

Type Systems

Lecture 14
ECS 240

Review

- λ -calculus is as expressive as a Turing machine
- We can encode a multitude of data types in the untyped λ -calculus
- To simplify programming it is useful to add types to the language
- We now start the study of type systems in the context of the typed λ -calculus

Types

- A program variable can assume a range of values during the execution of a program
- An upper bound of such a range is called a type of the variable
 - A variable of type “bool” should only assume boolean values
 - If x has type “bool” then
 - “not(x)” has a sensible meaning
 - but “ $1 + x$ ” should not be allowed

Typed and Untyped Languages

- Untyped languages
 - Do not restrict the range of values for a given variable
 - Operations might be applied to inappropriate arguments. The behavior in such cases might be unspecified
 - The pure λ -calculus is an extreme case of an untyped language (however, its behavior is completely specified)
- Typed languages
 - Variables are assigned (non-trivial) types
 - A type system keeps track of types
 - Types might or might not appear in the program itself
 - Languages can be explicitly typed or implicitly typed

Execution Errors

- The purpose of types is to prevent certain types of execution errors
- Trapped execution errors
 - Cause the computation to stop immediately
 - Well-specified behavior
 - Usually enforced by hardware
 - E.g., Division by zero
 - E.g., Invoking a floating point operation with a NaN
 - E.g., Dereferencing the address 0

Execution Errors (II)

- Untrapped execution errors
 - Behavior is unspecified (depends on the state of the machine)
 - Accessing past the end of an array
 - Jumping to an address in the data segment
- A program is considered safe if it does not cause untrapped errors
 - Languages in which all programs are safe are safe languages
- For a given language designate a set of forbidden errors
 - A superset of the untrapped errors
 - Includes some trapped errors as well
 - E.g., null pointer dereference
 - To ensure portability across architectures

Preventing Forbidden Errors - *Static Checking*

- Forbidden errors can be caught by a combination of static and run-time checking
- Static checking
 - Detects errors early, before testing
 - Types provide the necessary static information for static checking
 - E.g., ML, Modula-3, Java
 - Detecting certain/most errors statically is undecidable in most languages

Preventing Forbidden Errors - *Dynamic Checking*

- Required when static checking is undecidable
 - e.g., array-bounds checking
- Run-time encoding of types are still used
 - e.g., Scheme, Lisp
- Should be limited
 - Delays the manifestation of errors
- Can be done in hardware
 - e.g. null-pointer

Safe Languages

- There are typed languages that are not safe (weakly typed languages)
- All safe languages use types (either statically or dynamically)

	Typed		Untyped
	Static	Dynamic	
Safe	ML, Java, ...	Lisp, Scheme	λ -calculus
Unsafe	C, C++, ...	?	Assembly

- We will be concerned mainly with statically typed languages

Why Typed Languages?

- **Development**
 - Type checking catches many mistakes early
 - Reduced debugging time
 - Typed signatures are a powerful basis for design
 - Typed signatures enable separate compilation
- **Maintenance**
 - Types act as checked specifications
 - Types can enforce abstraction
- **Execution**
 - Static checking reduces the need for dynamic checking
 - Safe languages are easier to analyze statically
 - the compiler can generate better code

Why Not Typed Languages?

- Static type checking imposes constraints on the programmer
 - Some valid programs might be rejected
 - But often they can be made well-typed easily
 - Hard to step outside the language (e.g. OO programming in a non-OO language)
- Dynamic safety checks can be costly
 - 50% is a possible cost of bounds-checking in a tight loop
 - In practice, the overall cost is much smaller
 - Memory management must be automatic \Rightarrow need a garbage collector with the associated run-time costs
 - Some applications are justified to use weakly-typed languages

Properties of Type Systems

- How do types differ from other program annotations
 - Types are more precise than comments
 - Types are more easily mechanizable than program specifications
- Expected properties of type systems:
 - Types should be enforceable
 - Types should be checkable algorithmically
 - Typing rules should be transparent
 - It should be easy to see why a program is not well-typed

Why Formal Type Systems?

- Many typed languages have informal descriptions of the type systems (e.g., in language reference manuals)
- A fair amount of careful analysis is required to avoid false claims of type safety
- A formal presentation of a type system is a precise specification of the type checker
 - And allows formal proofs of type safety
- But even informal knowledge of the principles of type systems help

Formalizing a Type System

A multi-step process

1. Syntax

- Of expressions (programs)
- Of types
- Issues of binding and scoping

2. Static semantics (typing rules)

- Define the typing judgment and its derivation rules

3. Dynamic semantics (e.g., operational)

- Define the evaluation judgment and its derivation rules

4. Type soundness

- Relates the static and dynamic semantics
- State and prove the soundness theorem

Typing Judgments

- Judgments
 - A statement J about certain formal entities
 - Has a truth value $\models J$
 - Has a derivation $\vdash J$
- A common form of the typing judgment: $\Gamma \vdash e : \tau$
(e is an expression and τ is a type)
- Γ is a set of type assignments for the free variables of e
 - Defined by the grammar $\Gamma ::= \cdot \mid \Gamma, x : \tau$
 - Usually viewed as a set of type assignments
 - Type assignments for variables not free in e are not relevant
 - E.g, $x : \text{int}, y : \text{int} \vdash x + y : \text{int}$

Typing rules

- Typing rules are used to derive typing judgments
- Examples:

$$\frac{}{\Gamma \vdash 1 : \text{int}}$$

$$\frac{x : \tau \in \Gamma}{\Gamma \vdash x : \tau}$$

$$\frac{\Gamma \vdash e_1 : \text{int} \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 + e_2 : \text{int}}$$

Typing Derivations

- A typing derivation is a derivation of a typing judgment
- Example:

$$\frac{\frac{}{x : \text{int} \vdash x : \text{int}} \quad \frac{\frac{}{x : \text{int} \vdash x : \text{int}} \quad \frac{}{x : \text{int} \vdash 1 : \text{int}}}{x : \text{int} \vdash x + 1 : \text{int}}}{x : \text{int} \vdash x + (x + 1) : \text{int}}$$

- We say that $\Gamma \vdash e : \tau$ to denote that there is a derivation of this typing judgment
- Type checking: given Γ , e and τ find a derivation
- Type inference: given Γ and e , find τ and a derivation

