

Unsupervised Visual Representation Learning by Context Prediction

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Presented by Maheen Rashid for ECS 289G

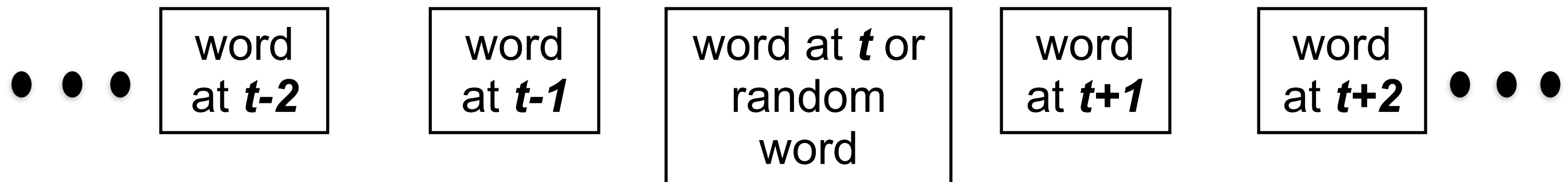
Motivation

- How can we scale to billions rather than millions of images?
 - Imagenet trained on ~ 1.2 million images
- Unsupervised learning
 - Problem - What should be represented?

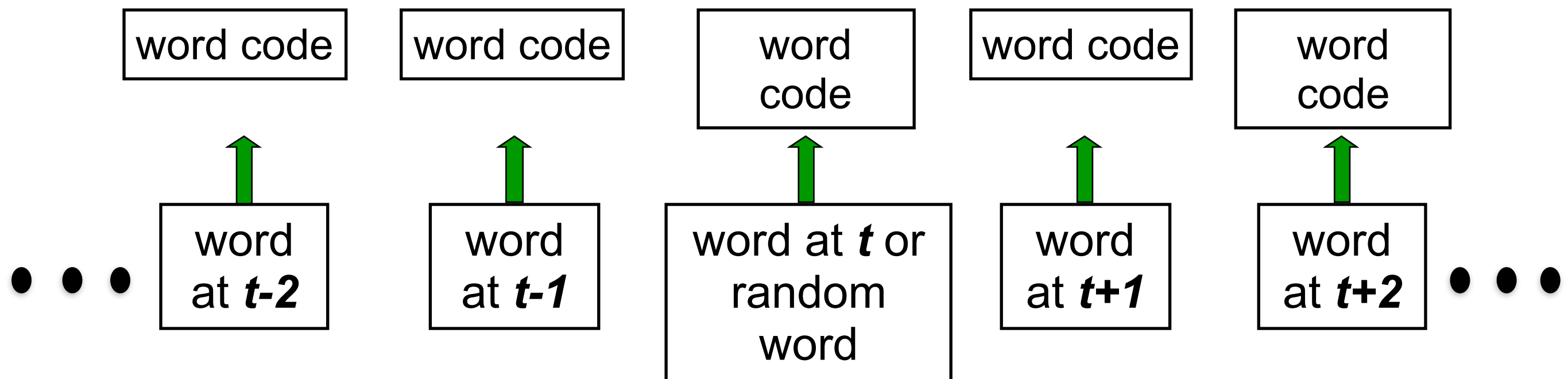
Inspiration - Context

- Similar words appear in similar contexts
- Learn to relate a given word to its surrounding words
- Context prediction becomes a 'pretext' task

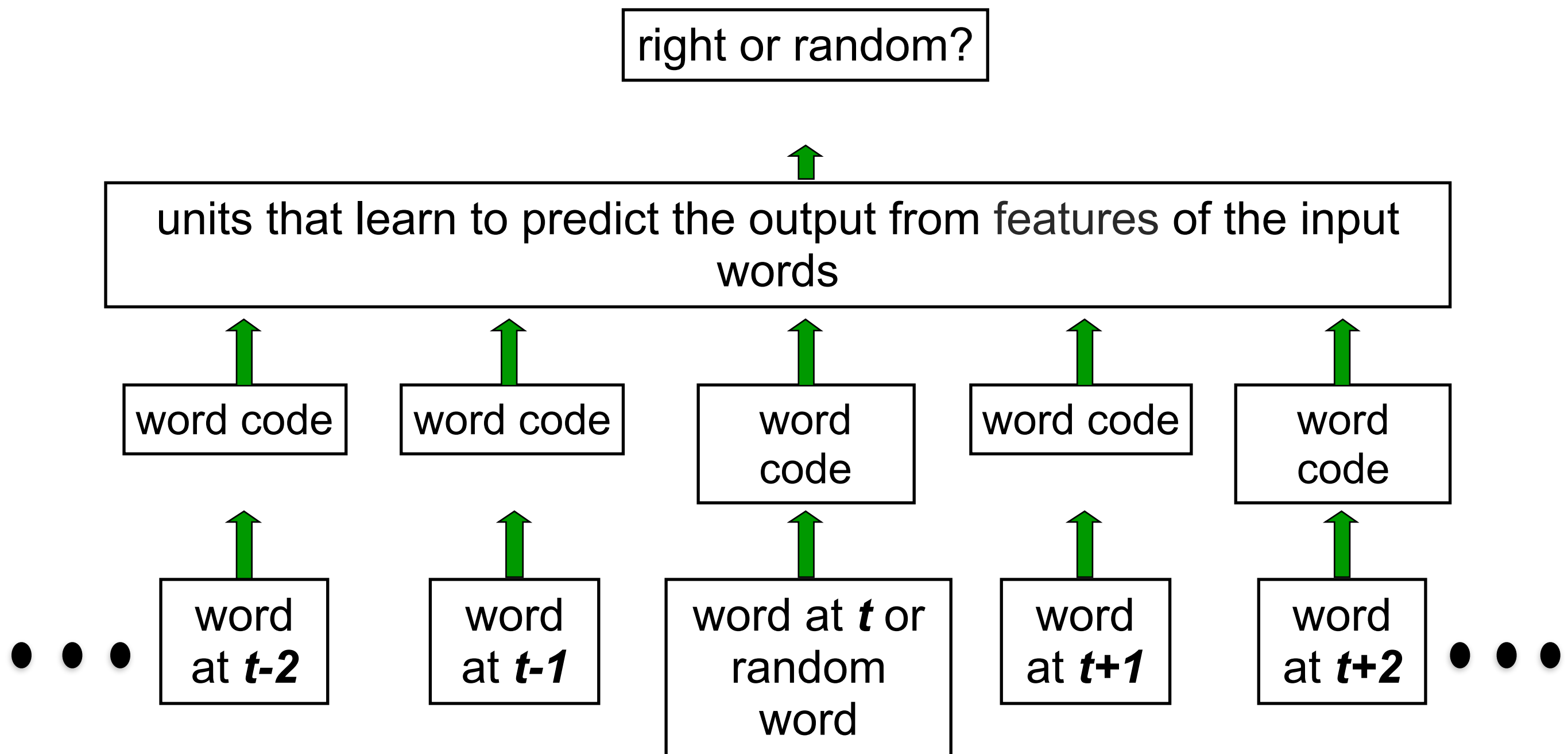
A simple way to learn feature vectors for words (Collobert and Weston, 2008)



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Right or Random for Images?



Slide from Carl Doersch

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A



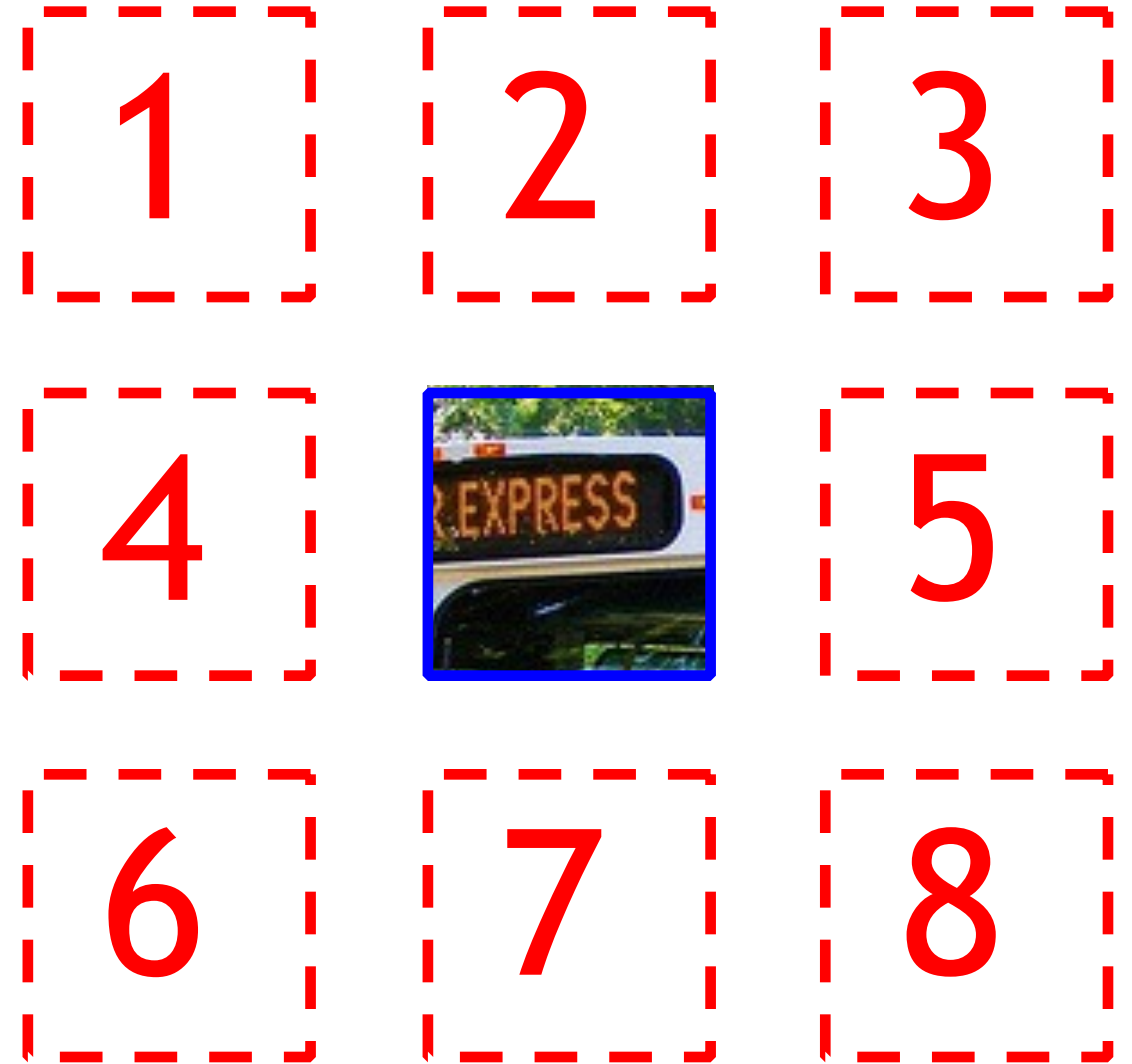
B



A



B



Can you tell where B goes relative to A?

Answer:



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Answer:



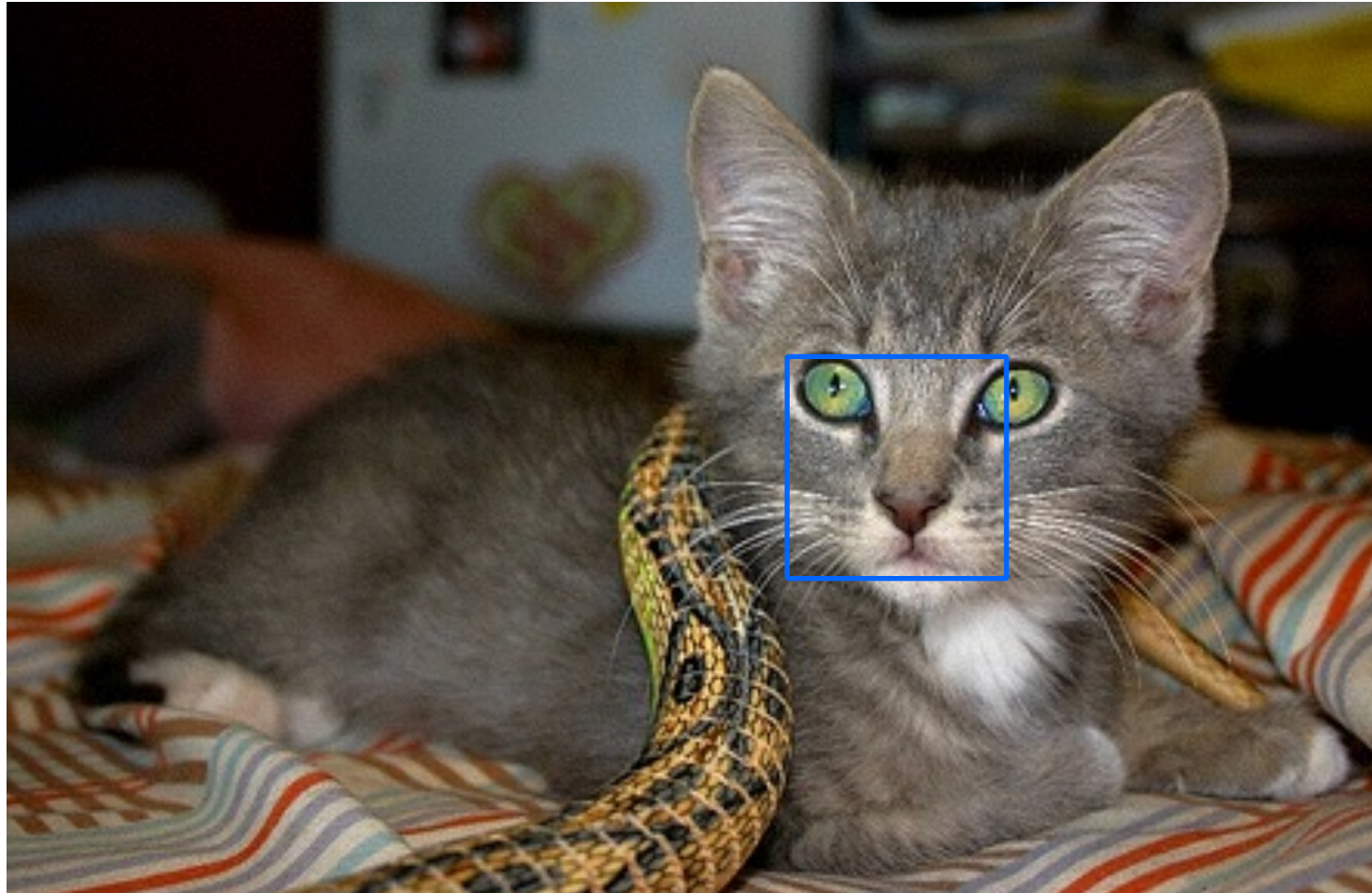
Doing this requires recognizing semantics!

