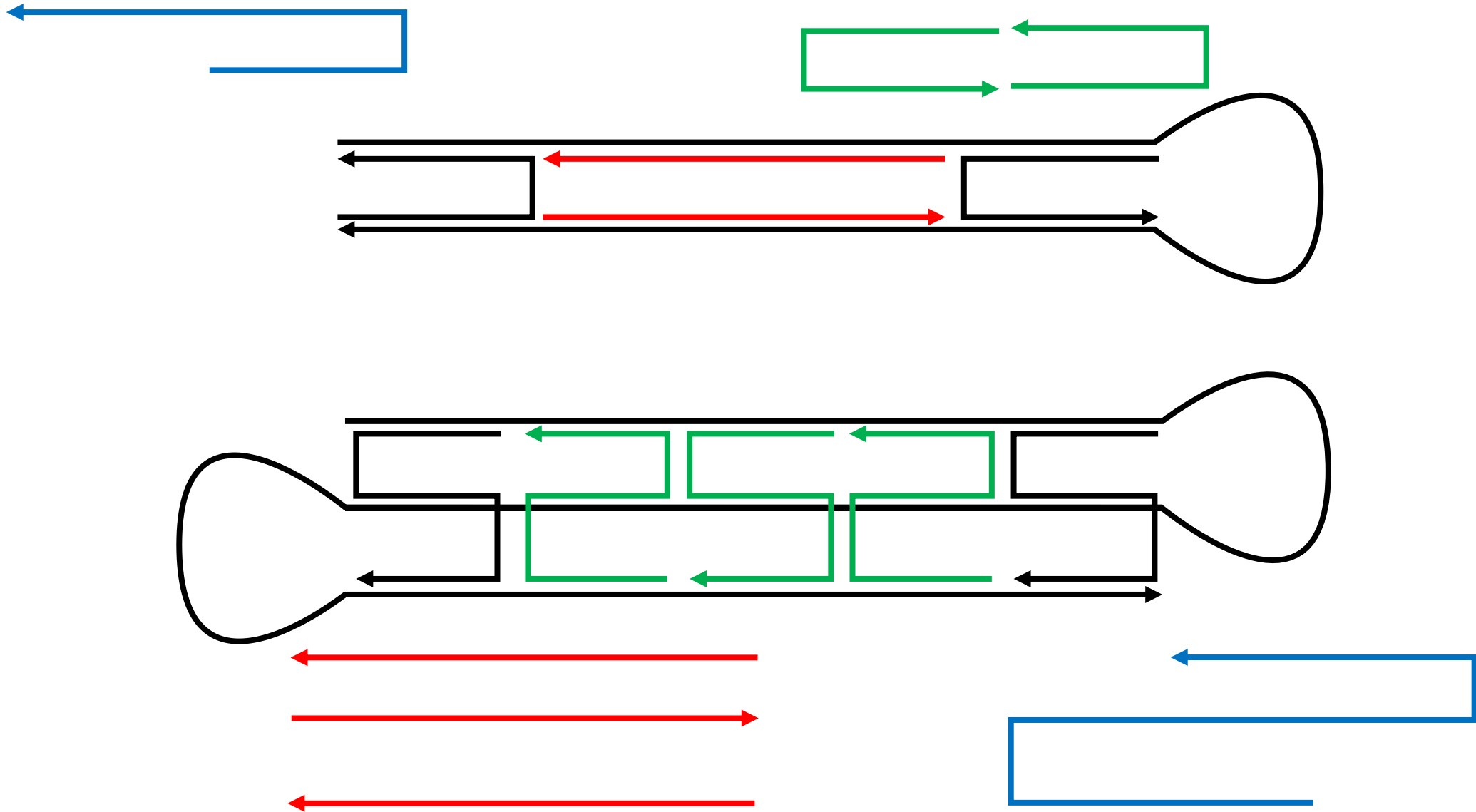
# (Feasible?) DNA implementation



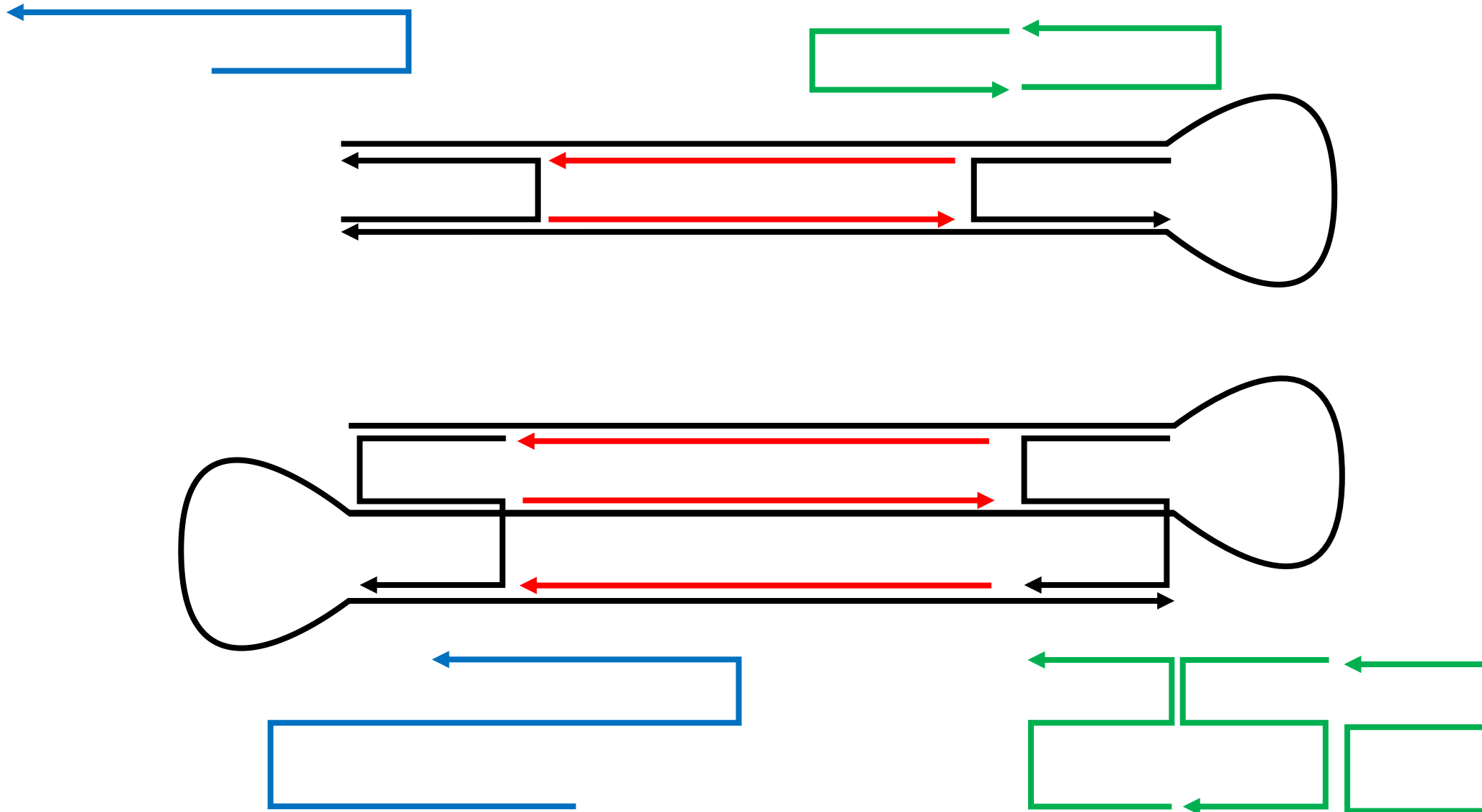
# (Feasible?) DNA implementation



# (Feasible?) DNA implementation



# (Feasible?) DNA implementation



# Thermodynamic self-assembly

Grafting the TBN model onto self-assembly

# A modest goal

- **Informal:** Design monomers that self-assemble **arbitrarily large complexes**.
  - size of a complex = # monomers in the complex

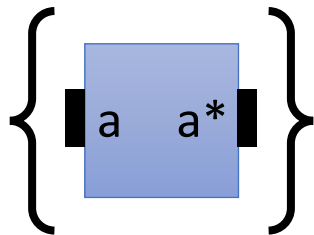
# A modest goal

- **Informal:** Design monomers that self-assemble **arbitrarily large complexes**.
  - size of a complex = # monomers in the complex
- **Formal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .

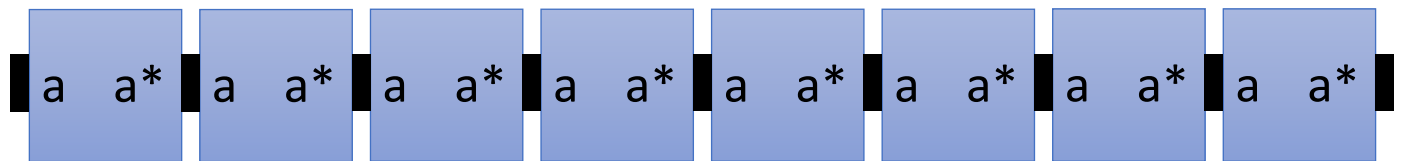
# A modest goal

- **Informal:** Design monomers that self-assemble **arbitrarily large complexes**.
  - size of a complex = # monomers in the complex
- **Formal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .
- Easy to do in Abstract Tile Assembly Model:

set of monomer types:

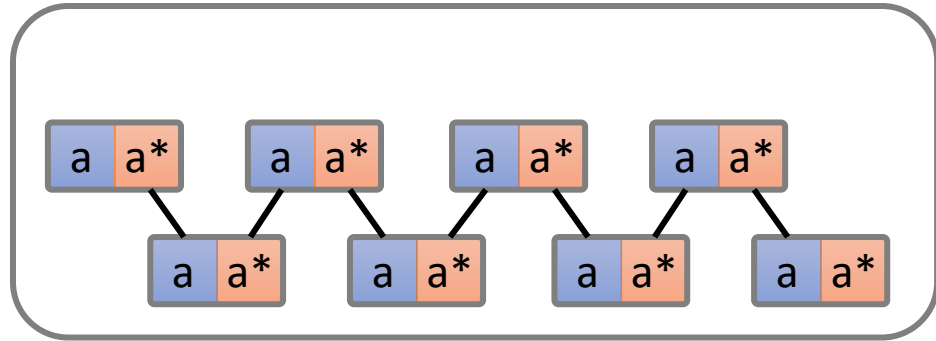


size-8 complex (assembly) formed  
with 8 copies of monomer

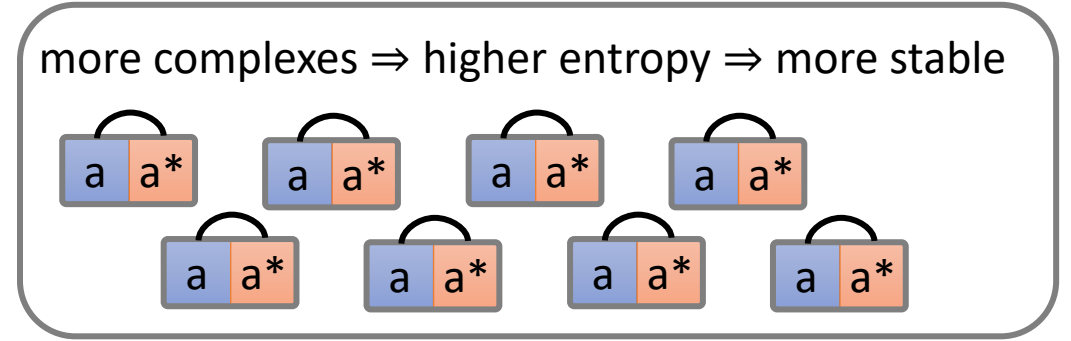
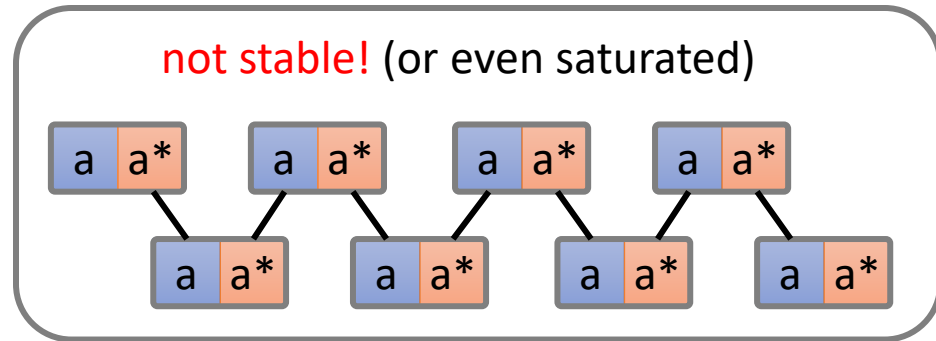




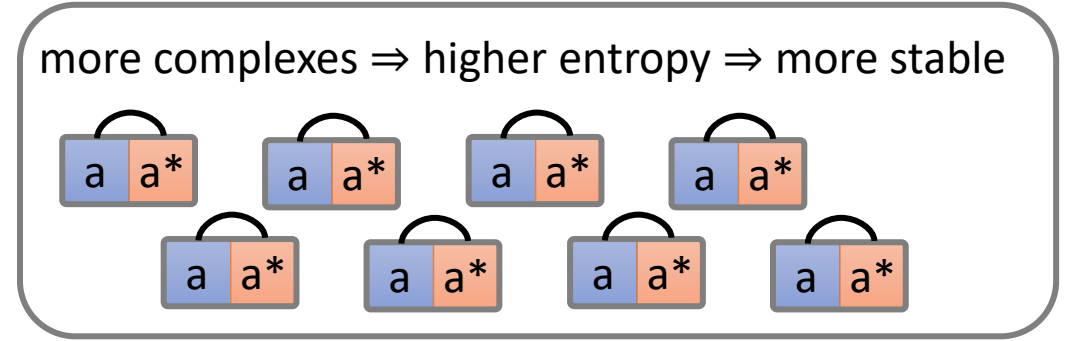
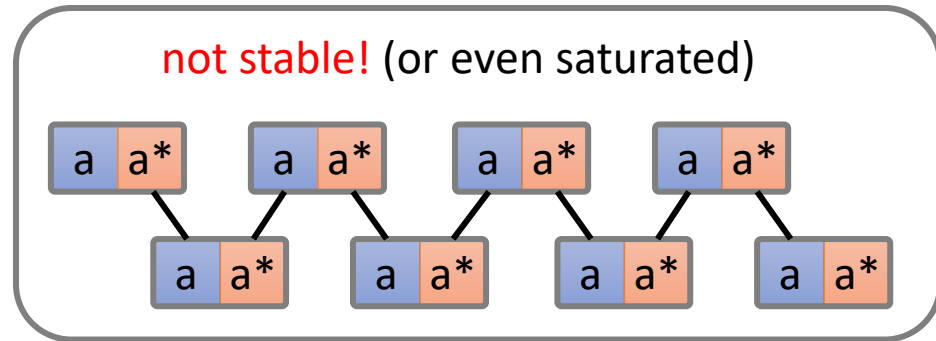
# Difficulty of self-assembling large complexes