Proving Type Soundness

- A typing judgment has a truth value
- Define what it means for a value to have a type
$$v \in \llbracket \tau \rrbracket$$
(e.g. $5 \in \llbracket \text{int} \rrbracket$ and $\text{true} \in \llbracket \text{bool} \rrbracket$)
- Define what it means for an expression to have a type
$$e \in \llbracket \tau \rrbracket \quad \text{iff} \quad \forall v. (e \Downarrow v \Rightarrow v \in \llbracket \tau \rrbracket)$$
- Prove type soundness
 - If $\cdot \vdash e : \tau$ then $e \in \llbracket \tau \rrbracket$
 - or equivalently
 - If $\cdot \vdash e : \tau$ and $e \Downarrow v$ then $v \in \llbracket \tau \rrbracket$
- This implies safe execution (since the result of an unsafe execution is not in $\llbracket \tau \rrbracket$ for any τ)

Next

- We will give formal description of first-order type systems (no type variables)
 - Function types (simply typed λ -calculus)
 - Simple types (integers and booleans)
 - Structured types (products and sums)
 - Imperative types (references and exceptions)
 - Recursive types
- The type systems of most common languages are first-order
- The we move to second-order type systems
 - Polymorphism and abstract types

First-Order Type Systems

Simply-Typed Lambda Calculus

- Syntax:

Terms $e ::= x \mid \lambda x:\tau. e \mid e_1 e_2$
 $\mid n \mid e_1 + e_2 \mid \text{iszero } e$
 $\mid \text{true} \mid \text{false} \mid \text{not } e \mid \text{if } e_1 \text{ then } e_2 \text{ else } e_3$

Types $\tau ::= \text{int} \mid \text{bool} \mid \tau_1 \rightarrow \tau_2$

- $\tau_1 \rightarrow \tau_2$ is the function type
- \rightarrow associates to the right
- Arguments have typing annotations
- This language is also called F_1

Static Semantics of F_1

- The typing judgment

$$\Gamma \vdash e : \tau$$

- The typing rules

$$\frac{x : \tau \in \Gamma}{\Gamma \vdash x : \tau} \quad \frac{\Gamma, x : \tau \vdash e : \tau'}{\Gamma \vdash \lambda x : \tau. e : \tau \rightarrow \tau'}$$
$$\frac{\Gamma \vdash e_1 : \tau_2 \rightarrow \tau \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash e_1 e_2 : \tau}$$

Static Semantics of F_1 (Cont.)

- More typing rules

$$\frac{}{\Gamma \vdash n : \text{int}} \qquad \frac{\Gamma \vdash e_1 : \text{int} \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 + e_2 : \text{int}}$$

$$\frac{}{\Gamma \vdash \text{true} : \text{bool}} \qquad \frac{\Gamma \vdash e : \text{bool}}{\Gamma \vdash \text{not } e : \text{bool}}$$

$$\frac{\Gamma \vdash e_1 : \text{bool} \quad \Gamma \vdash e_t : \tau \quad \Gamma \vdash e_f : \tau}{\Gamma \vdash \text{if } e_1 \text{ then } e_t \text{ else } e_f : \tau}$$

Typing Derivation in F_1

- Consider the term

$\lambda x : \text{int}. \lambda b : \text{bool}. \text{if } b \text{ then } f \ x \ \text{else } x$

- With the initial typing assignment $f : \text{int} \rightarrow \text{int}$

$$\frac{\frac{\frac{\Gamma \vdash f : \text{int} \rightarrow \text{int} \quad \Gamma \vdash x : \text{int}}{\Gamma \vdash f \ x : \text{int}} \quad \Gamma \vdash b : \text{bool}}{\Gamma \vdash \text{if } b \text{ then } f \ x \ \text{else } x : \text{int}} \quad \Gamma \vdash x : \text{int}}{\Gamma \vdash \lambda b : \text{bool}. \text{if } b \text{ then } f \ x \ \text{else } x : \text{bool} \rightarrow \text{int}} \quad \Gamma \vdash f : \text{int} \rightarrow \text{int}, x : \text{int}}{\Gamma \vdash \lambda x : \text{int}. \lambda b : \text{bool}. \text{if } b \text{ then } f \ x \ \text{else } x : \text{int} \rightarrow \text{bool} \rightarrow \text{int}}$$

Where $\Gamma = f : \text{int} \rightarrow \text{int}, x : \text{int}, b : \text{bool}$

Type Checking in F_1

- Type checking is easy because
 - Typing rules are syntax directed
 - Typing rules are compositional
 - All local variables are annotated with types
- In fact, type inference is also easy for F_1
- Without type annotations an expression does not have a unique type
 - $\vdash \lambda x. x : \text{int} \rightarrow \text{int}$
 - $\vdash \lambda x. x : \text{bool} \rightarrow \text{bool}$

Operational Semantics of F_1

- Judgment:

$$e \Downarrow v$$

- Values

$$v ::= n \mid \text{true} \mid \text{false} \mid \lambda x:\tau. e$$

- The evaluation rules ...

Operational Semantics of F_1 (Cont.)

- Call-by-value evaluation rules (sample)

$$\frac{}{\lambda x : \tau. e \Downarrow \lambda x : \tau. e}$$

$$\frac{e_1 \Downarrow \lambda x : \tau. e'_1 \quad e_2 \Downarrow v_2 \quad [v_2/x]e'_1 \Downarrow v}{e_1 e_2 \Downarrow v}$$

$$\frac{n \Downarrow n \quad \frac{e_1 \Downarrow n_1 \quad e_2 \Downarrow n_2 \quad n = n_1 + n_2}{e_1 + e_2 \Downarrow n}}{n \Downarrow n}$$

$$\frac{e_1 \Downarrow \text{true} \quad e_t \Downarrow v}{\text{if } e_1 \text{ then } e_t \text{ else } e_f \Downarrow v}$$

$$\frac{e_1 \Downarrow \text{false} \quad e_f \Downarrow v}{\text{if } e_1 \text{ then } e_t \text{ else } e_f \Downarrow v}$$

Evaluation undefined
for ill-typed programs !

