## High-Level Software for Networks <br> and Data Analysis <br> Duncan Temple Lang Statistics

## Outline

Introduction to R.
Comparison of high-level and lower-level software systems.

R \& Graphs and visualization.
Dynamic, interactive visualization on graphs.

## Introduction to R

Intepreted language and environment for data analysis, simulation, and general computing.

S language developed over many years at Bell Labs
Licensed to S-Plus/Insightful and commercially marketed as S-Plus.
$R$ is an Open Source project which is not "unlike" $S$, but quite different internally.

In 1998, John Chambers (Bell Labs) won the ACM Software Award for S.
$R$ is freely available - no cost, open source.
Works on most platforms, including Unix, OS X, Windows.
$R$ is
a language
an interpreter
a collection of packages providing extensive statistical functionality.
$R$ provides a vast collection of add-on packages contributed by the user community.

## Redositories

About 800 contributed packages.
http://cran.r-project.org - CRAN
http://www.bioconductor.org
http://www.omegahat.org
Several others.

## Functional Language

Functional language - "no" side effects.
Easier to understand code and debug
No references, pass by value => copies.
This is an issue when dealing with graphs and nodes.
When we modify an object, we must reassign it.
Can use lexical scoping/mutable state via environments, ....

Basic data structure is a vector
No scalar values $\Leftrightarrow>$ vector of length 1
Vector is an ordered set of homogeneous element types.
Create using $c()$ for concatenate
$c(1.2,3.6, c(1,2))$
c(TRUE, FALSE,
Basic data types are
numeric, integer, logical, character.
$R$ coerces to common type.

Can index a vector in various convenient ways: by position: $x[2], x[c(3,5,7)], x[1: 3]$
by omission/negation: $x[-2], \times[-c(3,5,7)]$ (can't mix negation and inclusion)
logical mask: $\times[c(T R U E, F A L S E, F A L S E, T R U E)]$
by name: $x=c(a=1, b=2, y=3.4)$ $x\left[c\left({ }^{\prime \prime} a^{\prime \prime}, " b "\right)\right], x\left[{ }^{\prime \prime} y^{\prime \prime}\right]$

Can also assign to subsets using the same notation $\times[c(" a ", " b ")]<-c(10,15.3)$ $x[c(1,2)]<-c(10,15.3)$ $x[c(T R U E, T R U E, F A L S E)]=c(10,15.3)$

Matrices and multi-dimensional arrays are basically vectors with an attribute giving the dimensions.

So matrices have homogeneous types of elements.
Sparse matrix support provided by SparseM package available on CRAN.

## Lists

For collecting objects that are not of the same type, need an additional data structure - a list.
$\operatorname{list}\left(a=1, b=c\left({ }^{\prime \prime} x^{\prime \prime}, " y\right.\right.$ " $)$, matrix(1:9, 3, 3))
Ordered and can have names.
Subsetting using [ works in the same way as for vectors,
BUT returns an object of the same type as being subsetted, i.e. a list.

$$
\mathrm{I}[\mathrm{c}(1,2)]
$$

To get individual element, use [[, i.e. $1[[1]], 1\left[\left[{ }^{\prime \prime} a^{\prime \prime}\right]\right]$

## Obiects \& Search Path

$R$ has a workspace for your session.
Assignments made at the top-level are stored by name in this environment.

Can discover current variables using objects().
Can remove objects via, e.g. $\mathrm{rm}(x, y)$
When we bring in addtional packages, we use the command library().

This ads the workspace for the package to the search path in which R looks for the variables mentioned in a calculation.
search()

## R Graphics

$R$ has rich graphics functionality.
2 basic systems
grz - regular graphics
grid graphics for ultra fine control.
Usual types of plots built-in, and many more specialized plots available in add on packages.

Static, presentation quality graphics with many, many controls.

require(seas)
data(mscdata)
par(cex=0.8)
plot.seas.temp(mscdata,id="1108447",add.alt=TRUE,style=c(0,1))


## Debuaaina - recover()

Add
options(error = recover)
to your session
e.g. via the file $\sim /$.Rprofile (read on startup)

When an error is encountered, you are placed in an interactive debugging environment.