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Unlabeled training image

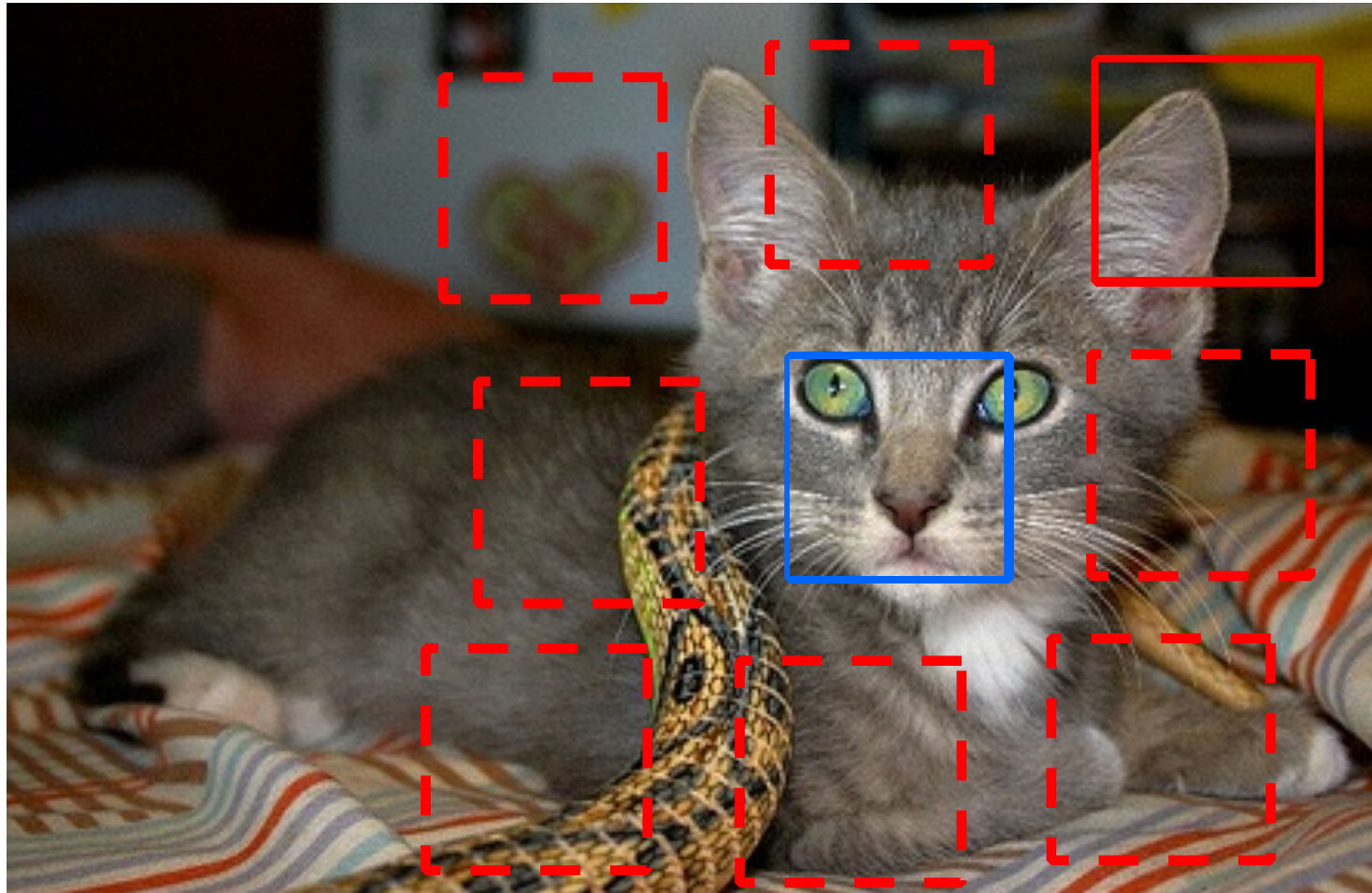


Unlabeled training image



Randomly Sample Patch

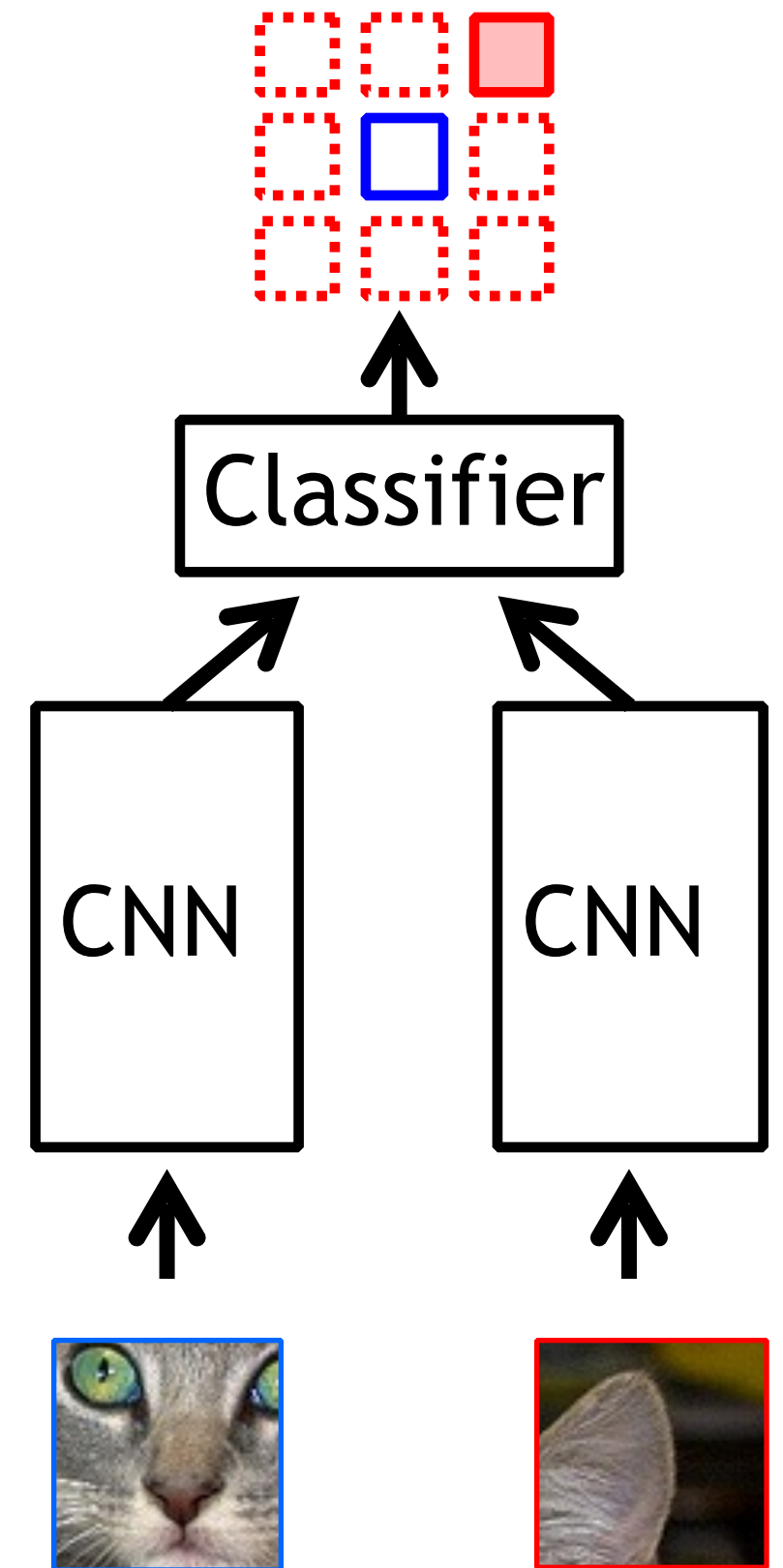
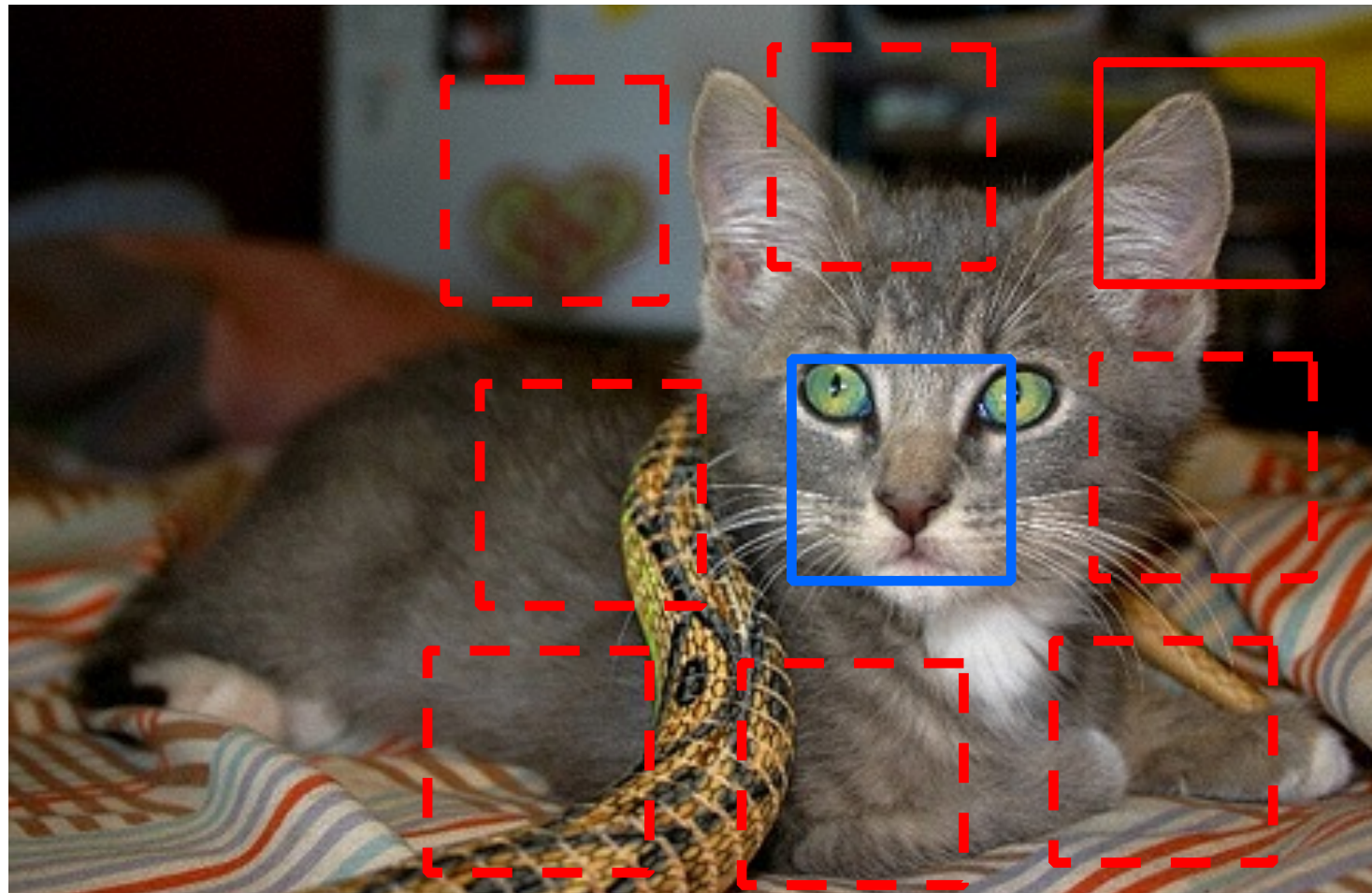
Unlabeled training image



Randomly Sample Patch

Sample Second Patch

Unlabeled training image



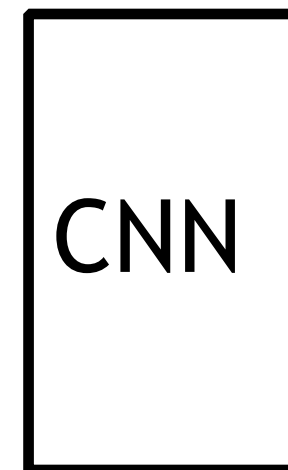
Train Deep Net to recover relative position

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CNN



Patch Features



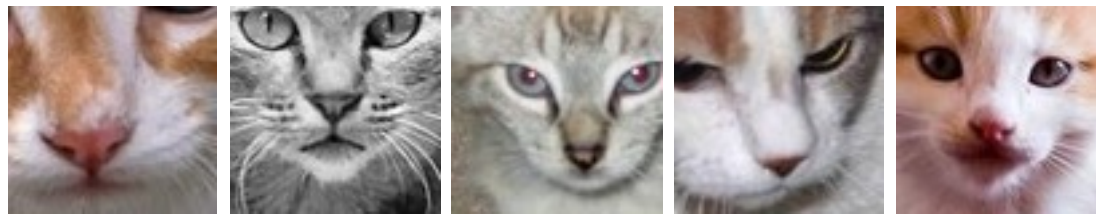
Slide from Carl Doersch

Input

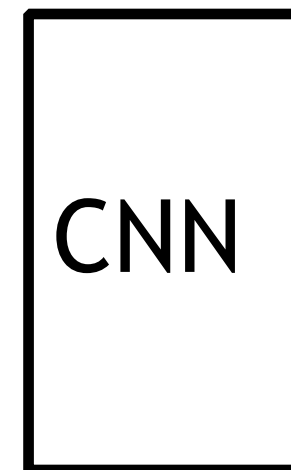


:

Nearest Neighbors

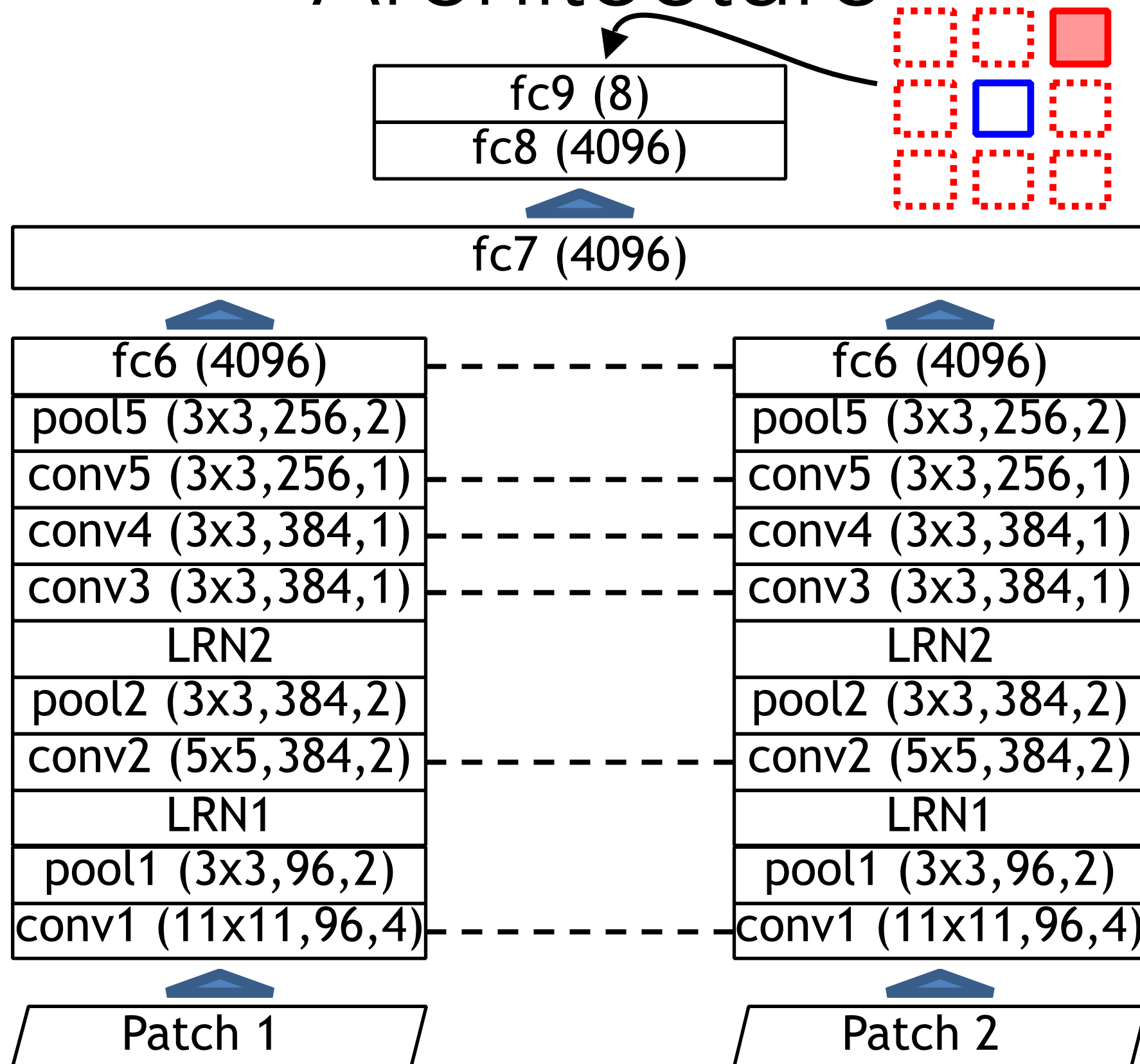


Patch Features



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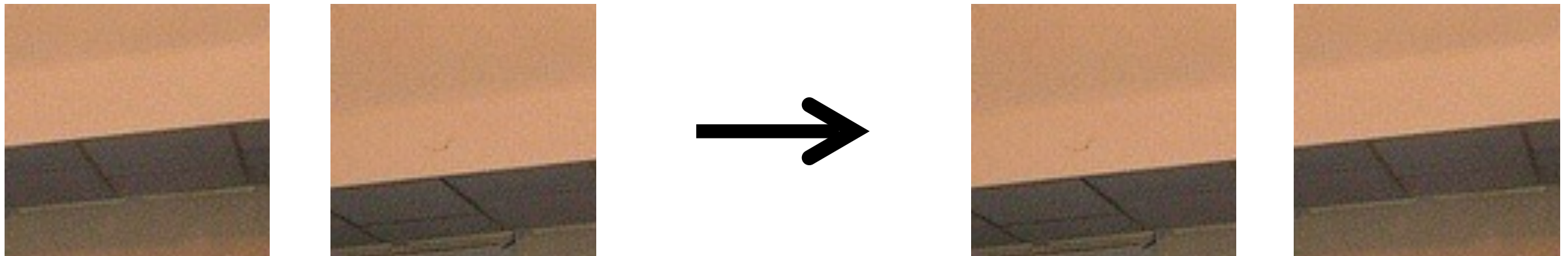
Architecture



