



Previously

- Intro to generic object recognition
- Supervised classification
 - Main idea
 - Skin color detection example

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Last time:

Example: skin color classification

- We can represent a class-conditional density using a histogram (a "non-parametric" distribution)

$P(x|skin)$
Feature $x = Hue$


$P(x|not\ skin)$
Feature $x = Hue$

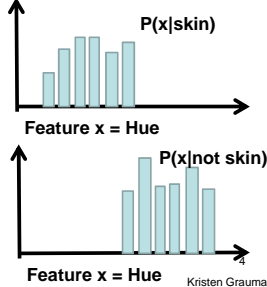
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Last time:

Example: skin color classification

- We can represent a class-conditional density using a histogram (a "non-parametric" distribution)





Now we get a new image, and want to label each pixel as skin or non-skin.


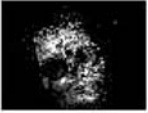
$P(\text{skin} | x) \propto P(x | \text{skin})P(\text{skin})$

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Last time:

Example: skin color classification

Now for every pixel in a new image, we can estimate probability that it is generated by skin.

Brighter pixels → higher probability of being skin

Classify pixels based on these probabilities

- if $p(\text{skin}|x) > \theta$, classify as skin
- if $p(\text{skin}|x) < \theta$, classify as not skin

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Today

- Window-based generic object detection
 - basic pipeline
 - boosting classifiers
 - face detection as case study

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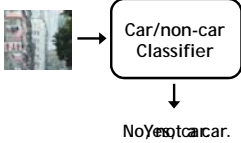
**Generic category recognition:
basic framework**

- Build/train object model
 - Choose a representation
 - Learn or fit parameters of model / classifier
- Generate candidates in new image
- Score the candidates

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Window-based models
Building an object model

Given the representation, train a binary classifier



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Window-based models
Generating and scoring candidates



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Window-based object detection: recap

Training:

1. Obtain training data
2. Define features
3. Define classifier

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Window-based object detection: recap

Training:

1. Obtain training data
2. Define features
3. Define classifier

Given new image:

1. Slide window
2. Score by classifier

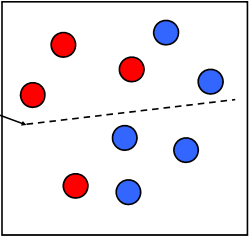
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Discriminative classifier construction

<p>Nearest neighbor</p> <p>10⁶ examples</p> <p>Shakhnarovich, Viola, Darrell 2003 Berg, Berg, Malik 2005...</p>	<p>Neural networks</p> <p>LeCun, Bottou, Bengio, Haffner 1998 Rowley, Baluja, Kanade 1998 ...</p>	
<p>Support Vector Machines</p> <p>Guyon, Vapnik Heisele, Serre, Poggio, 2001,...</p>	<p>Boosting</p> <p>Viola, Jones 2001, Torralba et al. 2004, Opelt et al. 2006,...</p>	<p>Conditional Random Fields</p> <p>McCallum, Freitag, Pereira 2000; Kumar, Hebert 2003 ...</p>

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Slide adapted from Antonio Torralba

Boosting intuition

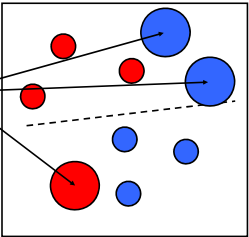


Weak Classifier 1

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Slide credit: Paul Viola

This diagram shows a square box containing several red and blue circles. A dashed line, representing a weak classifier, separates the points. The label 'Weak Classifier 1' has an arrow pointing to the dashed line. The classifier is not perfect, as some points are misclassified.

Boosting illustration

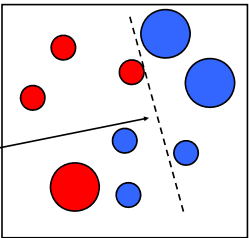


Weights Increased

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This diagram shows the same set of red and blue circles as the previous slide. The dashed line from the first classifier is still present. The points that were misclassified in the first step are now shown as larger circles. The label 'Weights Increased' has arrows pointing to these larger circles, indicating that their weight in the ensemble has been increased.