Can move around the different call frames by selecting a number,
view the available objects() and their values using the usual R commands

Exit call frame with empty command

## Profilina

$R$ is interpreted and so not as fast as compiled code.
(Although a lot of commands rapidly use native routines in R or BLAS, ATLAS, etc.)

When a script or function is slow, we can profile it to determine where the bottlenecks are.
Rprof("filename")
Run our commands
Rprof(NULL)
After ending the collection of profile information, can examine it via summaryRprof("filename")

Returns a data structure that we can manipulate directly in R

## High-level Languages

Compiled languages: C, C++, Objective C, Fortran.
Java is compiled and runs on a Virtual Machine (VM)
Both types of compiled languages require explicit type specification.
application to be completed before running
recompilation before re-testing.

## Higher Level Languages

Perl \& Python
General languages with an interpreter.
Both are general purpose languages, but with no particular focus on
numerical computation,
graphics.
Numerous add on modules, some of which are for numerical computation.

Graphics is brought in via various different types of extensions.

## Perl \& Python

Perl is best suited for text manipulation.
Regular expressions builtin to language.
Language is succinct and "cute", but resulting code can be difficult to maintain.

Object-oriented system somewhat ad hoc.
Python is very general purpose, less focused on text manipulation.

Object system at the core of the language.

## R \& Matlab

S (R \& S-Plus) is focused on statistics and data analysis.
Matlab is focused more on engineering.
The common intersection is linear algebra (matrices) and graphics.

Both systems are general purpose programming languages and so can be "used" to do just about anything any other language can do.

Both are vectorized and there is a benefit to using this.
Both can readily integrate native/compiled code such as $C$ \& Fortran to make use of existing software and improve speed.

## R \& Matlab

In Matlab, one tends to write the calculations for doing a computation, e.g. $\left(X^{\prime} X\right)^{-1} X^{\prime} Y$

In $R$, we make extensive use of symbolic representation of models via formula.

$$
\text { response } \sim \log (a g e)+\text { height + gender }
$$

Then, we can fit this model using different methods without having to expose the underlying calculations to the user.
$\operatorname{lm}(f$, data $=$ datal $)$
$\operatorname{lm}(f$, data $=$ data 2$)$
$\mathrm{glm}(f$, data $=$ datal $)$

## Formula Lanauaae

Note that the formula is an object in R, not just syntax.
Formula is symbolic and independent of the data.
Details about expanding categorical data in constructing the design matrix ( $X$ ) (i.e. contrasts) are orthogonal to the formula, and specified when fitting the model.

Additionally, we use the formula language for specifying plots.
plot(y ~x)
histogram( $x \mid$ gender)


$$
\begin{aligned}
& \text { Depth <- equal.count(quakes\$depth, number=8, overlap=.1) } \\
& \text { xyplot(lat } \sim \text { long I Depth, data = quakes) }
\end{aligned}
$$

EE <- equal.count(ethanol\$E, number=9, overlap=1/4)
xyplot(NOx ~ C | EE, data = ethanol, prepanel $=$ function(x, $y$ prepanel.loess(x, y, span=1),

xlab = "Compression Ratio",
ylab = "NOx (micrograms/J)",
panel $=$ function(x, $y)$ \{
panel.grid(h=-1, v= 2)
panel.xyplot(x, y)
panel.loess(x,y, span=1)
\},
aspect $=$ "xy")

## R \& Matlab

Matlab's object system is like S's older OOP system dynamic and loosely structured.

R has both S3 and S4 class systems
S3 is a dynamic system with no formal definition of a class.
class $(x)<-c(" A ", " B ")$ - is an $A$ and inherits from $B$.
Get single dispatch, i.e. foo( $x, y$ ) finds appropriate method for foo based on type of $x$.

S4 system uses explicit declarations for classes and methods. Quite different from C++ or Java or Python.

## R

$R$ has a rich and powerful package mechanism.
Used to easily publish software, and easily install on user's own machine.
install.packages()
Searches repositories on Web (or local) and can fetch all dependencies as part of the download and installation.

Relatively easy to go from writing code interactively to writing functions to putting them in a package.

If you are using $R$ to do your class project, an $R$ package is a convenient packaging medium.