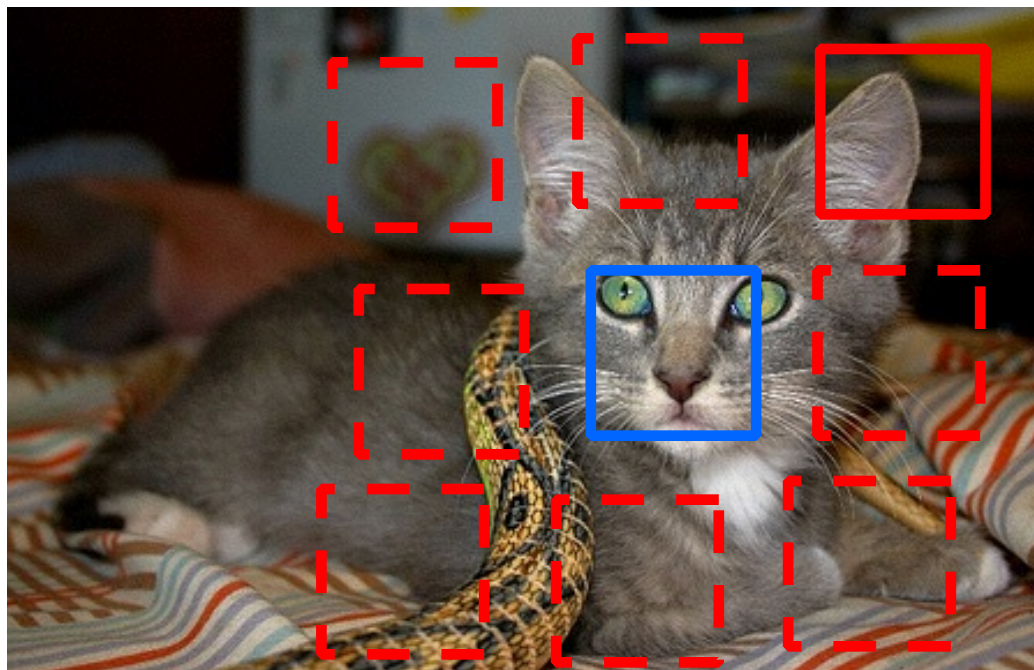
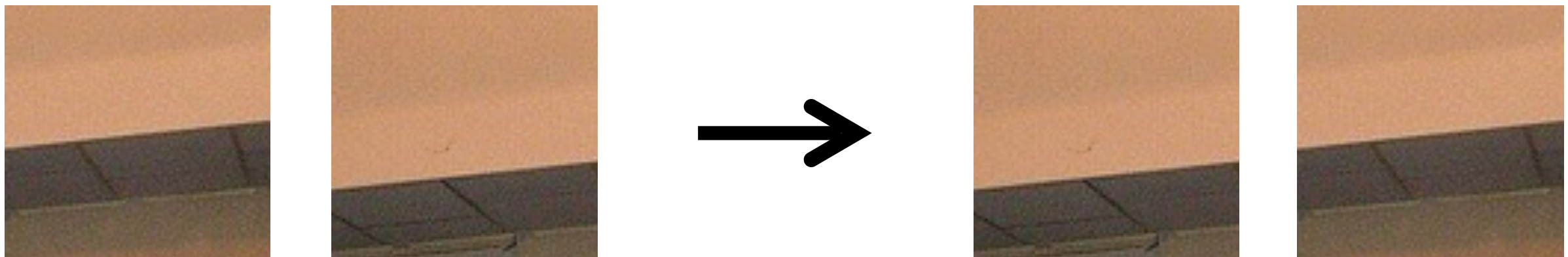
How to sample patches



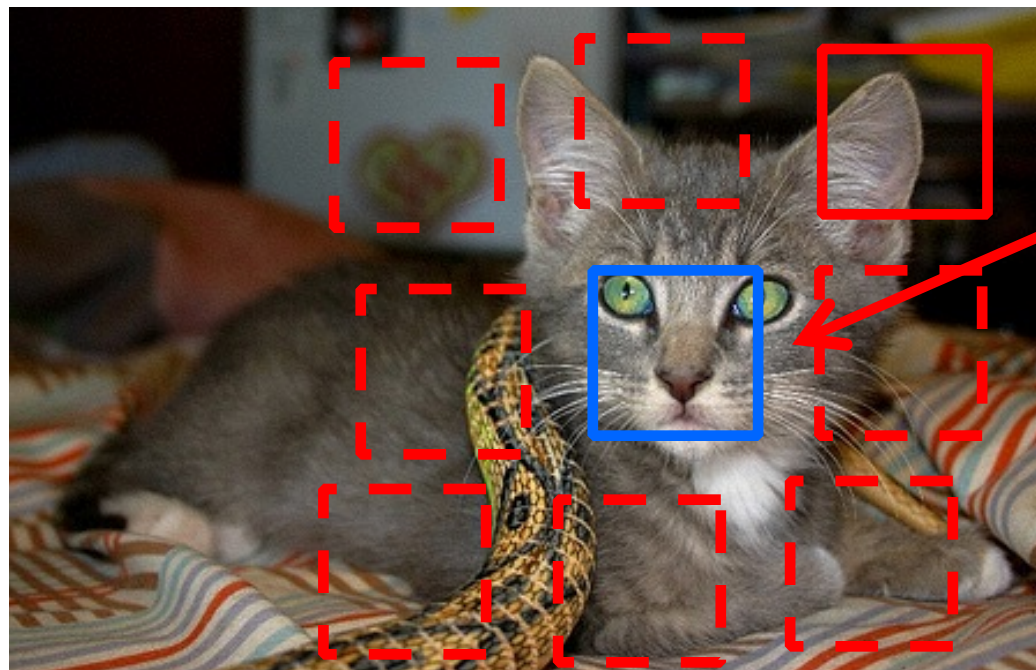
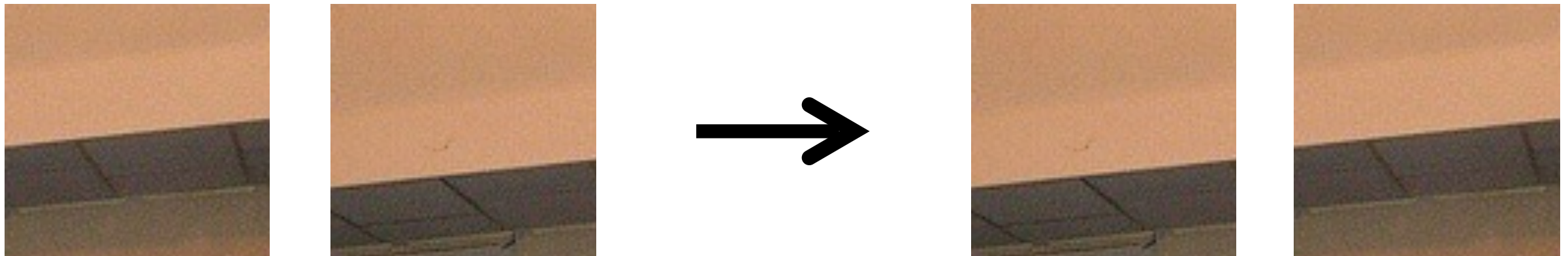
How to sample patches



How to sample patches

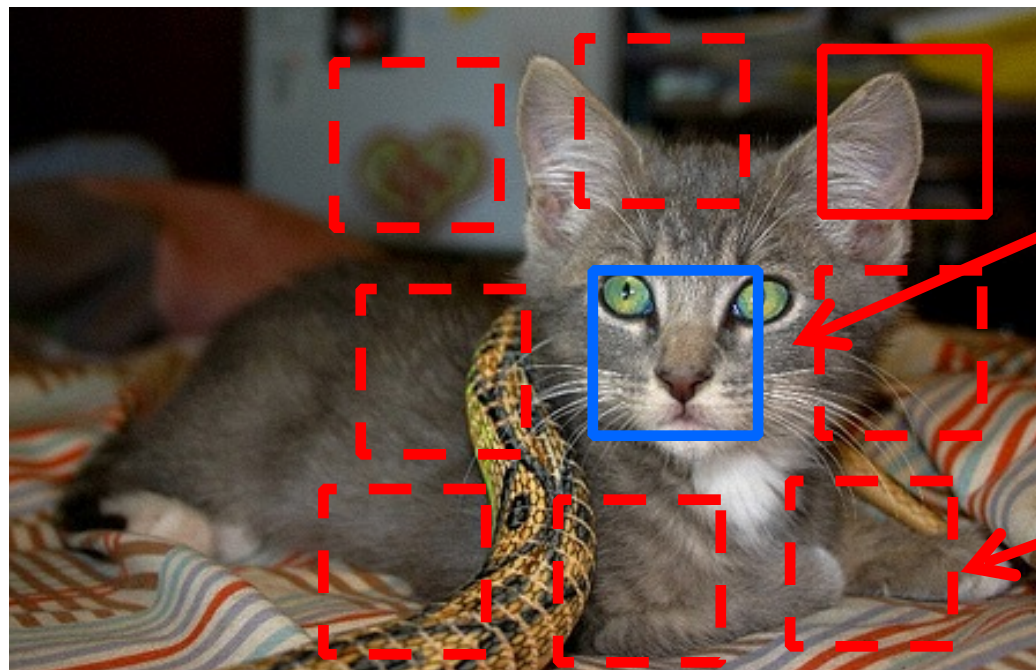
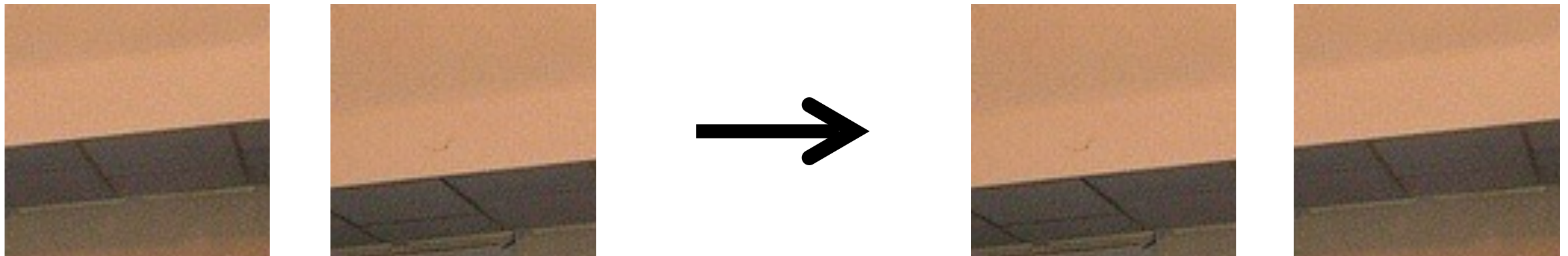


How to sample patches



Include a gap

How to sample patches



Include a gap

Jitter the patch locations

Another trivial shortcut

- Chromatic Aberration
- Shift colors towards grey (Projection)
- Drop 2 out of three channels during training

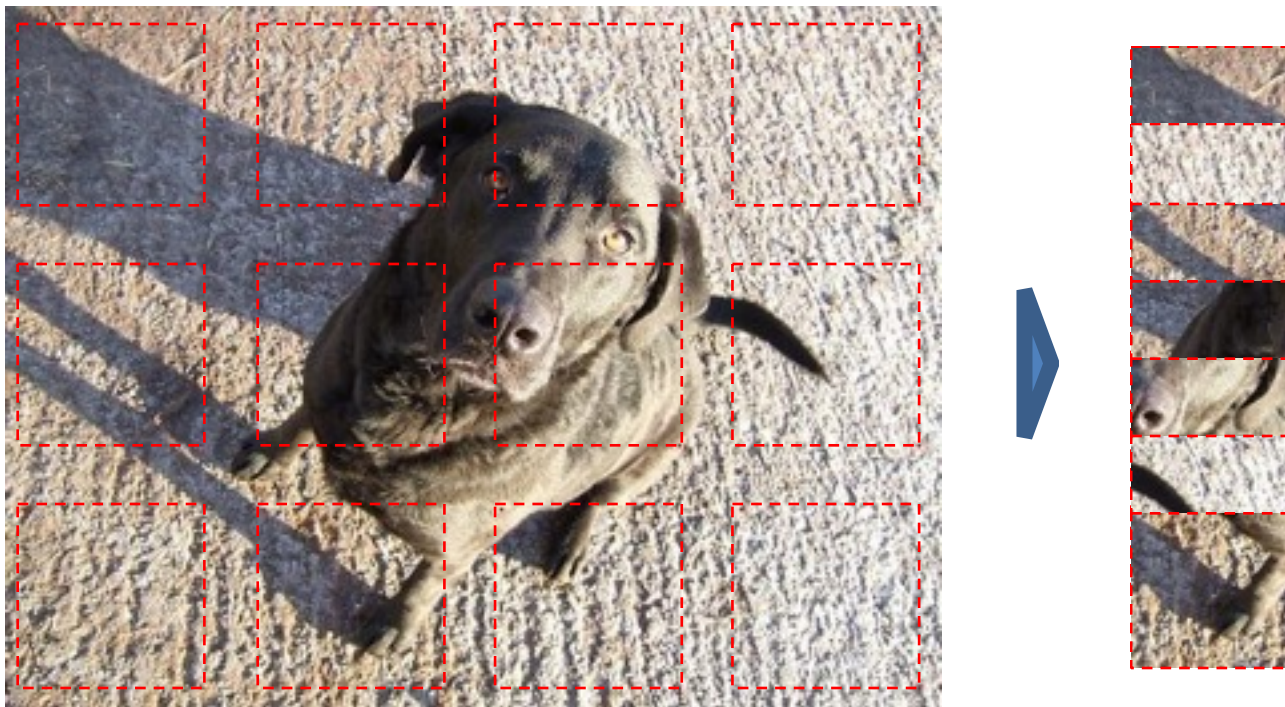
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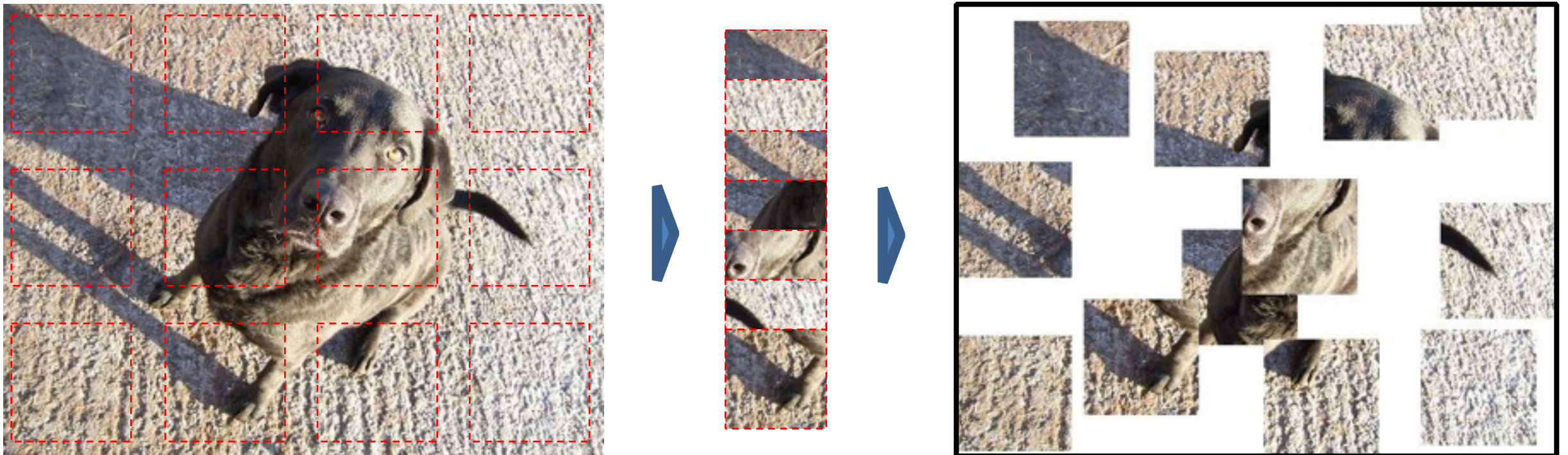
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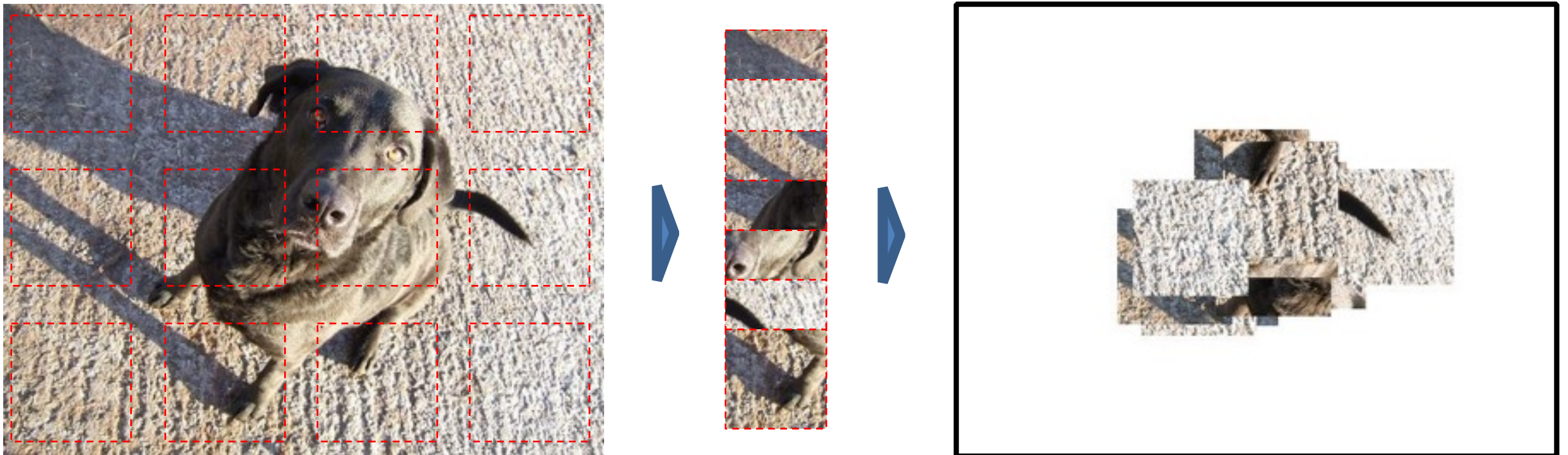
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Another trivial shortcut