Boosting illustration

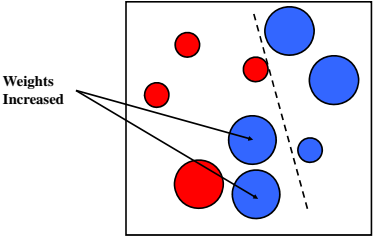


Weak Classifier 2

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This diagram shows the same set of weighted points. A new dashed line, representing a second weak classifier, is drawn. The label 'Weak Classifier 2' has an arrow pointing to this new dashed line. The second classifier is designed to be better at separating the weighted points than the first classifier was.

Boosting illustration

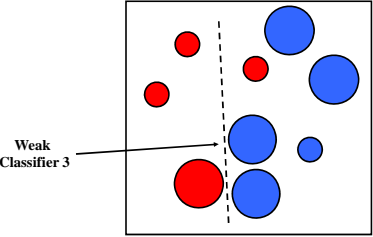


Weights Increased

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This diagram illustrates a weak classifier's decision boundary (dashed line) separating red and blue circles. The classifier has misclassified several points. The text 'Weights Increased' has arrows pointing to the misclassified points, indicating that their weights are being increased to focus the next classifier on these difficult examples.

Boosting illustration

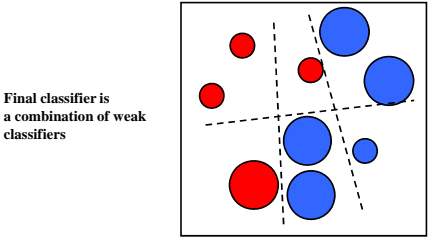


Weak Classifier 3

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This diagram shows a weak classifier's decision boundary (dashed line) separating red and blue circles. The text 'Weak Classifier 3' has an arrow pointing to the decision boundary, indicating this is the third weak classifier in the boosting process.

Boosting illustration



Final classifier is a combination of weak classifiers

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This diagram shows the final classifier's decision boundary (dashed line) separating red and blue circles. The text 'Final classifier is a combination of weak classifiers' indicates that the final decision boundary is the result of combining the decision boundaries of multiple weak classifiers.

Boosting: training

- Initially, weight each training example equally
- In each boosting round:
 - Find the weak learner that achieves the lowest *weighted* training error
 - Raise weights of training examples misclassified by current weak learner
- Compute final classifier as linear combination of all weak learners (weight of each learner is directly proportional to its accuracy)
- Exact formulas for re-weighting and combining weak learners depend on the particular boosting scheme (e.g., AdaBoost)

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Slide credit: Lana Lazebnik

Viola-Jones face detector

ACCEPTED CONFERENCE ON COMPUTER VISION AND PATTERN RECOGNITION 2001

Rapid Object Detection using a Boosted Cascade of Simple Features

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Abstract

This paper describes a machine learning approach for vi-

ected at 15 frames per second on a conventional 700 MHz Intel Pentium III. In other face detection systems, auxiliary information, such as image differences in video sequences,

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Viola-Jones face detector

Main idea:

- Represent local texture with efficiently computable “rectangular” features within window of interest
- Select discriminative features to be weak classifiers
- Use boosted combination of them as final classifier
- Form a cascade of such classifiers, rejecting clear negatives quickly

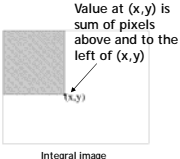
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Viola-Jones detector: features



"Rectangular" filters
 Feature output is difference between adjacent regions

Efficiently computable with integral image: any sum can be computed in constant time.