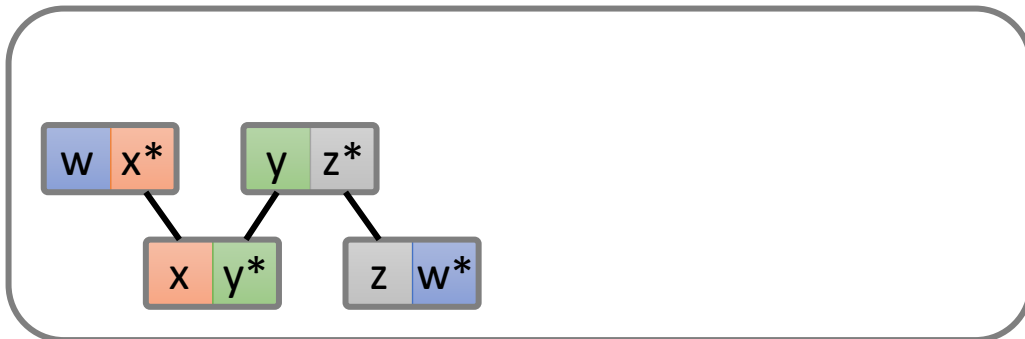
# Difficulty of self-assembling large complexes



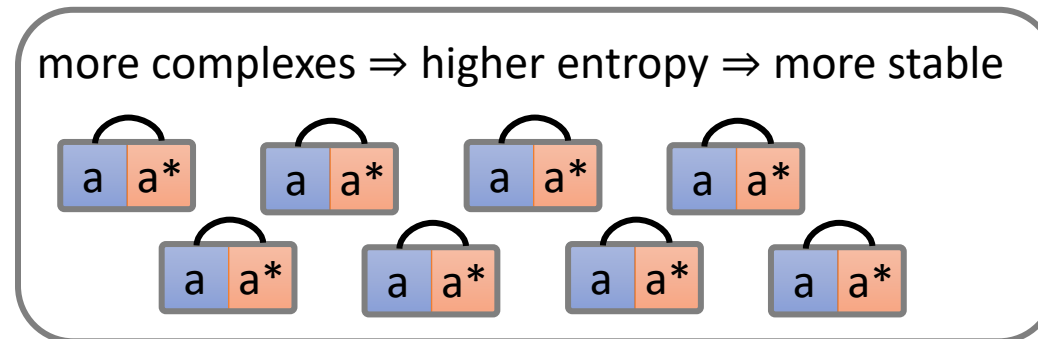
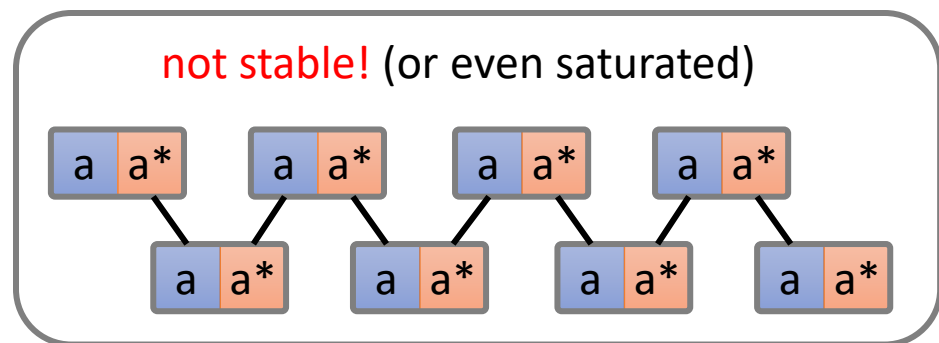
# Difficulty of self-assembling large complexes



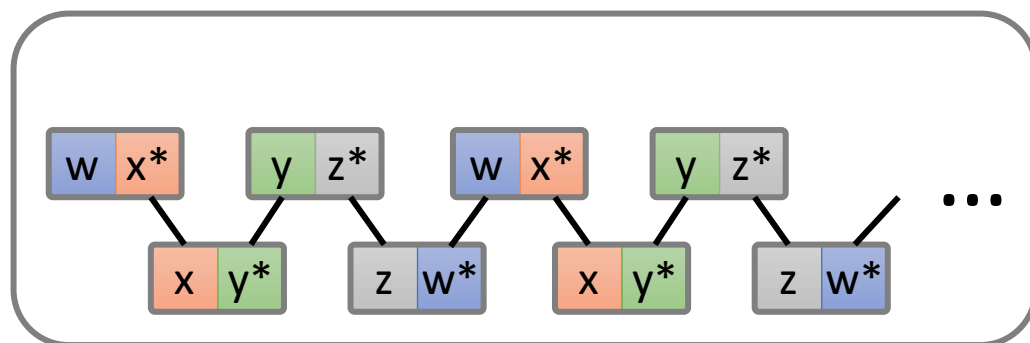
attempt 2:



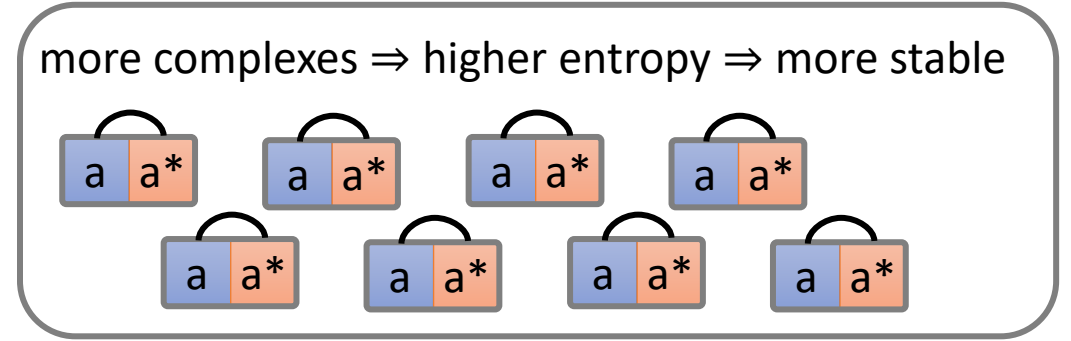
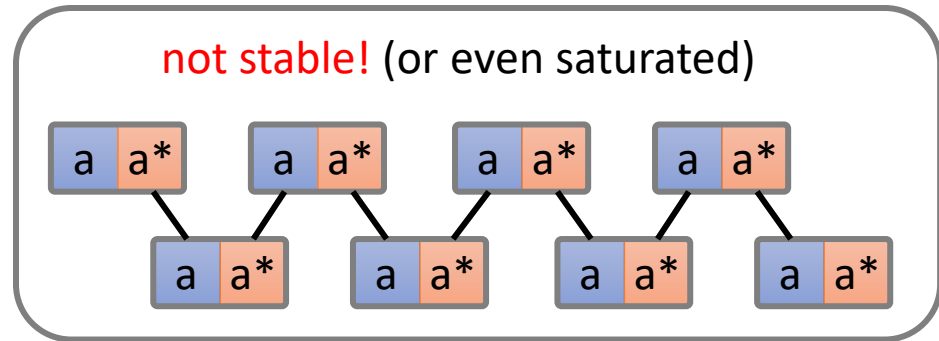
# Difficulty of self-assembling large complexes



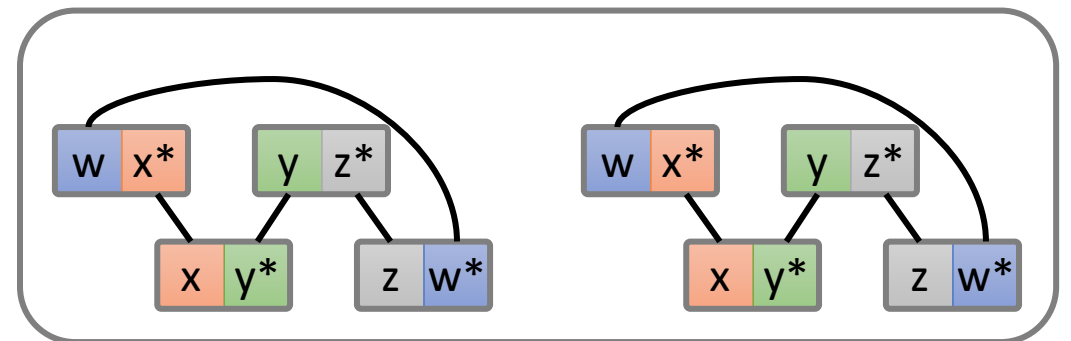
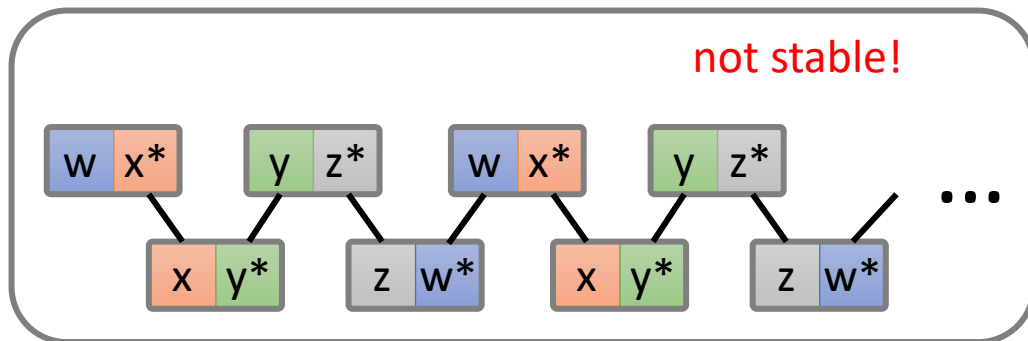
attempt 2:



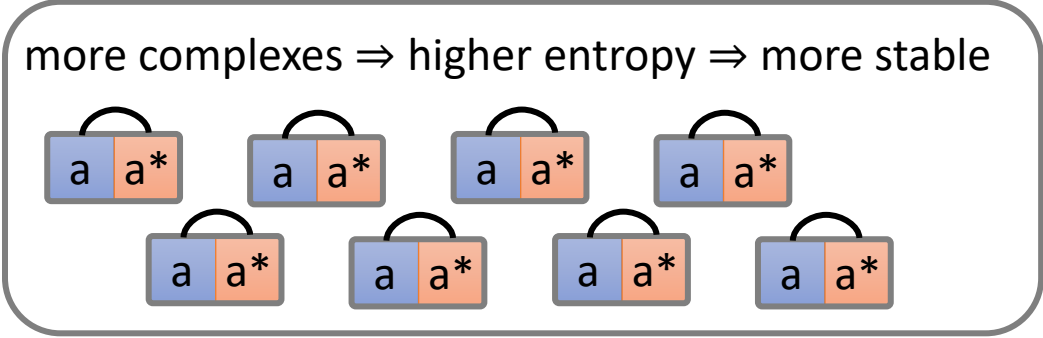
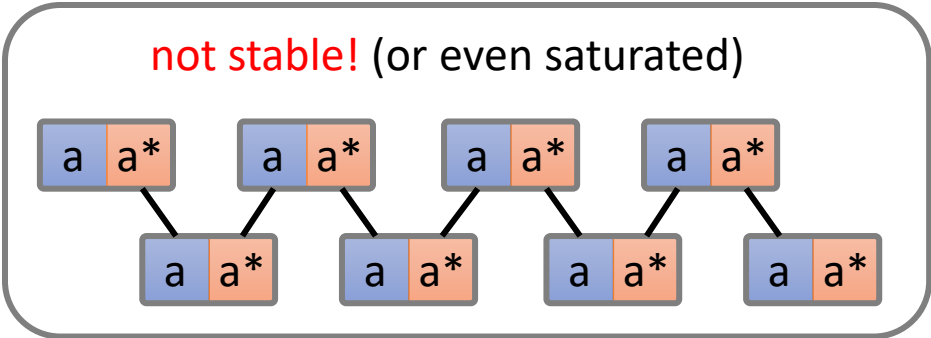
# Difficulty of self-assembling large complexes



attempt 2:

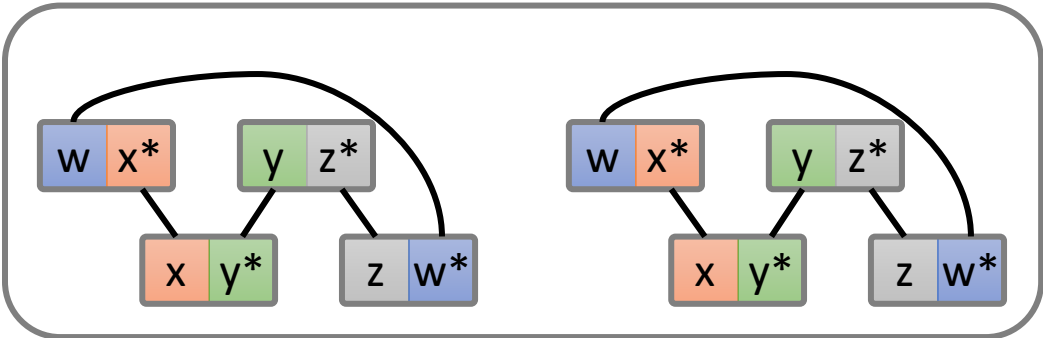
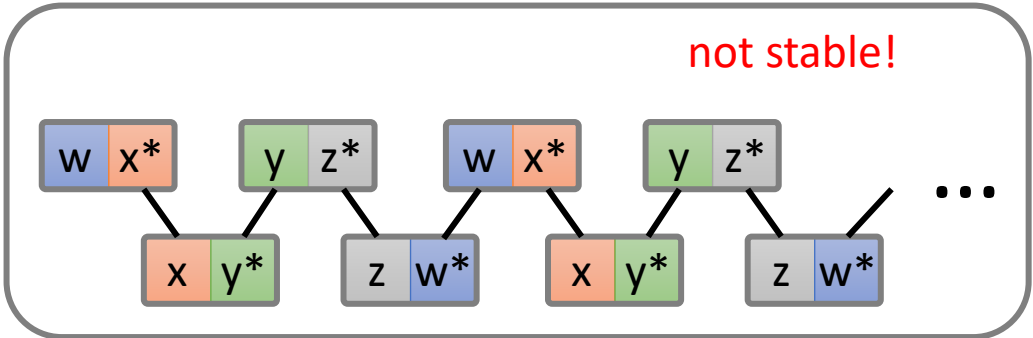


# Difficulty of self-assembling large complexes



These have more complexes, and each is self-saturating (every domain can be bound *within* the complex)

attempt 2:



# An even more modest goal

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .

# An even more modest goal

~~**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

**Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .



# An even more modest goal

~~**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

**Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

How large can we make  $S$  relative to  $D$  and  $M$ ?

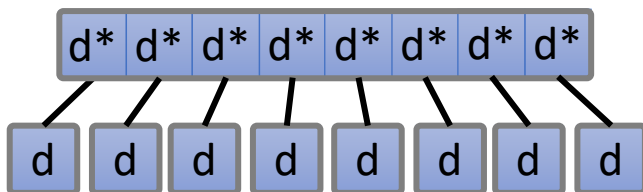
# An even more modest goal

~~Original goal: Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

**Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

How large can we make  $S$  relative to  $D$  and  $M$ ?

$D, M = O(1)$ ,  $S = \text{arbitrarily large}$



# An even more modest goal

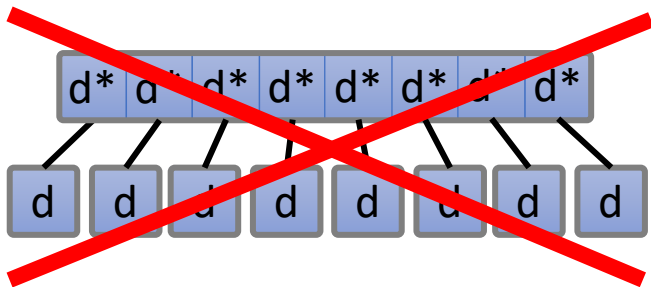
~~Original goal: Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

and  $O(1)$  domains per monomer

Re-**Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

How large can we make  $S$  relative to  $D$  and  $M$ ?