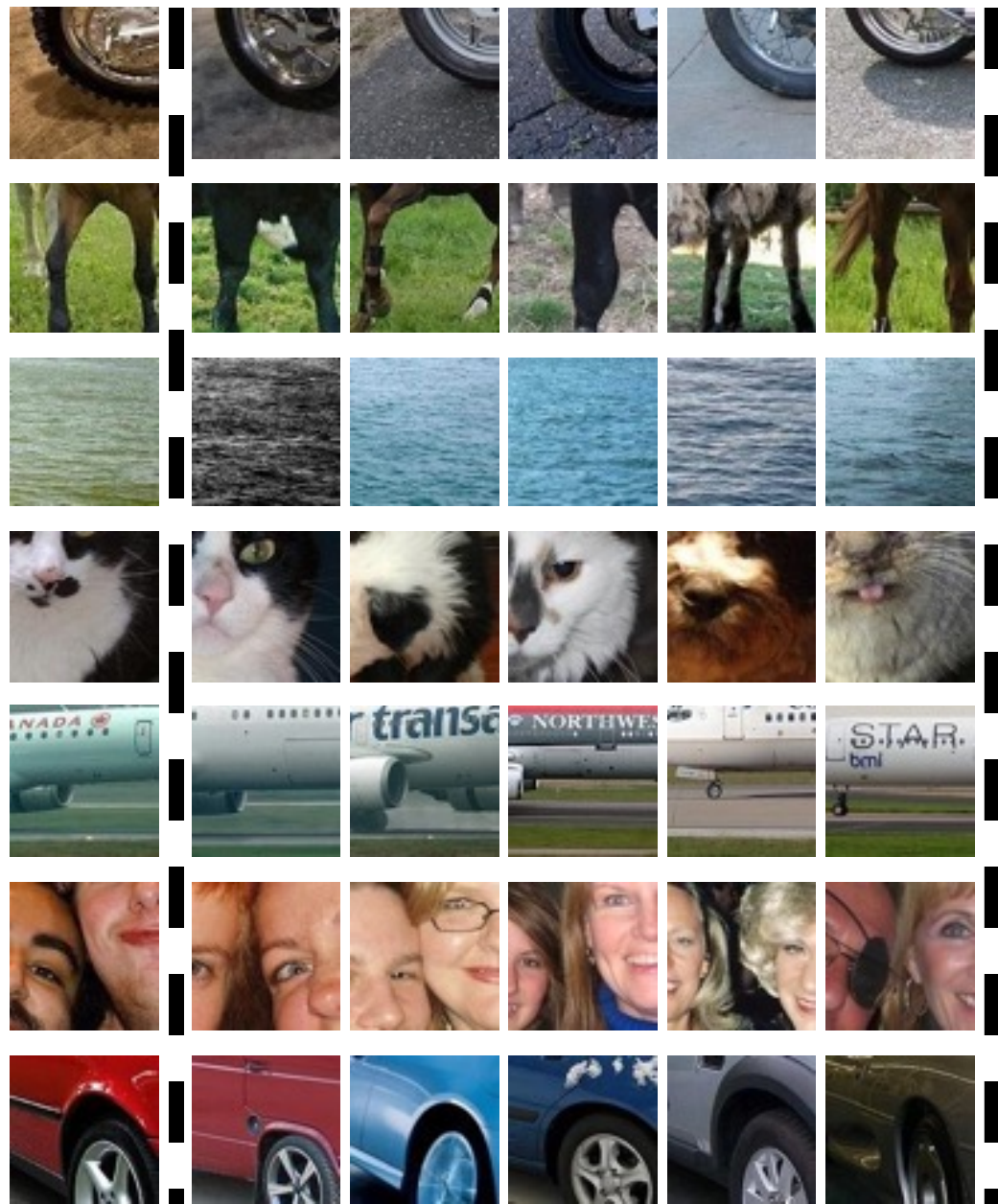
- Chromatic Aberration
- Shift colors towards grey (Projection)
- Drop 2 out of three channels during training



What is learned?

Input

Ours



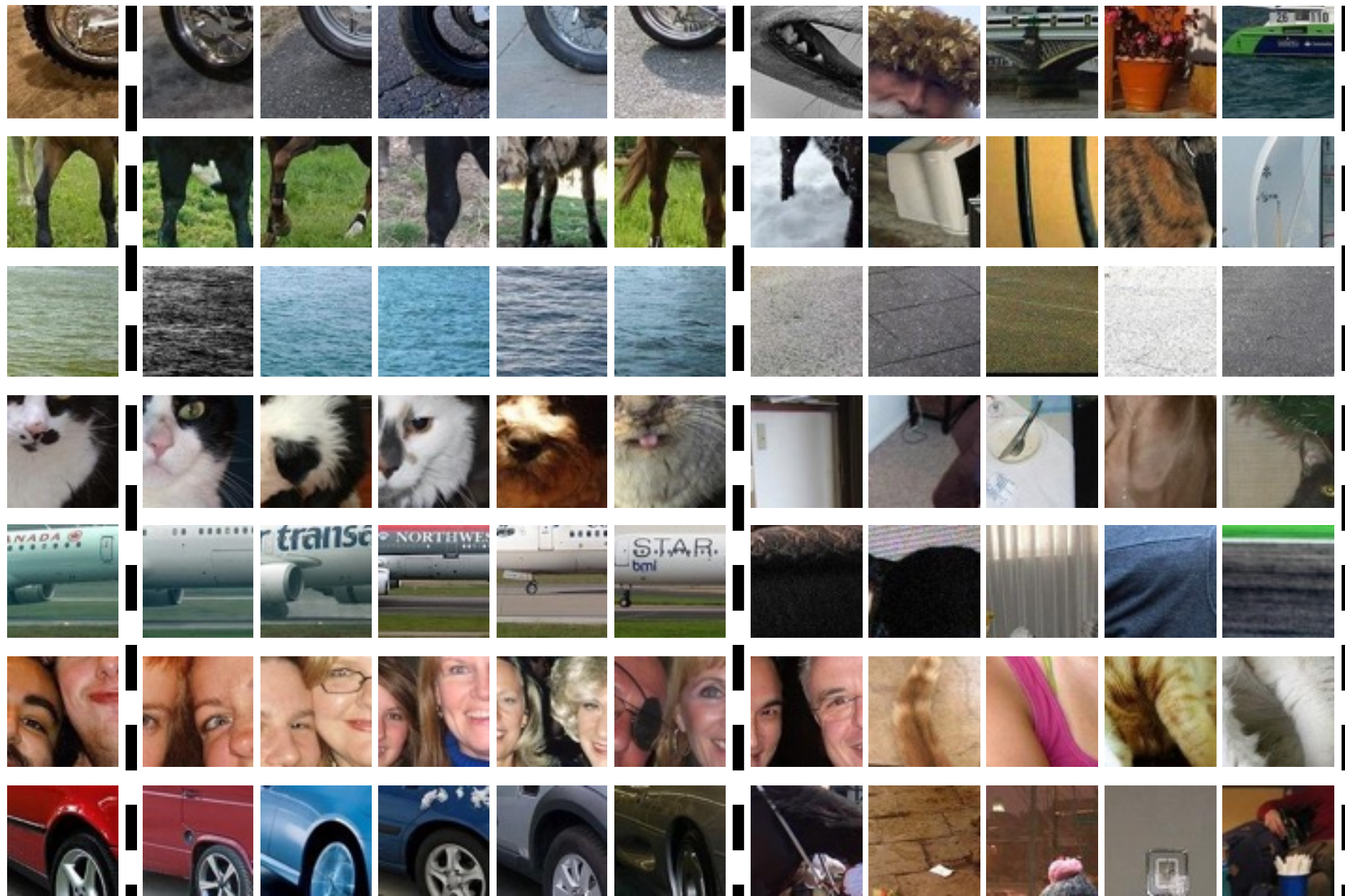
Slide from Carl Doersch

What is learned?

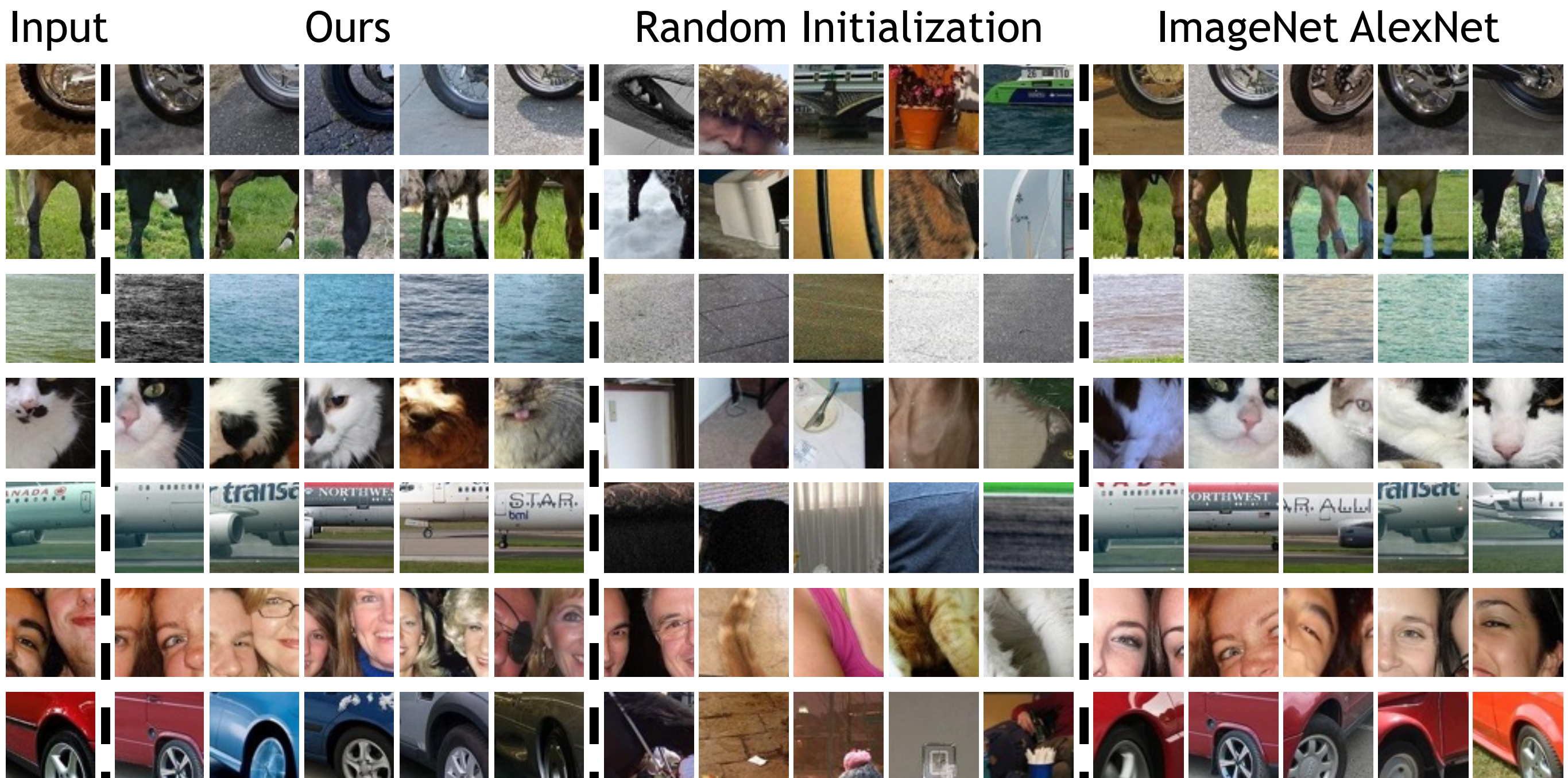
Input

Ours

Random Initialization

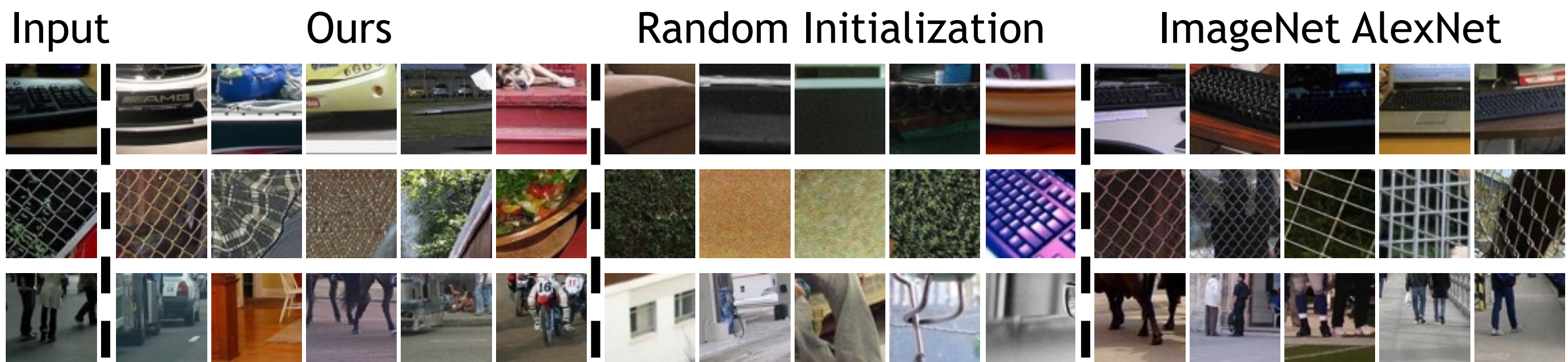


What is learned?



