

# Convolutional neural networks I

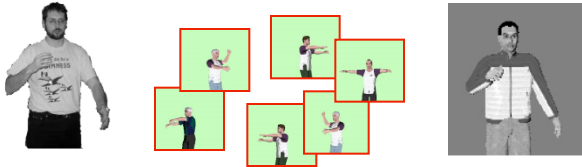
September 27<sup>th</sup>, 2019

Yong Jae Lee  
UC Davis

Many slides from Rob Fergus, Svetlana Lazebnik, Jia-Bin Huang, Derek Hoiem, Adriana Kovashka, Andrej Karpathy

# Standard classifiers

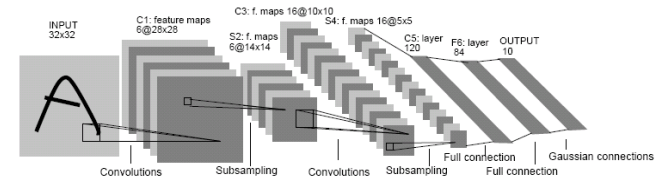
## Nearest neighbor



$10^6$  examples

Shakhnarovich, Viola, Darrell 2003  
Berg, Berg, Malik 2005...

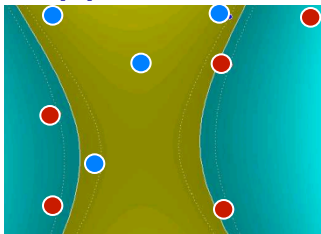
## Neural networks



LeCun, Bottou, Bengio, Haffner 1998  
Rowley, Baluja, Kanade 1998

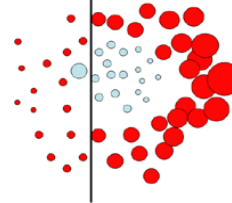
...

## Support Vector Machines



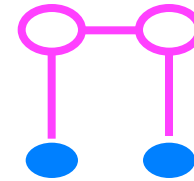
Guyon, Vapnik  
Heisele, Serre, Poggio,  
2001,...

## Boosting



Viola, Jones 2001,  
Torralba et al. 2004,  
Opelt et al. 2006,...

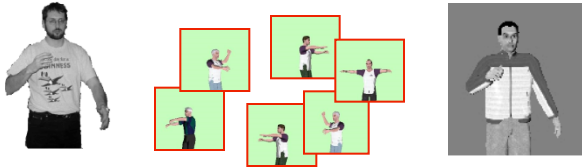
## Conditional Random Fields



McCallum, Freitag, Pereira  
2000; Kumar, Hebert 2003  
...

# Standard classifiers

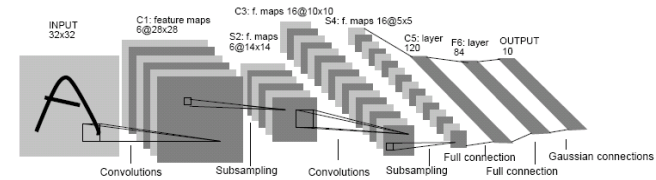
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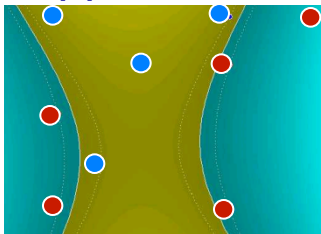
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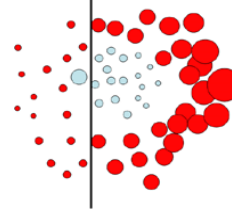
...

## Support Vector Machines



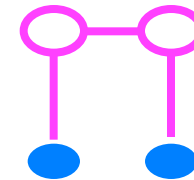
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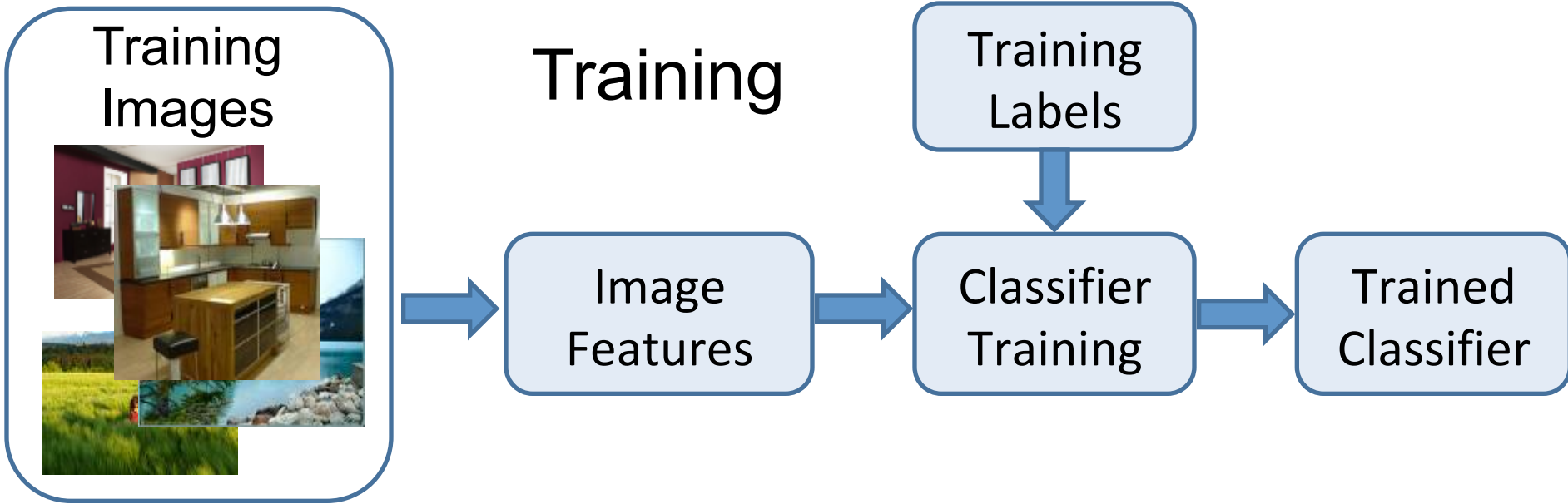
Viola, Jones 2001,  
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## Conditional Random Fields

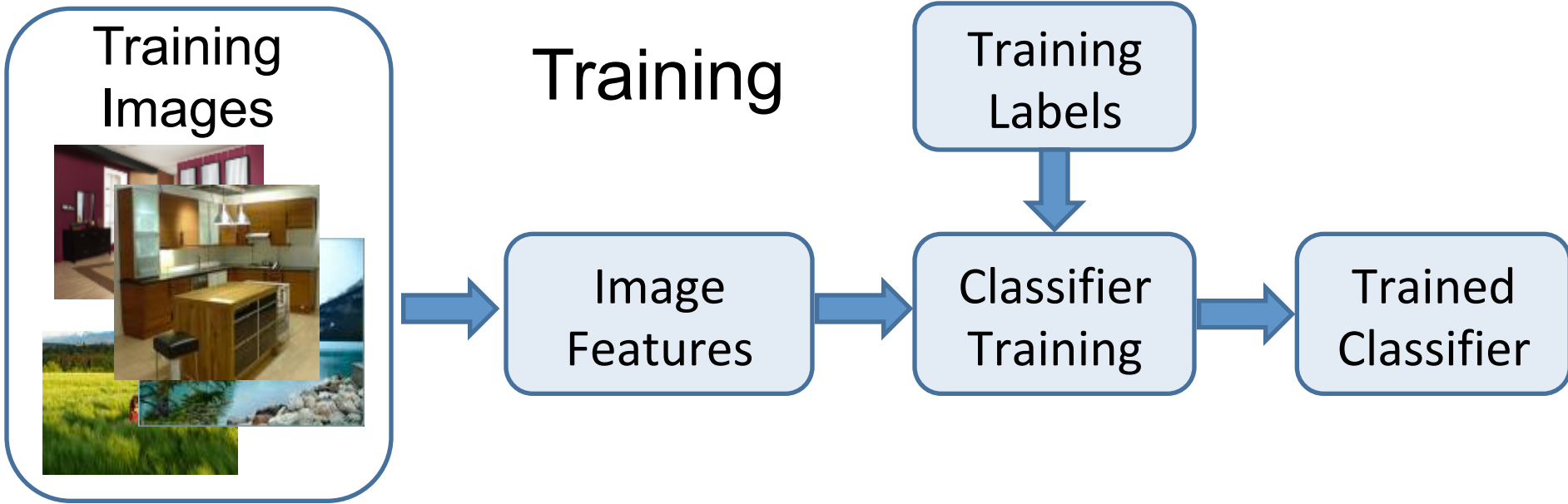


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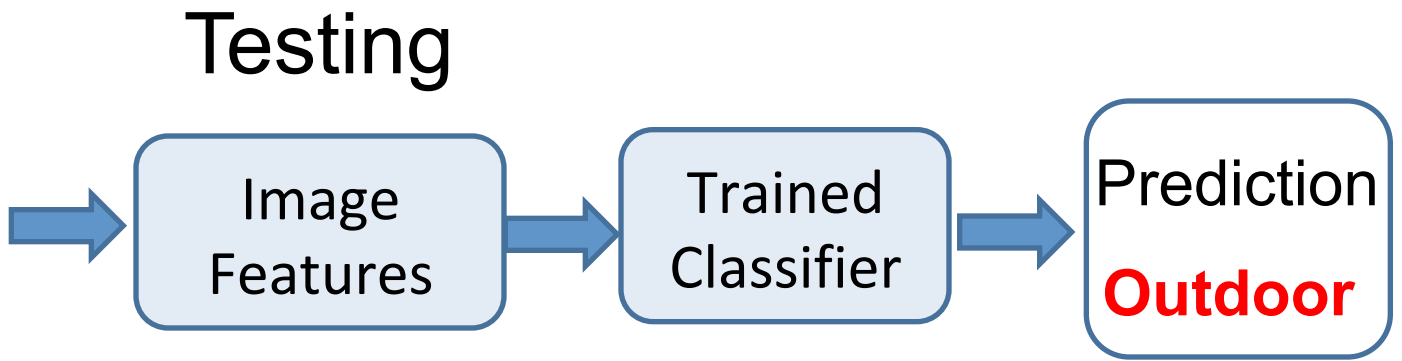
# Traditional Image Categorization: Training phase



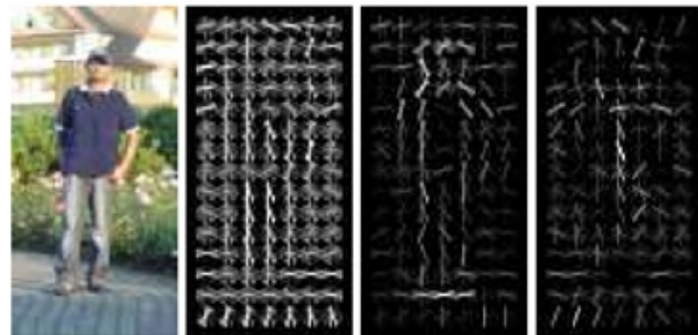
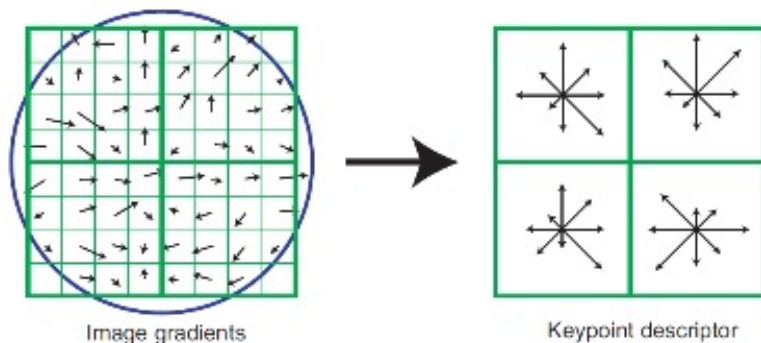
# Traditional Image Categorization: Testing phase



Test Image



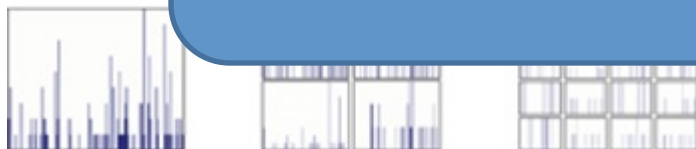
# Features have been key..