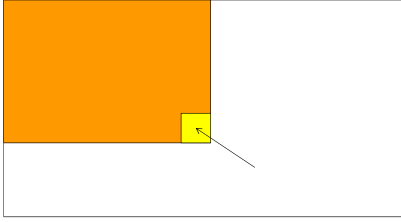


Value at (x,y) is sum of pixels above and to the left of (x,y)

Integral image

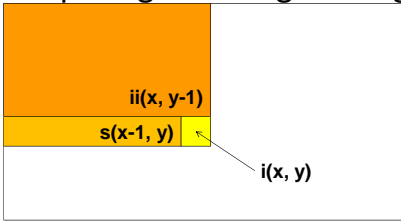
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Computing the integral image



Lana Lazebnik

Computing the integral image



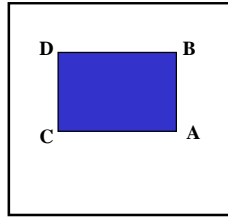
- Cumulative row sum: $s(x, y) = s(x-1, y) + i(x, y)$
- Integral image: $ii(x, y) = ii(x, y-1) + s(x, y)$

Lana Lazebnik

Computing sum within a rectangle

- Let A,B,C,D be the values of the integral image at the corners of a rectangle
- Then the sum of original image values within the rectangle can be computed as:

$$\text{sum} = A - B - C + D$$
- Only 3 additions are required for any size of rectangle!



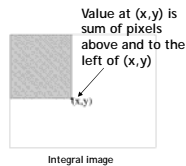
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Viola-Jones detector: features



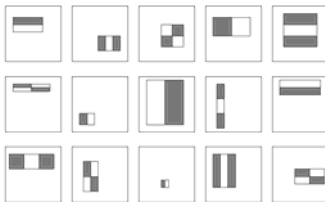
"Rectangular" filters
 Feature output is difference between adjacent regions

Efficiently computable with integral image: any sum can be computed in constant time



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Viola-Jones detector: features



Considering all possible filter parameters: position, scale, and type:

180,000+ possible features associated with each 24 x 24 window

Which subset of these features should we use to determine if a window has a face?

Use AdaBoost both to select the informative features and to form the classifier

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Viola-Jones detector: AdaBoost

- Want to select the single rectangle feature and threshold that best separates **positive** (faces) and **negative** (non-faces) training examples, in terms of *weighted error*.

Outputs of a possible rectangle feature on faces and non-faces.

Resulting weak classifier:

$$h_i(x) = \begin{cases} +1 & \text{if } f_i(x) > \theta_i \\ -1 & \text{otherwise} \end{cases}$$

For next round, reweight the examples according to errors, choose another filter/threshold combo.

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AdaBoost Algorithm

- Given example images $(x_1, y_1), \dots, (x_n, y_n)$ where $y_i \in \{0, 1\}$ for negative and positive examples respectively.

Start with uniform weights on training examples

For T rounds

- Evaluate *weighted error* for each feature, pick best.
- Re-weight the examples:
 - Incorrectly classified -> more weight
 - Correctly classified -> less weight

Final classifier is combination of the weak ones, weighted according to error they had.