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Still don't capture everything



Still don't capture everything

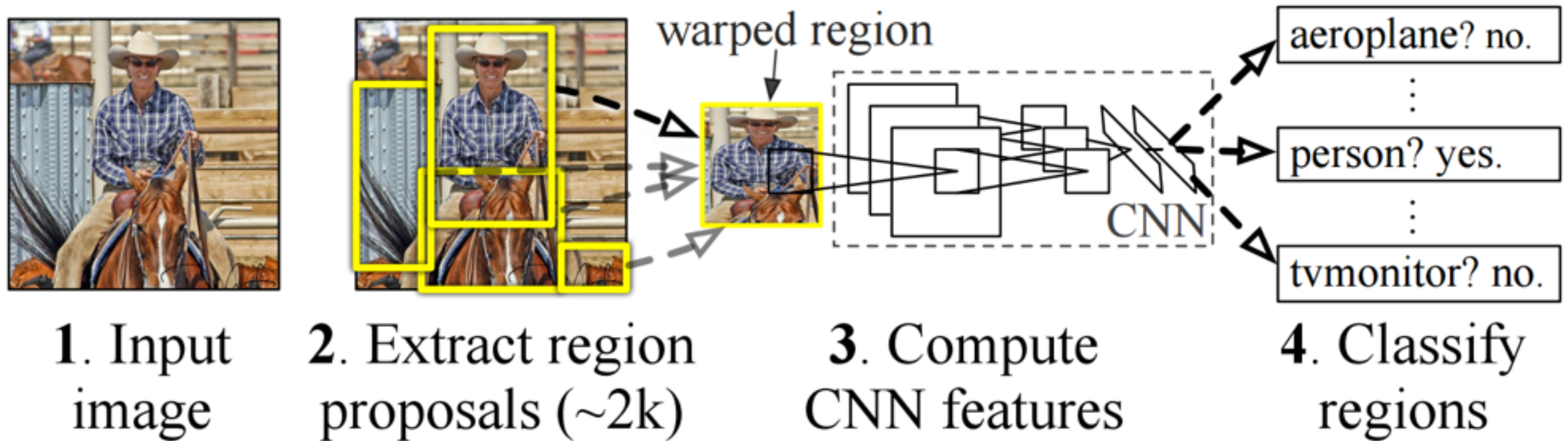


You don't always need to learn!

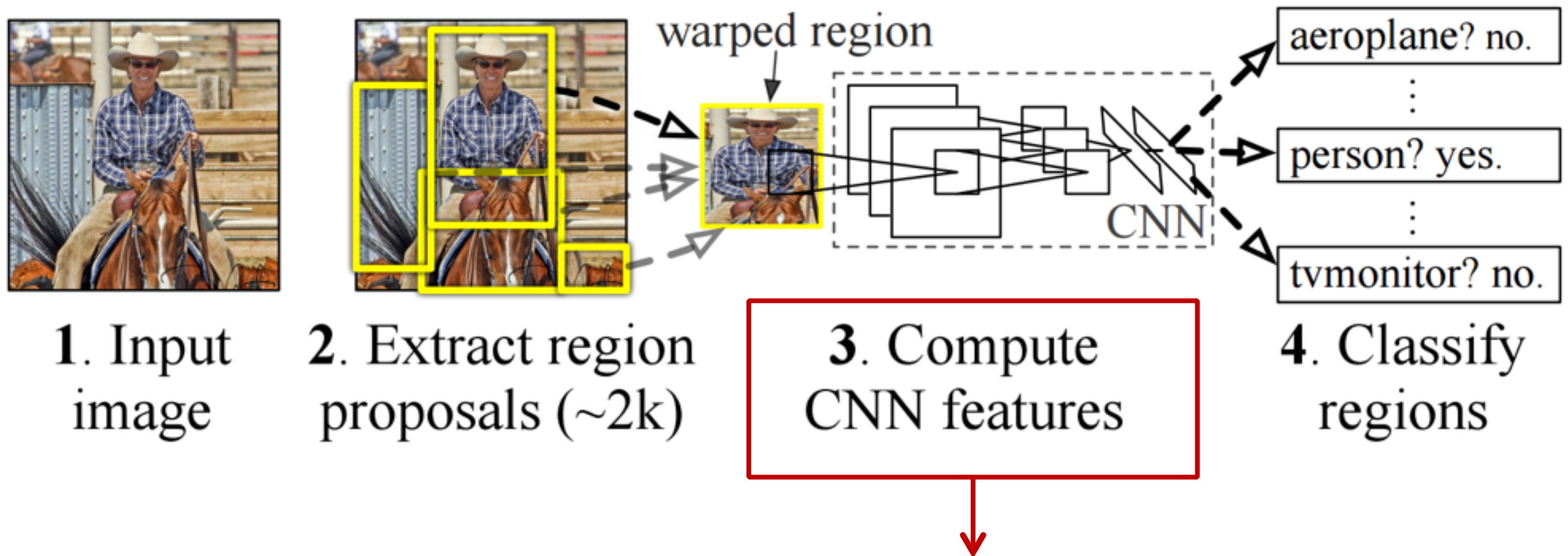


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Pre-Training for R-CNN



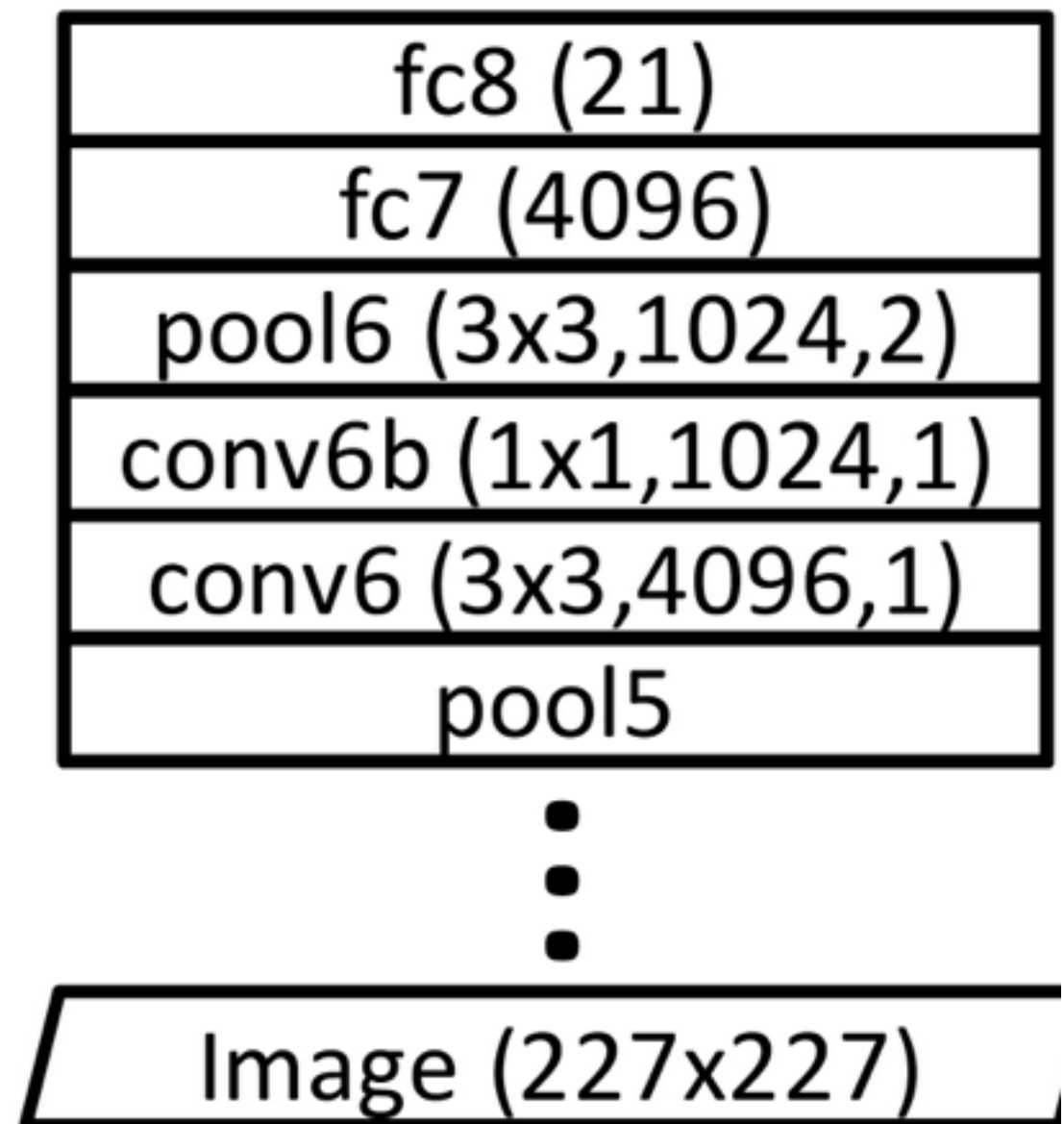
Pre-Training for R-CNN



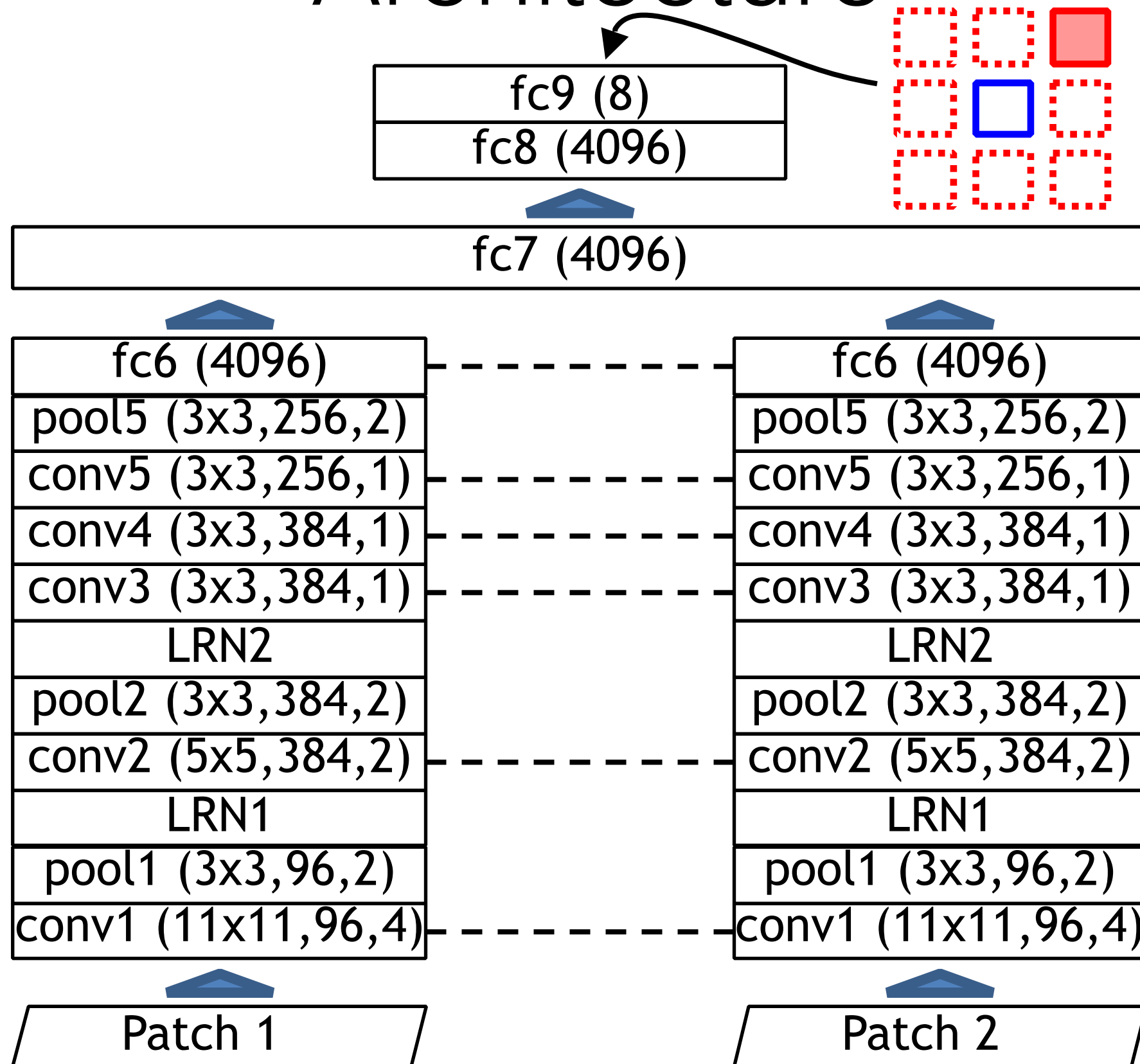
Pre-train on relative-position task, w/o labels

Details

- Use stack from patch context predictor before pool5
- Resize convolution layers to work on 227x227 instead of 96x96
- Use FC7 as the final representation



Architecture

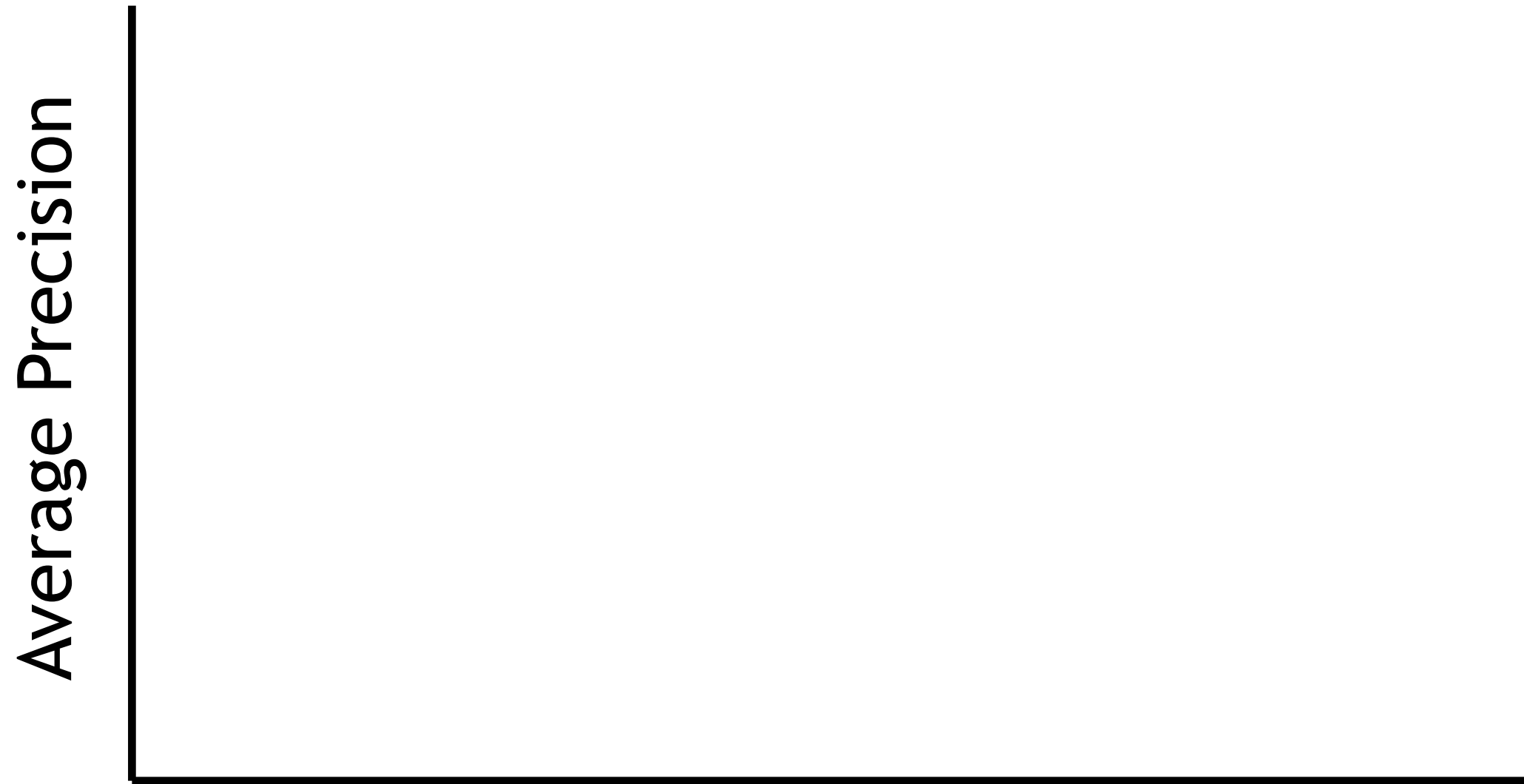


VOC 2007 Performance

(pretraining for R-CNN)