SIFT

HOG [Lazebnik et al. CVPR 05]

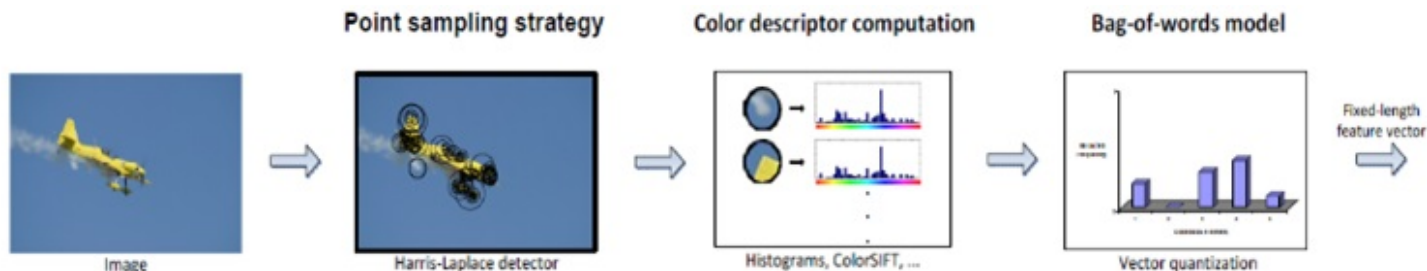
**Hand-crafted**



SPM [Lazebnik et al. CVPR 06]



DPM [Felzenszwalb et al. PAMI 10]

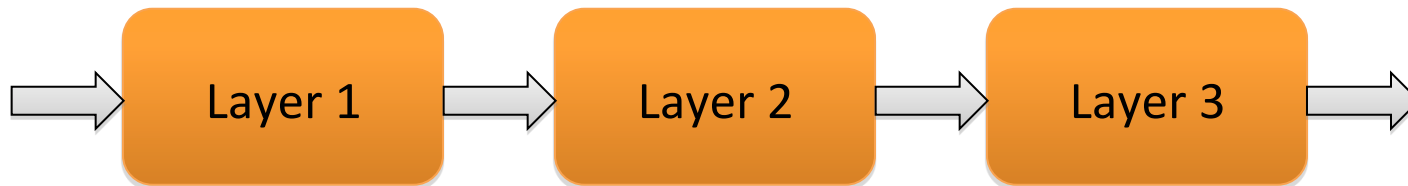


Color Descriptor [Van De Sande et al. PAMI 10]

# What about **learning** the features?

- Learn a *feature hierarchy* all the way from pixels to classifier
- Each layer extracts features from the output of previous layer
- Layers have (nearly) the same structure
- Train all layers jointly (“end-to-end”)

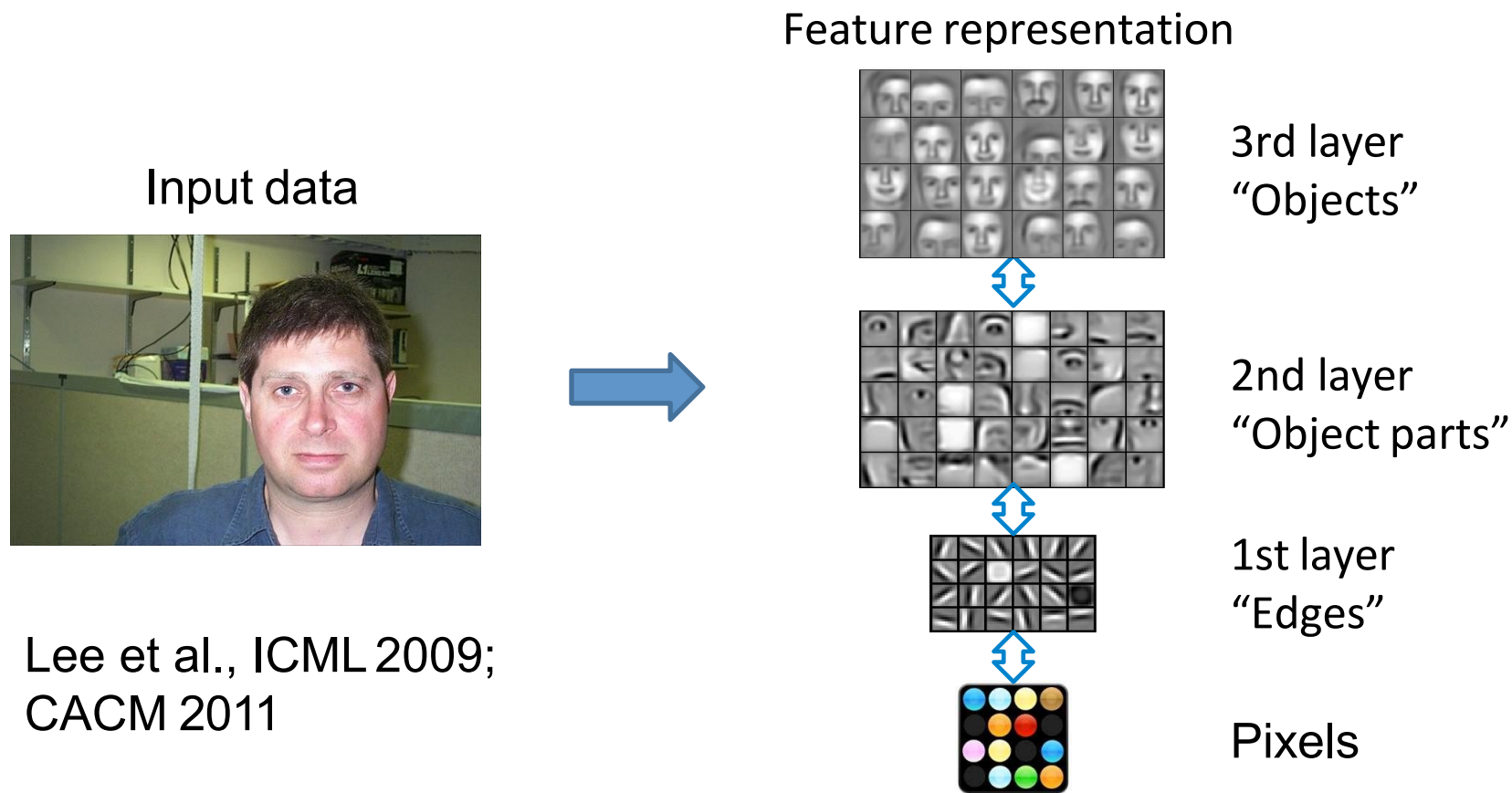
Image/  
Video  
Pixels



Simple  
Classifier

# Learning Feature Hierarchy

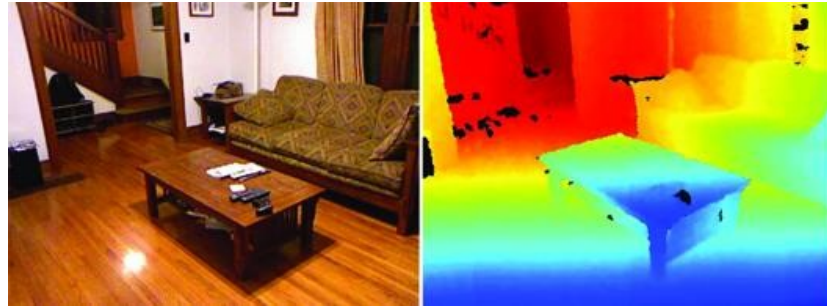
Goal: **Learn** useful higher-level features from images





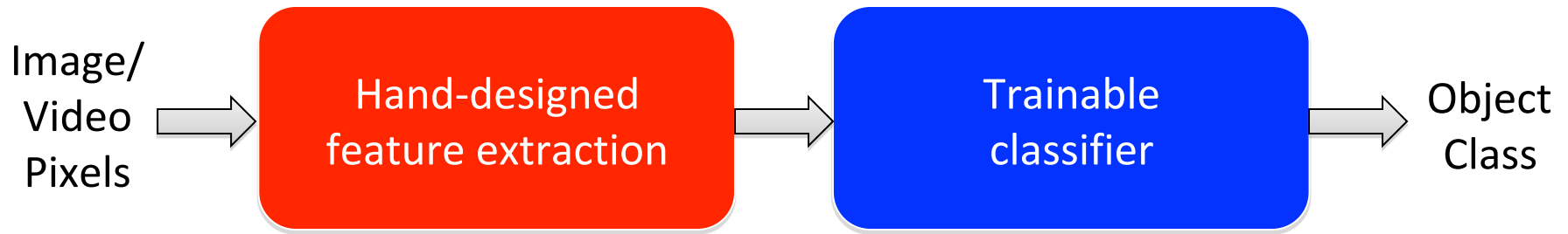
# Learning Feature Hierarchy

- Better performance
- Other domains (unclear how to hand engineer):
  - Kinect
  - Video
  - Multi spectral
- Feature computation time
  - Dozens of features needed for good performance
  - Prohibitive for large datasets (10's sec /image)