Type Soundness for F_1

- Theorem:
If $\cdot \vdash e : \tau$ and $e \Downarrow v$ then $\cdot \vdash v : \tau$
 - Also called, subject reduction theorem, type preservation theorem
- Try to prove by induction on e
 - Won't work because $[v_2/x]e'_1$ in the evaluation of $e_1 e_2$
 - Same problem with induction on $\cdot \vdash e : \tau$
- Try to prove by induction on τ
 - Won't work because e_1 has a "bigger" type than $e_1 e_2$
- Try to prove by induction on $e \Downarrow v$
 - To address the issue of $[v_2/x]e'_1$
 - This is it!

Type Soundness Proof

- Consider the case

$$\mathcal{E} :: \frac{e_1 \Downarrow \lambda x : \tau_2 . e'_1 \quad e_2 \Downarrow v_2 \quad [v_2/x]e'_1 \Downarrow v}{e_1 e_2 \Downarrow v}$$

and by inversion on the derivation of $e_1 e_2 : \tau$

$$\mathcal{D} :: \frac{\cdot \vdash e_1 : \tau_2 \longrightarrow \tau \quad \cdot \vdash e_2 : \tau_2}{\cdot \vdash e_1 e_2 : \tau}$$

- From IH on $e_1 \Downarrow \dots$ we have $\cdot, x : \tau_2 \vdash e'_1 : \tau$
- From IH on $e_2 \Downarrow \dots$ we have $\cdot \vdash v_2 : \tau_2$
- Need to infer that $\cdot \vdash [v_2/x]e'_1 : \tau$ and use the IH
 - We need a substitution lemma (by induction on e'_1)

Significance of Type Soundness

- The theorem says that the result of an evaluation has the same type as the initial expression
- The theorem does not say that
 - The evaluation never gets stuck (e.g., trying to apply a non-function, to add non-integers, etc.), nor that
 - The evaluation terminates
- Even though both of the above facts are true of F_1
- We need a small-step semantics to prove that the execution never gets stuck

Small-Step Contextual Semantics for F_1

- We define redexes

$$r ::= n_1 + n_2 \mid \text{if } b \text{ then } e_1 \text{ else } e_2 \mid (\lambda x:\tau. e_1) v_2$$

- and contexts

$$H ::= H_1 + e_2 \mid n_1 + H_2 \mid \text{if } H \text{ then } e_1 \text{ else } e_2 \mid H_1 e_2 \mid (\lambda x:\tau. e_1) H_2$$

- and local reduction rules

$$n_1 + n_2 \quad \rightarrow \quad n_1 \text{ plus } n_2$$

$$\text{if true then } e_1 \text{ else } e_2 \quad \rightarrow \quad e_1$$

$$\text{if false then } e_1 \text{ else } e_2 \quad \rightarrow \quad e_2$$

$$(\lambda x:\tau. e_1) v_2 \quad \rightarrow \quad [v_2/x]e_1$$

- and one global reduction rule

$$H[r] \rightarrow H[e] \quad \text{iff } r \rightarrow e$$

Contextual Semantics for F_1

- Decomposition lemmas:
 1. If $\cdot \vdash e : \tau$ and e is not a value then there exist (unique) H and r such that $e = H[r]$
 - any well typed expression can be decomposed
 - Any well-typed non-value can make progress
 2. Furthermore, there exists τ' such that $\cdot \vdash r : \tau'$
 - the redex is closed and well typed
 3. Furthermore, there exists e' such that $r \rightarrow e'$ and $\cdot \vdash e' : \tau'$
 - local reduction is type preserving
 4. Furthermore, for any e' , $\cdot \vdash e' : \tau'$ implies $\cdot \vdash H[e'] : \tau$
 - the expression preserves its type if we replace the redex with an expression of same type

Contextual Semantics of F_1

- Type preservation theorem
 - If $\cdot \vdash e : \tau$ and $e \rightarrow e'$ then $\cdot \vdash e' : \tau$
 - Follows from the decomposition lemma
- Progress theorem
 - If $\cdot \vdash e : \tau$ and e is not a value then there exists e' such that e can make progress: $e \rightarrow e'$
- Progress theorem says that execution can make progress on a well typed expression
- Furthermore, due to type preservation we know that the execution of a well typed expression never gets stuck
 - this is a common way to state and prove type safety of a language

Product Types - Static Semantics

- Extend the syntax with (binary) tuples
$$e ::= \dots \mid (e_1, e_2) \mid \text{fst } e \mid \text{snd } e$$
$$\tau ::= \dots \mid \tau_1 \times \tau_2$$
 - This language is sometimes called F_1^\times
- Same typing judgment $\Gamma \vdash e : \tau$

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash (e_1, e_2) : \tau_1 \times \tau_2}$$

$$\frac{\Gamma \vdash e : \tau_1 \times \tau_2}{\Gamma \vdash \text{fst } e : \tau_1} \quad \frac{\Gamma \vdash e : \tau_1 \times \tau_2}{\Gamma \vdash \text{snd } e : \tau_2}$$

Product Types: Dynamic Semantics and Soundness

- New form of values: $v ::= \dots \mid (v_1, v_2)$
- New (big step) evaluation rules:

$$\frac{e_1 \Downarrow v_1 \quad e_2 \Downarrow v_2}{(e_1, e_2) \Downarrow (v_1, v_2)}$$

$$\frac{e \Downarrow (v_1, v_2)}{\text{fst } e \Downarrow v_1} \quad \frac{e \Downarrow (v_1, v_2)}{\text{snd } e \Downarrow v_2}$$

- New contexts: $H ::= \dots \mid (H_1, e_2) \mid (v_1, H_2) \mid \text{fst } H \mid \text{snd } H$

- New redexes:

$$\text{fst } (v_1, v_2) \rightarrow v_1$$

$$\text{snd } (v_1, v_2) \rightarrow v_2$$

- Type soundness holds just as before

Records

- Records are like tuples with labels
- New form of expressions

$$e ::= \dots \mid \{L_1 = e_1, \dots, L_n = e_n\} \mid e.L$$

- New form of values

$$v ::= \{L_1 = v_1, \dots, L_n = v_n\}$$

- New form of types

$$\tau ::= \dots \mid \{L_1 : \tau_1, \dots, L_n : \tau_n\}$$

- ... follows the model of F_1^\times
 - typing rules
 - derivation rules
 - type soundness