DESCRIPTION file
$R$ code in $R$ / directory
Help pages for functions and data in Rd/ directory, written using prompt() and LaTeX-like markup.

R CMD INSTALL myPackage
or install.packages("path/to/package", repos = NULL)
R CMD check myPackage
to verify that it is "correct"

Additionally, Sweave is an authoring tool for creating "dynamic" reproducible documents.

One puts the code in the document, not the output of the R commands.

One can then generate different views by processing the workflow.

Can parameterize the computations with new inputs, e.g. data sets, parameters for simulations.

## Stat. Software for Graphs

We'll look at software for working with graphs.
$R$ for creating, manipulating and applying algorithms to graphs
graph and RBGL packages from BioConductor www.bioconductor.org

Rgraphviz and GGobi and rggobi for displaying graphs.
Rgraphviz is for "static" displays of graph structures.
GGobi is for dynamic, interactive displays of data and graph structures, as well as data associated with graphs (i.e. on nodes and edges)

## More Information

BioConductor monograph
Bioinformatics and Computational Biology Solutions with R and BioConductor.
Gentleman, Carey, Huber, Irizary, Dudoit
Chapters 19, 20, 21.
Vignettes
e.g. vignette("Rgraphviz")

R News

## Graphs in R

install.packages("graph", depend = TRUE, repos = "http://www.bioconductor.org")
library(graph)
Now we can create graphs.
$\mathrm{g}=$ randomGraph(letters[1:10], 1:4, .5)
class(g)
[1] "graphNEL"

Given a graph, can display it using R's graphics and Rgraphviz's layout plot(g)

Different layout algorithms available to us
dot - hierarchy
neato, fdp - spring layout twopi
circo
plot(g, "neato")

## graphNEL

Nodes and Edge list graph.
Can be directed or undirected.
new("graphNEL", nodes $=c\left(" a{ }^{\prime \prime}, " b ", " c\right.$ "), edgeL $=\operatorname{list}(a=$ list(edges = " $b ")$,
$b=$ list(edges = "b"),
$c=$ list(edges = $c(" a ", " b "))$ ),
edgeMode = "directed")
Edge mode can be "directed" or "undirected".
Edges can also have numeric weight values.

## Creatina Graphs

Adjacency matrix
square matrix, with l's and O's indicating whether a pair of nodes is connected or not.
row and column names identify the nodes.
$m=$ matrix(rbinom(25, 1, .2), 5, 5, dimnames $=$ list(letters[1:5], letters[1:5]))
as(m, "graphNEL") - coercion method
Or new("graphAM", adjMat = m, edgemode = "directed" )

## Different Graph Classes

From Sparse matrices to graphs via SparseM package on CRAN.
clusterGraph - a graph made up of complete but disjoint subgraphs.
distGraph - a complete graph, where the inter-node distances give the weights for the edges

## Operations on Graphs nodes, edges, acc, adj

nodes(g) \& edges(g)
return the nodes and the edges respectively.
Often need to identify edges by name, so use edgeNames()
$\operatorname{adj}(\mathrm{g}, \mathrm{c}($ "nodeID", "otherID"))
get a list with each element identifying which nodes are adjacent to that particular node.
$\operatorname{acc}(\mathrm{g}, \mathrm{c}($ "nodeID", "otherID"))
a list with each element identifying which nodes are reachable from this one and the length of the shortest path between them.

## Graph Ops. degree()

degree(g)
returns the in and out degree values for each node for a directed graph
and for undirected graphs, the simple degree distribution.

Connected components of a graph are obtained via connComp(g)
This returns a list of the different disjoint subcomponents.

## subGraph

ugraph $(\mathrm{g})$ gives the undirected graph. Again, a copy. subGraph(c("nodeID", "otherID", "yetAnother"), g) yields the subgraph

This is essentially a copy of the relevant nodes and edges. It is not done via references.
union(), intersection() and complement give new graphs

## Editina the Graph

addNode(g, c("nodeID", "otherID", ...))
addEdge(g,
removeNode("nodeID", g)
removeEdge("node1", "node2", g)
combineNodes(c("node1", "node2"), g) amalgamates the two nodes into 1
clearNode("nodeID", g)
removes edges to and from that node.