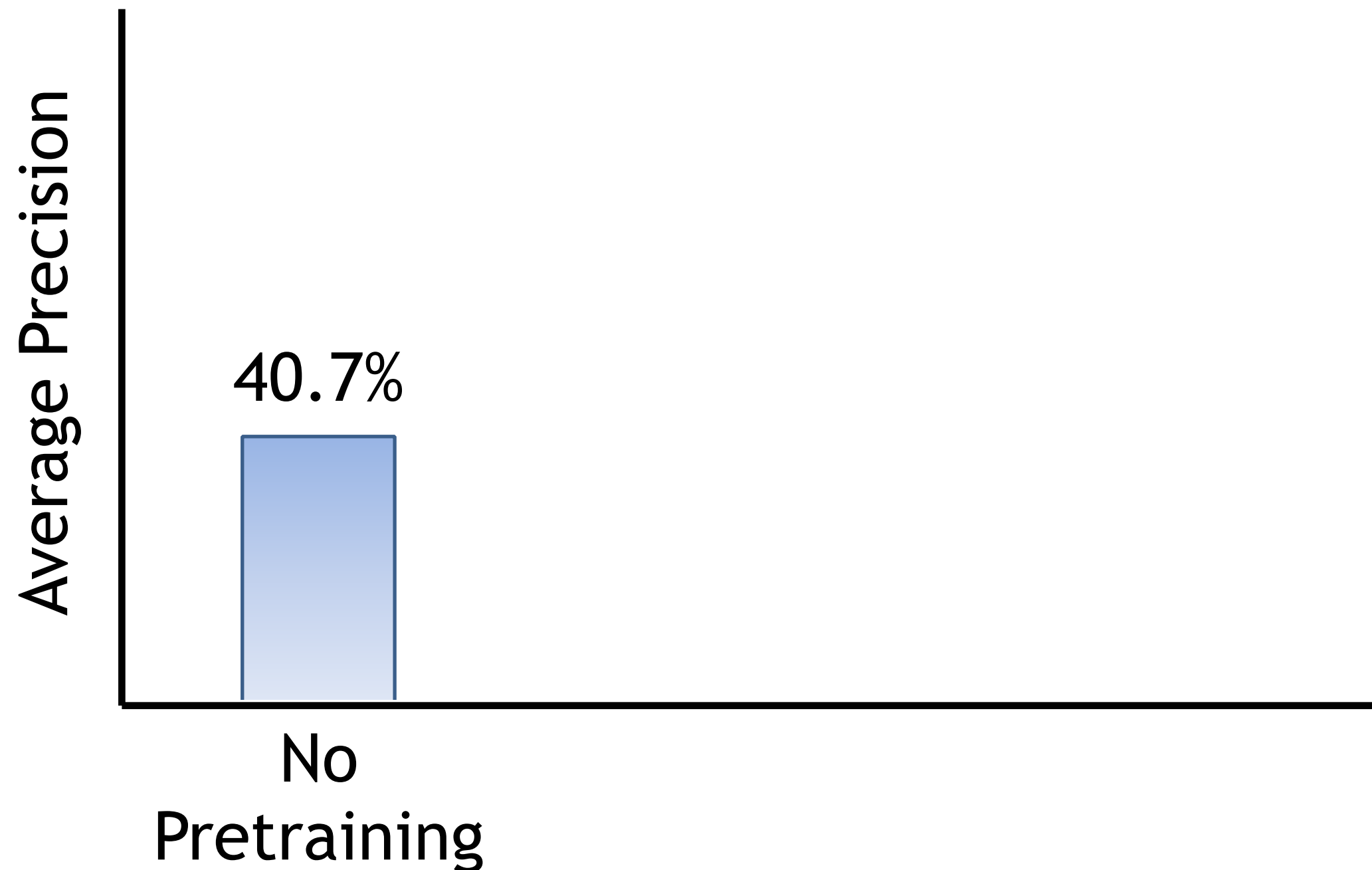
VOC 2007 Performance

(pretraining for R-CNN)



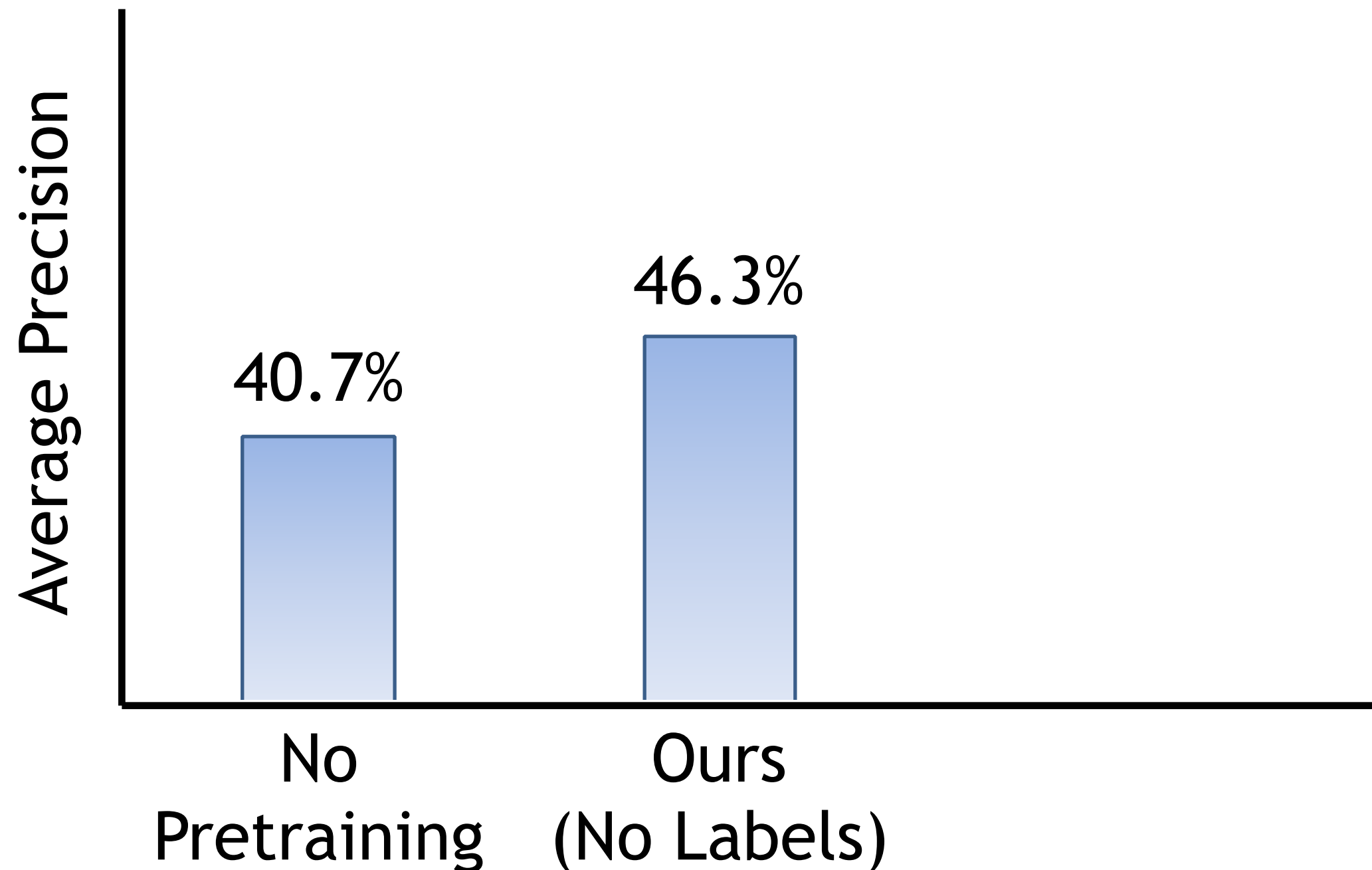
VOC 2007 Performance

(pretraining for R-CNN)



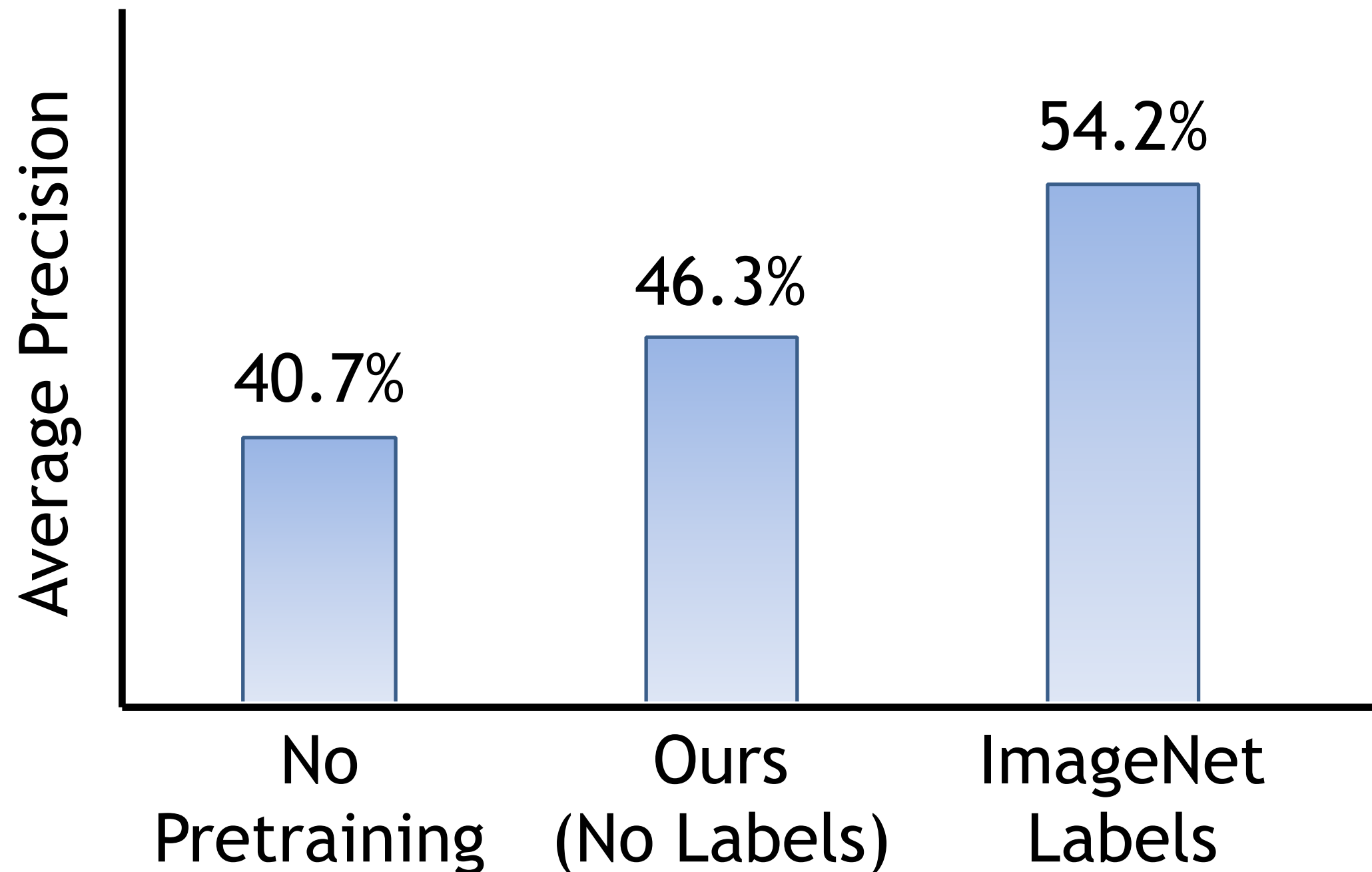
VOC 2007 Performance

(pretraining for R-CNN)

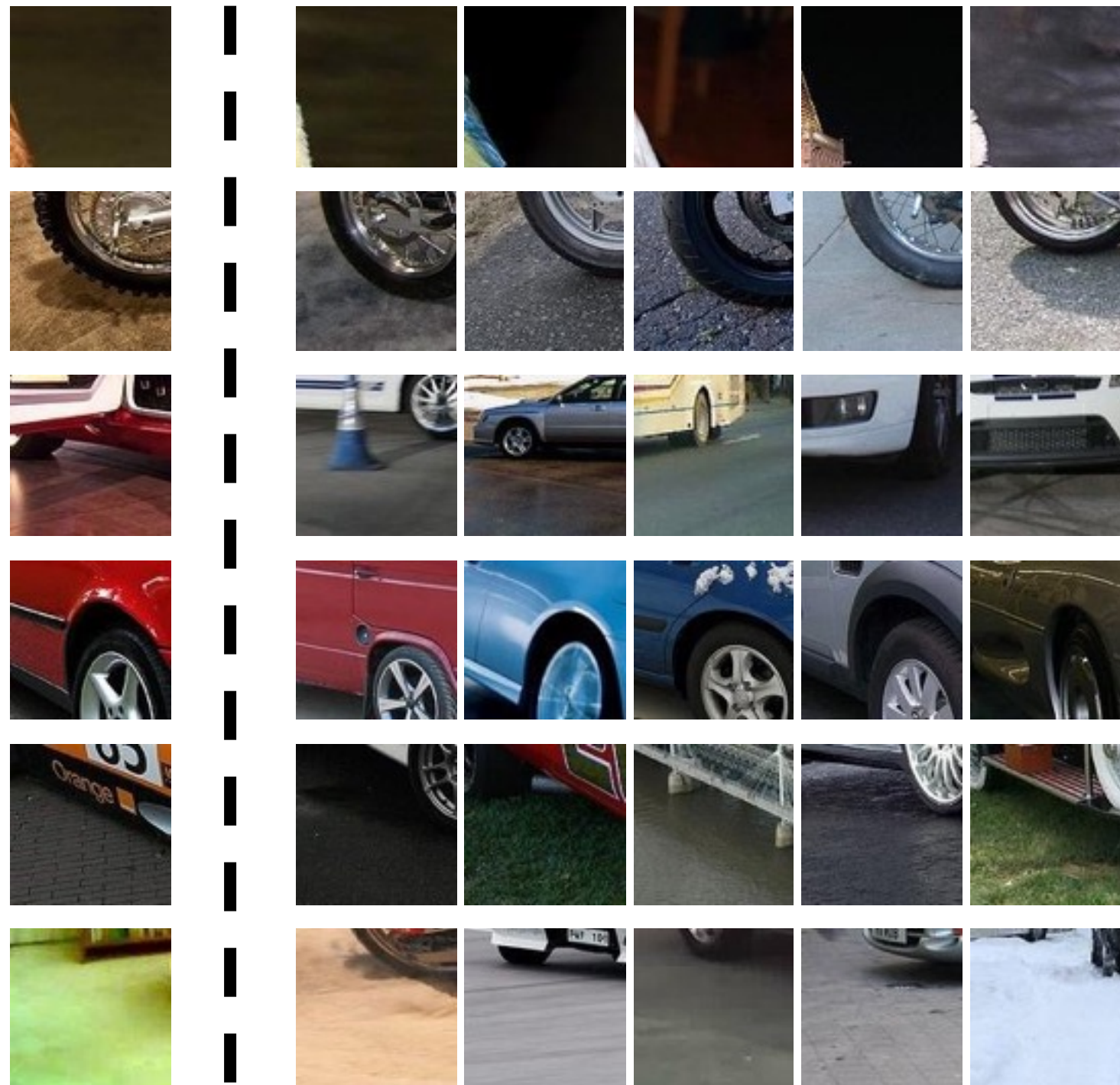


VOC 2007 Performance

(pretraining for R-CNN)

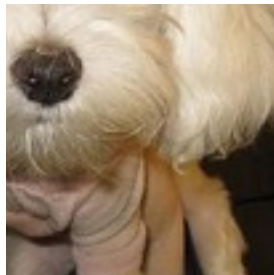
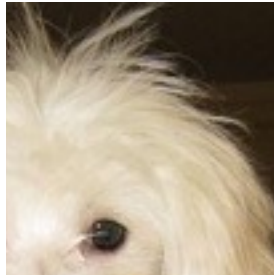
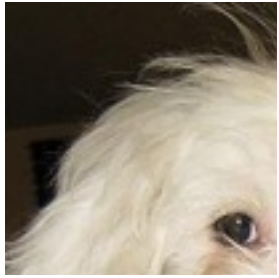


Unsupervised Object Discovery?