Sum Types

- We need types of the form
 - either an int or a float
 - either 0 or a pointer
 - either true or false
 - These are called disjoint union types
- New form of expressions and types
$$e ::= \dots \mid \text{injl } e \mid \text{inj } e \mid$$
$$\text{case } e \text{ of injl } x \rightarrow e_1 \mid \text{inj } y \rightarrow e_2$$
$$\tau ::= \dots \mid \tau_1 + \tau_2$$
 - A value of type $\tau_1 + \tau_2$ is either a τ_1 or a τ_2
 - Like union in C or Pascal, but safe
 - distinguishing between components is under compiler control
 - case is a binding operator: x is bound in e_1 and y is bound in e_2

Examples with Sum Types

- Consider the type “unit” with a single element called *
- The type “optional integer” defined as “unit + int”
 - Useful for optional arguments or return values
 - No argument: `injl *`
 - Argument is 5: `inj r 5`
 - To use the argument you must test the kind of argument
 - `case arg of injl x ⇒ “no_arg_case” | injr y ⇒ “...y...”`
 - `injl` and `inj r` are tags and `case` is tag checking
- Bool is a union type: `bool = unit + unit`
 - `true` is `injl *`
 - `false` is `inj r *`
 - `if e then e1 else e2` is `case e of injl x ⇒ e1 | injr y ⇒ e2`
 - Check the equivalence of the static and dynamic semantics

Static Semantics of Sum Types

- New typing rules

$$\frac{\Gamma \vdash e : \tau_1}{\Gamma \vdash \text{injl } e : \tau_1 + \tau_2} \quad \frac{\Gamma \vdash e : \tau_2}{\Gamma \vdash \text{injr } e : \tau_1 + \tau_2}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 + \tau_2 \quad \Gamma, x : \tau_1 \vdash e_l : \tau \quad \Gamma, y : \tau_2 \vdash e_r : \tau}{\Gamma \vdash \text{case } e_1 \text{ of } \text{injl } x \Rightarrow e_l \mid \text{injr } y \Rightarrow e_r : \tau}$$

- Types are not unique anymore

injl 1 : int + bool

injl 1 : int + (int → int)

- this complicates type checking, but still doable

Dynamic Semantics of Sum Types

- New values $v ::= \dots \mid \text{injl } v \mid \text{injrl } v$
- New evaluation rules

$$\frac{e \Downarrow v}{\text{injl } e \Downarrow \text{injl } v} \quad \frac{e \Downarrow v}{\text{injrl } e \Downarrow \text{injrl } v}$$

$$\frac{e \Downarrow \text{injl } v \quad [v/x]e_l \Downarrow v'}{\text{case } e \text{ of } \text{injl } x \Rightarrow e_l \mid \text{injrl } y \Rightarrow e_r \Downarrow v'}$$

$$\frac{e \Downarrow \text{injrl } v \quad [v/y]e_r \Downarrow v'}{\text{case } e \text{ of } \text{injl } x \Rightarrow e_l \mid \text{injrl } y \Rightarrow e_r \Downarrow v'}$$

Type Soundness for F_1^+

- Type soundness still holds
- No way to use a $\tau_1 + \tau_2$ inappropriately
- The key is that the only way to use a $\tau_1 + \tau_2$ is with case, which ensures that you are not using a τ_1 as a τ_2
- In C or Pascal checking the tag is the responsibility of the programmer!
 - Unsafe

Types for Imperative Features

- We looked at types for pure functional languages
- Now we look at types for imperative features
- Such types are used to characterize non-local effects
 - assignments
 - exceptions
- Contextual semantics is useful here

Reference Types

- Such types are used for mutable memory cells

- Syntax (as in ML)

$$e ::= \dots \mid \text{ref } e : \tau \mid e_1 := e_2 \mid ! e$$
$$\tau ::= \dots \mid \tau \text{ ref}$$

- $\text{ref } e$ - evaluates e , allocates a new memory cell, stores the value of e in it and returns the address of the memory cell
 - like `malloc` + initialization in `C`, or `new` in `C++` and `Java`
- $e_1 := e_2$, evaluates e_1 to a memory cell and updates its value with the value of e_2
- $! e$ - evaluates e to a memory cell and returns its contents

Global Effects with Reference Cells

- A reference cell can escape the static scope where it was created

$(\lambda f:\text{int} \rightarrow \text{int ref. } !(f\ 5))\ (\lambda x:\text{int. ref } x : \text{int})$

- The value stored in a reference cell must be visible from the entire program
- The “result” of an expression must now include the changes to the heap that it makes
- To model reference cells we must extend the evaluation model

Modeling References

- A heap is a mapping from addresses to values

$$h ::= \cdot \mid h, a \leftarrow v : \tau$$

- $a \in \text{Addresses}$
- We tag the heap cells with their types
- Types are useful only for static semantics. They are not needed for the evaluation \Rightarrow not a part of the implementation
- We call a “program” an expression along with a heap
$$p ::= \text{heap } h \text{ in } e$$
 - The initial program is “heap \emptyset in e ”
 - Heap addresses act as bound variables in the expression
 - This is a trick that allows easy reuse of properties of local variables for heap addresses
 - e.g., we can rename the address and its occurrences at will

Static Semantics of References

- Typing rules for expressions:

$$\frac{\Gamma \vdash e : \tau}{\Gamma \vdash (\text{ref } e : \tau) : \tau \text{ ref}} \qquad \frac{\Gamma \vdash e : \tau \text{ ref}}{\Gamma \vdash !e : \tau}$$

$$\frac{\Gamma \vdash e_1 : \tau \text{ ref} \quad \Gamma \vdash e_2 : \tau}{\Gamma \vdash e_1 := e_2 : \text{unit}}$$

- and for programs

$$\frac{\Gamma \vdash v_i : \tau_i \ (i = 1..n) \quad \Gamma \vdash e : \tau}{\vdash \text{heap } h \text{ in } e : \tau}$$

where $\Gamma = a_1 : \tau_1 \text{ ref}, \dots, a_n : \tau_n \text{ ref}$

and $h = a_1 \leftarrow v_1 : \tau_1, \dots, a_n \leftarrow v_n : \tau_n$

Exceptions

- A mechanism that allows non-local control flow
 - Useful for implementing the propagation of errors to caller
- Exceptions ensure that errors are not ignored
 - Compare with the manual error handling in C
- Languages with exceptions:
 - C++, ML, Modula-3, Java
- We assume that there is a special type `exn` of exceptions
 - `exn` could be `int` to model error codes
 - In Java or C++, `exn` is a special object type

Modeling Exceptions

- Syntax

$e ::= \dots \mid \text{raise } e \mid \text{try } e_1 \text{ handle } x \Rightarrow e_2$

$\tau ::= \dots \mid \text{exn}$

- We ignore here how exception values are created
 - In examples we will use integers as exception values
- The handler binds x in e_2 to the actual exception value
- The “raise” expression never returns to the immediately enclosing context
 - $1 + \text{raise } 2$ is well-typed
 - $\text{if } (\text{raise } 2) \text{ then } 1 \text{ else } 2$ is also well-typed
 - $(\text{raise } 2) 5$ is also well-typed
 - What should the type of `raise` be?