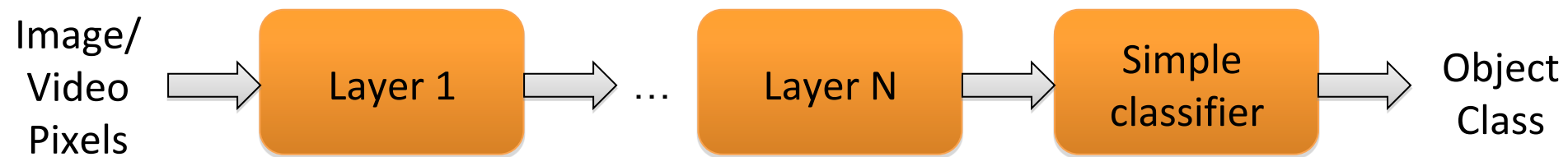


# “Shallow” vs. “deep” architectures

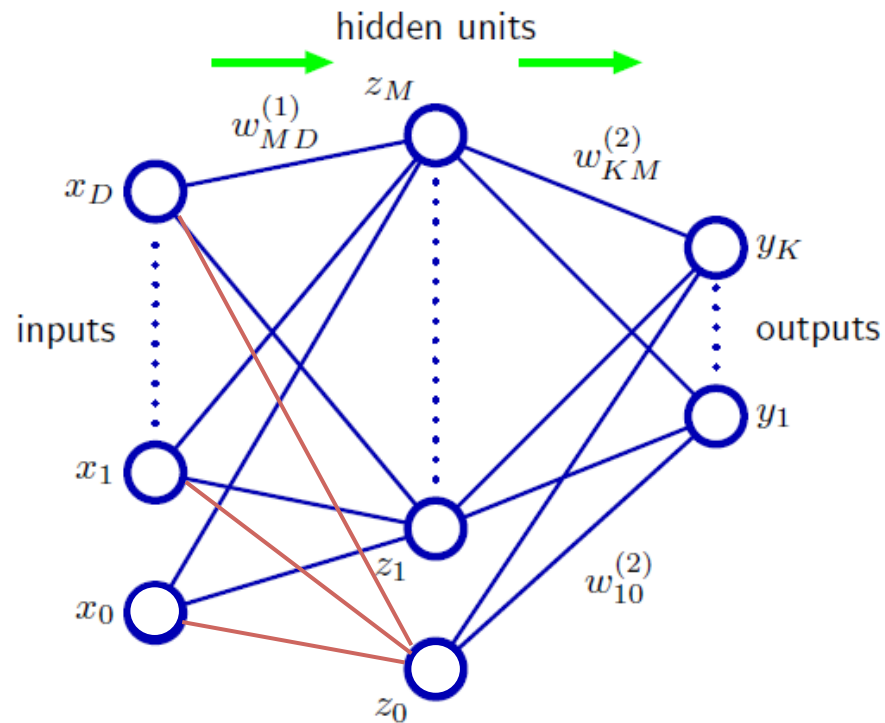
Traditional recognition: “Shallow” architecture



Deep learning: “Deep” architecture

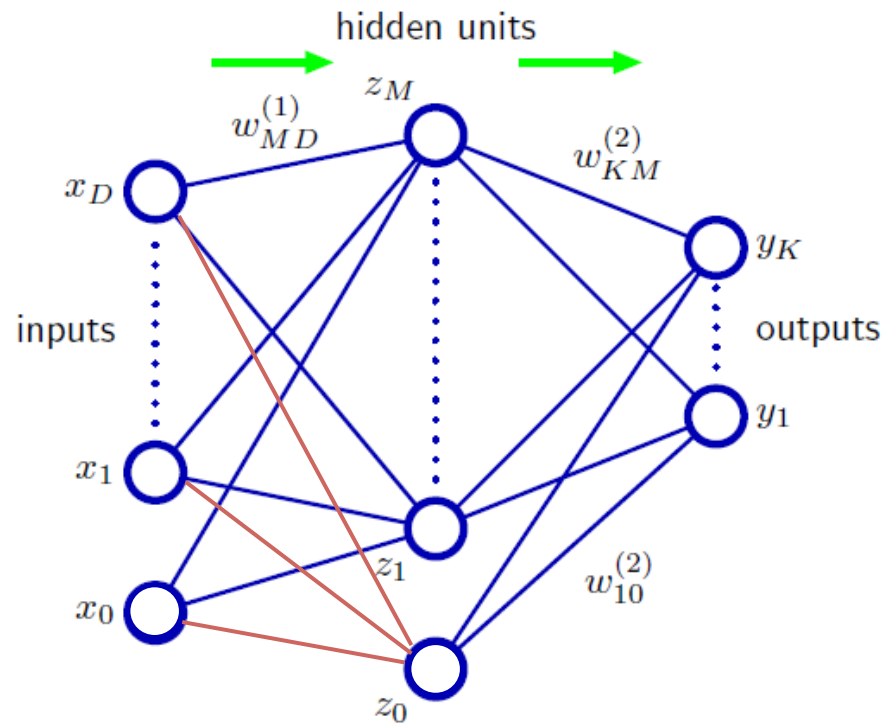


# Neural network definition



- *Nonlinear* classifier
- Can approximate any continuous function to arbitrary accuracy given sufficiently many hidden units

# Neural network definition



- Activations: 
$$a_j = \sum_{i=0}^D w_{ji}^{(1)} x_i$$
- Nonlinear activation function  $h$  (e.g. sigmoid, RELU):

$$z_j = h(a_j)$$

# Neural network definition

- Layer 2

$$a_j = \sum_{i=0}^D w_{ji}^{(1)} x_i$$

$$z_j = h(a_j)$$

- Layer 3 (final)

$$a_k = \sum_{j=0}^M w_{kj}^{(2)} z_j$$

- Outputs (e.g. sigmoid/softmax)

(binary)

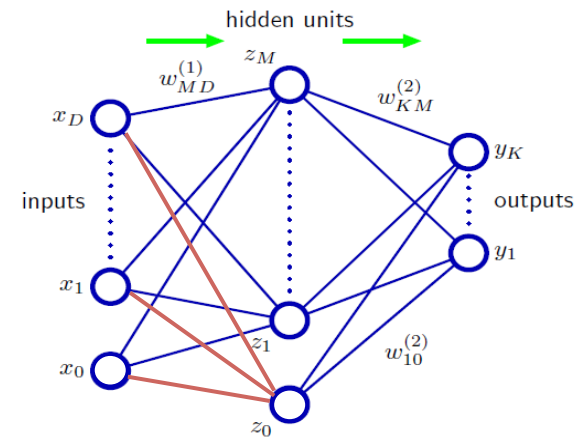
$$y_k = \sigma(a_k) = \frac{1}{1 + \exp(-a_k)}$$

(multiclass)

$$y_k = \frac{\exp(a_k)}{\sum_j \exp(a_j)}$$

- Putting everything together:

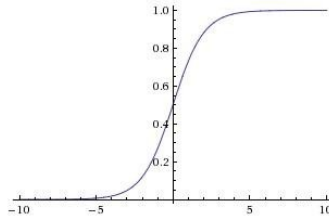
$$y_k(\mathbf{x}, \mathbf{w}) = \sigma \left( \sum_{j=0}^M w_{kj}^{(2)} h \left( \sum_{i=0}^D w_{ji}^{(1)} x_i \right) \right)$$



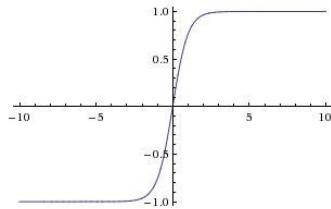
# Nonlinear activation functions

## Sigmoid

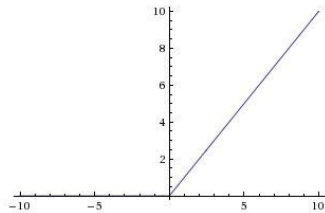
$$\sigma(x) = 1/(1 + e^{-x})$$



## tanh tanh(x)

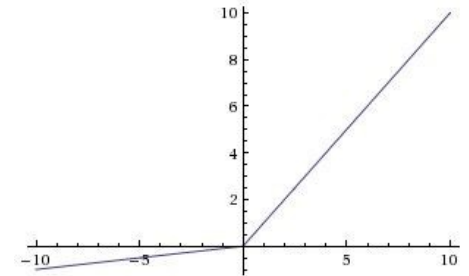


## ReLU max(0,x)



## Leaky ReLU

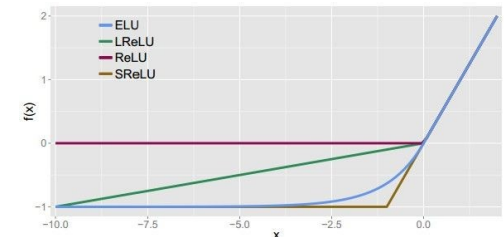
$$\max(0.1x, x)$$



## Maxout $\max(w_1^T x + b_1, w_2^T x + b_2)$

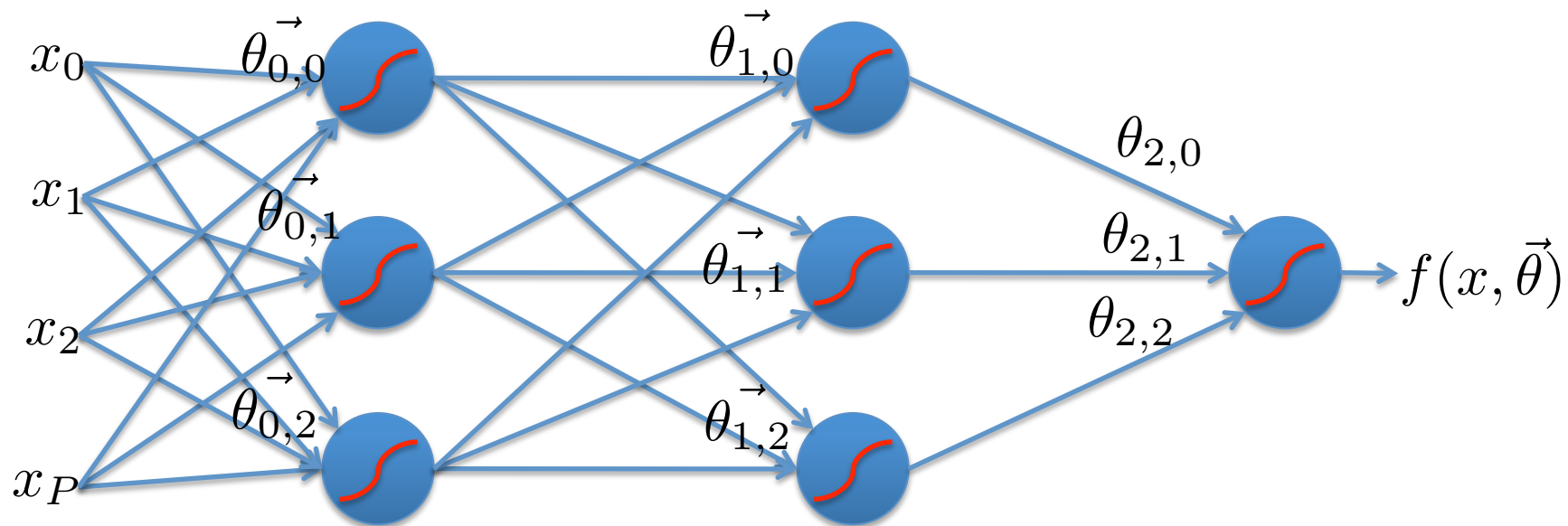
## ELU

$$f(x) = \begin{cases} x & \text{if } x > 0 \\ \alpha (\exp(x) - 1) & \text{if } x \leq 0 \end{cases}$$