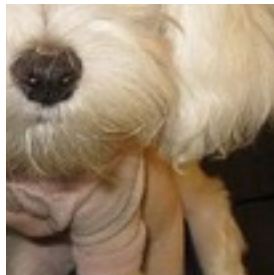
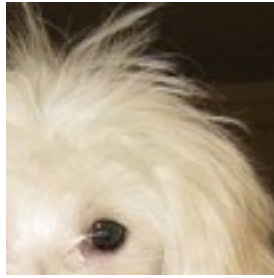
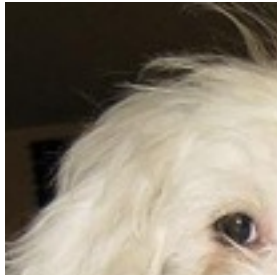


Slide from Carl Doersch

Unsupervised Object Discovery

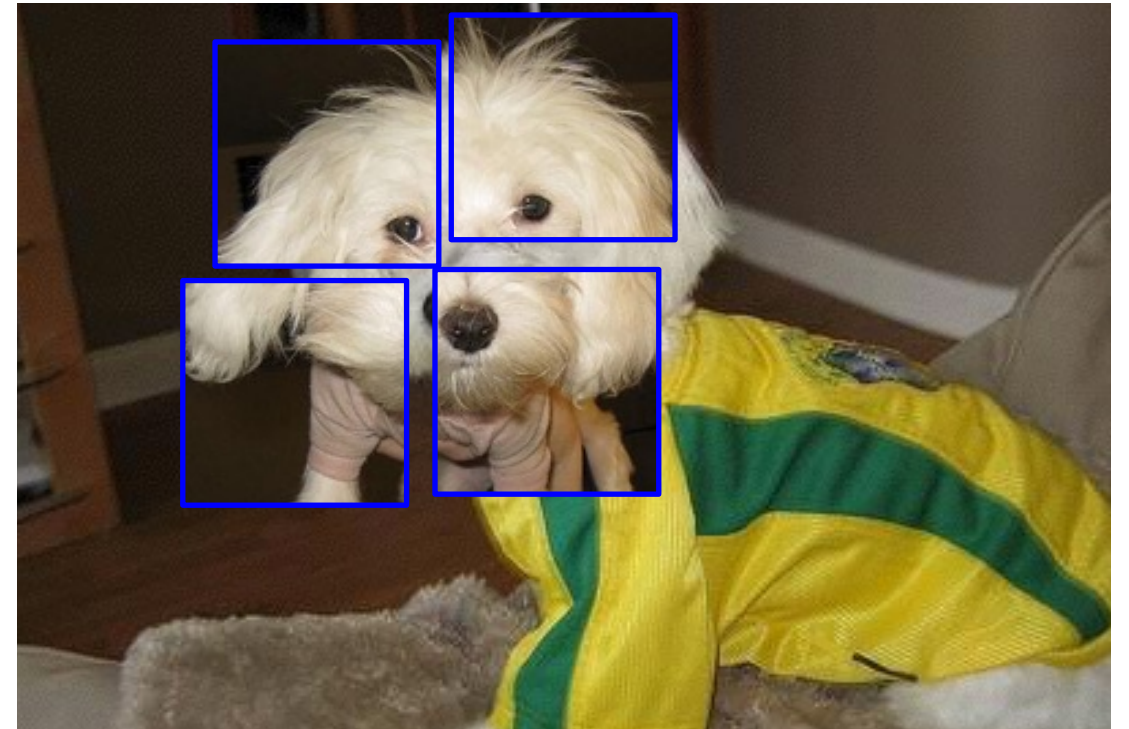
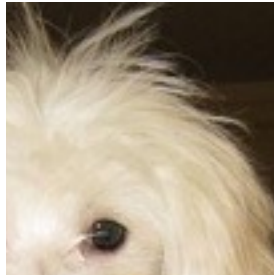
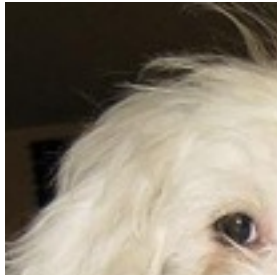


Unsupervised Object Discovery



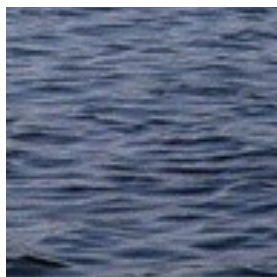
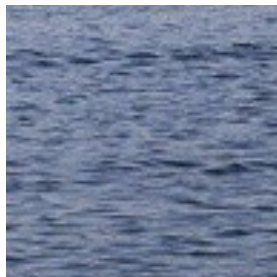
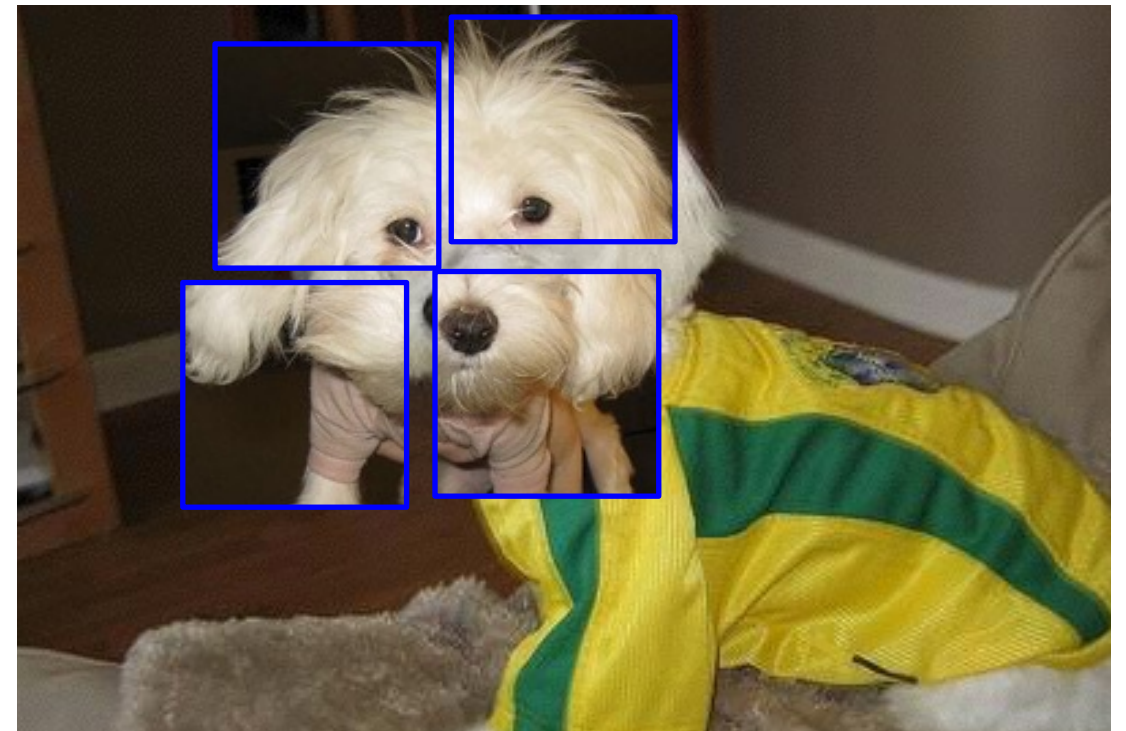
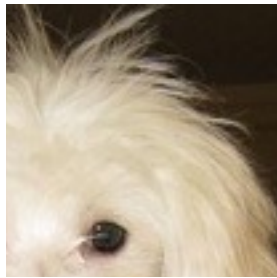
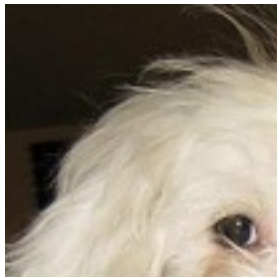
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Unsupervised Object Discovery



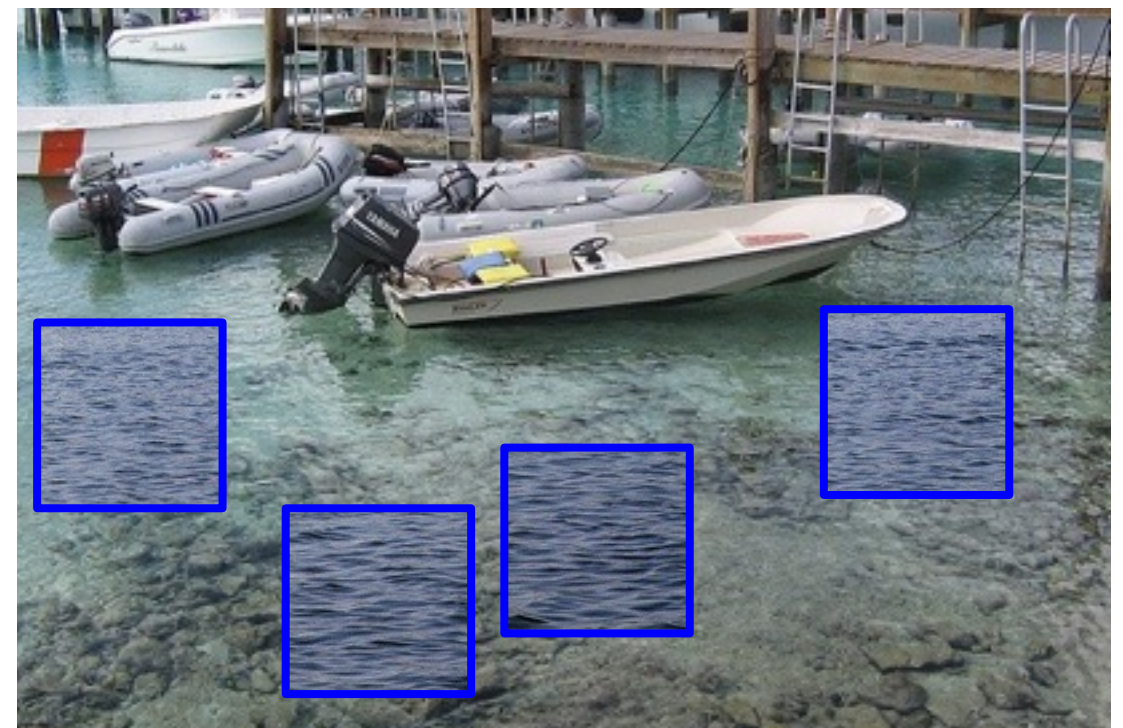
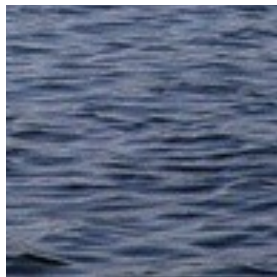
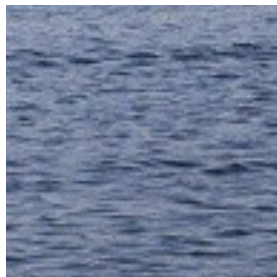
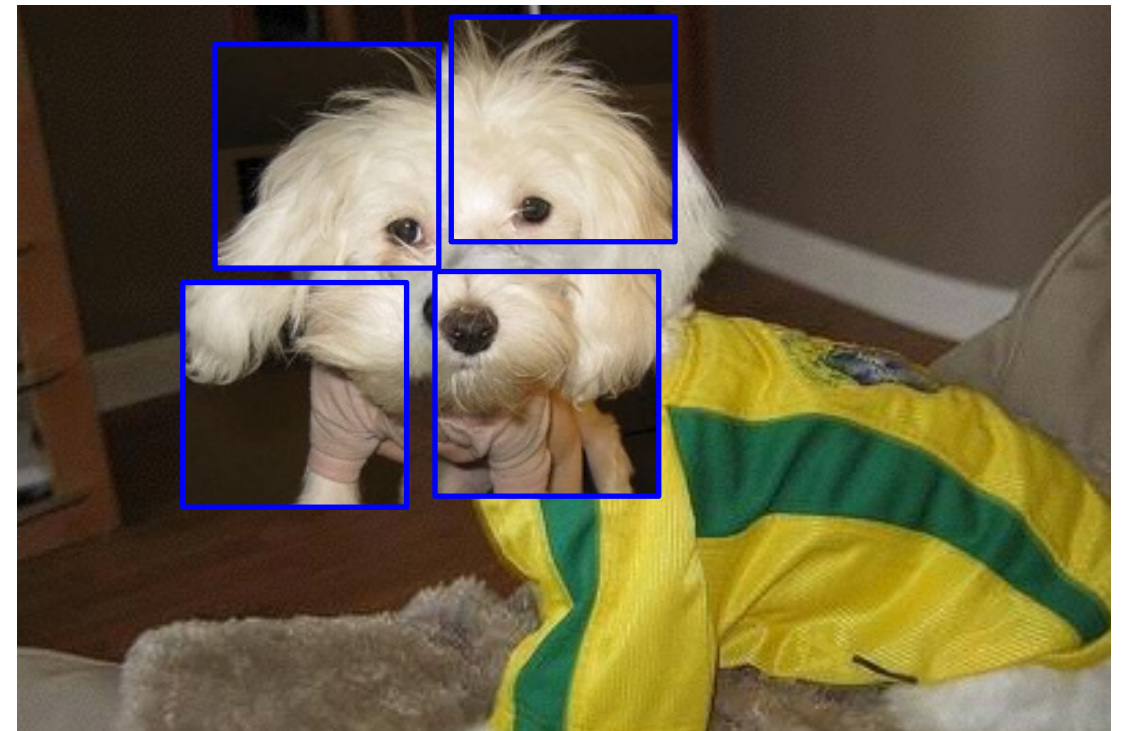
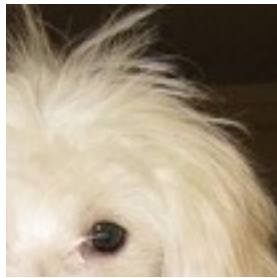
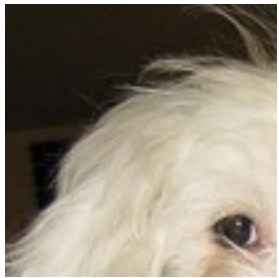
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Unsupervised Object Discovery



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Unsupervised Object Discovery