Example with Exceptions

- A (strange) factorial function

```
let f = λx:int.λres:int. if x = 0 then
                        raise res
                        else
                        f (x - 1) (res * x)
in try f 5 1 handle x ⇒ x
```

- The function returns in one step from the recursion
- The top-level handler catches the exception and turns it into a regular result

Typing Exceptions

- New typing rules

$$\frac{\Gamma \vdash e : \text{exn}}{\Gamma \vdash \text{raise } e : \tau}$$

$$\frac{\Gamma \vdash e_1 : \tau \quad \Gamma, x : \text{exn} \vdash e_2 : \tau}{\Gamma \vdash \text{try } e_1 \text{ handle } x \Longrightarrow e_2 : \tau}$$

- A raise expression has an arbitrary type
 - This is a clear sign that the expression does not return to its evaluation context
- The type of the body of try and of the handler must match
 - Just like for conditionals

Recursive Types Subtyping

Recursive Types

- It is useful to be able to define recursive data structures
- Example: lists
 - A list of elements of type τ (a τ list) is either empty or it is a pair of a τ and a τ list
$$\tau \text{ list} = \text{unit} + (\tau \times \tau \text{ list})$$
 - This is a recursive equation. We take its solution to be the smallest set of values L that satisfies the equation
$$L = \{*\} \cup (T \times L)$$
where T is the set of values of type τ
 - Note: this interpretation can be troublesome
 - E.g. $\tau = \tau \rightarrow \tau$, but only for trivial sets we have $T = T \rightarrow T$
 - Another interpretation is that the recursive equation is up-to set isomorphism

Recursive Types

- We introduce a recursive type constructor

$$\mu t. \tau$$

- The type variable t is bound in τ
- This is the solution to the equation

$$t \simeq \tau \quad (t \text{ is isomorphic with } \tau)$$

- E.g., $\tau \text{ list} = \mu t. (\text{unit} + \tau \times t)$
 - This allows “unnamed” recursive types
- We introduce syntactic operations for the conversion between $\mu t. \tau$ and $[\mu t. \tau / t] \tau$
 - E.g. between “ $\tau \text{ list}$ ” and “ $\text{unit} + \tau \times \tau \text{ list}$ ”

$$e ::= \dots \mid \text{fold}_{\mu t. \tau} e \mid \text{unfold}_{\mu t. \tau} e$$

$$\tau ::= \dots \mid t \mid \mu t. \tau$$

Example with Recursive Types

- Lists

$$\tau \text{ list} = \mu t. (\text{unit} + \tau \times t)$$

$$\text{nil}_\tau = \text{fold}_{\tau \text{ list}} (\text{injl } *)$$

$$\text{cons}_\tau = \lambda x:\tau. \lambda L:\tau \text{ list}. \text{fold}_{\tau \text{ list}} \text{ injr } (x, L)$$

- A list length function

$$\text{length}_\tau = \lambda L:\tau \text{ list}. \text{case } (\text{unfold}_{\tau \text{ list}} L) \text{ of } \text{injl } x \Rightarrow 0$$

$$| \text{ injr } y \Rightarrow 1 + \text{length}_\tau (\text{snd } y)$$

- Verify that

- $\text{nil}_\tau : \tau \text{ list}$

- $\text{cons}_\tau : \tau \rightarrow \tau \text{ list} \rightarrow \tau \text{ list}$

- $\text{length}_\tau : \tau \text{ list} \rightarrow \text{int}$

Static Semantics of Recursive Types

$$\frac{\Gamma \vdash e : \mu t. \tau}{\Gamma \vdash \text{unfold}_{\mu t. \tau} e : [\mu t. \tau / t] \tau}$$

$$\frac{\Gamma \vdash e : [\mu t. \tau / t] \tau}{\Gamma \vdash \text{fold}_{\mu t. \tau} e : \mu t. \tau}$$

- The typing rules are syntax directed
- Often, for syntactic simplicity, the fold and unfold operators are omitted
 - This makes type checking somewhat harder

Dynamics of Recursive Types

- We add a new form of values

$$v ::= \dots \mid \text{fold}_{\mu t. \tau} v$$

- The purpose of fold is to ensure that the value has the recursive type and not its unfolding

- The evaluation rules:

$$\frac{e \Downarrow v}{\text{fold}_{\mu t. \tau} e \Downarrow \text{fold}_{\mu t. \tau} v} \quad \frac{e \Downarrow \text{fold}_{\mu t. \tau} v}{\text{unfold}_{\mu t. \tau} e \Downarrow v}$$

- The folding annotations are for type checking only
- They can be dropped after type checking

Recursive Types in ML

- The language ML uses a simple syntactic trick to avoid having to write the explicit fold and unfold
- In ML recursive types are bundled with union types
 - datatype $t = C_1 \text{ of } \tau_1 \mid C_2 \text{ of } \tau_2 \mid \dots \mid C_n \text{ of } \tau_n$ (t can appear in τ_i)
 - E.g., datatype $\text{intlist} = \text{Nil of unit} \mid \text{Cons of int} \times \text{intlist}$
- When the programmer writes
 - $\text{Cons } (5, l)$
 - the compiler treats it as
 - $\text{fold}_{\text{intlist}} (\text{injr } (5, l))$
- When the programmer writes
 - $\text{case } e \text{ of Nil} \Rightarrow \dots \mid \text{Cons } (h, t) \Rightarrow \dots$
 - the compiler treats it as
 - $\text{case unfold}_{\text{intlist}} e \text{ of Nil} \Rightarrow \dots \mid \text{Cons } (h, t) \Rightarrow \dots$