$D, M = O(1)$ ,  $S =$  arbitrarily large



# An even more modest goal

~~Original goal: Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

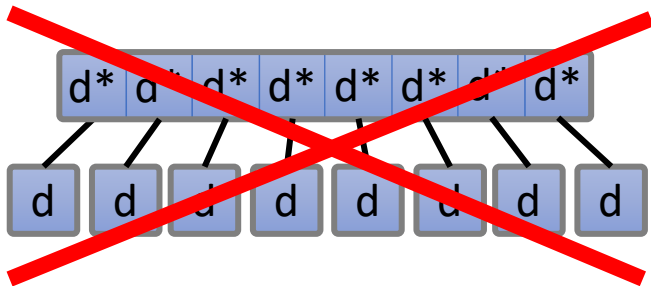
and  $O(1)$  domains per monomer

Re-**Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

How large can we make  $S$  relative to  $D$  and  $M$ ?

$D, M = O(1)$ ,  $S =$  arbitrarily large

$$S \approx D$$



# An even more modest goal

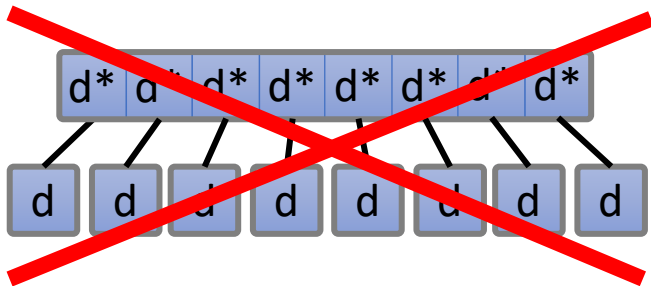
~~Original goal: Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

and  $O(1)$  domains per monomer

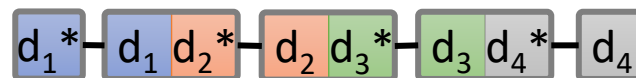
Re-**Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

How large can we make  $S$  relative to  $D$  and  $M$ ?

$D, M = O(1)$ ,  $S =$  arbitrarily large



$S \approx D$



# An even more modest goal

~~Original goal: Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

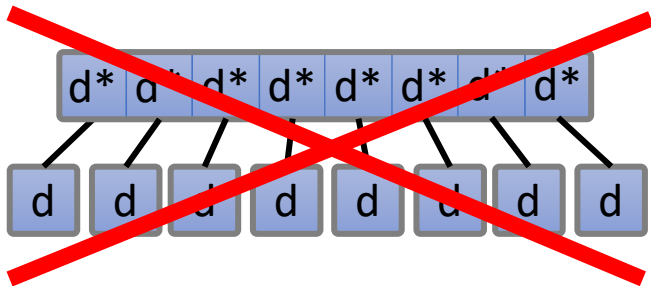
and  $O(1)$  domains per monomer

**Re- Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

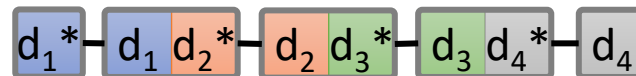
How large can we make  $S$  relative to  $D$  and  $M$ ?

$$S \approx D^2$$

$D, M = O(1)$ ,  $S =$  arbitrarily large



$$S \approx D$$



# An even more modest goal

~~Original goal: Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

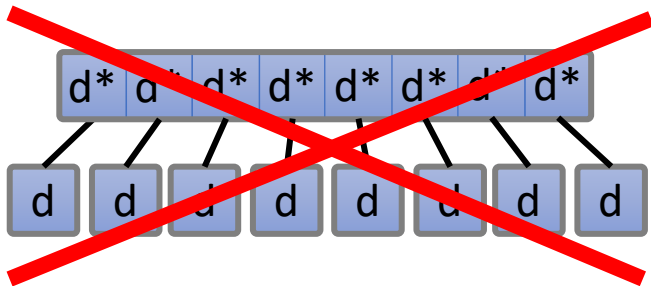
and  $O(1)$  domains per monomer

Re-**Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

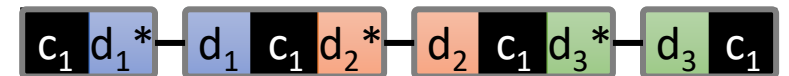
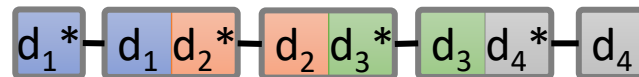
How large can we make  $S$  relative to  $D$  and  $M$ ?

$$S \approx D^2$$

$D, M = O(1)$ ,  $S =$  arbitrarily large



$$S \approx D$$



# An even more modest goal

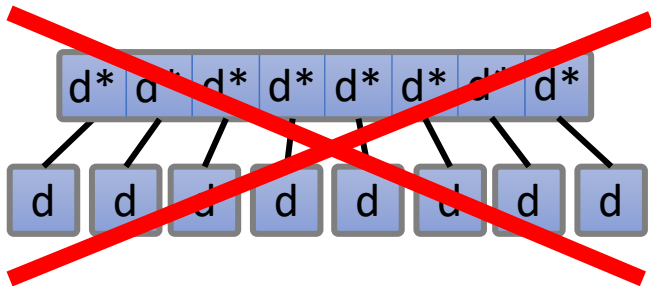
~~Original goal: Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex of size at least  $S$ .~~

and  $O(1)$  domains per monomer

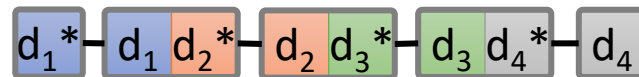
**Re- Revised goal:** For all  $S \in \mathbb{N}$ , design a set of  $M$  monomer types using  $D$  domain types with a stable complex of size at least  $S$ .

How large can we make  $S$  relative to  $D$  and  $M$ ?

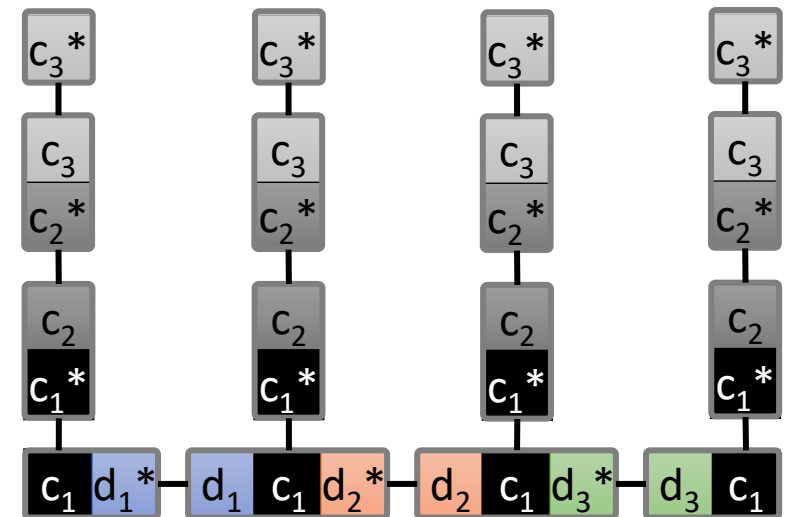
$D, M = O(1)$ ,  $S =$  arbitrarily large



$S \approx D$



$S \approx D^2$



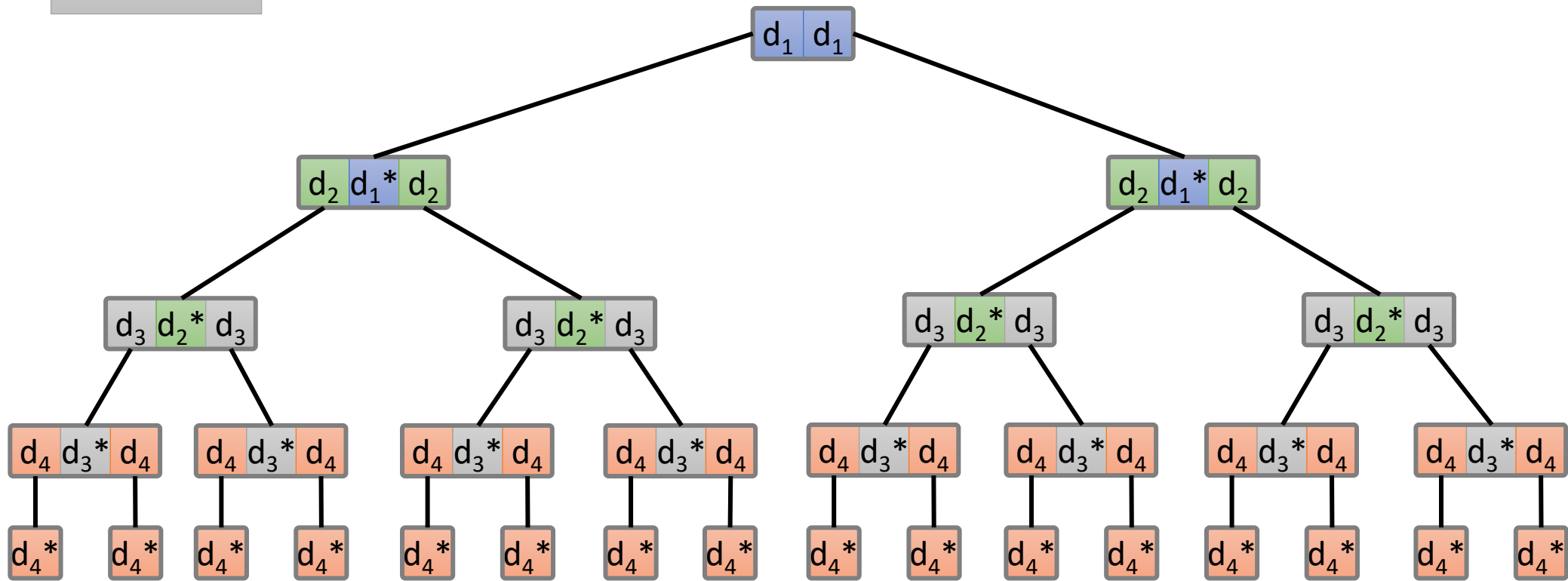


How large can we make  $S$  relative to  $D$  and  $M$ ?

$$S \approx 2^D?$$

How large can we make  $S$  relative to  $D$  and  $M$ ?

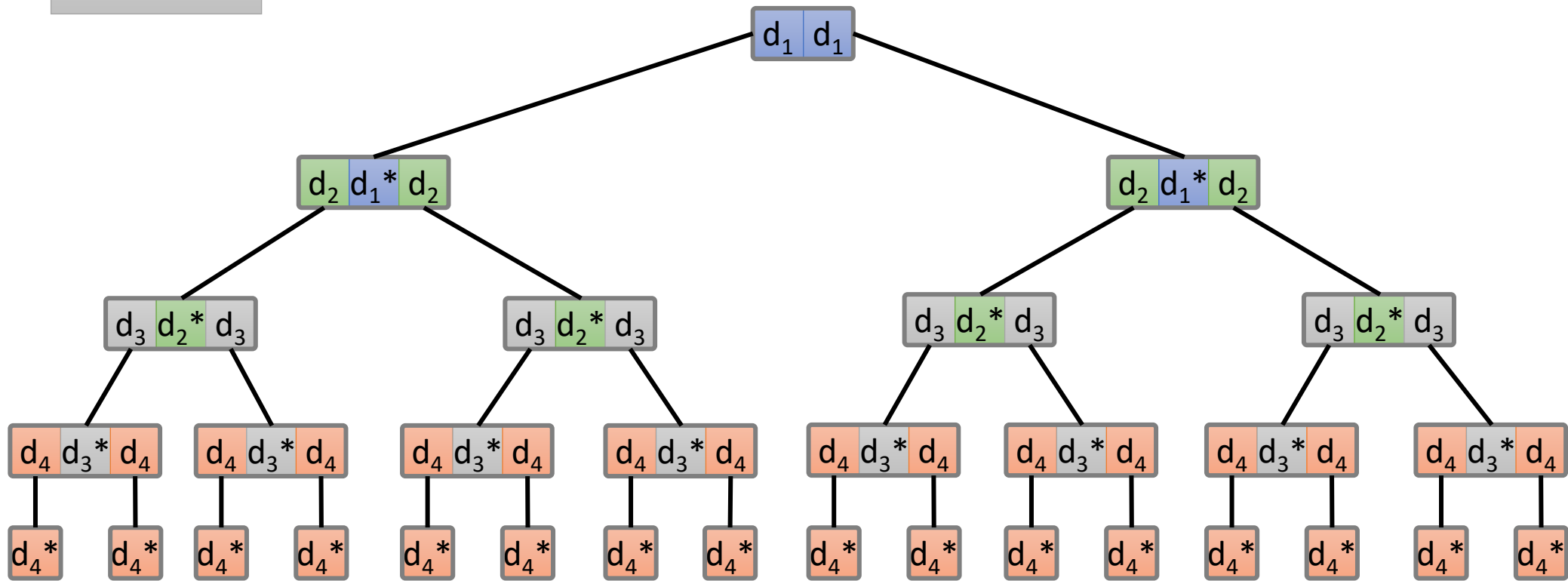
$$S \approx 2^D?$$



How large can we make  $S$  relative to  $D$  and  $M$ ?