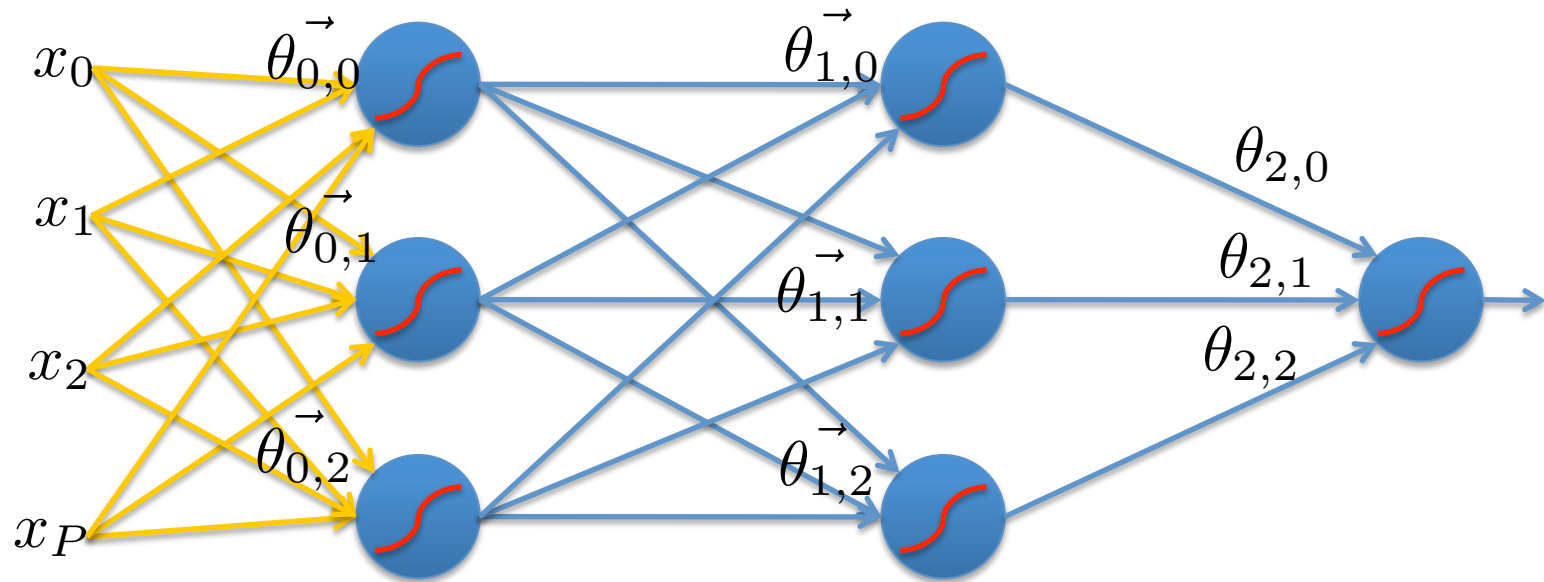
# Multilayer networks

- Cascade neurons together
- Output from one layer is the input to the next
- Each layer has its own sets of weights



# Feed-forward networks

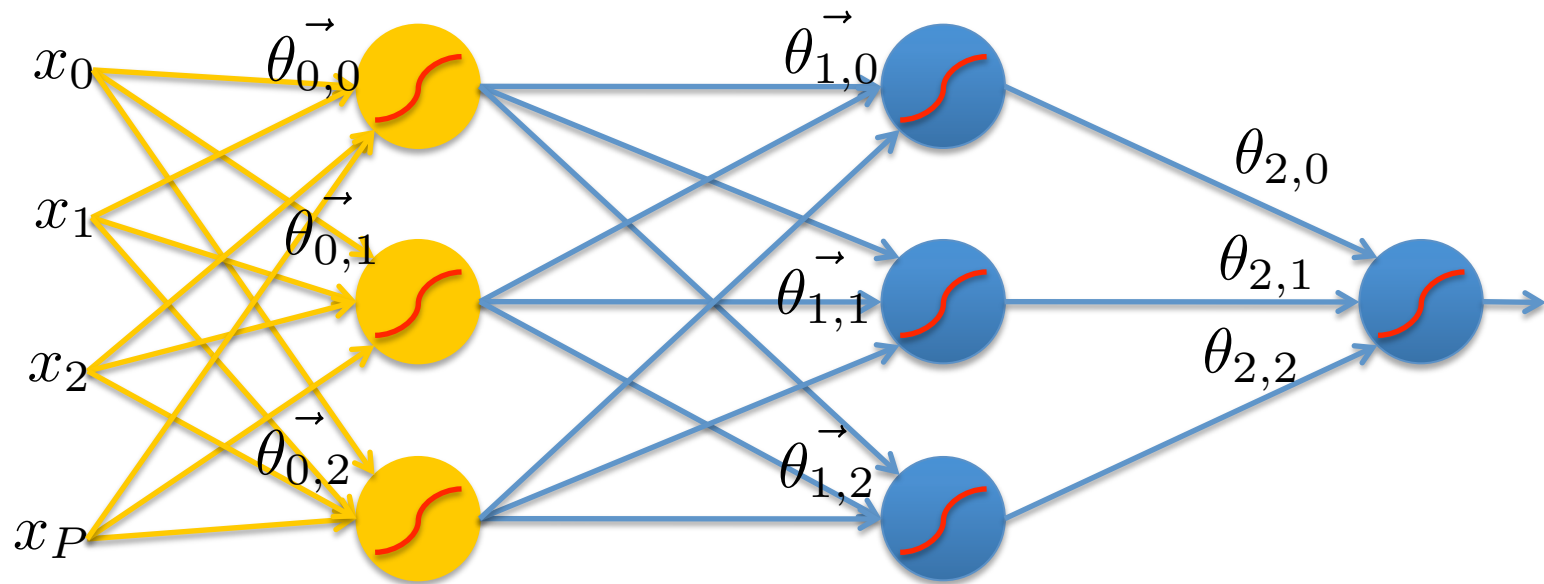
- Predictions are fed forward through the network to classify





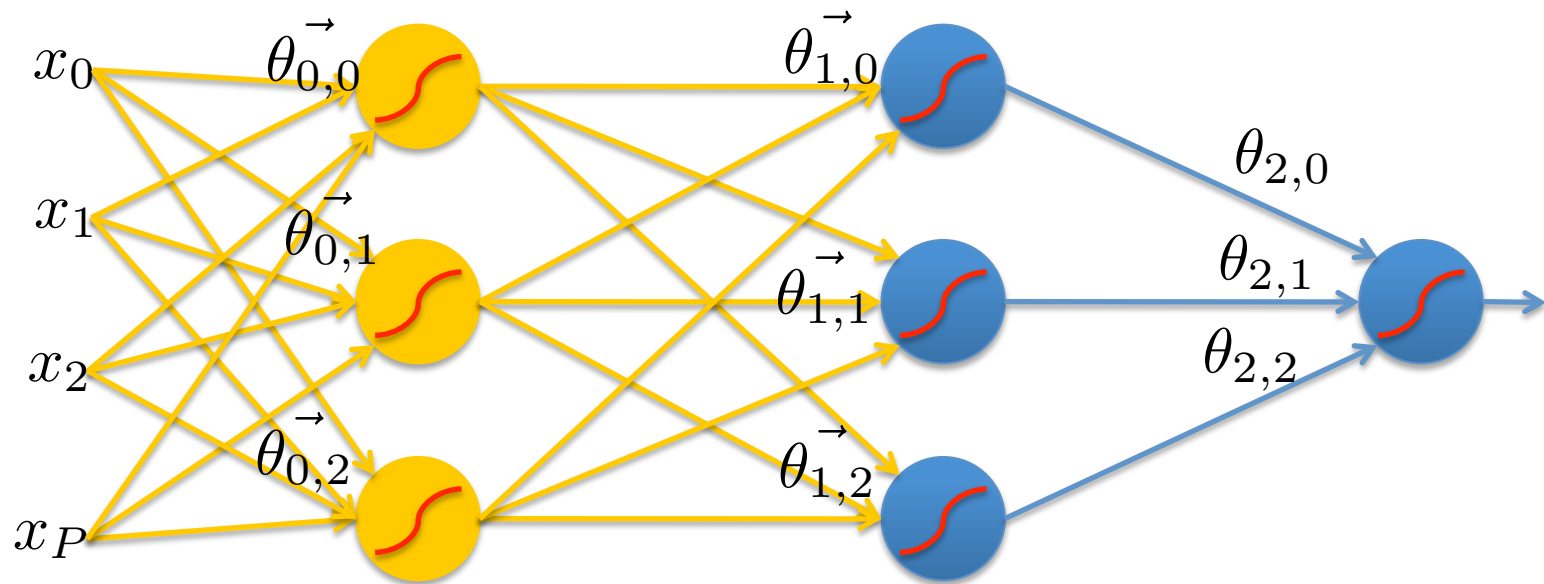
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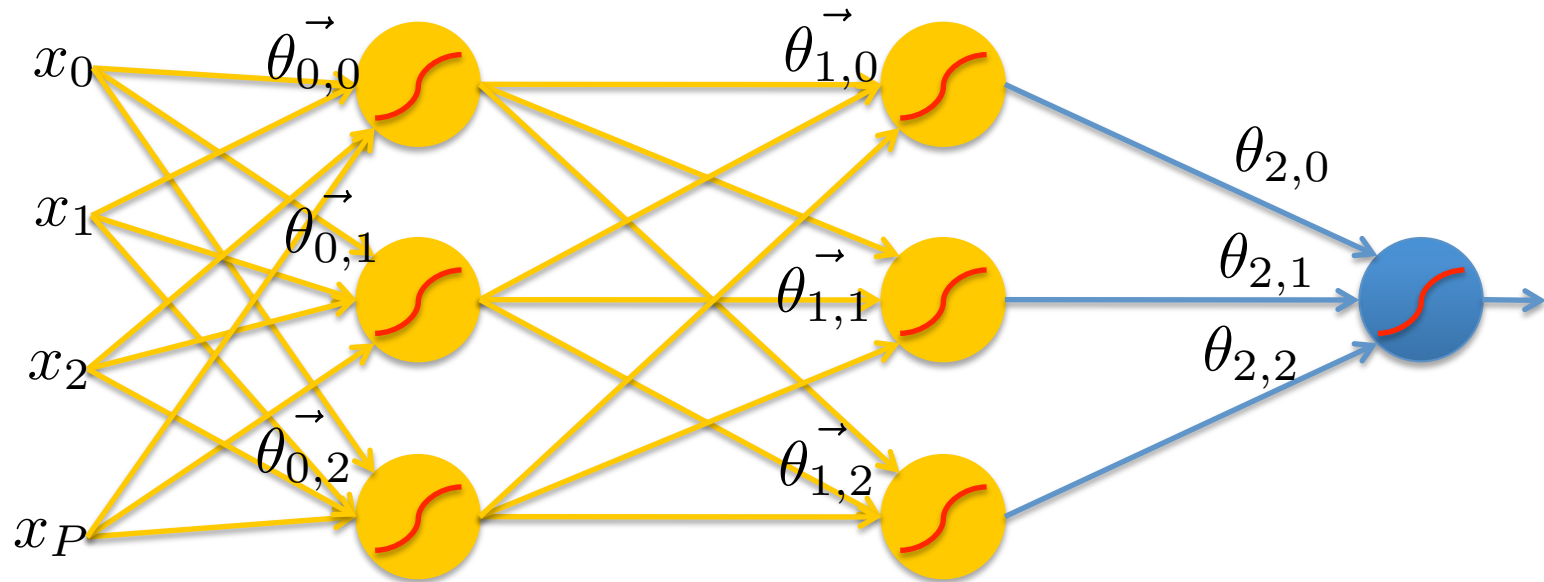
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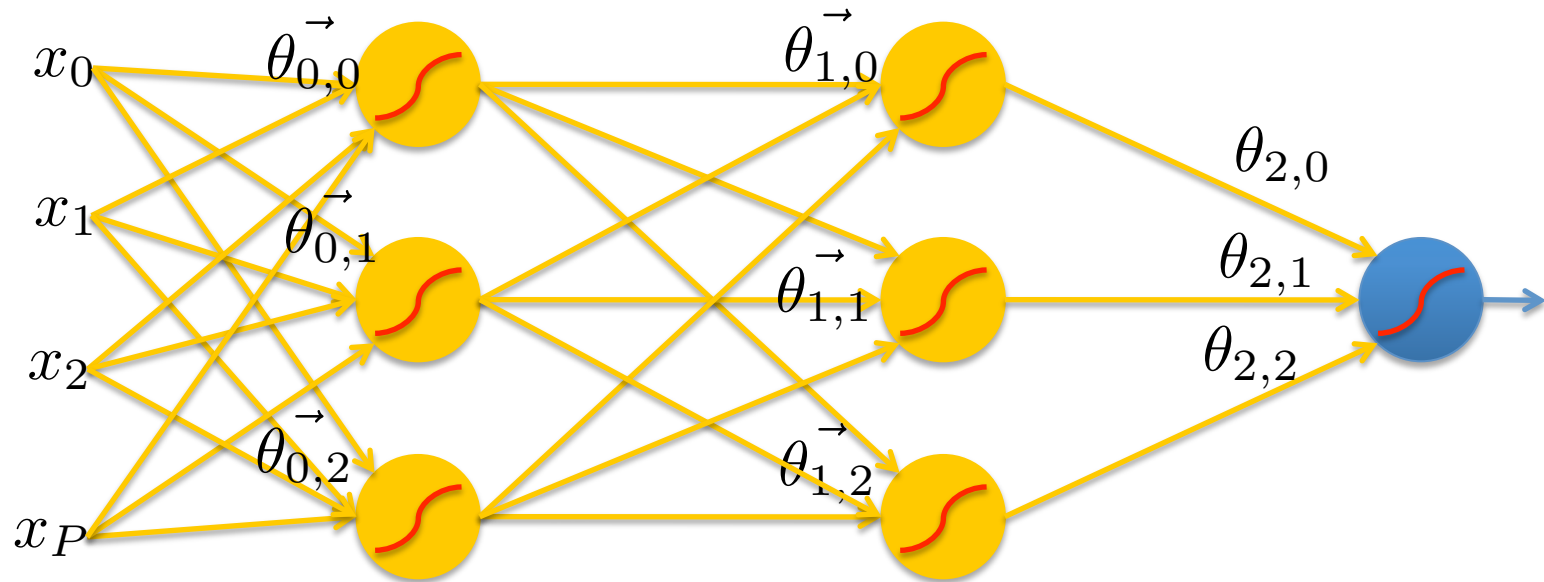
# Feed-forward networks