$\{x_1, \dots, x_n\}$

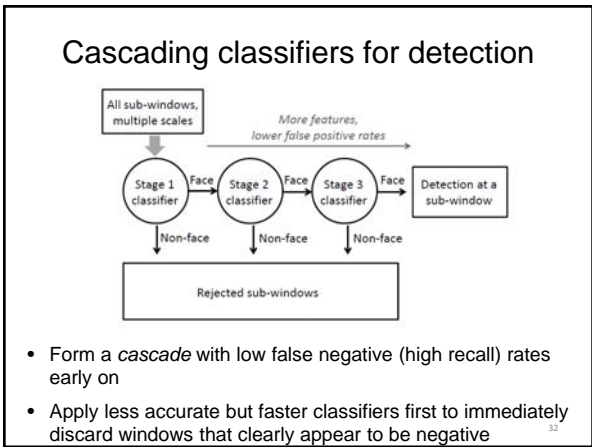
Freund & Schapire 1995

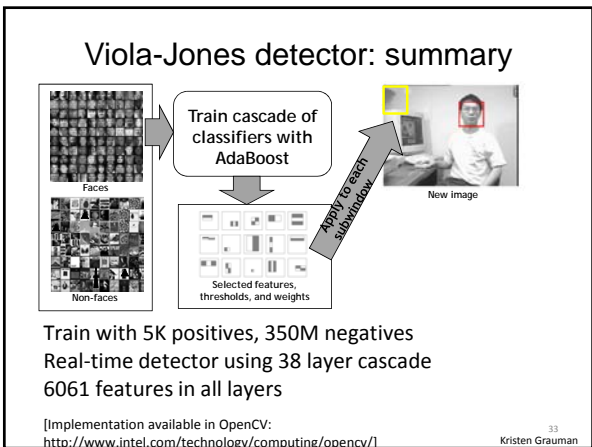
Viola-Jones Face Detector: Results

First two features selected

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- Even if the filters are fast to compute, each new image has a lot of possible windows to search.
- How to make the detection more efficient?





Viola-Jones detector: summary

- A seminal approach to real-time object detection
- Training is slow, but detection is very fast
- Key ideas
 - *Integral images* for fast feature evaluation
 - *Boosting* for feature selection
 - *Attentional cascade* of classifiers for fast rejection of non-face windows

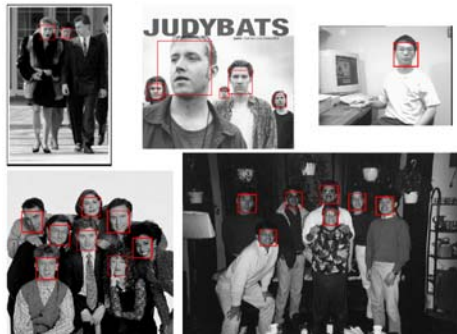
P. Viola and M. Jones. [Rapid object detection using a boosted cascade of simple features](#), CVPR 2001.

P. Viola and M. Jones. [Robust real-time face detection](#), IJCV 57(2), 2004.

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Viola-Jones Face Detector: Results

Visual Object Recognition Tutorial



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Viola-Jones Face Detector: Results

Visual Object Recognition Tutorial



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Visual Object Recognition Tutorial

Viola-Jones Face Detector: Results

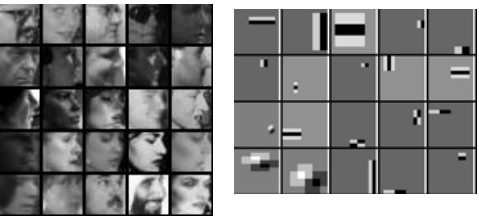


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Detecting profile faces?


Can we use the same detector?



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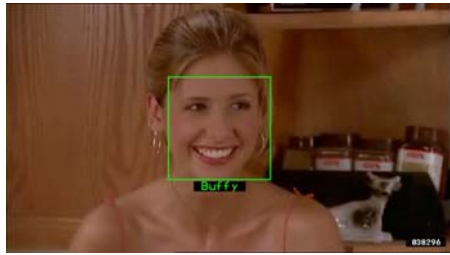
Visual Object Recognition Tutorial

Viola-Jones Face Detector: Results



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Example using Viola-Jones detector



Frontal faces detected and then tracked, character names inferred with alignment of script and subtitles.

Everingham, M., Sivic, J. and Zisserman, A. "Hello! My name is... Buffy" - Automatic naming of characters in TV video, BMVC 2006. <http://www.robots.ox.ac.uk/~vgg/research/nface/index.html>

Google now erases faces, license plates on Map Street View

By Steve Wala, CNET News.com
Friday, August 24, 2007 11:37 PM

Google has gotten a lot of flack from privacy advocates for photographing faces and license plate numbers and displaying them on the Street View in Google Maps. Originally, the company said only people who identified themselves could ask the company to remove their images.