$$S \approx 2^D?$$

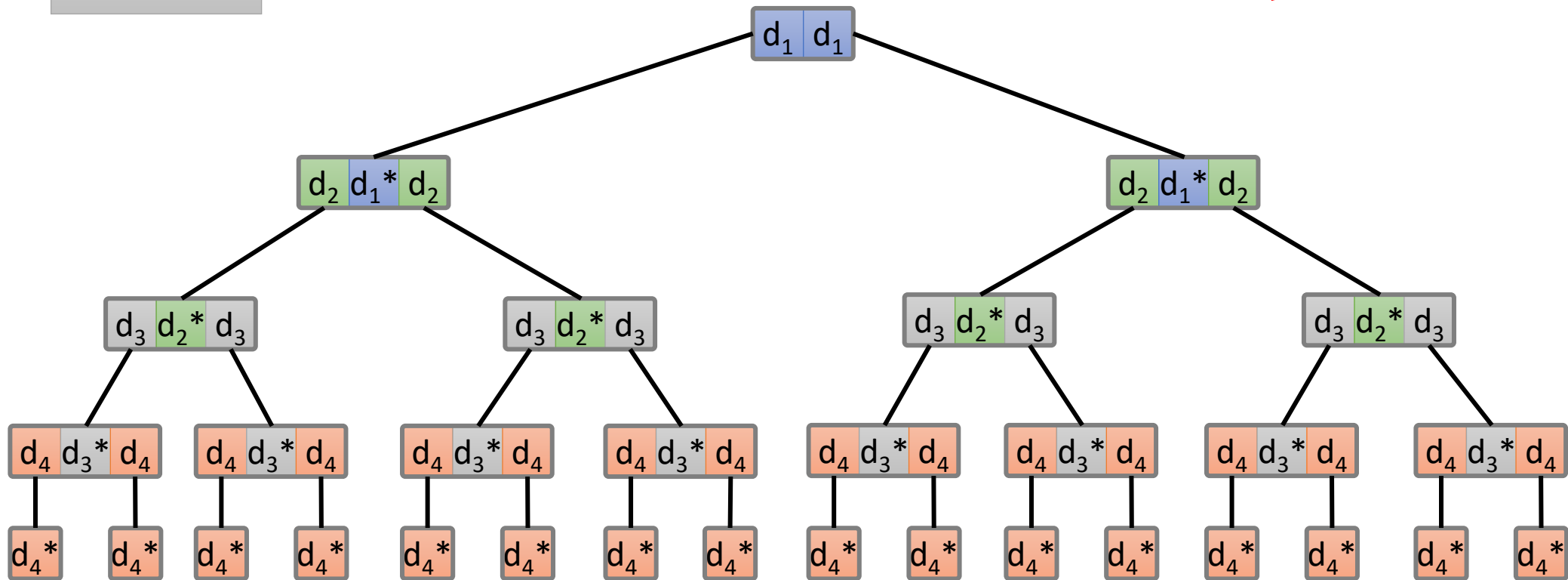
$$S \approx 2^{2^D}??$$



# How large can we make $S$ relative to $D$ and $M$ ?

$$S \approx 2^D?$$

~~$$S \approx 2^{2^D} ??$$~~



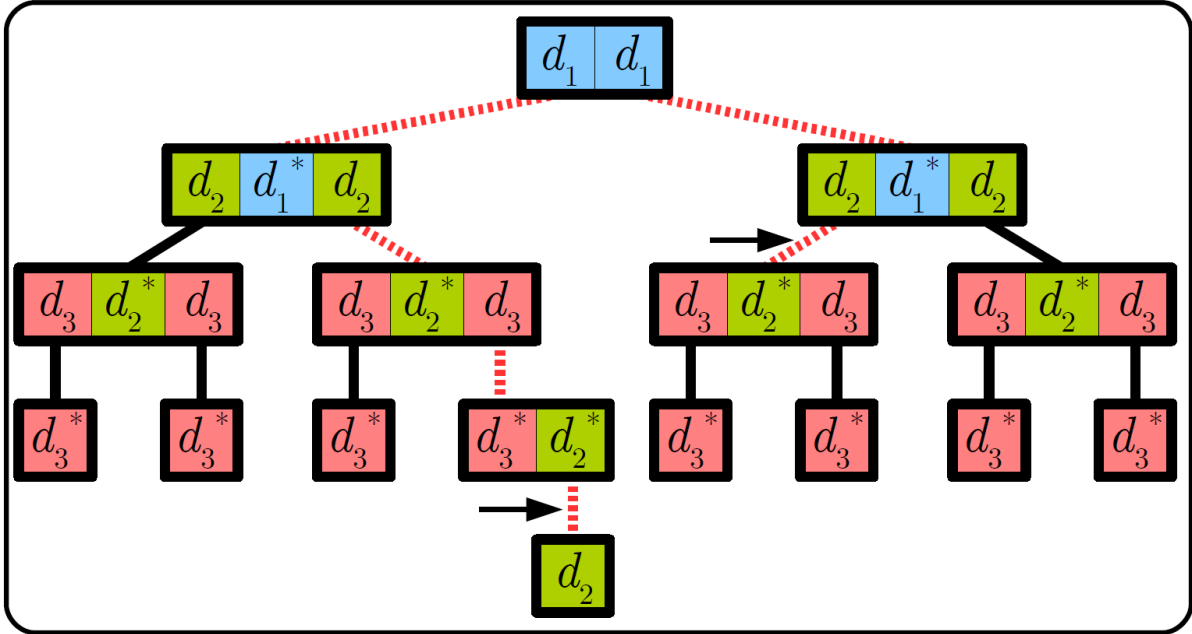
# Stable complexes have at most exponential size

**Theorem:** Any thermodynamic binding network with

- $D$  domain types,
- $M$  monomer types,
- $\leq A$  domains per monomer type (note  $D/A \leq M \leq A^{D+1}$ )

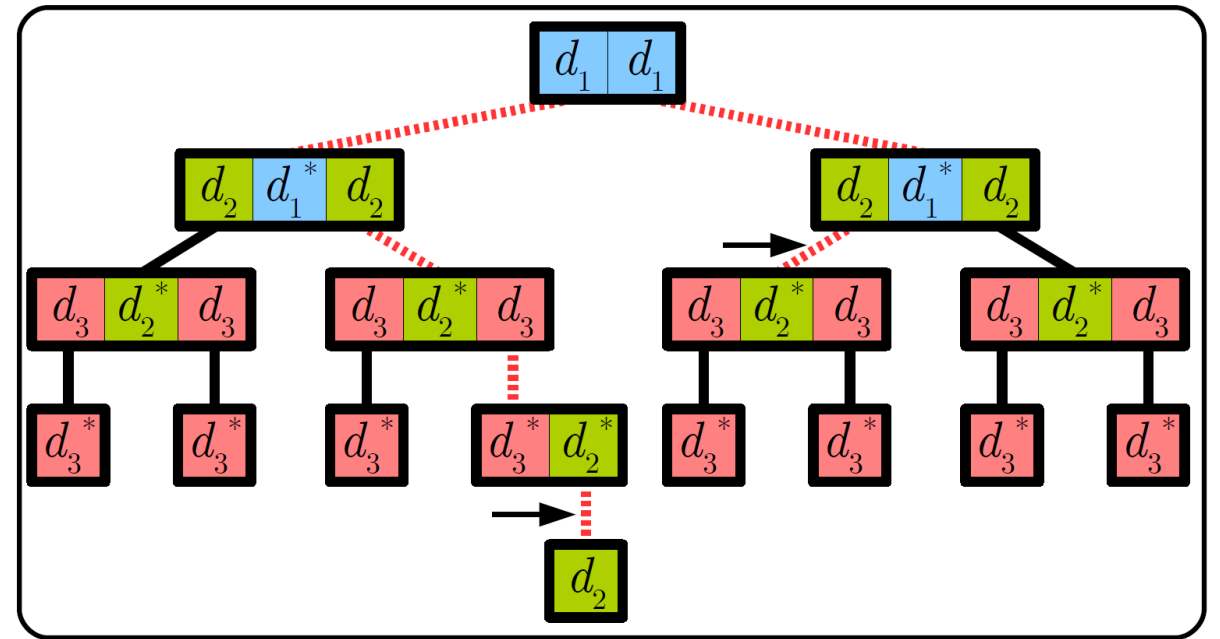
Has stable complexes of size  $\leq 2(M+D)(AD)^{2D+3} = \text{poly}(D^D)$  if  $A = O(1)$

Easy proof if binding graph is acyclic (tree)



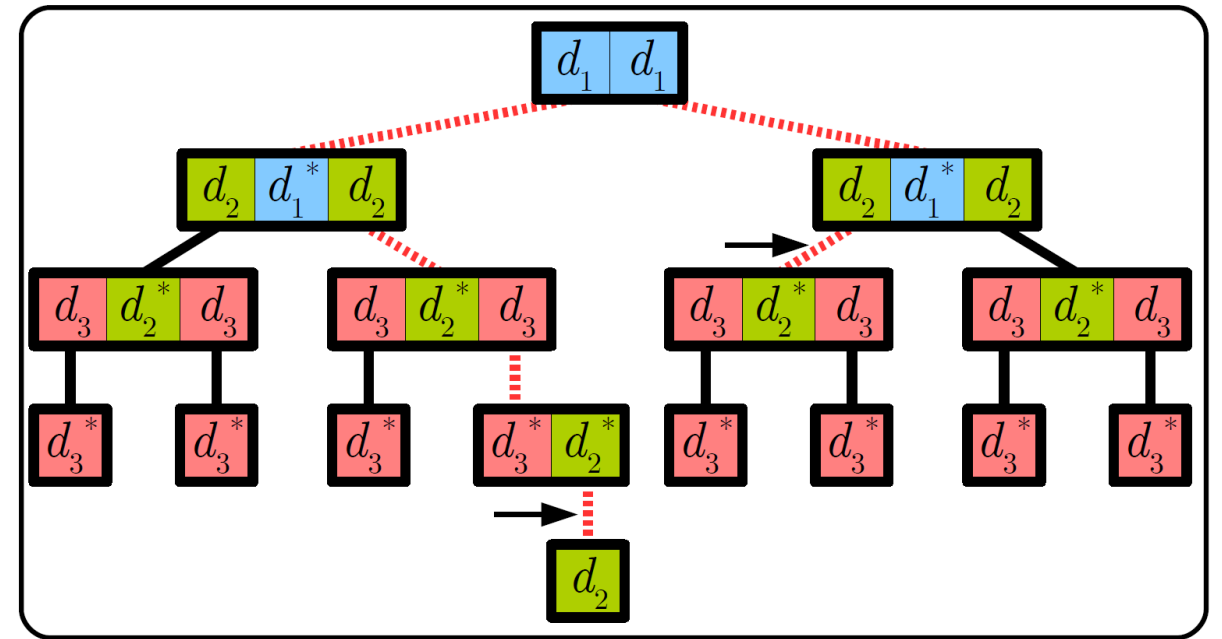
# Easy proof if binding graph is acyclic (tree)

- Since monomers have  $O(1)$  domains, binding graph is bounded degree



# Easy proof if binding graph is acyclic (tree)

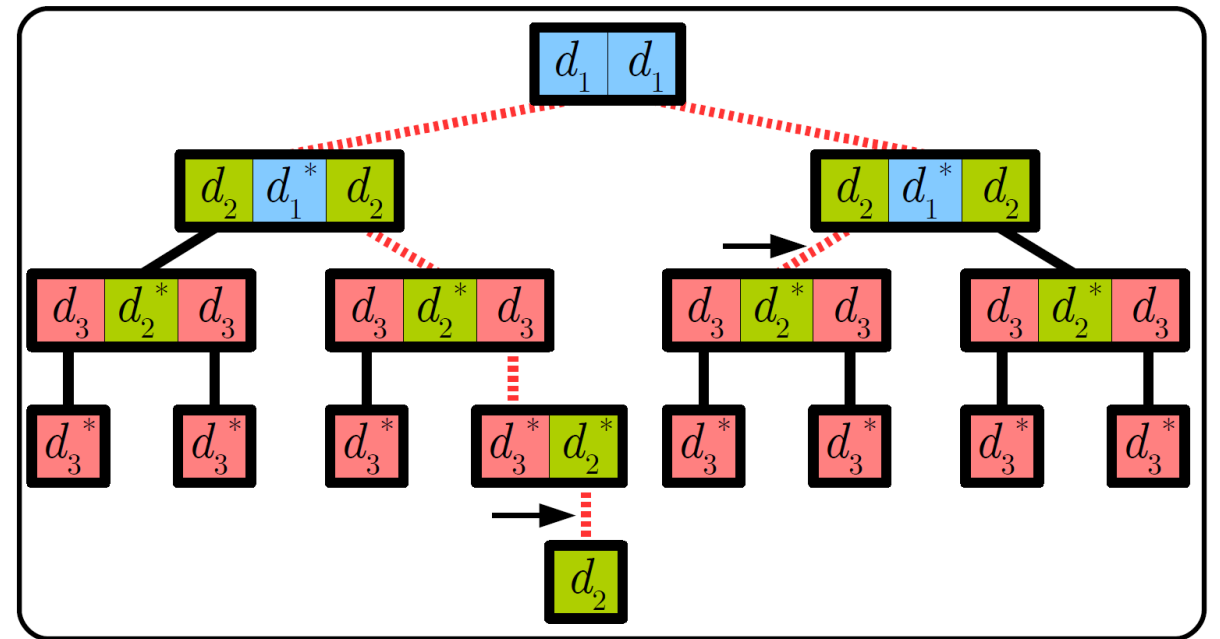
- Since monomers have  $O(1)$  domains, binding graph is bounded degree
- # nodes of tree is at most exponential in depth (longest path length  $\leq 2 \cdot \text{depth}$ )





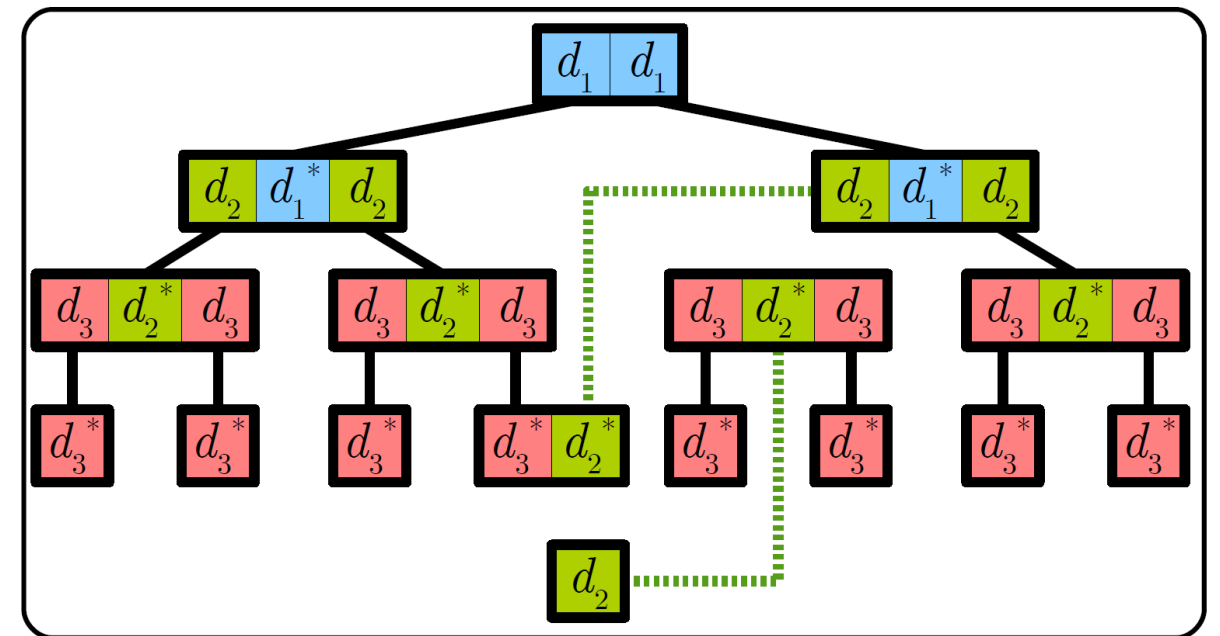
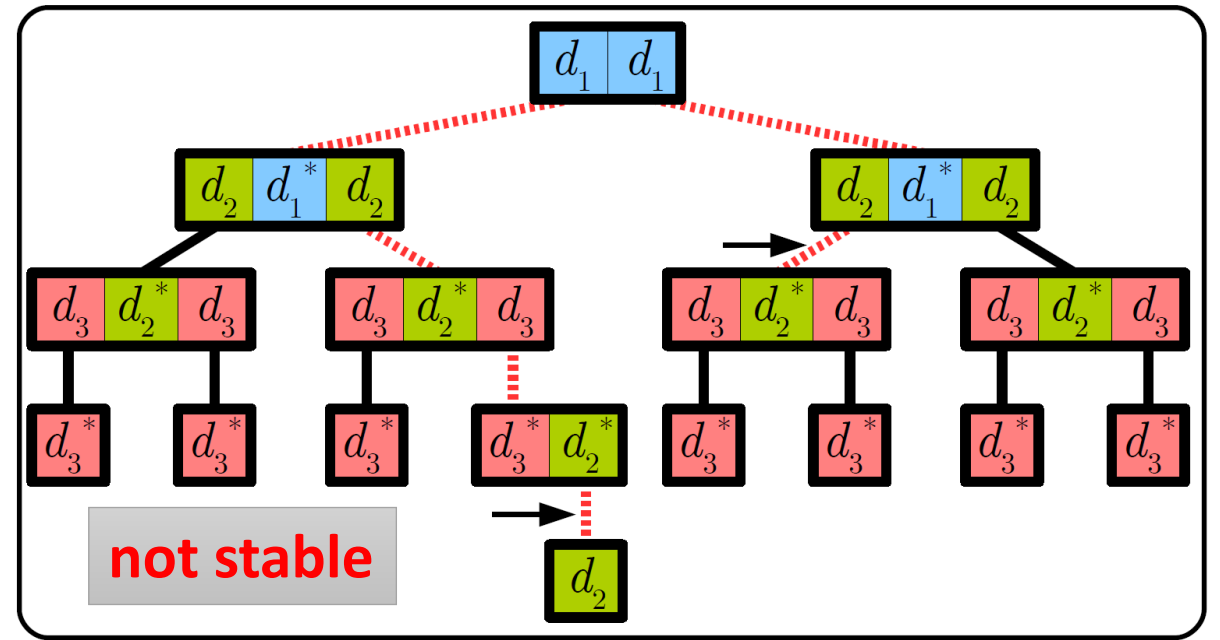
# Easy proof if binding graph is acyclic (tree)

- Since monomers have  $O(1)$  domains, binding graph is bounded degree
- # nodes of tree is at most exponential in depth (longest path length  $\leq 2 \cdot \text{depth}$ )
- If some path has  $> 2D$  edges, it must repeat some ordered pair  $(d_i, d_i^*)$  or  $(d_i^*, d_i)$



# Easy proof if binding graph is acyclic (tree)

- Since monomers have  $O(1)$  domains, binding graph is bounded degree
- # nodes of tree is at most exponential in depth (longest path length  $\leq 2 \cdot \text{depth}$ )
- If some path has  $> 2D$  edges, it must repeat some ordered pair  $(d_i, d_i^*)$  or  $(d_i^*, d_i)$
- Break into two saturated complexes as shown.