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Algorithm



Algorithm



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Algorithm



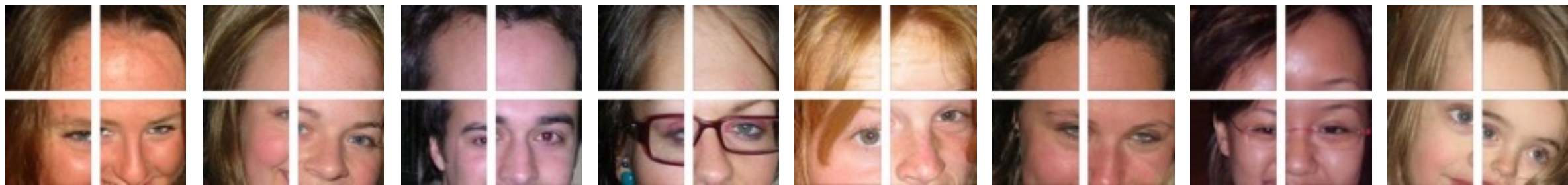
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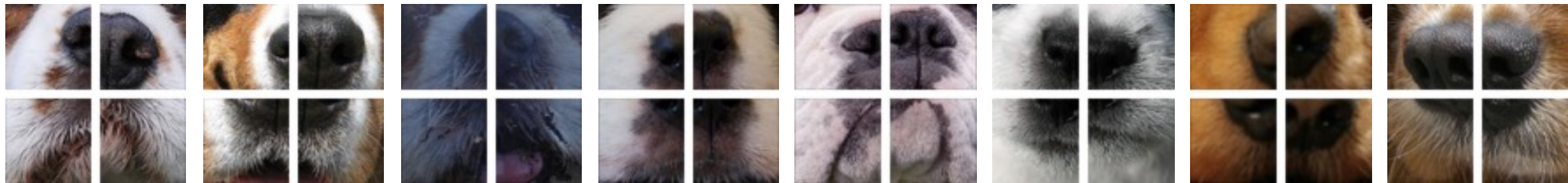
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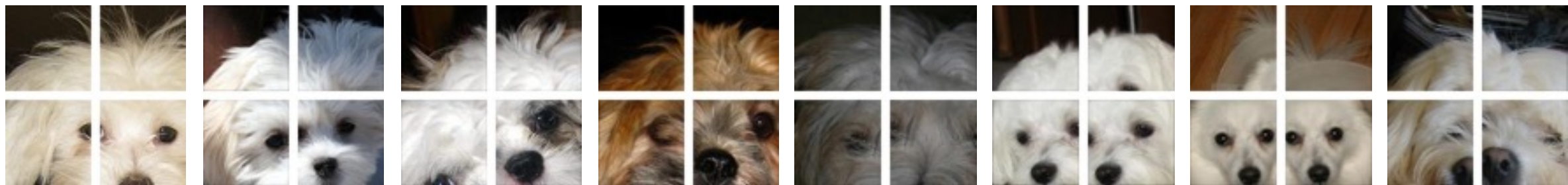
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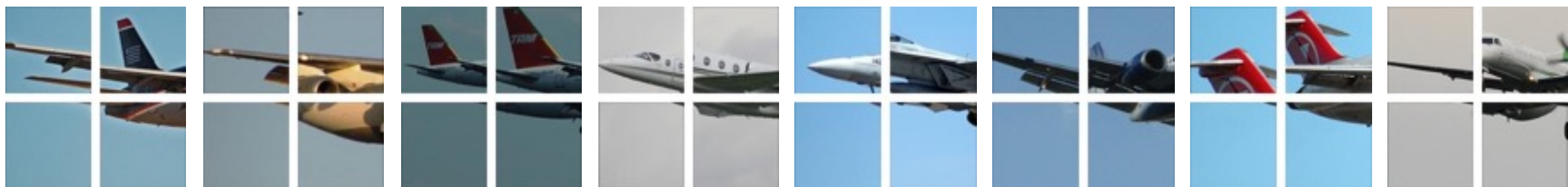
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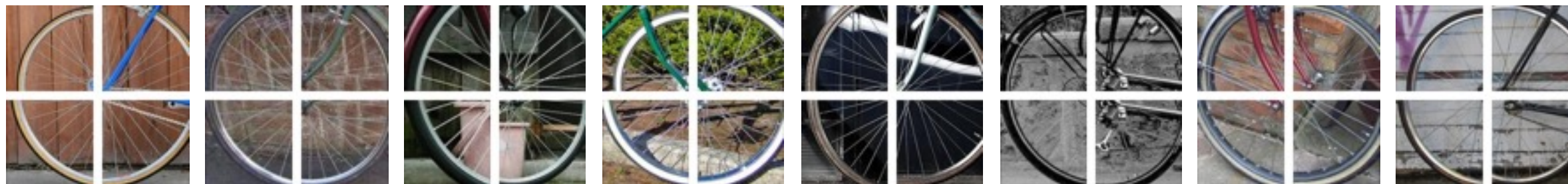


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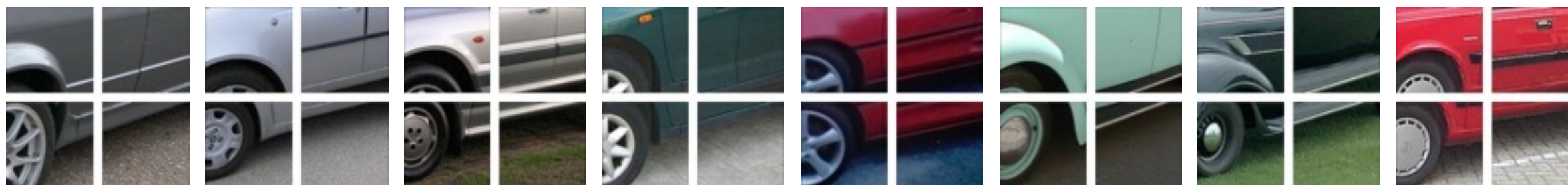


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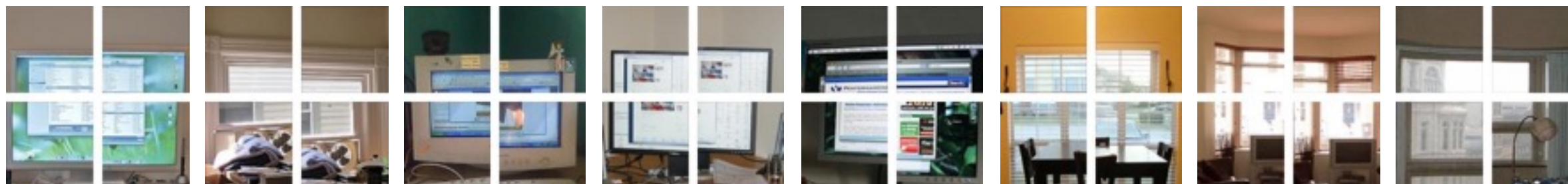
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32



43



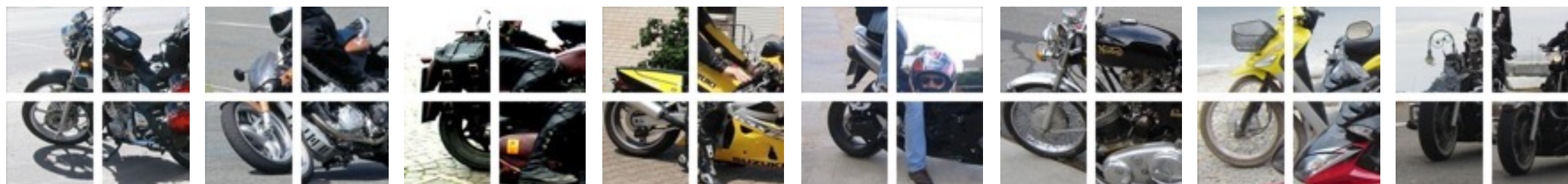
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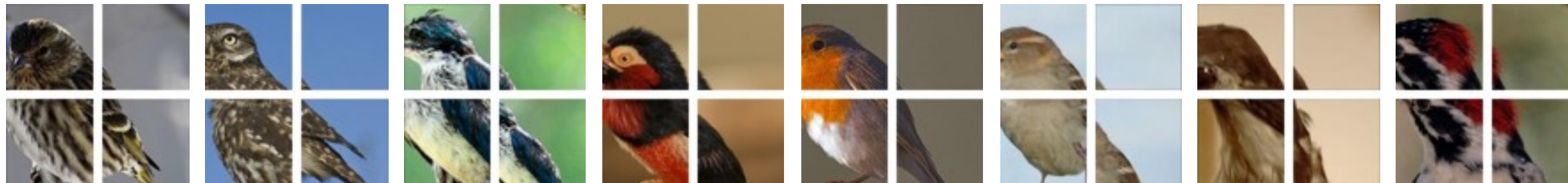


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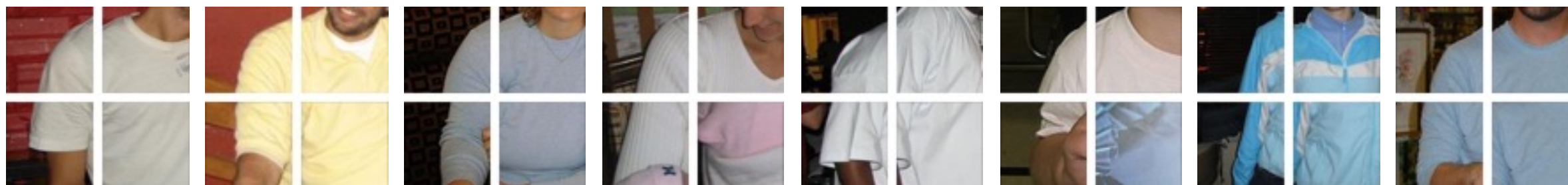


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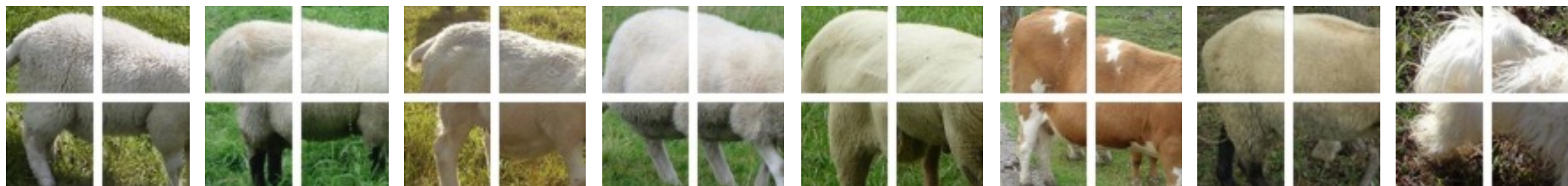
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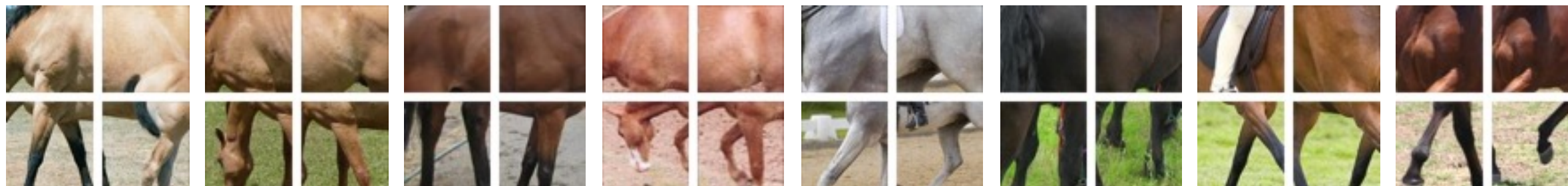
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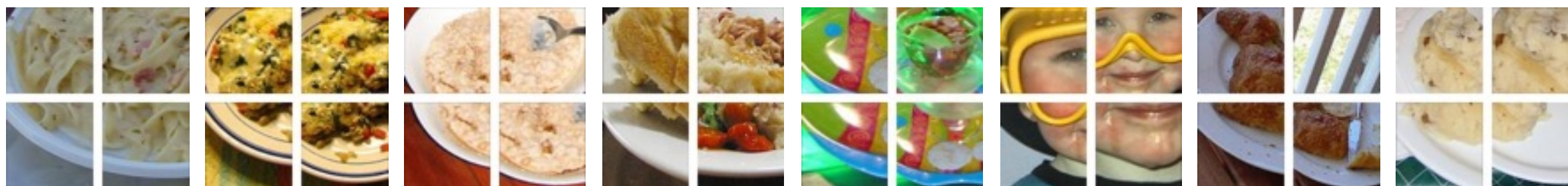
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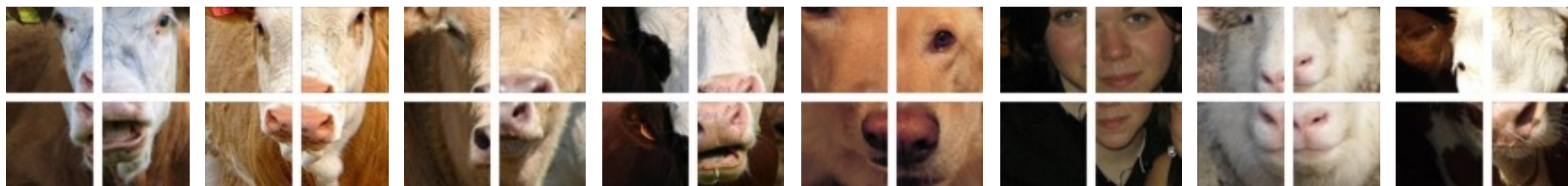
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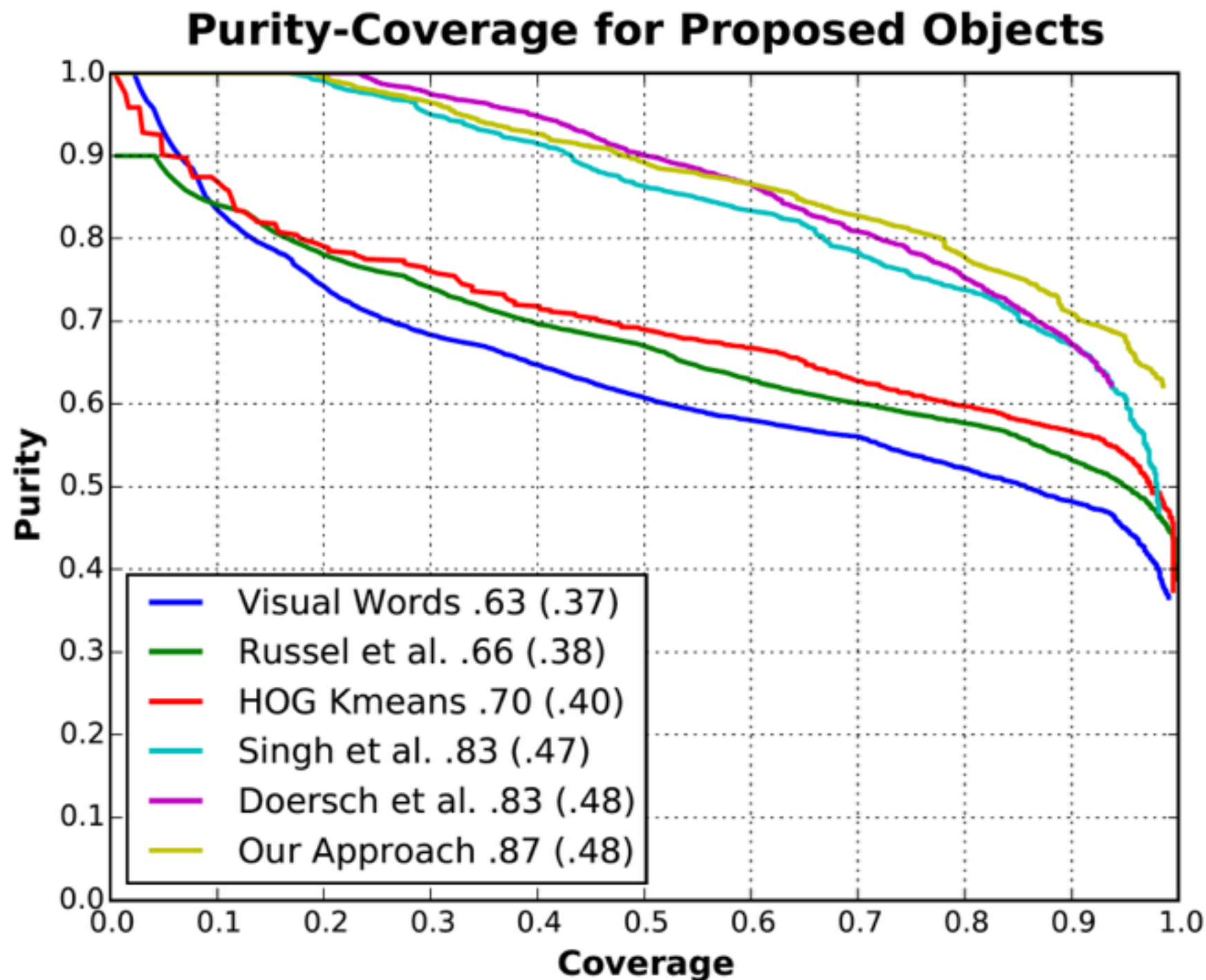


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Purity vs Coverage



Pretext Task

- Performance on Pascal VOC is 38.4% (Chance is 12.5%)
- On ImageNet accuracy is 39.5% on training set, and 40.5% on validation
- On GT box patches - similar performance. 39.2% overall with 45.6% on cars

Questions?