- Predictions are fed forward through the network to classify



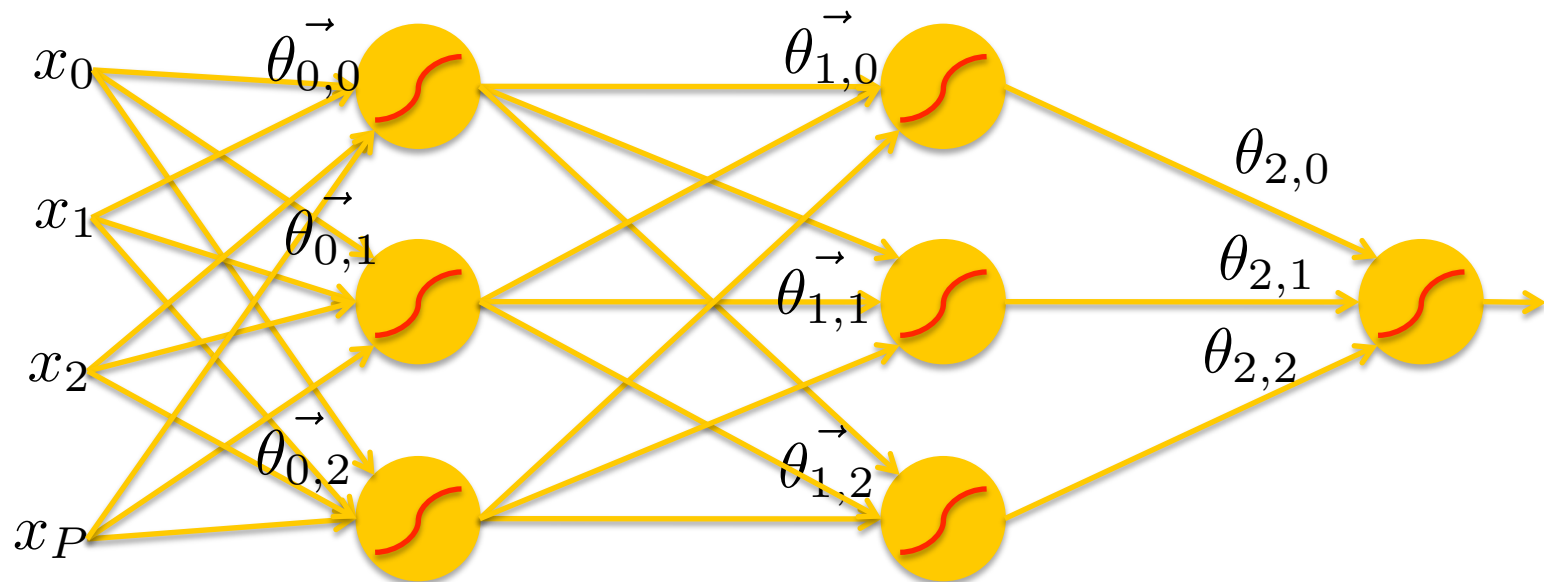
# Feed-forward networks

- Predictions are fed forward through the network to classify



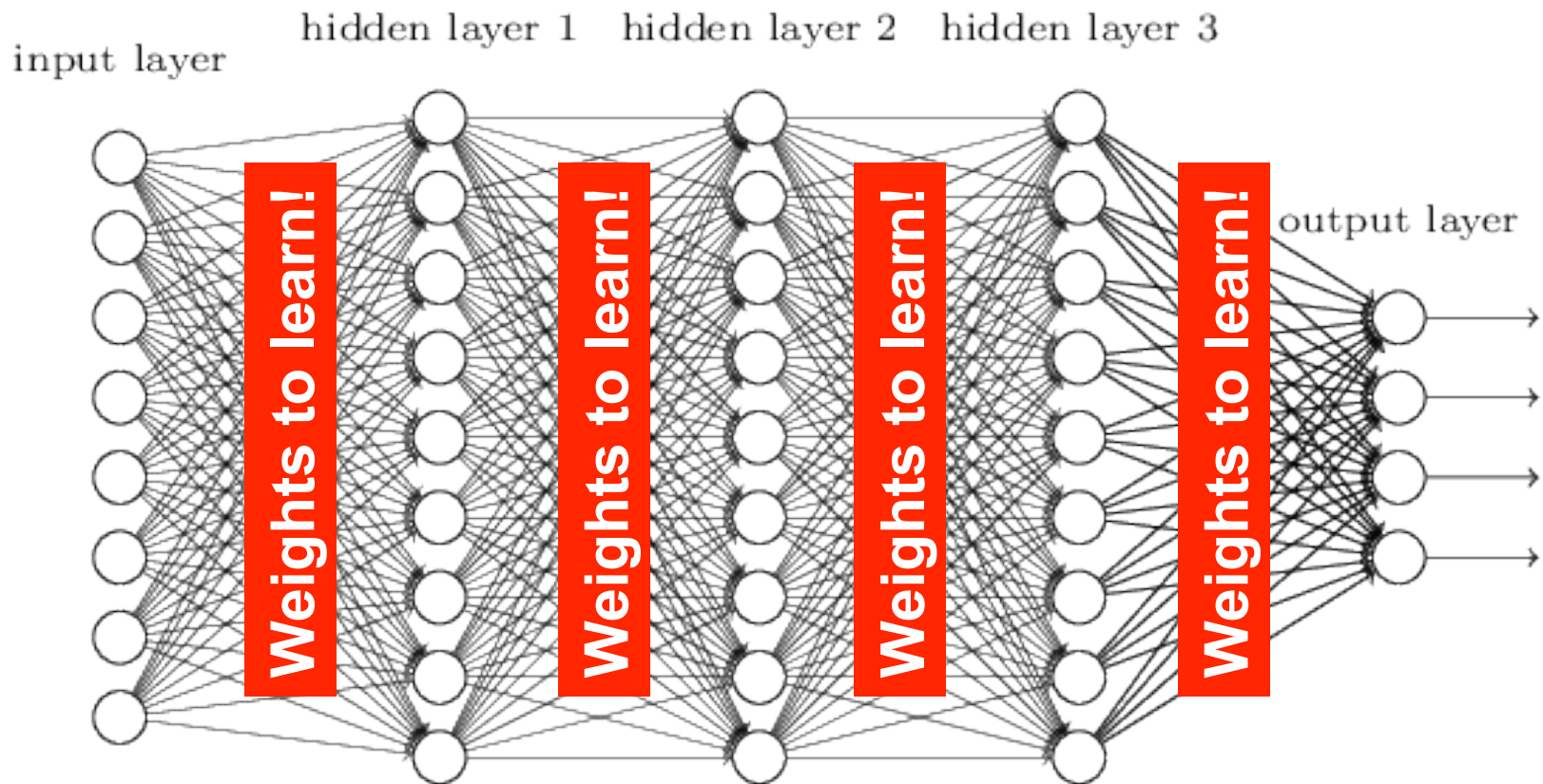
# Feed-forward networks

- Predictions are fed forward through the network to classify



# Deep neural networks

- Lots of hidden layers
- Depth = power (usually)