But Google has quietly changed that policy, partly in response to criticism, and now anyone can alert the company and have an image of a license plate or a recognizable face removed, not just the owner of the face or car. Says Marissa Mayer, vice president of search products and user experience at Google.

"It's a good policy for users and also clarifies the intent of the product," she said in an interview following her keynote at the Search Engine Strategies conference in San Jose, Calif., Wednesday.

The policy change was made about 10 days after the launch of the product in late May, but was not publicly announced, according to Mayer. The company is removing images only when someone notifies them and not proactively, she said. "It was definitely a big policy change inside."

Technology

Google street view blurs face of cow to protect its identity

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Consumer application: iPhoto 2009



<http://www.apple.com/ilife/iphoto/>

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Slide credit: Lana Lazebnik

Consumer application: iPhoto 2009

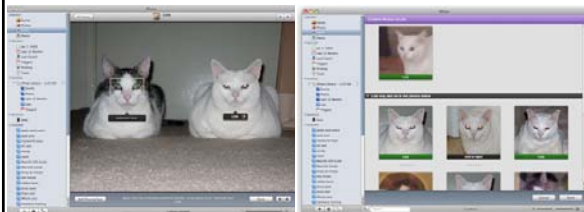
[Things iPhoto thinks are faces](#)



Slide credit: Lana Lazebnik

Consumer application: iPhoto 2009

Can be trained to recognize pets!



http://www.maclife.com/article/news/iphotos_faces_recognizes_cats

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Slide credit: Lana Lazebnik

Privacy Gift Shop – CV Dazzle

<http://www.wired.com/2015/06/facebook-can-recognize-even-dont-show-face/>
 Wired, June 15, 2015
 Slide: Kristen Grauman

Privacy Visor

<http://www.3ders.org/articles/20150812-japan-3d-printed-privacy-visors-will-block-facial-recognition-software.html>
 Slide: Kristen Grauman

Boosting: pros and cons

- Advantages of boosting
 - Integrates classification with feature selection
 - Flexibility in the choice of weak learners, boosting scheme
 - Testing is fast
 - Easy to implement
- Disadvantages
 - Needs many training examples
 - Often found not to work as well as an alternative discriminative classifier, support vector machine (SVM)
 - especially for many-class problems

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Slide credit: Lana Lazebnik

What other categories are amenable to *window-based representation*?

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Pedestrian detection

- Detecting upright, walking humans also possible using sliding window's appearance/texture; e.g.,



SVM with Haar wavelets
[Papageorgiou & Poggio, IJCV 2000]



Space-time rectangle features [Viola, Jones & Snow, ICCV 2003]



SVM with HoGs [Dalal & Triggs, CVPR 2005]

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Window-based detection: strengths

- Sliding window detection and global appearance descriptors:
 - Simple detection protocol to implement
 - Good feature choices critical
 - Past successes for certain classes

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Window-based detection: Limitations


- High computational complexity
 - > For example: 250,000 locations x 30 orientations x 4 scales = 30,000,000 evaluations!
 - > If training binary detectors independently, means cost increases linearly with number of classes
- With so many windows, false positive rate better be low

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Limitations (continued)

- Not all objects are "box" shaped




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Limitations (continued)

- If considering windows in isolation, context is lost



Sliding window Detector's view

Figure credit: Derek Hoiem

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Limitations (continued)

- In practice, often entails large, cropped training set (expensive)
- Requiring good match to a global appearance description can lead to sensitivity to partial occlusions



Image credit: Adam, Rivlin, & Shimshoni
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Summary

- Basic pipeline for window-based detection
 - Model/representation/classifier choice
 - Sliding window and classifier scoring
- Boosting classifiers: general idea
- Viola-Jones face detector
 - Exemplar of basic paradigm
 - Plus key ideas: rectangular features, Adaboost for feature selection, cascade
- Pros and cons of window-based detection

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Questions?

See you Thursday!

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