# Monomers as vectors

- monomer  $\{a, b^*, b^*, d, d, d, d, d^*, e, e^*\}$  represented as  $(1, -2, 0, 3, 0)$

# Monomers as vectors

- monomer {a, b\*,b\*, d,d,d,d,d\*, e,e\*} represented as (1,-2,0,3,0)
- sum of many monomers gives the number of excess domains in a fully bound (saturated) complex with those monomers
  - i.e., 2 copies of above monomer  $2 \cdot (1,-2,0,3,0) = (2,-4,0,6,0)$  have an excess of **2** a's, **4** b\*'s, **0** c's, **6** d's, **0** e's

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

**Proof:**

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

**Proof:**

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

**Proof:**

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.



# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .
  2. Let  $S_i = m_{1i} + m_{2i} + \dots + m_{ki}$ . Note that there is a  $m \times d$  matrix  $M$  such that  $S_i = M \cdot P_i$ .

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .
  2. Let  $S_i = m_{1i} + m_{2i} + \dots + m_{ki}$ . Note that there is a  $m \times d$  matrix  $M$  such that  $S_i = M \cdot P_i$ .
3. Take several infinite subsequences:

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .
  2. Let  $S_i = m_{1i} + m_{2i} + \dots + m_{ki}$ . Note that there is a  $m \times d$  matrix  $M$  such that  $S_i = M \cdot P_i$ .
3. Take several infinite subsequences:
  1. Since there are a finite number of domain types, some infinite subsequence of  $P_i$ 's agrees on which set of domain types are unbound.

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .
  2. Let  $S_i = m_{1i} + m_{2i} + \dots + m_{ki}$ . Note that there is a  $m \times d$  matrix  $M$  such that  $S_i = M \cdot P_i$ .
3. Take several infinite subsequences:
  1. Since there are a finite number of domain types, some infinite subsequence of  $P_i$ 's agrees on which set of domain types are unbound.
  2. By Dickson's Lemma we may assume  $P_1 < P_2 < \dots$  and  $S_1 < S_2 < \dots$  i.e., each has all the monomers of the previous, plus some more, and each has all the unbound domains of the previous, plus some more.

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .
  2. Let  $S_i = m_{1i} + m_{2i} + \dots + m_{ki}$ . Note that there is a  $m \times d$  matrix  $M$  such that  $S_i = M \cdot P_i$ .
3. Take several infinite subsequences:
  1. Since there are a finite number of domain types, some infinite subsequence of  $P_i$ 's agrees on which set of domain types are unbound.
  2. By Dickson's Lemma we may assume  $P_1 < P_2 < \dots$  and  $S_1 < S_2 < \dots$  i.e., each has all the monomers of the previous, plus some more, and each has all the unbound domains of the previous, plus some more.
4. Let  $d = P_2 - P_1$ . Then  $M \cdot d = M \cdot P_2 - M \cdot P_1 = S_2 - S_1 \geq 0$ .

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .
  2. Let  $S_i = m_{1i} + m_{2i} + \dots + m_{ki}$ . Note that there is a  $m \times d$  matrix  $M$  such that  $S_i = M \cdot P_i$ .
3. Take several infinite subsequences:
  1. Since there are a finite number of domain types, some infinite subsequence of  $P_i$ 's agrees on which set of domain types are unbound.
  2. By Dickson's Lemma we may assume  $P_1 < P_2 < \dots$  and  $S_1 < S_2 < \dots$  i.e., each has all the monomers of the previous, plus some more, and each has all the unbound domains of the previous, plus some more.
4. Let  $d = P_2 - P_1$ . Then  $M \cdot d = M \cdot P_2 - M \cdot P_1 = S_2 - S_1 \geq 0$ .
5. i.e.,  $S_2 = S_1 + M \cdot d$  and all three are nonnegative,

# Somewhat easy proof that unbounded size complexes cannot be assembled

**Original goal:** Design a set of monomer types so that, for all  $S \in \mathbb{N}$ , there is a stable complex  $P$  of size  $\geq S$ .

**Theorem:** Original goal is impossible.

## Proof:

1. Suppose otherwise, let  $P_1, P_2, \dots$  in  $\mathbb{N}^m$  be an infinite sequence of stable complexes increasing in size.  
 $m$  is number of monomer types,  $P_i(j) = \#$  monomers of type  $j$  in complex  $P_i$ .
2. Represent each monomer type as a vector in  $\mathbb{Z}^d$  as on previous slide.
  1.  $P_i$  is composed of monomers  $m_{1i}, m_{2i}, \dots, m_{ki}$ .
  2. Let  $S_i = m_{1i} + m_{2i} + \dots + m_{ki}$ . Note that there is a  $m \times d$  matrix  $M$  such that  $S_i = M \cdot P_i$ .
3. Take several infinite subsequences:
  1. Since there are a finite number of domain types, some infinite subsequence of  $P_i$ 's agrees on which set of domain types are unbound.
  2. By Dickson's Lemma we may assume  $P_1 < P_2 < \dots$  and  $S_1 < S_2 < \dots$  i.e., each has all the monomers of the previous, plus some more, and each has all the unbound domains of the previous, plus some more.
4. Let  $d = P_2 - P_1$ . Then  $M \cdot d = M \cdot P_2 - M \cdot P_1 = S_2 - S_1 \geq 0$ .
5. i.e.,  $S_2 = S_1 + M \cdot d$  and all three are nonnegative,
6. i.e., we can split  $S_2$  into 2 disjoint nonempty nonnegative subsets,  $S_1$  and  $M \cdot d$ . **QED**



# A digression into computational complexity

- INTEGER-PROGRAMMING problem

Given: integer matrix  $\mathbf{A}$ , integer vector  $\mathbf{b}$

Question: is there a nonnegative integer vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$ ?

# A digression into computational complexity

- INTEGER-PROGRAMMING problem  
Given: integer matrix  $\mathbf{A}$ , integer vector  $\mathbf{b}$   
Question: is there a nonnegative integer vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$ ?
- 0/1-INTEGGER-PROGRAMMING is **NP**-complete (Karp 1972).

# A digression into computational complexity

- INTEGER-PROGRAMMING problem

Given: integer matrix  $\mathbf{A}$ , integer vector  $\mathbf{b}$

Question: is there a nonnegative integer vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$ ?

- 0/1-INTEGGER-PROGRAMMING is **NP**-complete (Karp 1972).
- Non-obvious fact: INTEGER-PROGRAMMING is in **NP**. (*independently due to [Borosh and Treybig 1976], [Gathen and Sieveking 1978], [Kannan and Monma 1978]*)

# A digression into computational complexity

- INTEGER-PROGRAMMING problem

Given: integer matrix  $\mathbf{A}$ , integer vector  $\mathbf{b}$

Question: is there a nonnegative integer vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$ ?

- 0/1-INTEGGER-PROGRAMMING is **NP**-complete (Karp 1972).
- Non-obvious fact: INTEGER-PROGRAMMING is in **NP**. (*independently due to [Borosh and Treybig 1976], [Gathen and Sieveking 1978], [Kannan and Monma 1978]*)  
If  $\mathbf{Ax} = \mathbf{b}$  has a solution, it has a “small” solution...  $\max_i x_i \leq \exp(\max_{ij}(\mathbf{A}_{ij}, \mathbf{b}_j))$

# A digression into computational complexity

- INTEGER-PROGRAMMING problem
  - Given: integer matrix  $\mathbf{A}$ , integer vector  $\mathbf{b}$
  - Question: is there a nonnegative integer vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$ ?
- 0/1-INTEGGER-PROGRAMMING is **NP**-complete (Karp 1972).
- Non-obvious fact: INTEGER-PROGRAMMING is in **NP**. (*independently due to [Borosh and Treybig 1976], [Gathen and Sieveking 1978], [Kannan and Monma 1978]*)
  - If  $\mathbf{Ax} = \mathbf{b}$  has a solution, it has a “small” solution...  $\max_i x_i \leq \exp(\max_{ij}(\mathbf{A}_{ij}, \mathbf{b}_j))$
- Papadimitriou’s proof: [*On the complexity of integer programming*. Papadimitriou, JACM 1981]
  - If  $\mathbf{x}$  is a *large enough* solution, there is  $\mathbf{0} < \mathbf{y} < \mathbf{x}$ ,  $\mathbf{y} \in \mathbb{N}^m$ , such that  $\mathbf{Ay} = \mathbf{0}$ .

# A digression into computational complexity

- INTEGER-PROGRAMMING problem

Given: integer matrix  $\mathbf{A}$ , integer vector  $\mathbf{b}$

Question: is there a nonnegative integer vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$ ?

- 0/1-INTEGGER-PROGRAMMING is **NP**-complete (Karp 1972).
- Non-obvious fact: INTEGER-PROGRAMMING is in **NP**. (*independently due to [Borosh and Treybig 1976], [Gathen and Sieveking 1978], [Kannan and Monma 1978]*)  
If  $\mathbf{Ax} = \mathbf{b}$  has a solution, it has a “small” solution...  $\max_i x_i \leq \exp(\max_{ij}(\mathbf{A}_{ij}, \mathbf{b}_j))$
- Papadimitriou’s proof: [*On the complexity of integer programming*. Papadimitriou, JACM 1981]
  - If  $\mathbf{x}$  is a *large enough* solution, there is  $\mathbf{0} < \mathbf{y} < \mathbf{x}$ ,  $\mathbf{y} \in \mathbb{N}^m$ , such that  $\mathbf{Ay} = \mathbf{0}$ .
  - Defining  $\mathbf{z} = \mathbf{x} - \mathbf{y}$ ,  $\mathbf{Az} = \mathbf{A}(\mathbf{x} - \mathbf{y}) = \mathbf{Ax} - \mathbf{Ay} = \mathbf{Ax} - \mathbf{0} = \mathbf{b}$ .

# A digression into computational complexity

- INTEGER-PROGRAMMING problem

Given: integer matrix  $\mathbf{A}$ , integer vector  $\mathbf{b}$

Question: is there a nonnegative integer vector  $\mathbf{x}$  such that  $\mathbf{Ax} = \mathbf{b}$ ?

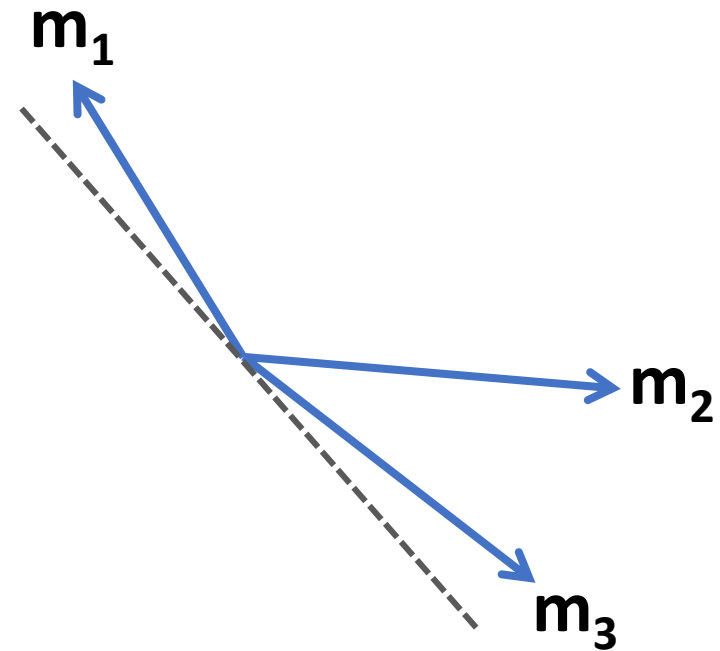
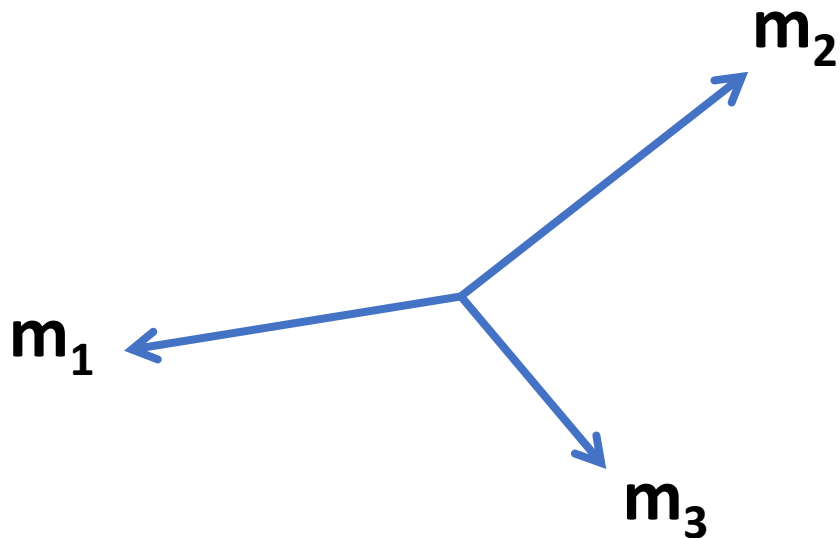
- 0/1-INTEGGER-PROGRAMMING is **NP**-complete (Karp 1972).
- Non-obvious fact: INTEGER-PROGRAMMING is in **NP**. (*independently due to [Borosh and Treybig 1976], [Gathen and Sieveking 1978], [Kannan and Monma 1978]*)  
If  $\mathbf{Ax} = \mathbf{b}$  has a solution, it has a “small” solution...  $\max_i x_i \leq \exp(\max_{ij}(\mathbf{A}_{ij}, \mathbf{b}_j))$
- Papadimitriou’s proof: [*On the complexity of integer programming*. Papadimitriou, JACM 1981]
  - If  $\mathbf{x}$  is a *large enough* solution, there is  $\mathbf{0} < \mathbf{y} < \mathbf{x}$ ,  $\mathbf{y} \in \mathbb{N}^m$ , such that  $\mathbf{Ay} = \mathbf{0}$ .
  - Defining  $\mathbf{z} = \mathbf{x} - \mathbf{y}$ ,  $\mathbf{Az} = \mathbf{A}(\mathbf{x} - \mathbf{y}) = \mathbf{Ax} - \mathbf{Ay} = \mathbf{Ax} - \mathbf{0} = \mathbf{b}$ .
  - So  $\mathbf{z}$  is a strictly smaller solution than  $\mathbf{x}$ :  $\mathbf{x}$  cannot be the *smallest* solution.