# Convolutional Neural Networks (CNN, ConvNet, DCN)

- CNN = a multi-layer neural network with
  - **Local** connectivity:
    - Neurons in a layer are only connected to a small region of the layer before it
  - **Share** weight parameters across spatial positions:
    - Learning shift-invariant filter kernels

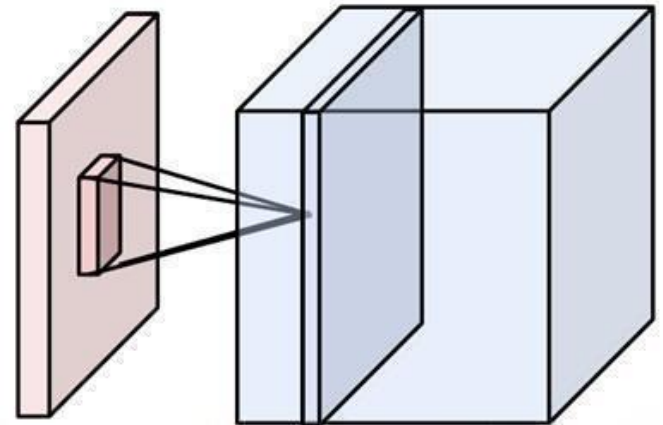
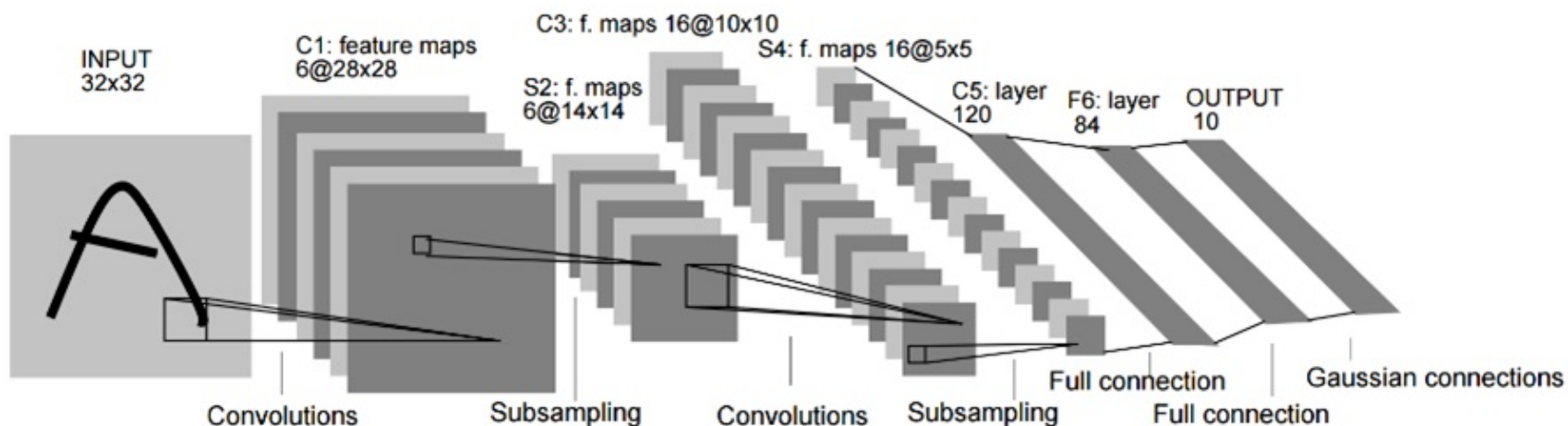


Image credit: A. Karpathy

# LeNet [LeCun et al. 1998]



- Stack multiple stages of feature extractors
- Higher stages compute more global, more invariant features
- Classification layer at the end

Gradient-based learning applied to document recognition [[LeCun, Bottou, Bengio, Haffner 1998](#)]

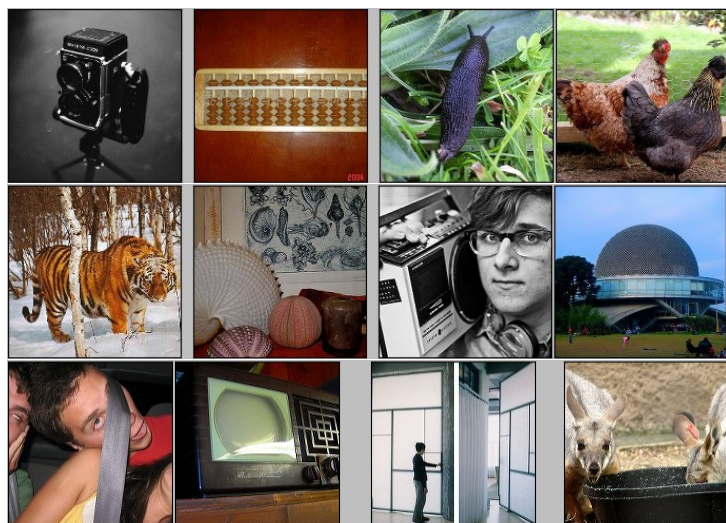


LeNet-1 from 1993



# ImageNet Challenge 2012

IMAGENET



[Deng et al. CVPR 2009]

- ~14 million labeled images, 20k classes
- Images gathered from Internet
- Human labels via Amazon Turk
- **ImageNet Challenge: 1.2 million training images, 1000 classes**

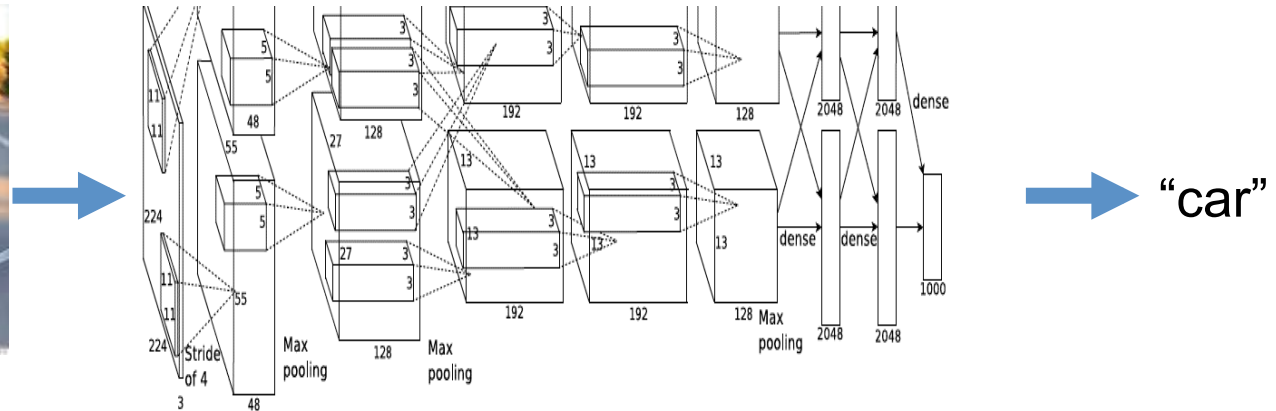
A. Krizhevsky, I. Sutskever, and G. Hinton,  
ImageNet Classification with Deep Convolutional Neural Networks, NIPS 2012