Encoding Call-by-Value λ -calculus in F_1^μ

- So far, F_1 was so weak that we could not encode non-terminating computations
 - Cannot encode recursion
 - Cannot write the $\lambda x.x x$ (self-application)
- The addition of recursive types makes typed λ -calculus as expressive as untyped λ -calculus !
- We can show a conversion algorithm from call-by-value untyped λ -calculus to call-by-value F_1^μ

Untyped Programming in F_1^μ

- We write \underline{e} for the conversion of the term e to F_1^μ
 - The type of \underline{e} is $V = \mu t. t \rightarrow t$

- The conversion rules

$$\underline{x} = x$$

$$\underline{\lambda x. e} = \text{fold}_V (\lambda x:V. \underline{e})$$

$$\underline{e_1 e_2} = (\text{unfold}_V \underline{e_1}) \underline{e_2}$$

- Verify that

1. $\cdot \vdash \underline{e} : V$

2. $e \Downarrow v$ if and only if $\underline{e} \Downarrow \underline{v}$

- We can express non-terminating computation

$$D = (\text{unfold}_V (\text{fold}_V (\lambda x:V. (\text{unfold}_V x) x))) (\text{fold}_V (\lambda x:V. (\text{unfold}_V x) x))$$

or, equivalently

$$D = (\lambda x:V. (\text{unfold}_V x) x) (\text{fold}_V (\lambda x:V. (\text{unfold}_V x) x))$$

Subtyping

Introduction to Subtyping

- Viewing types as denoting sets of values, it is natural to consider a subtyping relation between types as induced by the subset relation between sets
- Informal intuition:
 - If τ is a subtype of σ then any expression with type τ also has type σ
 - If τ is a subtype of σ then any expression of type τ can be used in a context that expects a σ
 - Subtyping is reflexive and transitive
 - We write $\tau < \sigma$ to say that τ is a subtype of σ

Subtyping Examples

- FORTRAN introduced $\text{int} < \text{real}$
 - $5 + 1.5$ is well-typed in many languages
- PASCAL had $[1..10] < [0..15] < \text{int}$
- It is generally accepted that subtyping is a fundamental property of object-oriented languages
 - Let S be a subclass of C . Then an instance of S can be used where an instance of C is expected
 - This is “subclassing \Rightarrow subtyping” philosophy

Subsumption

- We formalize the informal requirement on subtyping
- Rule of subsumption
 - If $\tau < \sigma$ then an expression of type τ also has type σ

$$\frac{\Gamma \vdash e : \tau \quad \tau < \sigma}{\Gamma \vdash e : \sigma}$$

- But now type safety is in danger:
 - If we say that $\text{int} < \text{int} \rightarrow \text{int}$
 - Then we can prove that “5 5” is well typed!
- There is a way to construct the subtyping relation to preserve type safety

Defining Subtyping

- The formal definition of subtyping is by derivation rules for the judgment $\tau < \sigma$
- We start with subtyping on the base types
 - E.g. $\text{int} < \text{real}$ or $\text{nat} < \text{int}$
 - These rules are language dependent and are typically based directly on types-as-sets arguments
- We then make subtyping a preorder (reflexive and transitive)

$$\frac{}{\tau < \tau} \qquad \frac{\tau_1 < \tau_2 \quad \tau_2 < \tau_3}{\tau_1 < \tau_3}$$

- Then we build-up subtyping for “larger” types

Subtyping for Pairs

- Try

$$\frac{\tau < \sigma \quad \tau' < \sigma'}{\tau \times \tau' < \sigma \times \sigma'}$$

- Show (informally) that whenever a $\sigma \times \sigma'$ can be used, a $\tau \times \tau'$ can also be used:
- Consider the context $H = H' [\text{fst } \bullet]$ expecting a $\sigma \times \sigma'$
 - Then H' expects a σ
 - Because $\tau < \sigma$ then H' accepts a τ
 - Take $e : \tau \times \tau'$. Then $\text{fst } e : \tau$ so it works in H'
 - Thus e works in H
- The case of “ $\text{snd } \bullet$ ” is similar

Subtyping for Functions

- Try the (naive) rule

$$\frac{\tau < \sigma \quad \tau' < \sigma'}{\tau \rightarrow \tau' < \sigma \rightarrow \sigma'}$$

- This rule is unsound
 - Let $\Gamma = f : \text{int} \rightarrow \text{bool}$ (and assume $\text{int} < \text{real}$)
 - We show using the above rule that $\Gamma \vdash f \ 5.0 : \text{bool}$
 - But this is wrong since 5.0 is not a valid argument of f

$$\frac{\Gamma \vdash f : \text{int} \rightarrow \text{bool} \quad \frac{\text{int} < \text{real} \quad \text{bool} < \text{bool}}{\text{int} \rightarrow \text{bool} < \text{real} \rightarrow \text{bool}}}{\frac{\Gamma \vdash f : \text{real} \rightarrow \text{bool} \quad \Gamma \vdash 5.0 : \text{real}}{\Gamma \vdash f \ 5.0 : \text{bool}}}$$

Subtyping for Functions (Cont.)

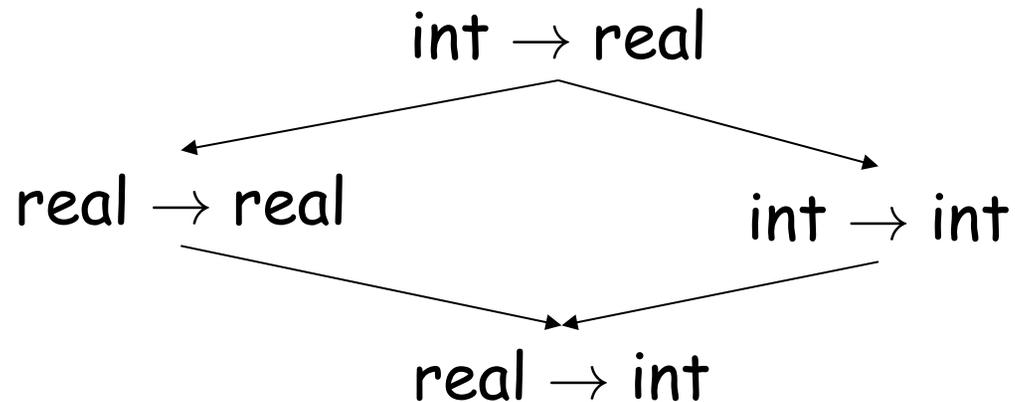
- The correct rule

$$\frac{\sigma < \tau \quad \tau' < \sigma'}{\tau \rightarrow \tau' < \sigma \rightarrow \sigma'}$$