# Farkas' Lemma

Given vectors  $\mathbf{m}_1, \mathbf{m}_2, \dots$ , they obey one of two constraints:

a) are directions of balanced forces

b) lie on one side of some hyperplane





# Farkas' Lemma

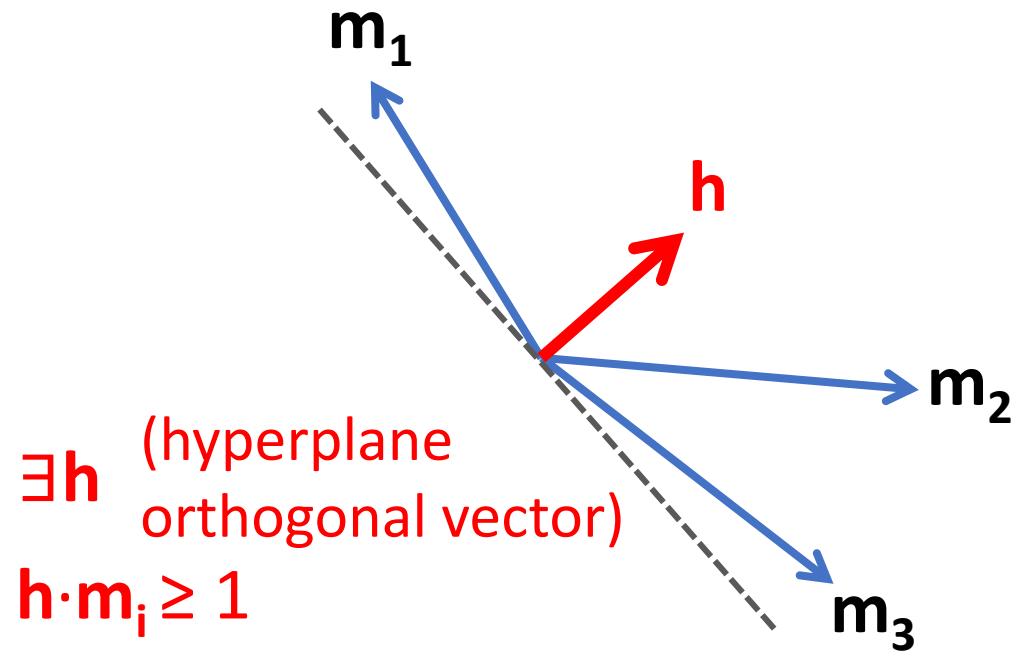
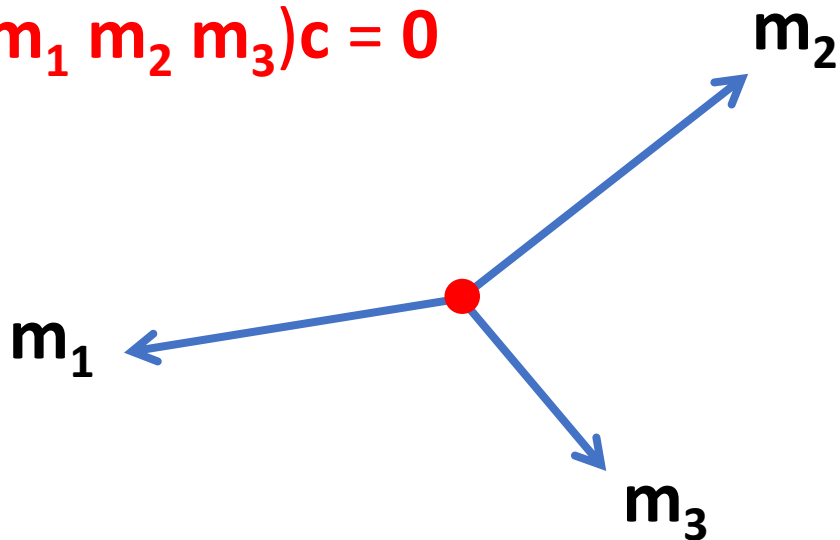
Given vectors  $\mathbf{m}_1, \mathbf{m}_2, \dots$ , they obey one of two constraints:

a) are directions of balanced forces

b) lie on one side of some hyperplane

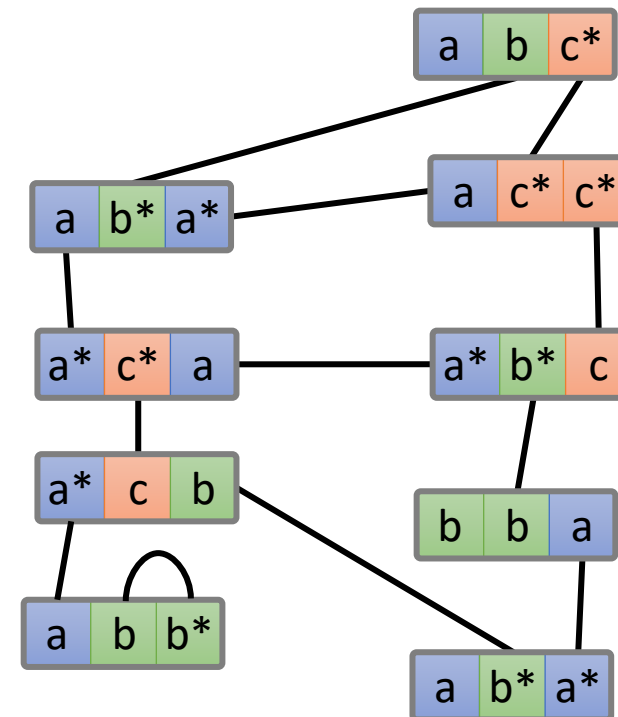
$\exists \mathbf{c}$  (counts of monomers)

$$(\mathbf{m}_1 \ \mathbf{m}_2 \ \mathbf{m}_3) \mathbf{c} = 0$$



# How to prove exponential complex size bound for complexes with cycles in binding graph?

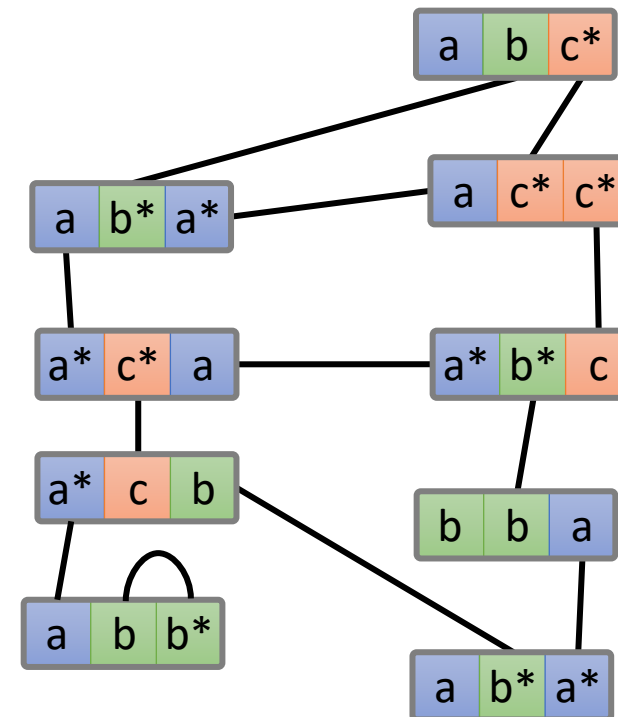
monomer collection  $\mathbf{c} \in \mathbb{N}^M$



# How to prove exponential complex size bound for complexes with cycles in binding graph?

- $\mathbf{A} = d \times m$  matrix:  $\mathbf{A}_{ij}$  = monomer  $\mathbf{m}_j$ 's excess of domain  $d_i$  over  $d_i^*$

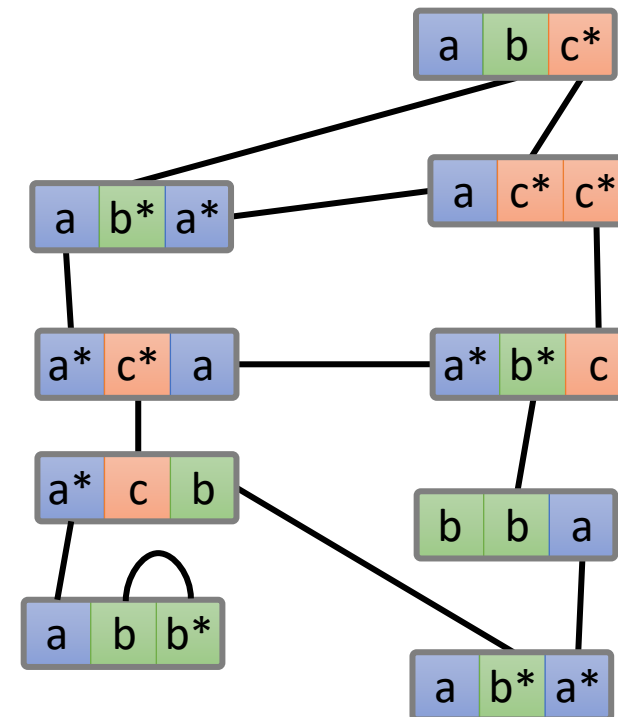
monomer collection  $\mathbf{c} \in \mathbb{N}^M$



# How to prove exponential complex size bound for complexes with cycles in binding graph?

- $\mathbf{A} = d \times m$  matrix:  $\mathbf{A}_{ij}$  = monomer  $\mathbf{m}_j$ 's excess of domain  $d_i$  over  $d_i^*$
- If  $\mathbf{Ac} = \mathbf{b}$ , then  $\mathbf{b}_i$  = total # unbound  $d_i$  in any saturated configuration of  $\mathbf{c}$

monomer collection  $\mathbf{c} \in \mathbb{N}^M$

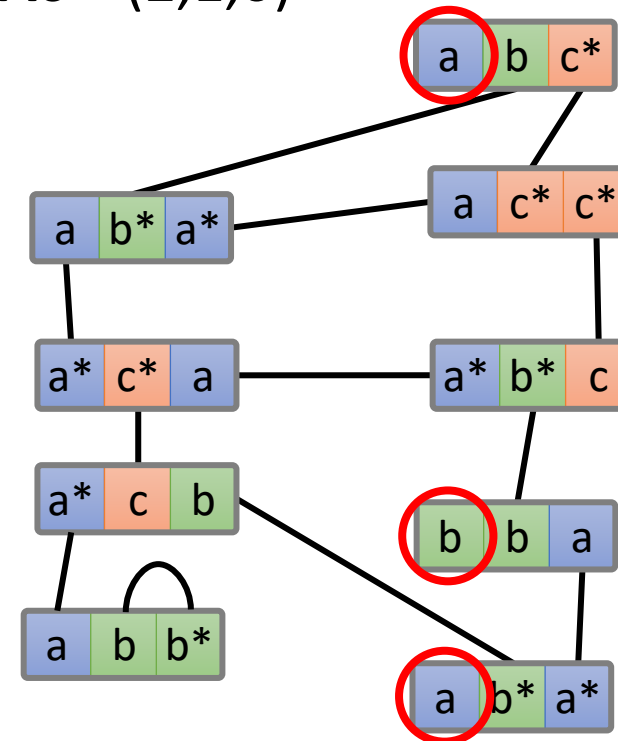


# How to prove exponential complex size bound for complexes with cycles in binding graph?

- $\mathbf{A} = d \times m$  matrix:  $\mathbf{A}_{ij}$  = monomer  $\mathbf{m}_j$ 's excess of domain  $d_i$  over  $d_i^*$
- If  $\mathbf{Ac} = \mathbf{b}$ , then  $\mathbf{b}_i$  = total # unbound  $d_i$  in any saturated configuration of  $\mathbf{c}$

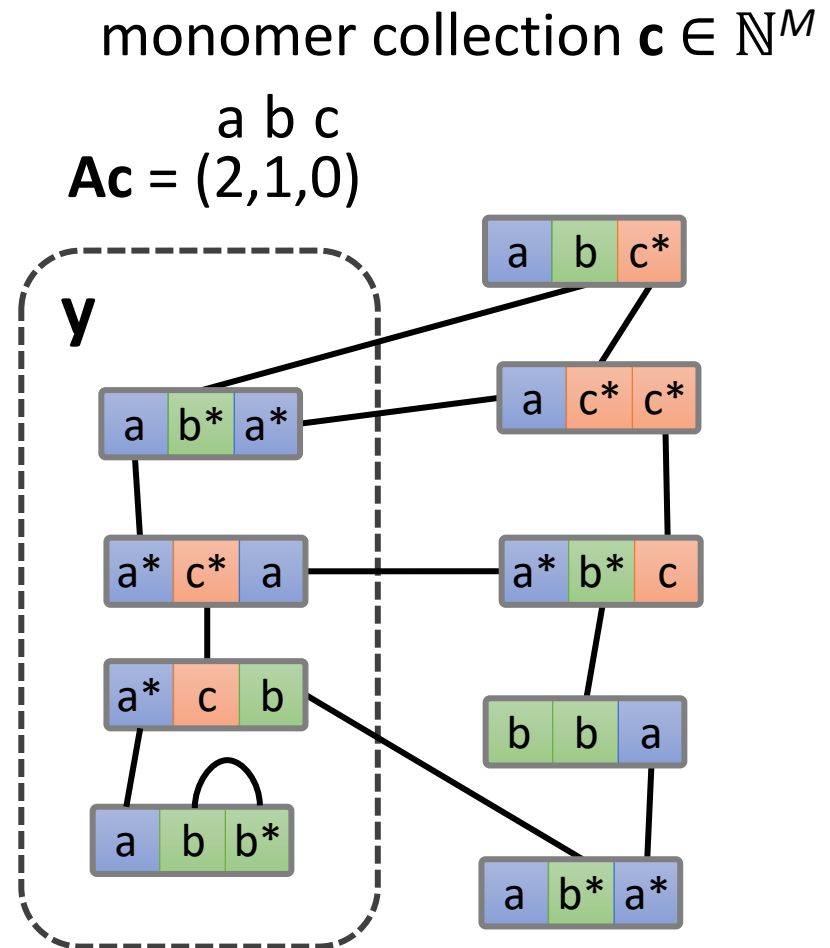
monomer collection  $\mathbf{c} \in \mathbb{N}^M$

$$\mathbf{Ac} = \begin{matrix} a & b & c \\ (2, 1, 0) \end{matrix}$$



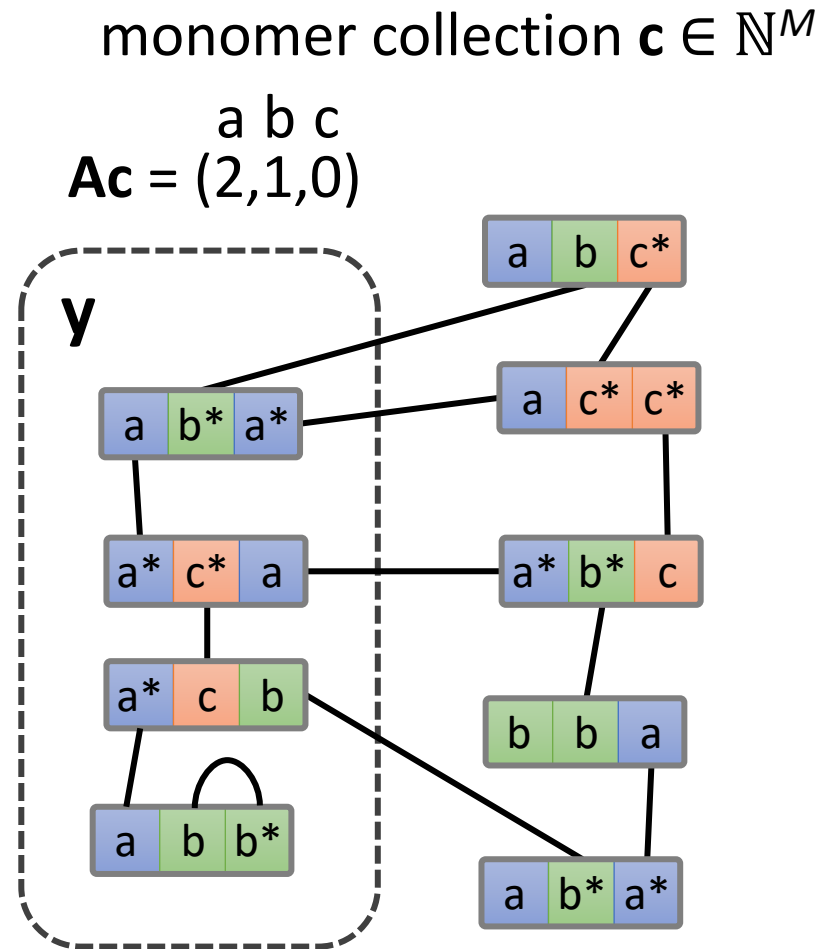
# How to prove exponential complex size bound for complexes with cycles in binding graph?