# AlexNet for image classification

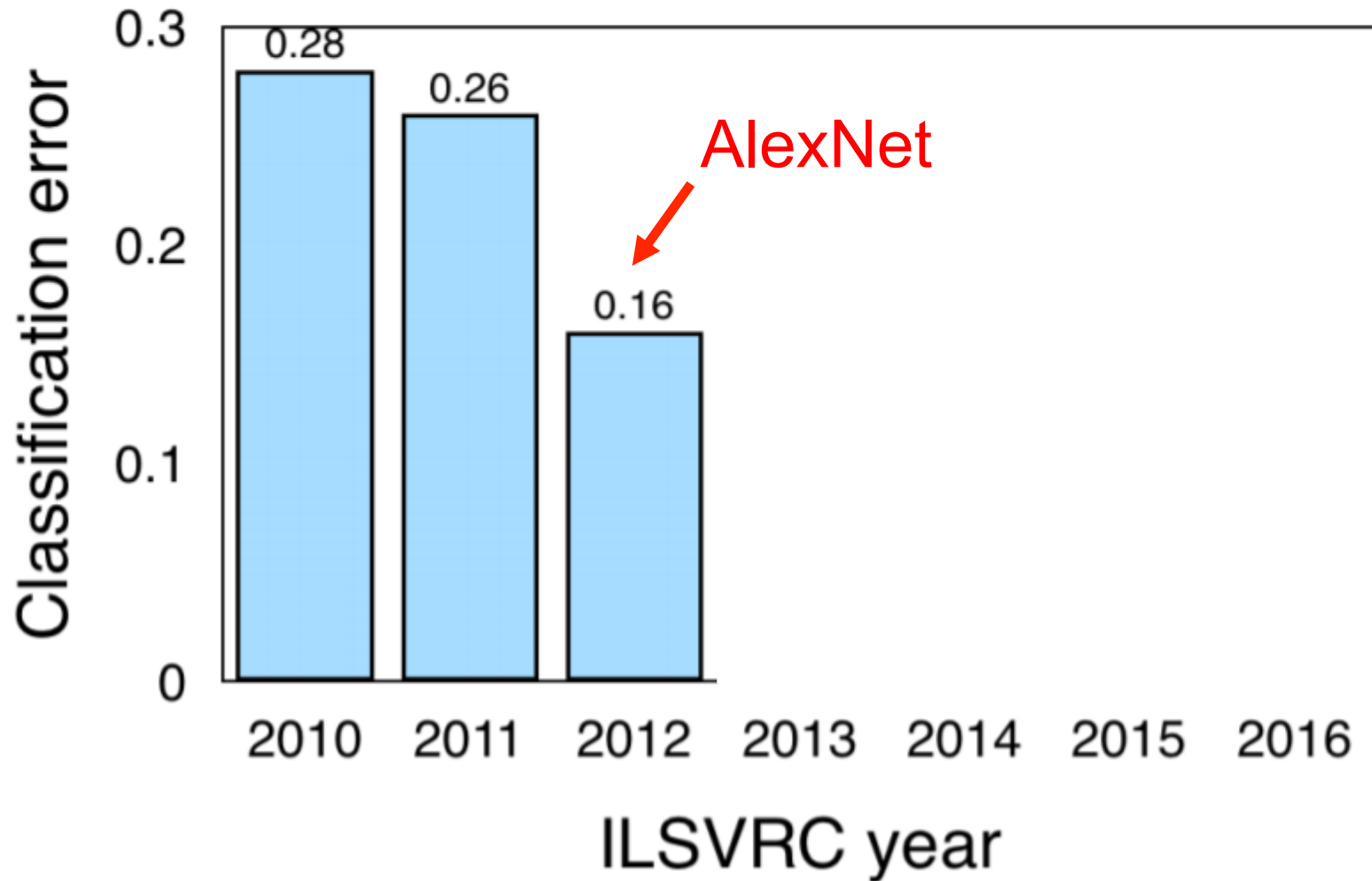


AlexNet



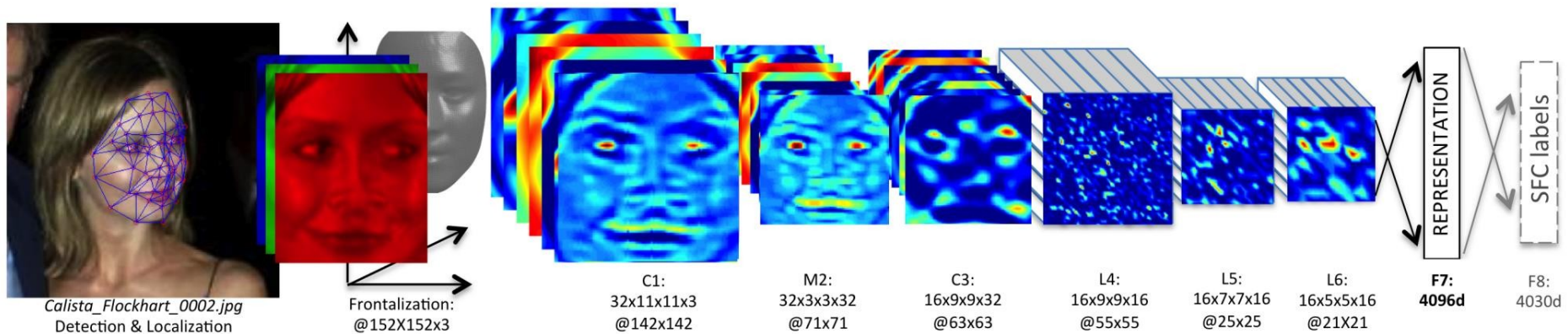
Fixed input size: 224x224x3

# ImageNet Classification Challenge



# Industry Deployment

- Used in Facebook, Google, Microsoft
- Startups
- Image Recognition, Speech Recognition, ....
- Fast at test time



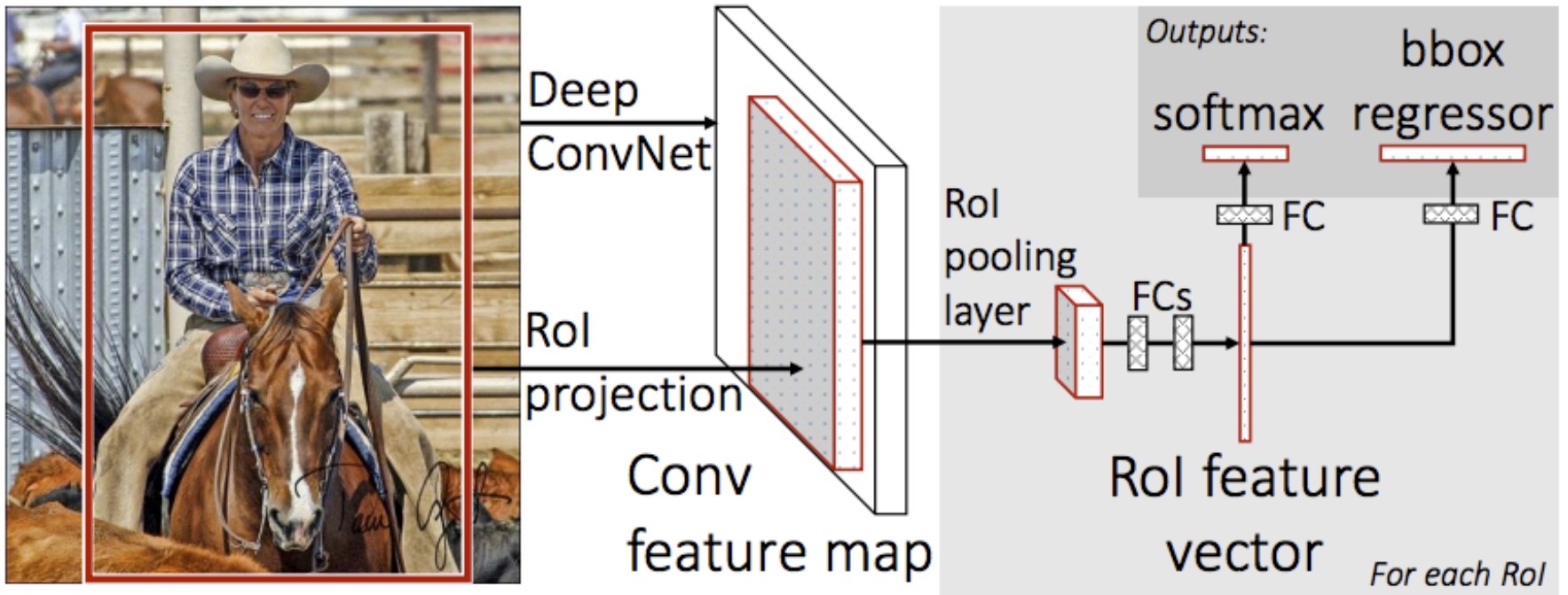
Taigman et al. DeepFace: Closing the Gap to Human-Level Performance in Face Verification, CVPR'14

# Beyond classification

- Detection
- Segmentation
- Regression
- Pose estimation
- Matching patches
- Synthesis

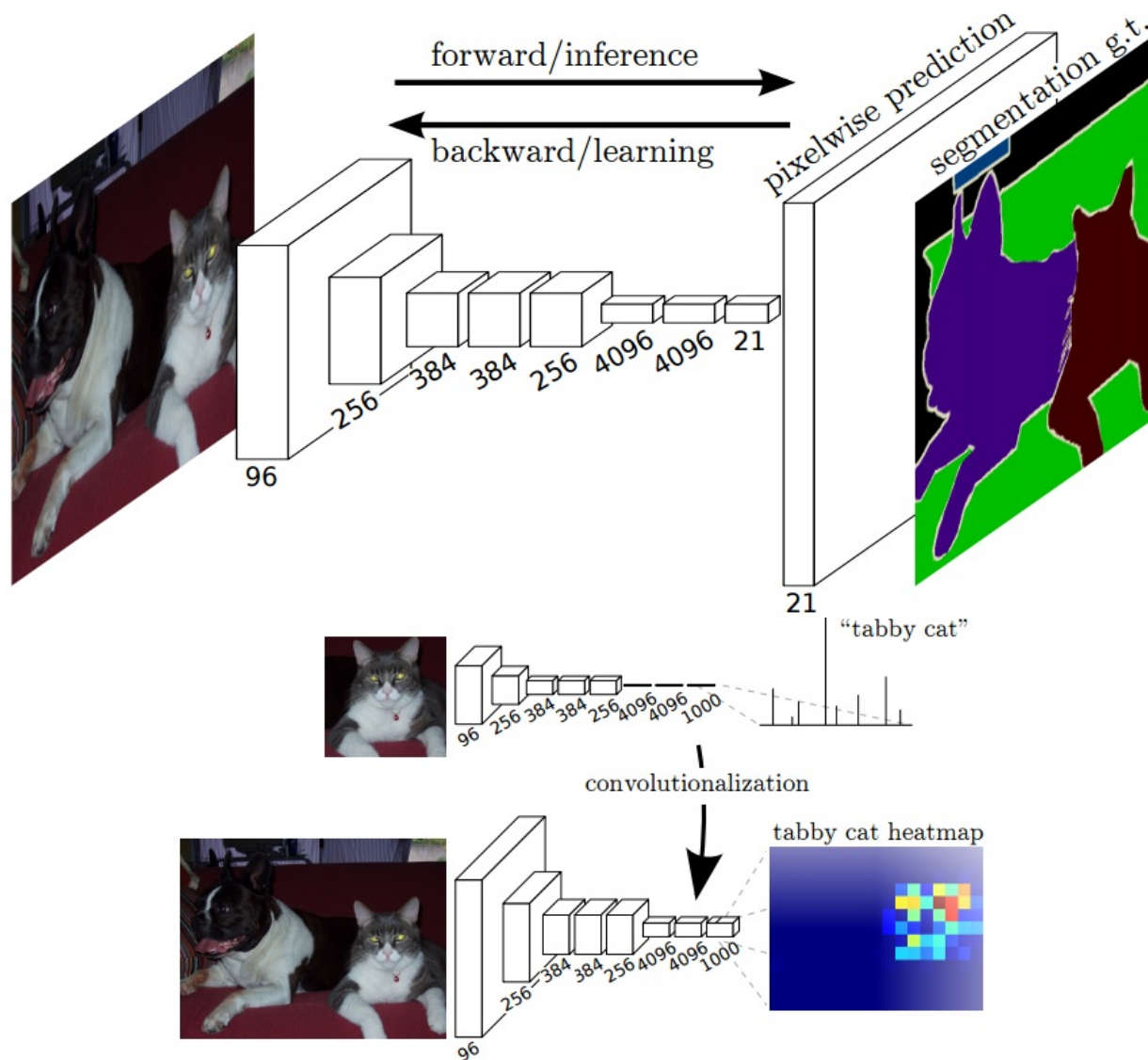
and many more...

# CNNs for Object detection



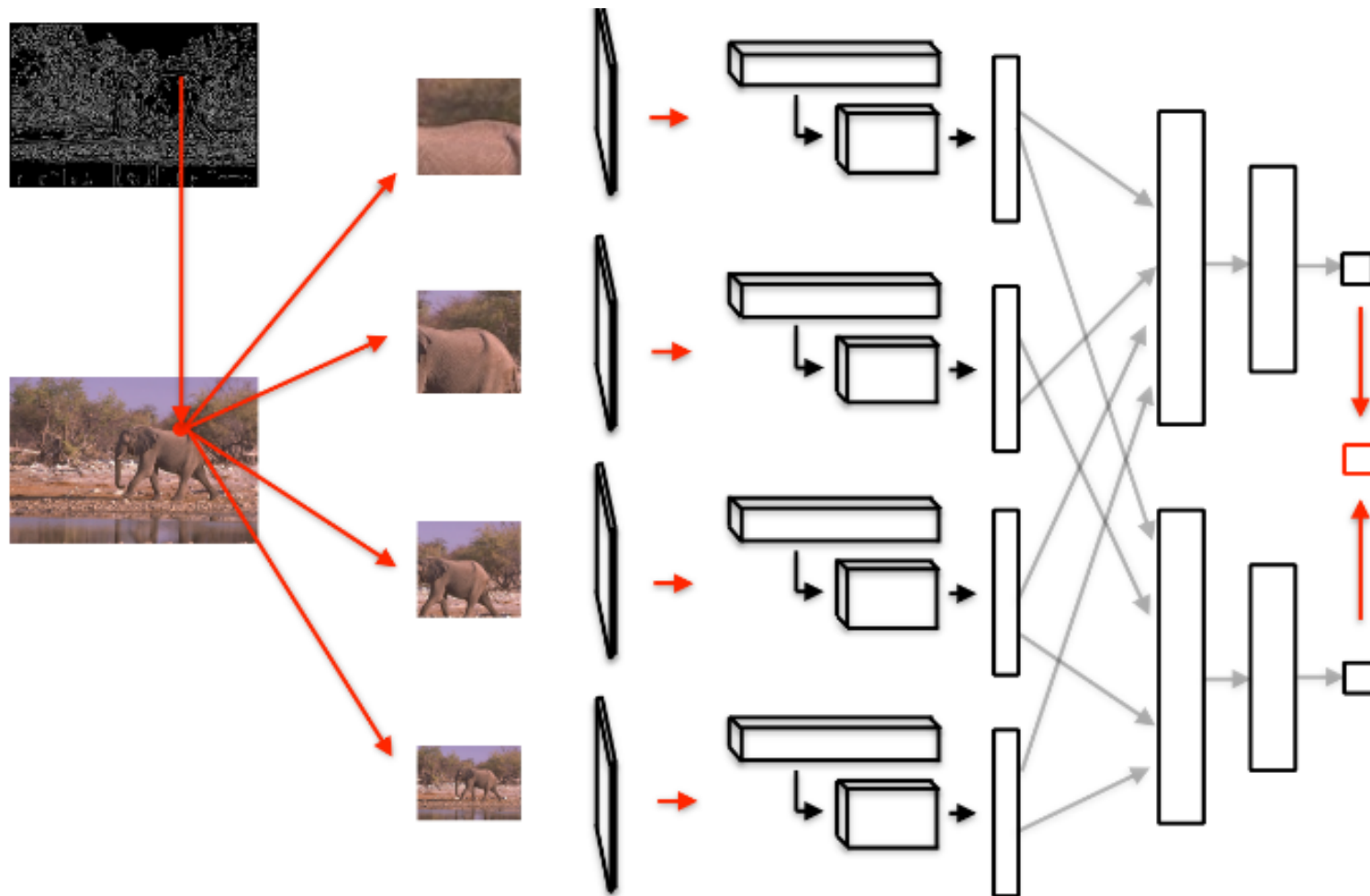
Fast-RCNN [Girshick et al. ICCV 2015]