- We say that \rightarrow is covariant in the result type and contravariant in the argument type
- Informal correctness argument:
 - Pick $f : \tau \rightarrow \tau'$
 - f expects an argument of type τ
 - It also accepts an argument of type $\sigma < \tau$
 - f returns a value of type τ'
 - Which can also be viewed as a σ' (since $\tau' < \sigma'$)
 - Hence f can be used as $\sigma \rightarrow \sigma'$

More on Contravariance

- Consider the subtype relationships



- In what sense $f \in \text{real} \rightarrow \text{int} \Rightarrow f \in \text{int} \rightarrow \text{int}$?
 - “ $\text{real} \rightarrow \text{int}$ ” has a larger domain!
- This suggests that “subtype-as-subset” interpretation is not straightforward

Subtyping References

- Try covariance

$$\frac{\tau < \sigma}{\tau \text{ ref} < \sigma \text{ ref}}$$

Wrong!

- Example: assume $\tau < \sigma$
 - The following holds (if we assume the above rule):
$$x : \sigma, y : \tau \text{ ref}, f : \tau \rightarrow \text{int} \vdash y := x; f (! y)$$
 - Unsound: f is called on a σ but is defined only on τ
 - Java has covariant arrays !
- If we want covariance of references we can recover type safety with a runtime check for each $y := x$
 - The actual type of x matches the actual type of y
 - But this is generally considered a bad design

Subtyping References (Cont.)

- Try contravariance:

$$\frac{\tau < \sigma}{\sigma \text{ ref} < \tau \text{ ref}}$$

Also Wrong!

- Example: assume $\tau < \sigma$
- The following holds (if we assume the above rule):
$$x : \sigma, y : \sigma \text{ ref}, f : \tau \rightarrow \text{int} \vdash y := x; f (! y)$$
- Unsound: f is called on a σ but is defined only on τ
- References are invariant
 - no subtyping for references (unless we are prepared to add run-time checks)
 - hence, arrays should be invariant
 - hence, mutable records should be invariant

Subtyping Recursive Types

- Recall $\tau \text{ list} = \mu t.(\text{unit} + \tau \times t)$
 - We would like $\tau \text{ list} < \sigma \text{ list}$ whenever $\tau < \sigma$
- Try simple covariance:

$$\frac{\tau < \sigma}{\mu t. \tau < \mu t. \sigma} \quad \text{Wrong!}$$

- This is wrong if t occurs contravariantly in τ
- Take $\tau = \mu t. t \rightarrow \text{int}$ and $\sigma = \mu t. t \rightarrow \text{real}$
- Above rule says that $\tau < \sigma$
- We have $\tau \simeq \tau \rightarrow \text{int}$ and $\sigma \simeq \sigma \rightarrow \text{real}$
- $\tau < \sigma$ would mean covariant function type!
- How can we still have the subtyping for lists?

Subtyping Recursive Types (Cont.)

- The correct rule

$$\frac{\begin{array}{c} t < s \\ \vdots \\ \tau < \sigma \end{array}}{\mu t. \tau < \mu s. \sigma}$$

- We add as an assumption that the type variables stand for types with the desired subtype relationship
 - Before we assumed that they stand for the same type!
- Verify that subtyping now works properly for lists
- There is no subtyping between $\mu t. t \rightarrow \text{int}$ and $\mu t. t \rightarrow \text{real}$

Second-Order Type Systems

The Limitations of F_1

- In F_1 each function works exactly for one type
- Example: sorting function
 - $\text{sort} : (\tau \rightarrow \tau \rightarrow \text{bool}) \rightarrow \tau \text{ array} \rightarrow \text{unit}$
- The various sorting functions differ only in typing
 - At runtime they perform exactly the same operations
 - Need different versions only to keep the type checker happy
- Two alternatives:
 - Circumvent the type system (example: C, Java), or
 - Use a more flexible type system that lets us write only one sorting function (example: ML, Java 1.5)

Polymorphism

- Informal definition
 - A function is polymorphic if it can be applied to “many” types of arguments
- Various kinds of polymorphism depending on the definition of “many”
 - subtype (or bounded) polymorphism
 - “many” = all subtypes of a given type
 - ad-hoc polymorphism
 - “many” = depends on the function
 - choose behavior at runtime (depending on types, e.g. sizeof)
 - parametric predicative polymorphism
 - “many” = all monomorphic types
 - parametric impredicative polymorphism
 - “many” = all types

Parametric Polymorphism: Types as Parameters

- We introduce type variables and allow expressions to have variable types

- We introduce polymorphic types

$$\tau ::= b \mid \tau_1 \rightarrow \tau_2 \mid t \mid \forall t. \tau$$

$$e ::= x \mid \lambda x:\tau. e \mid e_1 e_2 \mid \Lambda t. e \mid e[\tau]$$

- $\Lambda t. e$ is type abstraction (or generalization)
- $e[\tau]$ is type application (or instantiation)

- Examples:

- $id = \Lambda t. \lambda x:t. x \quad : \quad \forall t. t \rightarrow t$

- $id[int] = \lambda x:int. x \quad : \quad int \rightarrow int$

- $id[bool] = \lambda x:bool. x \quad : \quad bool \rightarrow bool$

- “id 5” is invalid. Use “id [int] 5” instead

Impredicative Polymorphism

- The typing rules:

$$\frac{x : \tau \text{ in } \Gamma}{\Gamma \vdash x : \tau} \quad \frac{\Gamma, x : \tau \vdash e : \tau'}{\Gamma \vdash \lambda x : \tau. e : \tau \rightarrow \tau'}$$

$$\frac{\Gamma \vdash e_1 : \tau \rightarrow \tau' \quad \Gamma \vdash e_2 : \tau}{\Gamma \vdash e_1 e_2 : \tau'}$$

$$\frac{\Gamma \vdash e : \tau}{\Gamma \vdash \Lambda t. e : \forall t. \tau} \quad t \text{ does not occur in } \Gamma$$

$$\frac{\Gamma \vdash e : \forall t. \tau'}{\Gamma \vdash e[\tau] : [\tau/t]\tau'}$$

Impredicative Polymorphism (Cont.)