- $\mathbf{A} = d \times m$  matrix:  $\mathbf{A}_{ij}$  = monomer  $\mathbf{m}_j$ 's excess of domain  $d_i$  over  $d_i^*$
- If  $\mathbf{Ac} = \mathbf{b}$ , then  $\mathbf{b}_i$  = total # unbound  $d_i$  in any saturated configuration of  $\mathbf{c}$
- If  $|\mathbf{c}| >$  exponential in  $D$ , Papadimtriou's proof gives us subcollection  $\mathbf{y} < \mathbf{c}$  such that  $\mathbf{Ay} = \mathbf{0}$ , (*Farkas' Lemma says that if this fails, then monomer vectors all lie on one side of a hyperplane, see next slide*)



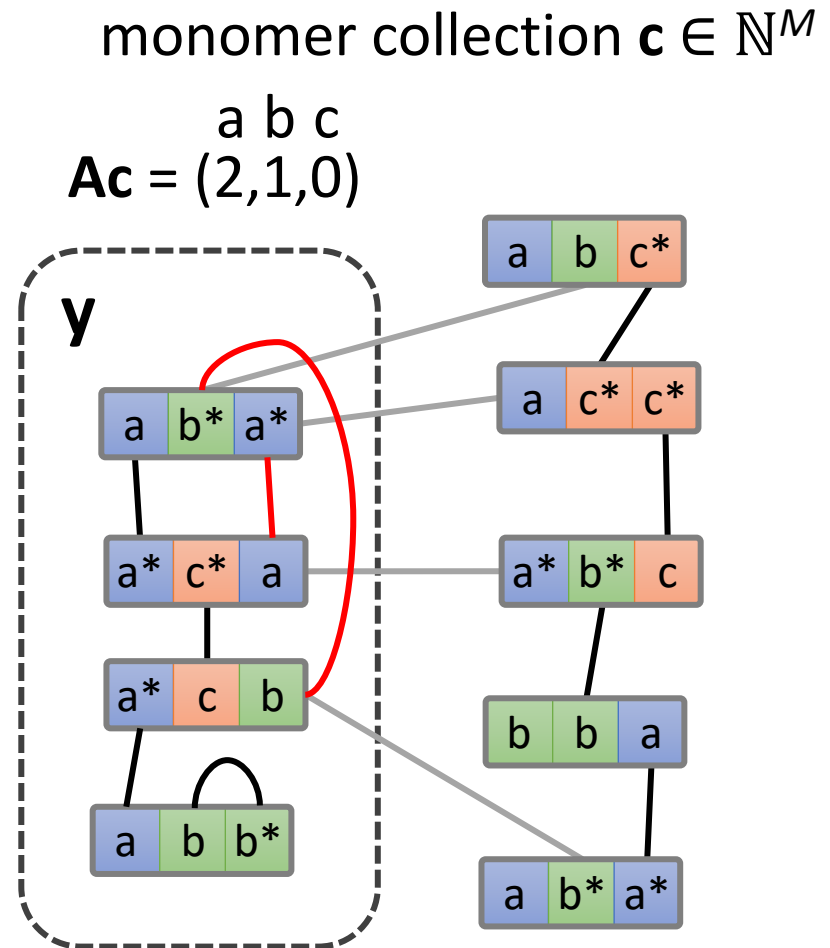
# How to prove exponential complex size bound for complexes with cycles in binding graph?

- $\mathbf{A} = d \times m$  matrix:  $\mathbf{A}_{ij}$  = monomer  $\mathbf{m}_j$ 's excess of domain  $d_i$  over  $d_i^*$
- If  $\mathbf{Ac} = \mathbf{b}$ , then  $\mathbf{b}_i$  = total # unbound  $d_i$  in any saturated configuration of  $\mathbf{c}$
- If  $|\mathbf{c}| >$  exponential in  $D$ , Papadimitriou's proof gives us subcollection  $\mathbf{y} < \mathbf{c}$  such that  $\mathbf{Ay} = \mathbf{0}$ , (*Farkas' Lemma says that if this fails, then monomer vectors all lie on one side of a hyperplane, see next slide*)
- i.e.,  $\#d_i$  in  $\mathbf{y} = \#d_i^*$  in  $\mathbf{y}$ , so  $\mathbf{y}$  is self-saturating.



# How to prove exponential complex size bound for complexes with cycles in binding graph?

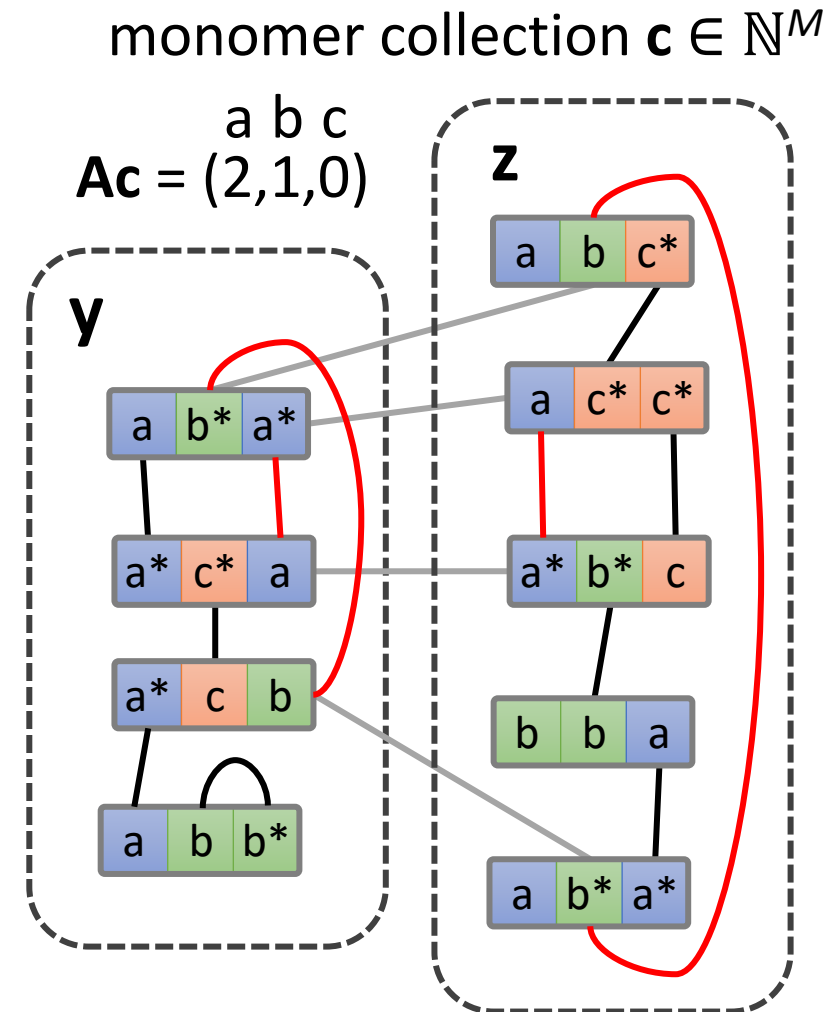
- $\mathbf{A} = d \times m$  matrix:  $\mathbf{A}_{ij}$  = monomer  $\mathbf{m}_j$ 's excess of domain  $d_i$  over  $d_i^*$
- If  $\mathbf{Ac} = \mathbf{b}$ , then  $\mathbf{b}_i$  = total # unbound  $d_i$  in any saturated configuration of  $\mathbf{c}$
- If  $|\mathbf{c}| >$  exponential in  $D$ , Papadimitriou's proof gives us subcollection  $\mathbf{y} < \mathbf{c}$  such that  $\mathbf{Ay} = \mathbf{0}$ , (*Farkas' Lemma says that if this fails, then monomer vectors all lie on one side of a hyperplane, see next slide*)
- i.e.,  $\#d_i$  in  $\mathbf{y} = \#d_i^*$  in  $\mathbf{y}$ , so  $\mathbf{y}$  is self-saturating.
- So whatever bonds were broken to separate  $\mathbf{y}$  can be re-bound within  $\mathbf{y}$ .





# How to prove exponential complex size bound for complexes with cycles in binding graph?

- $\mathbf{A} = d \times m$  matrix:  $\mathbf{A}_{ij}$  = monomer  $\mathbf{m}_j$ 's excess of domain  $d_i$  over  $d_i^*$
- If  $\mathbf{Ac} = \mathbf{b}$ , then  $\mathbf{b}_i$  = total # unbound  $d_i$  in any saturated configuration of  $\mathbf{c}$
- If  $|\mathbf{c}| >$  exponential in  $D$ , Papadimtriou's proof gives us subcollection  $\mathbf{y} < \mathbf{c}$  such that  $\mathbf{Ay} = \mathbf{0}$ , (*Farkas' Lemma says that if this fails, then monomer vectors all lie on one side of a hyperplane, see next slide*)
- i.e.,  $\#d_i$  in  $\mathbf{y} = \#d_i^*$  in  $\mathbf{y}$ , so  $\mathbf{y}$  is self-saturating.
- So whatever bonds were broken to separate  $\mathbf{y}$  can be re-bound within  $\mathbf{y}$ .
- By symmetry, the same bonds in  $\mathbf{z} = \mathbf{c} - \mathbf{y}$  can be re-bound within  $\mathbf{z}$ .



If all monomer types lie on one side of hyperplane  $\mathbf{h}$ ...

If all monomer types lie on one side of hyperplane  $h$ ...

- Consider “slack monomers”  $\{d_1^*\}, \{d_2^*\}, \dots$ , adding just enough to bind to all the excess  $d_i$  domains, so **saturated** (fully bound) == **all domains bound**

If all monomer types lie on one side of hyperplane  $\mathbf{h}$ ...

- Consider “slack monomers”  $\{d_1^*\}, \{d_2^*\}, \dots$ , adding just enough to bind to all the excess  $d_i$  domains, so **saturated** (fully bound) == **all domains bound**
- If  $\mathbf{c}$  is count of all monomers including slack monomers ( $\mathbf{c}(i) = \text{count of } \mathbf{m}_i$ ), then  **$\mathbf{Ac} = \mathbf{0}$** , where each column of **A** represents a monomer (counts of domains).

If all monomer types lie on one side of hyperplane  $\mathbf{h}$ ...

- Consider “slack monomers”  $\{d_1^*\}, \{d_2^*\}, \dots$ , adding just enough to bind to all the excess  $d_i$  domains, so **saturated** (fully bound) == **all domains bound**
- If  $\mathbf{c}$  is count of all monomers including slack monomers ( $\mathbf{c}(i)$  = count of  $\mathbf{m}_i$ ), then  $\mathbf{A}\mathbf{c} = \mathbf{0}$ , where each column of  $\mathbf{A}$  represents a monomer (counts of domains).
- dot-product  $\mathbf{h}$  on both sides:  $\mathbf{h} \cdot \mathbf{A}\mathbf{c} = \mathbf{h} \cdot \mathbf{0} = 0$ , distribute through:  $\sum_i (\mathbf{h} \cdot \mathbf{m}_i) \mathbf{c}(i) = 0$

If all monomer types lie on one side of hyperplane  $\mathbf{h}$ ...

- Consider “slack monomers”  $\{d_1^*\}, \{d_2^*\}, \dots$ , adding just enough to bind to all the excess  $d_i$  domains, so **saturated** (fully bound) == **all domains bound**
- If  $\mathbf{c}$  is count of all monomers including slack monomers ( $\mathbf{c}(i)$  = count of  $\mathbf{m}_i$ ), then  $\mathbf{Ac} = \mathbf{0}$ , where each column of  $\mathbf{A}$  represents a monomer (counts of domains).
- dot-product  $\mathbf{h}$  on both sides:  $\mathbf{h} \cdot \mathbf{Ac} = \mathbf{h} \cdot \mathbf{0} = 0$ , distribute through:  $\sum_i (\mathbf{h} \cdot \mathbf{m}_i) \mathbf{c}(i) = 0$
- Let  $S$  be set of monomers with “small” counts, move them to one side:  
–  $\sum_{i \in S} (\mathbf{h} \cdot \mathbf{m}_i) \mathbf{c}(i) = \sum_{i \notin S} (\mathbf{h} \cdot \mathbf{m}_i) \mathbf{c}(i)$

If all monomer types lie on one side of hyperplane  $\mathbf{h}$ ...