# Labeling Pixels: Semantic Labels





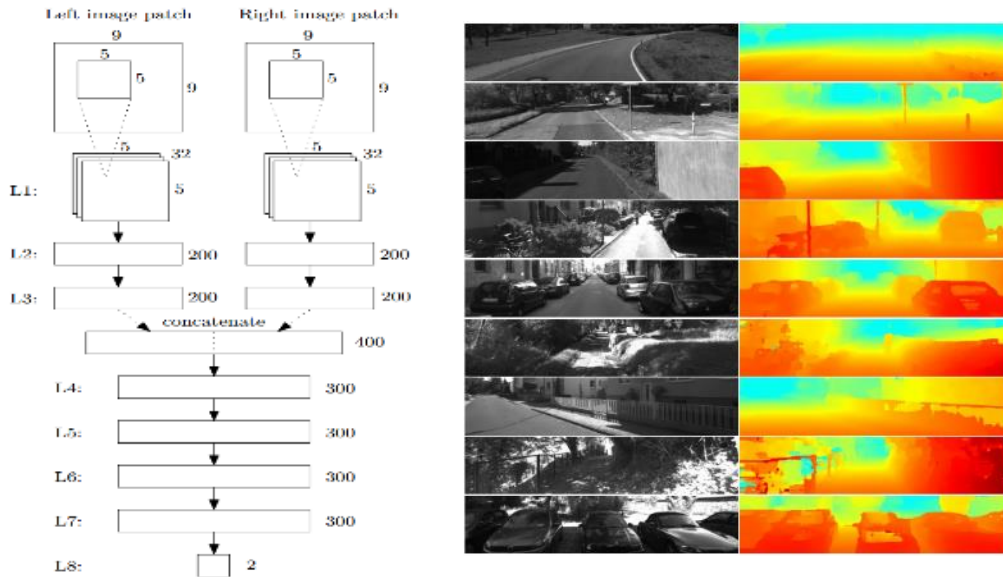
# Labeling Pixels: Edge Detection



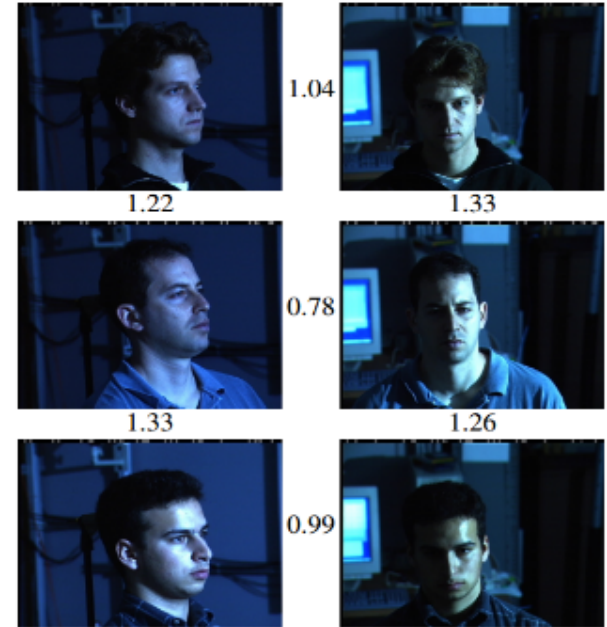
DeepEdge: A Multi-Scale Bifurcated Deep Network for Top-Down Contour Detection  
[Bertasius et al. CVPR 2015]



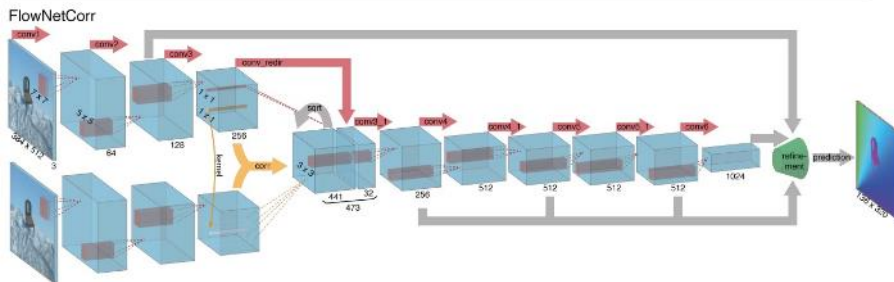
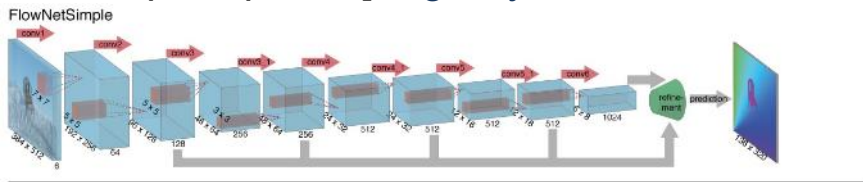
# CNN as a Similarity Measure for Matching



Stereo matching [[Zbontar and LeCun CVPR 2015](#)]  
 Compare patch [[Zagoruyko and Komodakis 2015](#)]



FaceNet [[Schroff et al. 2015](#)]

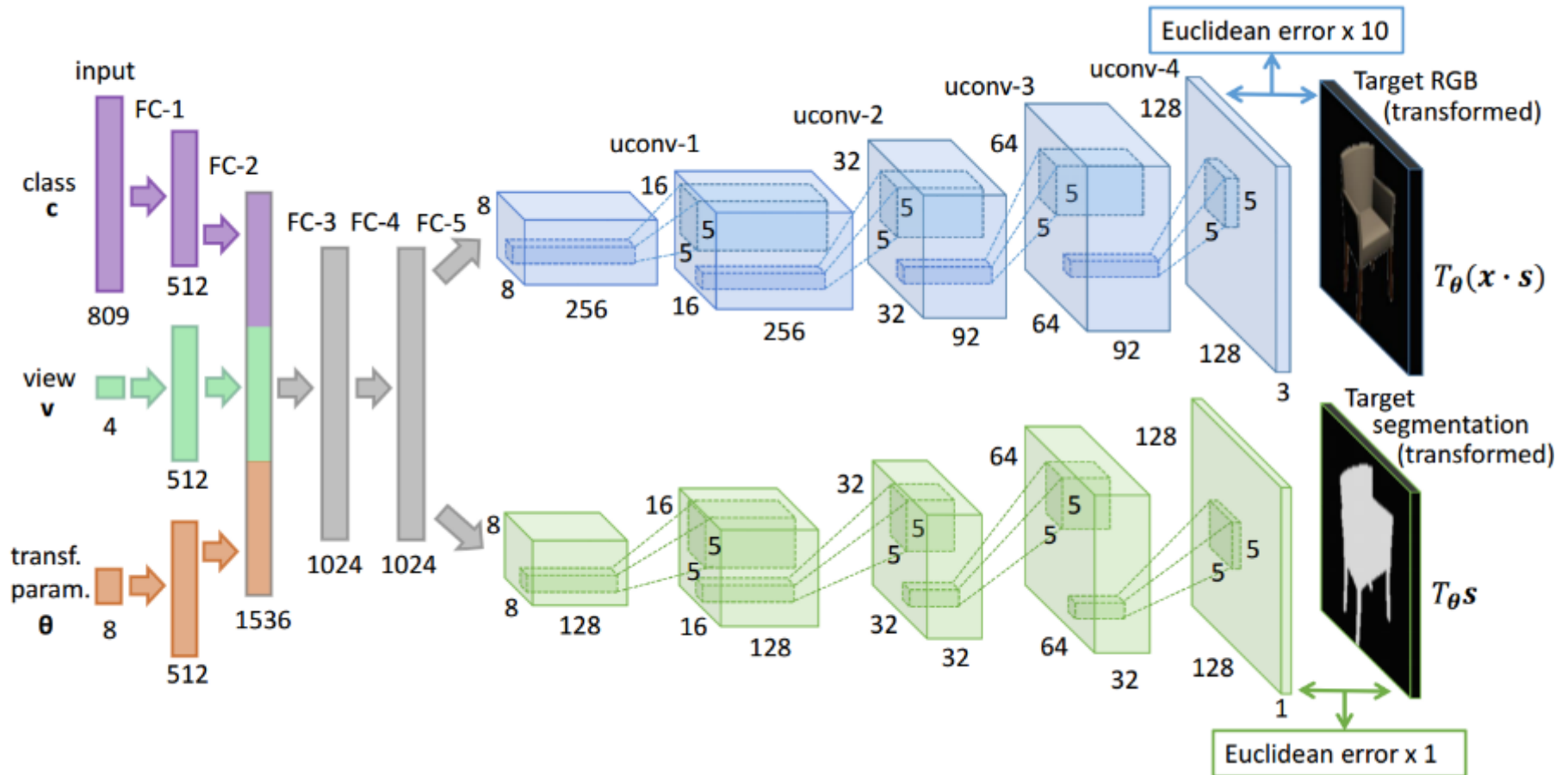


FlowNet [[Fischer et al 2015](#)]



Match ground and aerial images  
 [[Lin et al. CVPR 2015](#)]

# CNN for Image Generation



# Chair Morphing

1



# Questions?

See you Monday!