- Verify that “id [int] 5” has type int
- Note the side-condition in the rule for type abstraction
 - Prevents ill-formed terms like: $\lambda x:t.\Lambda t.x$
- The evaluation rules are just like those of F_1
 - This means that type abstraction and application are all performed at compile time
 - We do not evaluate under Λ ($\Lambda t. e$ is a value)
 - We do not have to operate on types at run-time
 - This is called phase separation: type checking and execution

Expressiveness of Impredicative Polymorphism

- This calculus is called
 - F_2
 - system F
 - second-order λ -calculus
 - polymorphic λ -calculus
- Polymorphism is extremely expressive
- We can encode many base and structured types in F_2

What's Wrong with F_2

- Simple syntax but very complicated semantics
 - id can be applied to itself: “id $[\forall t. t \rightarrow t]$ id”
 - This can lead to paradoxical situations in a pure set-theoretic interpretation of types
 - E.g., the meaning of id is a function whose domain contains a set (the meaning of $\forall t. t \rightarrow t$) that contains id !
 - This suggests that giving an interpretation to impredicative type abstraction is tricky
- Complicated termination proof (Girard)
- Type reconstruction (typeability) is undecidable
 - If the type application and abstraction are missing
- How to fix it?
 - Restrict the use of polymorphism

Predicative Polymorphism

- Restriction: type variables can be instantiated only with monomorphic types
- This restriction can be expressed syntactically
$$\tau ::= b \mid \tau_1 \rightarrow \tau_2 \mid \dagger$$
$$\sigma ::= \tau \mid \forall \dagger. \sigma \mid \sigma_1 \rightarrow \sigma_2$$
$$e ::= x \mid e_1 e_2 \mid \lambda x:\sigma. e \mid \Lambda \dagger. e \mid e [\tau]$$
 - Type application is restricted to mono types
 - Cannot apply “id” to itself anymore
- Same typing rules
- Simple semantics and termination proof
- Type reconstruction still undecidable
- Must restrict further !

Prenex Predicative Polymorphism

- Restriction: polymorphic type constructor at top level only
- This restriction can also be expressed syntactically
$$\tau ::= b \mid \tau_1 \rightarrow \tau_2 \mid \dagger$$
$$\sigma ::= \tau \mid \forall \dagger. \sigma$$
$$e ::= x \mid e_1 e_2 \mid \lambda x:\tau. e \mid \Lambda \dagger. e \mid e [\tau]$$
 - Type application is restricted to mono types (i.e., predicative)
 - Abstraction only on mono types
 - The only occurrences of \forall are at the top level of a type
 $(\forall \dagger. \dagger \rightarrow \dagger) \rightarrow (\forall \dagger. \dagger \rightarrow \dagger)$ is not a valid type
- Same typing rules
- Simple semantics and termination proof
- Decidable type inference !

Expressiveness of Prenex Predicative F_2

- We have simplified too much !
- Not expressive enough to encode nat, bool
 - But such encodings are only of theoretical interest anyway
- Is it expressive enough in practice?
 - Almost
 - Cannot write something like
 $(\lambda s:\forall t.\tau. \dots s \text{ [nat] } x \dots s \text{ [bool] } y) (\Delta t. \dots \text{ code for sort})$
 - Because the type of formal argument s cannot be polymorphic

ML's Polymorphic Let

- ML solution: slight extension of the predicative F_2
 - Introduce “let $x : \sigma = e_1$ in e_2 ”
 - With the semantics of “ $(\lambda x : \sigma. e_2) e_1$ ”
 - And typed as “ $[e_1/x] e_2$ ”

$$\frac{\Gamma \vdash e_1 : \sigma \quad \Gamma, x : \sigma \vdash e_2 : \tau}{\Gamma \vdash \text{let } x : \sigma = e_1 \text{ in } e_2 : \tau}$$

- This lets us write the polymorphic sort as
let
 $s : \forall t. \tau = \Lambda t. \dots$ code for polymorphic sort ...
in
 ... s [nat] x ... s [bool] y
- Surprise: this was a major ML design flaw!

ML Polymorphism and References

- let is evaluated using call-by-value but is typed using call-by-name
 - What if there are side effects ?
- Example:
let $x : \forall t. (t \rightarrow t)$ ref = $\Delta t.$ ref $(\lambda x : t. x)$
in
 x [bool] := $\lambda x: \text{bool. not } x$
 (! x [int]) 5
end
 - Will apply “not” to 5
 - Similar examples can be constructed with exceptions
- It took 10 years to find and agree on a clean solution

The Value Restriction in ML

- A type in a let is generalized only for syntactic values

$$\frac{\Gamma \vdash e_1 : \sigma \quad \Gamma, x : \sigma \vdash e_2 : \tau}{\Gamma \vdash \text{let } x : \sigma = e_1 \text{ in } e_2 : \tau} \quad \begin{array}{l} e_1 \text{ is a syntactic} \\ \text{value or } \sigma \text{ is} \\ \text{monomorphic} \end{array}$$

- Since e_1 is a value, its evaluation cannot have side-effects
- In this case call-by-name and call-by-value are the same
- In the previous example $\text{ref } (\lambda x:t. x)$ is not a value
- This is not too restrictive in practice !

Subtype Bounded Polymorphism

- We can bound the instances of a given type variable

$$\forall t < \tau. \sigma$$

- Consider a function $f : \forall t < \tau. t \rightarrow \sigma$
- How is this different from $f' : \tau \rightarrow \sigma$
 - We can also invoke f' on any subtype of τ
- They are different if t appears in σ
 - E.g, $f : \forall t < \tau. t \rightarrow t$ and $f' : \tau \rightarrow \tau$
 - Take $x : \tau' < \tau$
 - We have $f [\tau'] x : \tau'$
 - And $f' x : \tau$
 - We lost information with f'

Not covered in this class

- A lot!
- Dependent Types
- Types for abstraction and modularity
- Pi calculus
- Object calculi
- Type-based analysis
- Constraint-based analysis
- Applications (looked at some)
- And more ...