- Consider “slack monomers”  $\{d_1^*\}, \{d_2^*\}, \dots$ , adding just enough to bind to all the excess  $d_i$  domains, so **saturated** (fully bound) == **all domains bound**
- If  $\mathbf{c}$  is count of all monomers including slack monomers ( $\mathbf{c}(i)$  = count of  $\mathbf{m}_i$ ), then  $\mathbf{A}\mathbf{c} = \mathbf{0}$ , where each column of  $\mathbf{A}$  represents a monomer (counts of domains).
- dot-product  $\mathbf{h}$  on both sides:  $\mathbf{h}\cdot\mathbf{A}\mathbf{c} = \mathbf{h}\cdot\mathbf{0} = 0$ , distribute through:  $\sum_i(\mathbf{h}\cdot\mathbf{m}_i)\mathbf{c}(i) = 0$
- Let  $S$  be set of monomers with “small” counts, move them to one side:

$$-\sum_{i \in S}(\mathbf{h}\cdot\mathbf{m}_i)\mathbf{c}(i) = \sum_{i \notin S}(\mathbf{h}\cdot\mathbf{m}_i)\mathbf{c}(i)$$

- Then “small”  $\geq -\sum_{i \in S}(\mathbf{h}\cdot\mathbf{m}_i)\mathbf{c}(i) = \sum_{i \notin S}(\mathbf{h}\cdot\mathbf{m}_i)\mathbf{c}(i) \geq \sum_{i \notin S}\mathbf{c}(i)$

$\mathbf{c}(i)$  (count of  $i$ 'th monomer) is small by definition, and  $\mathbf{h}\cdot\mathbf{m}_i = O(1)$

above

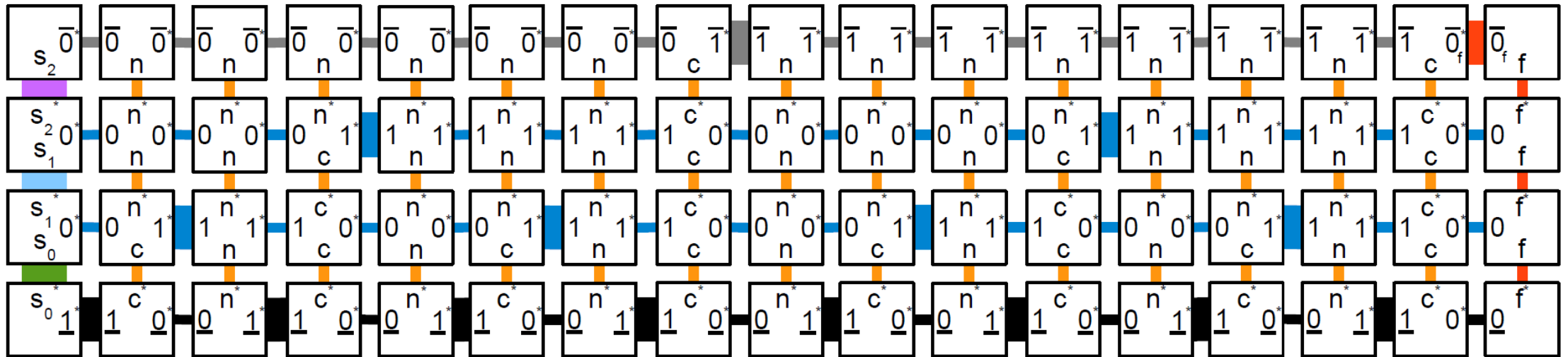
since  $\mathbf{h}\cdot\mathbf{m}_i \geq 1$

# Applying thermodynamic model to tile assembly

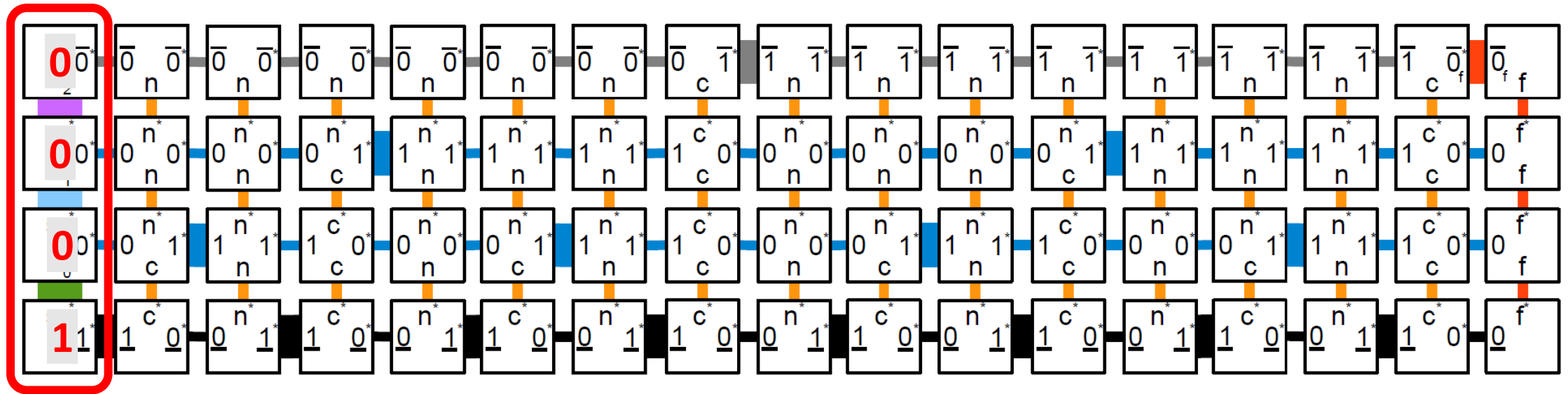
- Let's incorporate the thermodynamic binding network model into the abstract tile assembly model.
- How can we create a large assembly from a small number of tile types?



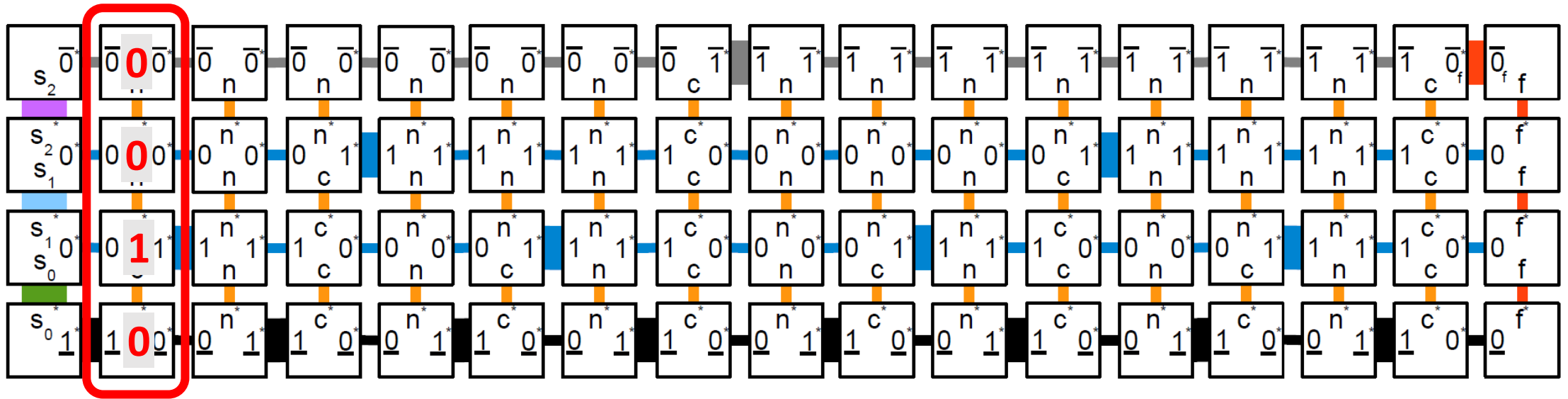
# A thermodynamically **unstable** tile assembly counter



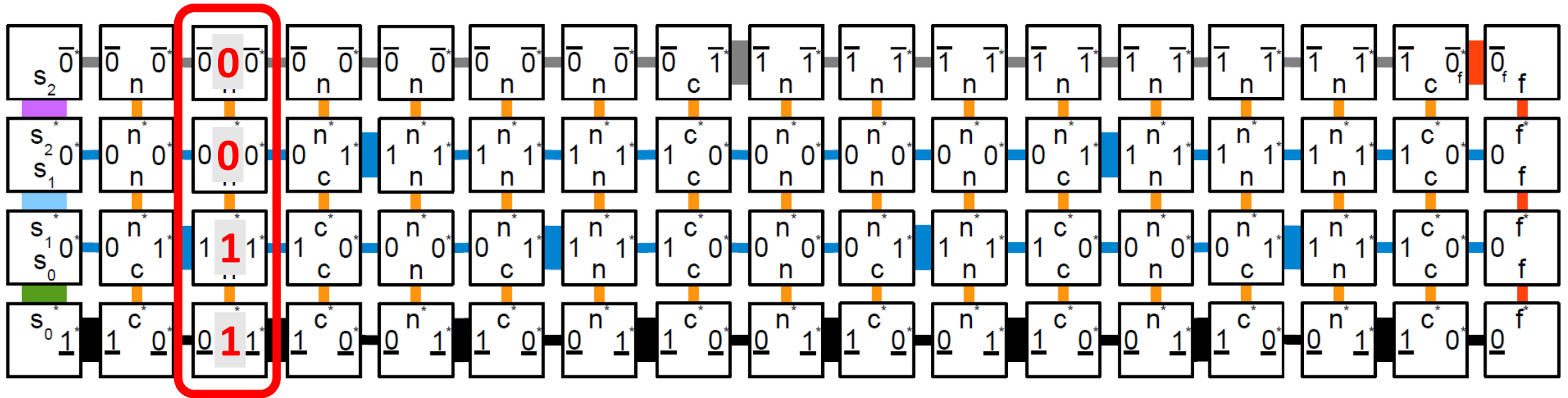
# A thermodynamically **unstable** tile assembly counter



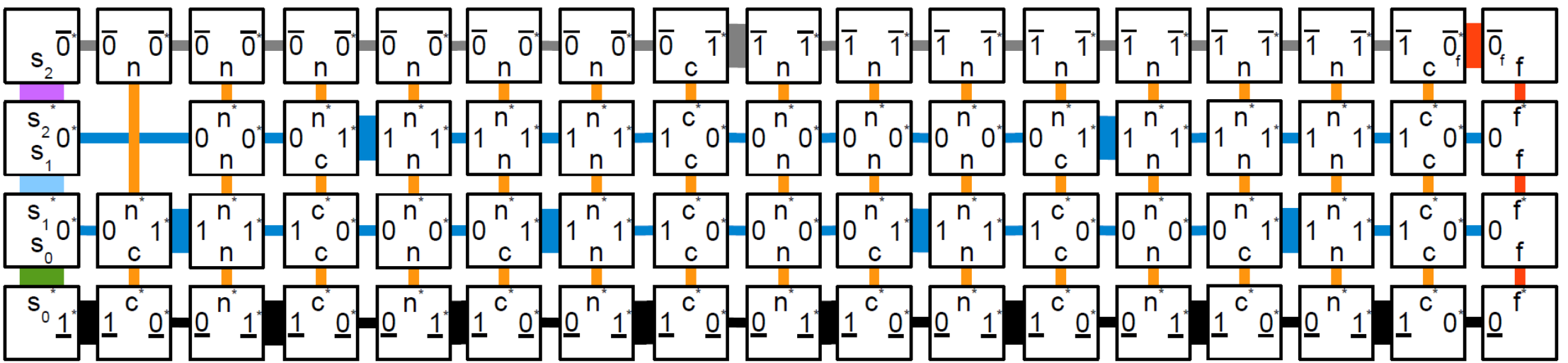
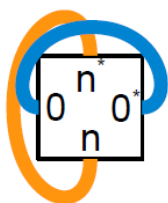
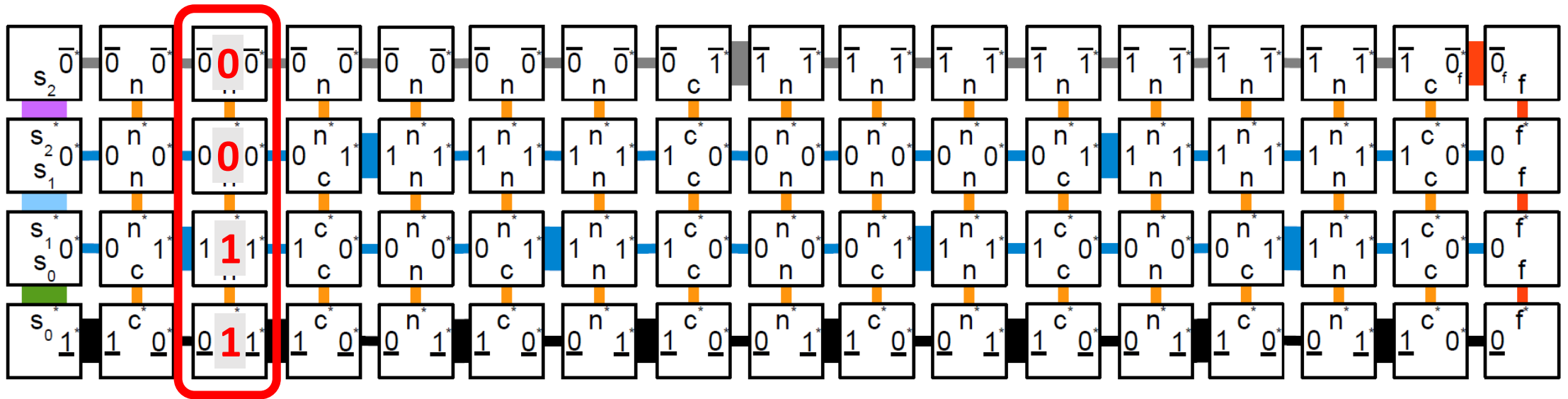
# A thermodynamically **unstable** tile assembly counter



# A thermodynamically **unstable** tile assembly counter

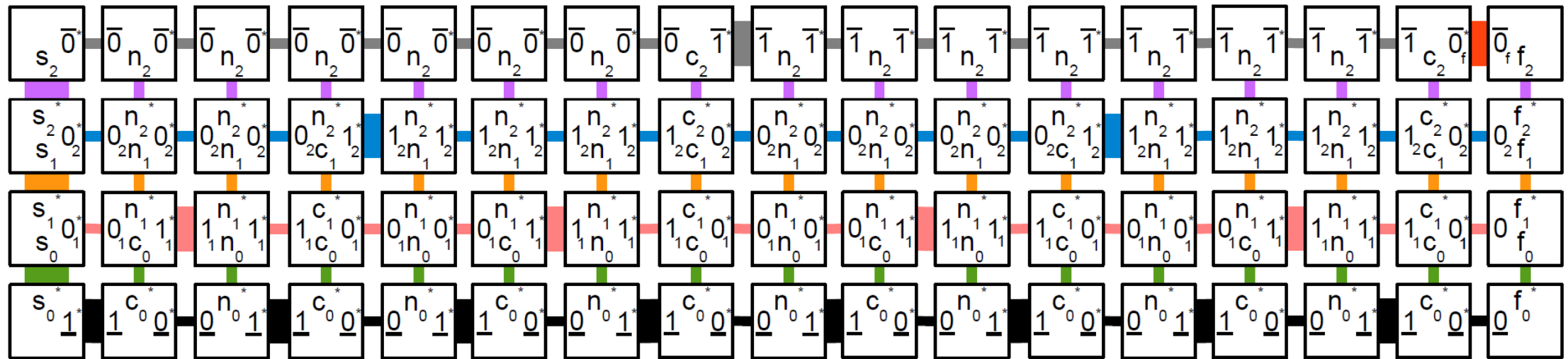


# A thermodynamically **unstable** tile assembly counter



# A thermodynamically **stable** tile assembly counter

Difference is that each row (corresponding to bits of the same significance) has glues labeled with the row number



# Conclusions

- Strong bonds (surprisingly) aren't sufficient to self-assemble large thermodynamically stable structures. *Geometry helps!*
- Kinetically self-assembling a thermodynamically stable structure has very strong guarantees on errors:
  - target structure eventually results despite arbitrary kinetic errors.
  - If it's the only stable structure, and free energy of other structures is much less, then it's the only result you'll see.
- Bad news: **NP**-complete to tell if a given configuration is unstable... even **NP**-hard to approximate entropy of stable configuration:  
[Breik, Thachuk, Heule, Soloveichik, *Computing properties of stable configurations of thermodynamic binding networks*, Theoretical Computer Science 2019]