## Controlling the Plotting

The simple plot(graph, "layout") command gives convenient results.

However, we often want to control different features of the plot, e.g.
node labels shape, color, fill color
edge color, label line type, etc.


```
myNodes = as.character(outer(letters, 1:3, paste, sep = ""))
ga = randomEGraph(myNodes, edges = 50)
plot(ga, "neato")
# Create a character vector with value "red"
# and names identifying the nodes with degree >= 3
hiNodes = nodes(ga)[degree(ga) >= 3]
cols = structure(rep("red", length(hiNodes)),
    names = hiNodes)
lowNodes = nodes(ga)[degree(ga) == 0]
lowNodes = structure(rep("skyblue", length(lowNodes)),
        names = lowNodes)
plot(ga, "neato", cex = .2,
    attrs = list(node = list(color = "lightgreen")),
    nodeAttrs = list(fillcolor = c(cols, lowNodes)))
```

Specify graph and layout type.
Then can specify a collection of global attributes.
And then node and edge specific settings, i.e. for particular nodes and edges.

The settings are merged together, with the most specific for a given node used.

Need only specify the ones you want to change. These are merged with the values returned from getDefaultAttrs()

Settings for graph, cluster, node and edge.

Use getDefaultAttrs() to find out what attributes may be set for the different levels.

For edges, need to identify the edge for which a setting is intended.
Use edge name, in form "src~dest"
e.g.
$\operatorname{plot}\left(\mathrm{g}\right.$, edgeAttrs $=\operatorname{list}\left(\right.$ label $=c\left(" a^{\sim} b^{\prime \prime}=" s s h "\right)$,

$$
\text { col = } \left.c\left(" a \sim b^{\prime \prime}=" r e d^{\prime \prime}\right)\right)
$$

## Only Layout

The simple plot() command does both layout and rendering.

If we want to use the layout information in multiple situations, or simply do calculations on it, we can separate the two steps.
agopen() does the layout and returns an instance of the "Ragraph" class.

## Accessing the Layout

$I=$ agopen(g, layoutType = "neato", name ="") plot(l)

Can also do the plotting ourselves using R's own graphics tools.

The layout object has lists of nodes and edges and we can access these via AgNode() and AgEdge().

Can then get the center of each nodes, get its coordinates, etc.

This allows us then to entirely control what is drawn, delegating graphviz to layout, and R's graphics to high quality rendering in different formats.

## User Defined Node Rendering

plot(layout, drawNode $=$ function(node) ...)
The function can draw whatever it wants, however it wants to using many different sources of information.

Can even produce an Image Map using imageMap()
Using RGtk, tcltk or soon wxWindows, we can build interactive tools for working with graphs.

## RBGL

Vincent Carey provides an interface to the Boost Graph library, a C++ collection of algorithms by Siek et al.

Can pass a graph object from any of the types in the graph package to any of these algorithms.

## RBGL functions

Algorithms currently include
Traversal: Depth and Breadth first searches (dfs, bfs) return the visited nodes in order.

Shortest Paths: sp.between, djkstra.sp, bellman.ford.sp, dag.sp, johnson.all.pairs.sp

Minimal Spanning Trees: mstree.kruskal.
Connectvity:
Max. Flow Algorithms.

## Temporal Graphs

We can look at the structure of a graph by doing different layouts.

We can even see how that structure changes over time.
layout the union of the entire collection of graphs color only the edges (and nodes) that are present for a given "time" period.

Use animation or interactive controls to change "time".
Can build such a GUI in R using RGtk or tcltk.

## Data on Graphs

Generally, we are not just interested in a graph and its structure only.
Rather, we have data for each node, and potentially observations on the edges.
E.g. computer network we have information about the operating system on each computer, its users, login sessions, files, etc.

Edges: connections between machines on the network have information about the ports, the length of the session, number of bytes, etc.

GGobi for interactive, dynamic graphics with spport for graphs

Open Source, freely available from http://www.ggobi.org
Also, connection with $R$ via rggobi.
And can program own link actions via RGtk and rggobi.


## Statistics for Graphs

Distributions for measures on graphs to determine whether they are stochastically similar.

Probabilities of detecting edges
false positives, false negatives and missing data.

